## MATH 709 TAKE HOME EXAM

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**Problem 1** (Problem 6-9). Let  $F: \mathbb{R}^2 \to \mathbb{R}^3$  be the map  $F(x,y) = (e^y \cos x, e^y \sin x, e^{-y})$ . For which positive numbers r is F transverse to the sphere  $S_r(0) \subseteq \mathbb{R}^3$ ? For which positive numbers r is  $F^{-1}(S_r(0))$  an embedded submanifold of  $\mathbb{R}^2$ ?

Solution. Note that we have ||F(x,y)|| = r only when

$$r^{2} = e^{2y}\cos^{2}x + e^{2y}\sin^{2}x + e^{-2y} = e^{2y} + e^{-2y};$$

that is, when

$$y = \frac{1}{2} \log \left( \frac{1}{2} \left( r^2 \pm \sqrt{r^4 - 4} \right) \right).$$

Hence  $||F(x,y)|| \ge \sqrt{2} \ \forall (x,y) \in \mathbb{R}^2$ , and therefore F is trivially transverse to  $S_r$  for  $r \in [0,\sqrt{2})$   $(F^{-1}(S_r(0)))$  is empty in this case). Now, for every  $(x,y) \in \mathbb{R}^2$ , we must have  $F(x,y) \perp T_{F(x,y)}S_r$  if  $F(x,y) \in S_r$ . Then we compute the inner product of F(x,y) with the columns of DF(x,y):

$$(e^y\cos x, e^y\sin x, e^{-y})\cdot\begin{pmatrix} -e^y\sin x\\ e^y\cos x\\ 0\end{pmatrix} = 0 \quad \text{and} \quad (e^y\cos x, e^y\sin x, e^{-y})\cdot\begin{pmatrix} e^y\cos x\\ e^y\sin x\\ -e^{-y}\end{pmatrix} = e^{2y} - e^{-2y}.$$

The second inner product is zero only when y = 0, which is the case only when  $||F(x,y)|| = \sqrt{2}$ . Hence, since  $T_{F(x,y)}S_r$  and  $DF_{(x,y)}(T_{(x,y)}\mathbb{R}^2)$  span  $T_{F(x,y)}\mathbb{R}^3$  only when  $r \neq \sqrt{2}$ , we conclude that F is transverse to  $S_r$  for  $r \in [0, \sqrt{2}) \cup (\sqrt{2}, \infty)$ .

Now, by part a) of Theorem  $6.30^1$  from the text, we are guaranteed that  $F^{-1}(S_r(0))$  is an embedded submanifold of  $\mathbb{R}^2$  for  $r \in [0, \sqrt{2}) \cup (\sqrt{2}, \infty)$ ; so we only need to check when  $r = \sqrt{2}$ . But note that in this case  $F^{-1}(S_{\sqrt{2}}(0))$  is just a line in  $\mathbb{R}^2$ , so it is an embedded submanifold as well.

**Problem 2** (Problem 7-1). Show that for any Lie group G, the multiplication map  $m: G \times G \to G$  is a smooth submersion. (Hint: use local sections.)

*Proof.* Following the provided hint, note that for each  $g \in G$ , the map  $\sigma_g \colon G \to G \times G$  given by  $x \mapsto (g, g^{-1}x)$  (which is clearly well defined) is a smooth local section of m, since

$$m(\sigma_g(x)) = m((g,g^{-1}x)) = g(g^{-1}x) = (gg^{-1})x = ex = x.$$

Hence, since every point  $(g_1, g_2) \in G \times G$  is in the image of  $\sigma_{g_1}$ , we know by The Local Section Theorem<sup>2</sup> that m is a smooth submersion. To see this, take any point  $p = (g_1, g_2) \in G \times G$  and

<sup>&</sup>lt;sup>1</sup>Here's the statement, for reference:

Suppose N and M are smooth manifolds and  $S \subseteq M$  is an embedded submanifold. If  $F \colon N \to M$  is a smooth map that is transverse to S, then  $F^{-1}(S)$  is an embedded submanifold of N whose codimension is equal to the codimension of S in M.

<sup>&</sup>lt;sup>2</sup>The theorem states that if M and N are smooth manifolds and  $\pi: M \to N$  is a smooth map, then  $\pi$  is a smooth submersion if and only if every point of M is in the image of a smooth local section of  $\pi$ .

let  $\sigma_{g_1}: U \to G \times G$  be a smooth local section such that  $\sigma_{g_1}(q) = p$ . Here U is an open set of G containing q, where  $q = m(\sigma_{q_1}(q)) = m(p) \in G$ . Then,

$$m \circ \sigma_{g_1} = \operatorname{Id}_U \implies dm_p \circ d\sigma_{g_1} \Big|_{g} = \operatorname{Id}_{T_q} G \implies dm_p \text{ is surjective.}$$

**Problem 3** (Problem 7-2). Let G be a Lie group.

- a) Let  $m: G \times G \to G$  denote the multiplication map. Using Proposition 3.14<sup>3</sup> to identify  $T_{(e,e)}(G \times G)$  with  $T_eG \oplus T_eG$ , show that the differential  $dm_{(e,e)}: T_eG \oplus T_eG \to T_eG$  is given by  $dm_{(e,e)}(X,Y) = X + Y$ . (Hint: compute  $dm_{(e,e)}(X,0)$  and  $dm_{(e,e)}(0,Y)$  separately.)
- b) Let  $i: G \to G$  denote the inversion map. Show that  $di_e: T_eG \to T_eG$  is given by  $di_e(X) = -X$ .

*Proof of a).* Consider the maps  $\dot{m}, \ddot{m}: G \to G \times G$  given by  $x \mapsto (x, e)$  and  $y \mapsto (e, y)$ , respectively. Note that  $m \circ \dot{m} = m \circ \ddot{m} = \mathrm{Id}_G$ . Thus,

$$dm_{(e,e)}(X,Y) = dm_{(e,e)}(X,0) + dm_{(e,e)}(0,Y)$$

$$= d(m \circ \dot{m})_e(X) + d(m \circ \ddot{m})_e(Y)$$

$$= d \operatorname{Id}_G|_e(X) + d \operatorname{Id}_G|_e(Y)$$

$$= X + Y.$$

Proof of b). Let  $\varphi = m \circ (\operatorname{Id}_G \times i) : G \to G$ . Note that  $(m \circ (\operatorname{Id}_G \times i))(x) = m((x, x^{-1})) = xx^{-1} = e$ . Therefore,

$$0 = d\varphi_{e}(X)$$

$$= dm_{(e,e)} \circ d(\operatorname{Id}_{G} \times i)_{e}(X)$$

$$= dm_{(e,e)} \circ (\operatorname{Id}_{T_{e}G} \times di_{e})(X)$$

$$= dm_{(e,e)}(\operatorname{Id}_{T_{e}G}(X), di_{e}(X))$$

$$= dm_{(e,e)}(X, di_{e}(X))$$

$$= X + di_{e}(X).$$
 (by part a)).

Hence it follows that  $di_e(X) = -X$ , as desired.

**Problem 4** (Problem 7-6). Suppose G is a Lie group and U is any neighborhood of the identity. Show that there exists a neighborhood V of the identity such that  $V \subseteq U$  and  $gh^{-1} \in U$  whenever  $g, h \in V$ .

**Proposition** (The Tangent Space to a Product Manifold). Let  $M_1, \ldots, M_k$  be smooth manifolds, and for each j, let  $\pi_j : M_1 \times \cdots \times M_k \to M_j$  be the projection onto the  $M_j$  factor. For any point  $p = (p_1, \ldots, p_k) \in M_1 \times \cdots \times M_k$  and tangent vector  $\nu \in T_p(M_1 \times \cdots \times M_k)$ , the map

$$\alpha: T_p(M_1 \times \cdots \times M_k) \longrightarrow T_{p_1}M_1 \oplus \cdots \oplus T_{p_k}M_k$$

defined by

$$\alpha(\nu) = (d(\pi_1)_p(\nu), \dots, d(\pi_k)_p(\nu))$$

is an isomorphism. The same is true if one of the spaces  $M_i$  is a smooth manifold with boundary.

<sup>&</sup>lt;sup>3</sup>Here's the proposition, for reference:

Proof. Define  $f: G \times G \to G$  by  $f(g,h) = gh^{-1}$  and let  $W = f^{-1}(U)$ . By assumption  $e \in U$ , so  $(e,e) \in W$  and there are neighborhoods  $W_1, W_2$  of e such that  $(e,e) \in W_1 \times W_2 \subseteq W$ . Then  $V = W_1 \cap W_2$  is the desired neighborhood of the identity. Note that by elementary set theory, we have  $f(f^{-1}(U) \subseteq U)$ , so it holds that  $W_1 \cap W_2 \subseteq U$  and  $gh^{-1} \in U$  whenever  $g, h \in W_1 \cap W_2$ , as desired.

**Problem 5.** Determine all of the Lie subgroups of the Lie group  $(\mathbb{R}^2, +)$ .

Solution. Let us break down all of the Lie subgroups of  $(\mathbb{R}^2, +)$  by dimensions:

- <u>0 dimension</u>: For  $\mathbb{Q}$  and  $\mathbb{Z}$  with the discrete topology, we have  $(\mathbb{Z},+)$ ,  $(\mathbb{Q},+)$ ,  $(\mathbb{Z}^2,+)$ ,  $(\mathbb{Q}^2,+)$ , and  $(\mathbb{Z} \times \mathbb{Q},+)$  (similarly  $(\mathbb{Q} \times \mathbb{Z},+)$ ). Note that these groups are clearly subgroups of  $(\mathbb{R}^2,+)$  (in the algebraic sense) and they are also immersed submanifolds of  $\mathbb{R}^2$ . in addition, they are countably infinite, so they are zero-dimensional (discrete) Lie groups.
- $\begin{array}{ll} \underline{1 \text{ dimension}} \colon & -\text{ If } \mathbb{Q} \text{ and } \mathbb{Z} \text{ are given the discrete topology, then } (\mathbb{R} \times \mathbb{Q}, +) \text{ and } (\mathbb{R} \times \mathbb{Z}, +) \text{ (similarly } (\mathbb{Q} \times \mathbb{R}, +) \text{ and } (\mathbb{Z} \times \mathbb{R}, +)) \text{ are Lie subgroups of } (\mathbb{R}^2, +) \text{ having dimension } 1. \end{array}$ 
  - All lines through the origin.
- <u>2 dimension</u>: All of the Lie subgroups of  $(\mathbb{R}^2, +)$  of codimension 0 are exactly the open Lie subgroups of  $(\mathbb{R}^2, +)$ . But by *Lemma 7.12*<sup>4</sup>, we have that these subgroups must also be closed. However, since  $\mathbb{R}^2$  is connected, we have that  $(\mathbb{R}^2, +)$  does not contain any proper nontrivial two-dimensional Lie subgroup.

I believe that these are (up to isomorphism) all of the Lie subgroups of  $(\mathbb{R}^2, +)$ .

<sup>&</sup>lt;sup>4</sup>The lemma states that if G is a Lie group and  $H \subseteq G$  is an open subgroup, then H is an embedded Lie subgroup. In addition, H is closed, so it is a union of connected components of G.