

Review Sheet 14

1) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ reflection across $y=x$.

With $\lambda_1=1$, we have $v_1=(1,1)$; and $\lambda_2=-1$, $v_2=(-1,1)$.
 $B=\{v_1, v_2\}$

$$M(T) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

2) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ 180° rotation about origin.

$\lambda_1=-1$, $v_1=(1,0)$; $v_2=(0,1)$
 $B=\{v_1, v_2\}$

$$M(T) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

3) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ 60° CC rotation

No such basis exists

4) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $T(x,y)=(x+y, x+y)$

$\lambda_1=2$, $v_1=(1,1)$; $\lambda_2=0$, $v_2=(-1,1)$ $B=\{v_1, v_2\}$

$$M(T) = \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix}$$

5) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $T(x,y)=(x,x)$

$\lambda_1=1$, $v_1=(1,1)$; $\lambda_2=0$, $v_2=(0,1)$ $B=\{v_1, v_2\}$

$$M(T) = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

6) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$, $T(x,y,z)=(x,y,0)$

$\lambda_1=0$, $v_1=(0,0,1)$; $\lambda_2=1$, $v_2=(1,0,0)$, $v_3=(0,1,0)$ $M(T) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

7) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ 180° rotation about x -axis

$\lambda_1=-1$, $v_1=(0,1,0)$, $v_2=(0,0,1)$; $\lambda_2=1$, $v_3=(1,0,0)$ $M(T) = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

8) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ $T(x,y,z)=(x,2y,3z)$

$\lambda_1=1$, $v_1=(1,0,0)$; $\lambda_2=2$, $v_2=(0,1,0)$; $\lambda_3=3$, $v_3=(0,0,1)$ $B=\{v_1, v_2, v_3\}$

$$M(T) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

9) -1 : Swapping column 1 & 2 flips sign, & det. of diagonal matrix is $1 \cdot \dots \cdot 1 = 1$.

-1 : We need to swap 5 rows, so $(-1)^5 \cdot 1 = -1$.

-720 : We need to swap 3 columns; then we multiply along the diagonal: $(-1)(1 \cdot 2 \cdot 3 \cdot 4 \cdot 5 \cdot 6) = -720$.

0 : By adding rows (specifically, $1+4+5+6=(0 \ 0 \ 0 \ 0 \ -1 \ -1)$, and $2+3=(0 \ 0 \ 0 \ 0 \ 1 \ 1)$), we see that one row is linearly dependent on the others. Thus $\det A = 0$.