

Problem 1. *a)* Use the method of undetermined coefficients to set up the 5×5 Vandermonde system that would determine a fourth-order accurate finite difference approximation to $u''(x)$ based on 5 equally spaced points,

$$u''(x) = c_{-2}u(x-2h) + c_{-1}u(x-h) + c_0u(x) + c_1u(x+h) + c_2u(x+2h) + O(h^4). \quad (1)$$

b) Compute the coefficients using the MATLAB code `fdstencil.m` available from the Randy LeVeque's website. The codes will be posted also in MyCourses under Contents/Codes (download both `fdstencil.m` and `fdcoeffV.m`). Verify that the coefficients satisfy the system you determined in part *a*).

Solution to *a*). In order to use the method of undetermined coefficients we first need to Taylor-expand the expressions on Eq. (1):

$$u(x+h) = u(x) + u'(x)h + u''(x)\frac{h^2}{2} + u'''(x)\frac{h^3}{6} + u^{(4)}(x)\frac{h^4}{24} + O(h^5) \quad (2a)$$

$$u(x-h) = u(x) - u'(x)h + u''(x)\frac{h^2}{2} - u'''(x)\frac{h^3}{6} + u^{(4)}(x)\frac{h^4}{24} + O(h^5) \quad (2b)$$

$$u(x+2h) = u(x) + 2u'(x)h + 2u''(x)h^2 + u'''(x)\frac{4h^3}{3} + u^{(4)}(x)\frac{2h^4}{3} + O(h^5) \quad (2c)$$

$$u(x-2h) = u(x) - 2u'(x)h + 2u''(x)h^2 - u'''(x)\frac{4h^3}{3} + u^{(4)}(x)\frac{2h^4}{3} + O(h^5). \quad (2d)$$

Now, matching these expressions with the coefficients c_i on (1), we get

$$\begin{aligned} u''(x) &= (c_{-2} + c_{-1} + c_0 + c_1 + c_2)u(x) \\ &+ (-2c_{-2} - c_{-1} + c_1 + 2c_2)hu'(x) \\ &+ \frac{1}{2}(4c_{-2} + c_{-1} + c_1 + 4c_2)h^2u''(x) \\ &+ \frac{1}{6}(-8c_{-2} - c_{-1} + c_1 + 8c_2)h^3u'''(x) \\ &+ \frac{1}{24}(16c_{-2} + c_{-1} + c_1 + 16c_2)h^4u^{(4)}(x). \end{aligned}$$

In order for this expression to be compatible with Eq. (1), the following linear system must be satisfied:

$$\begin{aligned} c_{-2} + c_{-1} + c_0 + c_1 + c_2 &= 0 \\ -2c_{-2} - c_{-1} + c_1 + 2c_2 &= 0 \\ 4c_{-2} + c_{-1} + c_1 + 4c_2 &= \frac{2}{h^2} \\ -8c_{-2} - c_{-1} + c_1 + 8c_2 &= 0 \\ 16c_{-2} + c_{-1} + c_1 + 16c_2 &= 0, \end{aligned}$$

or, in matrix form,

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ -2 & -1 & 0 & 1 & 2 \\ 4 & 1 & 0 & 1 & 4 \\ -8 & -1 & 0 & 1 & 8 \\ 16 & 1 & 0 & 1 & 16 \end{bmatrix} \begin{bmatrix} c_{-2} \\ c_{-1} \\ c_0 \\ c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \frac{2}{h^2} \\ 0 \\ 0 \end{bmatrix}. \quad (3)$$

The solution to this system is

$$\begin{bmatrix} c_{-2} \\ c_{-1} \\ c_0 \\ c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{12h^2} \\ \frac{4}{3h^2} \\ -\frac{5}{2h^2} \\ \frac{4}{3h^2} \\ -\frac{1}{12h^2} \end{bmatrix}.$$

□

Solution to [b](#)). Indeed, using the provided code in the `fdcoeffV.m` file, we get $h^2 * c_i$, where c_i are the coefficients that we got on part [a](#)):

```
1 >> j = [-2:2];
2 >> fdcoeffV(2,0,j)
3
4 ans =
5 -0.0833    1.3333   -2.5000    1.3333   -0.0833
```

□

Problem 2. Consider the following finite difference approximation for $u'(\bar{x})$

$$Du(\bar{x}) = \frac{1}{2h} [3u(\bar{x}) - 4u(\bar{x} - h) + u(\bar{x} - 2h)]. \quad (4)$$

[a](#)) Approximate the derivative $u'(\bar{x})$ for one of the choices below

i. $u(x) = e^{-3x} \sin(2x), \bar{x} = 1.23$

ii. $u(x) = \arctan(4x), \bar{x} = -0.45$

using the formula above for $h = 10^{-1}, h = 5 \times 10^{-2}, h = 10^{-2}, h = 5 \times 10^{-3}, h = 10^{-3}$, and $h = 5 \times 10^{-4}$. Make a table containing approximate derivatives and the corresponding errors (error = actual - approximate) for all h values.

[b](#)) Plot h values vs. absolute errors in log-log scale (i.e., plot $\log(h_i)$ vs. $\log|E(h_i)|$). You can use ~~MATLAB~~ `loglog` (Mathematica's `ListLogLogPlot`!) to produce the plot.

[c](#)) Assume that the error behaves according to $|E(h)| \approx Ch^p$ and determine the (numerical) order of convergence p using your results from part [b](#)). Find the constant C in the error expression.

Solution to [a](#)). Start with the first function, [i](#). We rewrite its derivative approximation (4) as a function of h :

$$Du(h)|_{\bar{x}=1.23} = \frac{1}{2h} \left[3e^{-3 \cdot 1.23} \sin(2 \cdot 1.23) - 4e^{-3 \cdot (1.23-h)} \sin[2 \cdot (1.23-h)] + e^{-3 \cdot (1.23-2h)} \sin[2 \cdot (1.23-2h)] \right].$$

The values for this function for the given values of h are seen on the output on the following Mathematica snippet:

```
1 In[1]:= D1[h_] :=
2 1/(2*h)* (
3 3*E^(-3*1.23)*Sin[2*1.23] -
4 4*E^(-3*(1.23 - h))*Sin[2*(1.23 - h)] +
5 E^(-3*(1.23 - 2 h))*Sin[2*(1.23 - 2 h)]
6 );
7 Table[D1[h], {h, {10^-1, 5*10^-2, 10^-2, 5*10^-3, 10^-3, 5*10^-4 }}]
8
9 Out[2]= {-0.0834738, -0.0853506, -0.0859593, -0.0859781, -0.0859842, -0.0859843}
```

Similarly, for function *ii.*,

$$Du(h)|_{\bar{x}=-0.45} = \frac{1}{2h} [3 \arctan [4 \cdot (-0.45)] - 4 \arctan [4 \cdot (-0.45 - h)] + \arctan [4 \cdot (-0.45 - 2h)]] ,$$

we get

```

1 In[3]:= D2[h_] :=
2   1/(2*h)*(
3     3*ArcTan[4*(-0.45)]
4     - 4*ArcTan[4*(-0.45 - h)]
5     + ArcTan[4*(-0.45 - 2 h)]
6   );
7 Table[D2[h], {h, {10^-1, 5*10^-2, 10^-2, 5*10^-3, 10^-3, 5*10^-4 }}]
8
9 Out[4]= {0.909797, 0.933326, 0.942927, 0.943277, 0.943391, 0.943395}

```

The actual values for the derivatives of these functions evaluated at the given respective \bar{x} values are

```

1 In[1]:= D[E^(-3x)*Sin[2x], x] /. x -> 1.23
2 In[2]:= D[ArcTan[4x], x] /. x -> -0.45
3
4 Out[1]= -0.0859844
5 Out[2]= 0.943396

```

Let us summarize our results in the following table:¹

h	(i.) Du	(i.) E	(ii.) Du	(ii.) E
10^{-1}	-0.0834738	0.00251063	0.909797	0.0335994
5×10^{-2}	-0.0853506	0.000633807	0.933326	0.0100705
10^{-2}	-0.0859593	0.0000251206	0.942927	0.000469375
5×10^{-3}	-0.0859781	6.26751×10^{-6}	0.943277	0.000119657
10^{-3}	-0.0859842	2.50265×10^{-7}	0.943391	4.86187×10^{-6}
5×10^{-4}	-0.0859843	6.25523×10^{-8}	0.943395	1.21785×10^{-6}

□

Solution to *b*). The following plots were generated using Mathematica's ListLogLogPlot:

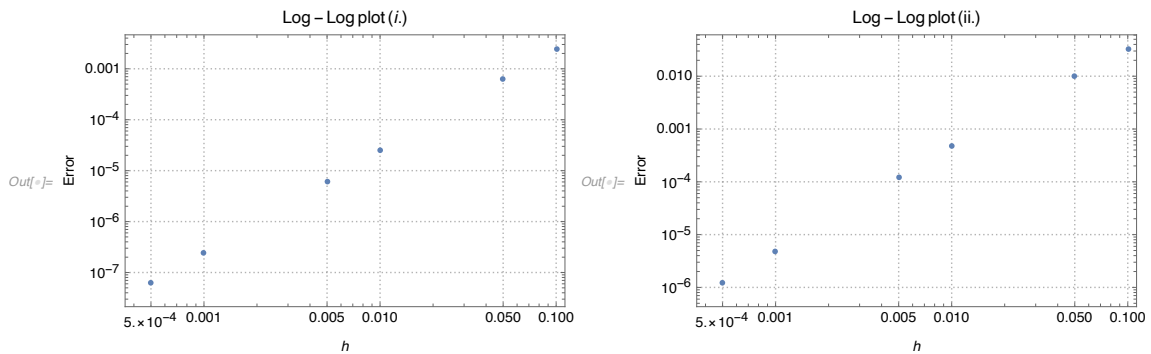


Figure 1: Log-Log plots of the absolute errors (y-axis) vs. the h values (x-axis) for the derivative approximations to the function in *i.* (left) and the function in *ii.* (right). □

¹The left-superscripts denote the function (*i.* or *ii.*) to which the derivative approximations (Du) and the errors (E) belong. Also, the errors are written as absolute-value errors.

Solution to c). If the error behaves like $|E(h)| \approx Ch^p$, then we must have

$$\log |E(h)| \approx \log |C| + p \log h.$$

The Mathematica snippet below shows that $p \approx 2$, which signals that the approximation (4) has quadratic order of convergence. We also see that $\log^{(i.)} C = -1.37376$ and $\log^{(ii.)} C = 1.17351$, so that $\log^{(i.)} C \approx 0.25$ and $\log^{(ii.)} C \approx 3.23$.

```

1 In[30]:=
2 logdata1 = Table[{Log[h[[i]]], Log[error1[[i]]]}, {i, 1, 6}];
3 logdata2 = Table[{Log[h[[i]]], Log[error2[[i]]]}, {i, 1, 6}];
4 Fit[logdata1, {1, x}, x]
5 Fit[logdata2, {1, x}, x]
6
7 Out[31]= -1.37376 + 2.0016 x
8 Out[32]= 1.17351 + 1.93804 x

```

□

Problem 3. Consider the BVP

$$u_{xx} = 1 - |x|, \quad x \in (-1, 1) \quad (5a)$$

$$u(-1) = 5, \quad u(1) = 7. \quad (5b)$$

- a) Solve the BVP analytically.
- b) Discretize the BVP using grid points $x_i = -1 + ih$, $i = 0, 1, \dots, n+1$ where $h = 2/(n+1)$ by using the centered finite difference scheme. Solve the resulting linear system with an $n \times n$ coefficient matrix and plot the numerical solution for $n = 49$ along with the exact solution you computed in part (a).
- c) Record the L^1 , L^2 , and L^∞ norm errors for $n = 24, 49, 99, 199$.
- d) Find the slope of the line in a log-log plot of the error $\|u_n - u_{\text{exact}}\|_p$ ($p = 1, 2, \infty$) as a function of n . Is this what would you expect? Explain.
- e) Solve the linear system for $n \in \{9, 49, 99, 999, 4999, 9999\}$ and document the CPU times.

Solution to a). Integrating twice, we get

$$u(x) = \begin{cases} \iint (1+x) dx^2 & x \in (-1, 0]; \\ \iint (1-x) dx^2 & x \in [0, 1). \end{cases} \quad (6a)$$

Since the function u is assumed to be continuous, the value of the piecewise at $x = 0$ must be consistent. In fact, since we are evaluating a second-order ODE, the function u must be (at least) C^2 , which means that not just u , but also u' and u'' must have a consistent value at $x = 0$; we shall use this in what follows to determine some of the coefficients of integration.

Expanding (6a), we have

$$u(x) = \begin{cases} \frac{x^3}{6} + \frac{x^2}{2} + {}^-C_1 x + {}^-C_2 & x \in (-1, 0]; \\ -\frac{x^3}{6} + \frac{x^2}{2} + {}^+C_1 x + {}^+C_2 & x \in [0, 1). \end{cases} \quad (6b)$$

Hence we have four yet-to-be-determined constants ${}^-C_1$, ${}^-C_2$, ${}^+C_1$, and ${}^+C_2$. At $x = 0$, the two expressions must be equal; thus,

$$u(0) = {}^-C_2 = {}^+C_2.$$

So we may drop the superscript and just call this constant C_2 . Now, as we alluded to earlier, $u'(0)$ must also have a consistent value from the expressions in the piecewise; so

$$u'(0) = {}^-C_1 = {}^+C_1.$$

Thus, again, we drop the superscript and call this constant C_1 . Hence we are left with two coefficients C_1 and C_2 , and we have two boundary conditions, so the problem can be fully determined:

$$\begin{aligned} 5 &= u(-1) = -\frac{1}{6} + \frac{1}{2} - C_1 + C_2; \\ 7 &= u(1) = -\frac{1}{6} + \frac{1}{2} + C_1 + C_2. \end{aligned}$$

So we have the system

$$\begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} \frac{14}{3} \\ \frac{20}{3} \end{bmatrix},$$

with solution

$$\begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{17}{3} \end{bmatrix}$$

Therefore, we conclude that our function u is given by

$$u(x) = \begin{cases} \frac{x^3}{6} + \frac{x^2}{2} + x + \frac{17}{3} & x \in (-1, 0]; \\ -\frac{x^3}{6} + \frac{x^2}{2} + x + \frac{17}{3} & x \in [0, 1). \end{cases}$$

Or, simply,

$$u(x) = -\frac{|x|^3}{6} + \frac{x^2}{2} + x + \frac{17}{3} \quad \square \quad (7)$$



Solution to [b](#)). The centered discretization of the BVP (5) is of the form

$$\frac{u_{i-1} - 2u_i + u_{i+1}}{h^2} = 1 - |x_i|, \quad i = 1, \dots, n$$

or, in matrix form,

$$\underbrace{\frac{1}{h^2} \begin{bmatrix} -2 & 1 & & & \\ 1 & -2 & 1 & & \\ & 1 & -2 & 1 & \\ & & \ddots & \ddots & \ddots \\ & & & 1 & -2 & 1 \\ & & & & 1 & -2 \end{bmatrix}}_{\mathbf{A}} \underbrace{\begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_i \\ \vdots \\ u_n \end{bmatrix}}_{\mathbf{u}} = \underbrace{\begin{bmatrix} 1 - |x_1| - 5/h^2 \\ 1 - |x_2| \\ \vdots \\ \vdots \\ 1 - |x_{n-1}| \\ 1 - |x_n| - 7/h^2 \end{bmatrix}}_{\mathbf{f}}.$$

The following **MATLAB** code solves this linear system for \mathbf{u} and plots both the numerical solution and the closed-form solution we found in part [a](#)):

```
1 %Set constants:
2 a = -1;
3 b = 1;
4 alph = 5;
5 bet = 7;
6 n = 49;
7 h = (b-a)/(n+1);
8
9 %Generate the matrix A (size nxn):
10 A = zeros(n); %initialize nxn matrix
11 for i = 1:n
12     for j = 1:n
13         if i == j
14             A(i,i) = -2/h^2;
15         elseif (j == i+1) || (i == j+1)
16             A(i,j) = 1/h^2;
17         end
18     end
19 end
```

```

20
21 %define the x grid in either of the two ways:
22
23 %Method 1:
24 % for i = 0:n+1
25 %     x(i+1) = -1+i*h;
26 % end
27
28 %or Method 2:
29 x = linspace(a,b,n+2); %size n+2 (n interior pts + 2 BCs)
30
31 %define function vector f:
32 f = zeros(n,1); %initialize nx1 vector
33 for i = 1:n
34     if i==1
35         f(i) = 1 - abs(x(i+1)) - alph/h^2;
36     elseif i == n
37         f(i) = 1 - abs(x(i+1)) - bet/h^2;
38     else
39         f(i) = 1 - abs(x(i+1));
40     end
41 end
42
43 %Use linear solver to solve Au=f for u:
44 u = linsolve(A,f);
45 usol = [alpha; u; beta]; %extend solution to include BCs
46
47 %Plot results:
48 plot(x,usol, "r--x")
49 hold on
50 funct = @(t) -(abs(t)^3)/6 + t^2/2 + t + 17/3; %closed-form solution
51 fplot(funct, [-1,1], "g--o")
52 ylabel("u(x)")
53 xlabel("x")
54 legend("Numerical Solution", "Exact Solution", 'Location','northwest')
55 exportgraphics(gcf, 'BVP_1.pdf')

```

The code generates the following plot:

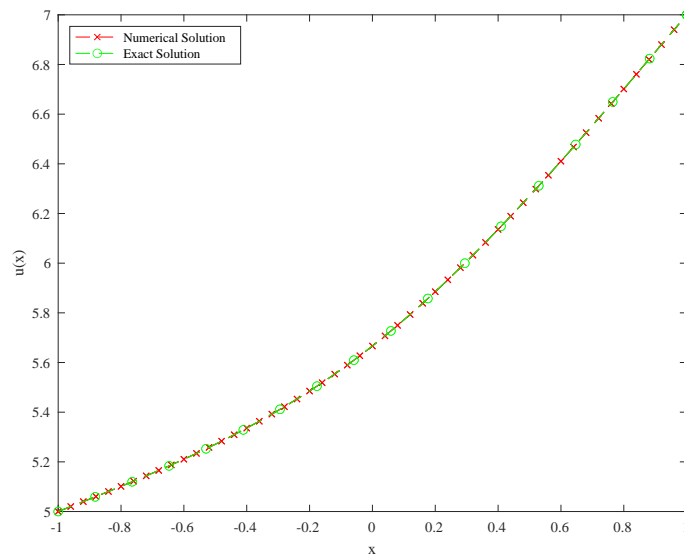


Figure 2: Closed-form and numerical solutions (for $n = 49$ grid points) of the BVP (5).

They match quite nicely!

□



Solution to c). We modify the code to record all three norms for the different n-values:

```

1 %Set constants:
2 a = -1;
3 b = 1;
4 alph = 5;
5 bet = 7;
6 N = [24,49,99,199];
7
8 %initialize vectors of norms to be used later:
9 norml1_vec = zeros(size(N,2),1);
10 norml2_vec = zeros(size(N,2),1);
11 normlinf_vec = zeros(size(N,2),1);
12
13 for n = N
14
15     h = (b-a)/(n+1);
16
17     %Generate the matrix A (size nxn):
18     A = zeros(n); %initialize nxn matrix
19     for i = 1:n
20         for j = 1:n
21             if i == j
22                 A(i,i) = -2/h^2;
23             elseif (j == i+1) || (i == j+1)
24                 A(i,j) = 1/h^2;
25             end
26         end
27     end
28
29     %define the x grid:
30     x = linspace(a,b,n+2); %size n+2 (n interior pts + 2 BCs)
31
32     %define function vector f:
33     f = zeros(n,1); %initialize nx1 vector
34     for i = 1:n
35         if i==1
36             f(i) = 1 - abs(x(i+1)) - alph/h^2;
37         elseif i == n
38             f(i) = 1 - abs(x(i+1)) - bet/h^2;
39         else
40             f(i) = 1 - abs(x(i+1));
41         end
42     end
43
44     %Use linear solver to solve Au=f for u:
45     u = linsolve(A,f);
46     usol = [alph; u; bet]; %extend solution to include BCs
47
48     %closed-form solution
49     funct = @(t) -(abs(t)^3)/6 + t^2/2 + t + 17/3;
50
51
52     %generate vector of errors
53     error_vec = zeros(n,1);
54     for i = 1:n
55         error_vec(i) = usol(i) - funct(x(i));
56     end
57
58     l1 = norm(error_vec,1);
59     l2 = norm(error_vec,2);
60     l_inf = norm(error_vec,Inf);
61
62     %fill in vectors of norms (we'll use these in the next part):
63     it = find(N==n); %get the n-index of the tuple N
64     norml1_vec(it) = l1;
65     norml2_vec(it) = l2;
66     normlinf_vec(it) = l_inf;
67
68     %displays the norms, for each n
69     norm_display_1 = ['The L1 norm for n= ',num2str(n), ' is ', num2str(l1)];
70     norm_display_2 = ['The L2 norm for n= ',num2str(n), ' is ', num2str(l2)];
71     norm_display_inf = ['The L^inf norm for n= ',num2str(n), ' is ', num2str(l_inf)];
72     disp(norm_display_1)
73     disp(norm_display_2)
74     disp(norm_display_inf)
75 end

```

The resulting norms are

```

1 The L1 norm for n= 24 is 0.0033067
2 The L2 norm for n= 24 is 0.00076889
3 The L^inf norm for n= 24 is 0.000256
4 The L1 norm for n= 49 is 0.006656
5 The L2 norm for n= 49 is 0.001089
6 The L^inf norm for n= 49 is 0.00026667
7 The L1 norm for n= 99 is 0.003332
8 The L2 norm for n= 99 is 0.00038494
9 The L^inf norm for n= 99 is 6.6667e-05
10 The L1 norm for n= 199 is 0.0016665
11 The L2 norm for n= 199 is 0.00013609
12 The L^inf norm for n= 199 is 1.6667e-05

```

□

Solution to d). The figure shows a log-log plot of the errors that we found on part c):

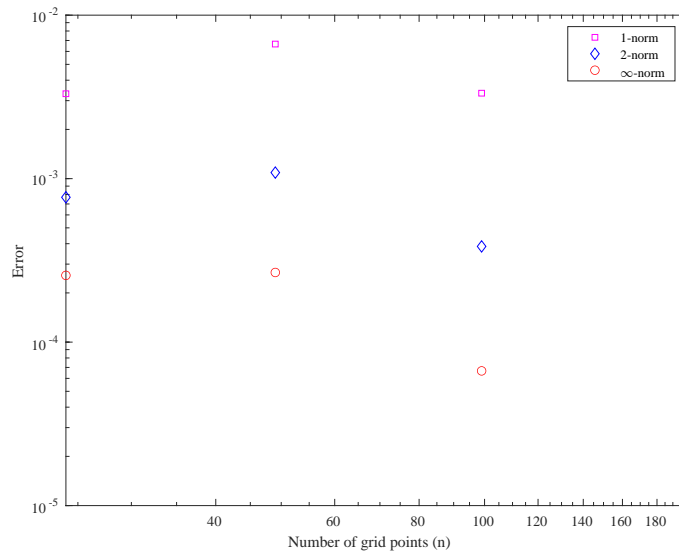


Figure 3: Log-Log plot of the errors using 1-, 2-, and ∞ -norms, as a function of the number of grid points n .

The results for $n = 24$ stray from what would otherwise be a (fairly) straight line. Nevertheless, we could get a slope for all three norms by considering the values at any two n -values other than $n = 24$. For instance, we may add in our code

```

1 %Get the slopes
2 slope_l1 = ( norml1_vec(end-1) - norml1_vec(end-2) ) / ( N(end-1) - N(end-2) );
3 slope_l2 = ( norml2_vec(end-1) - norml2_vec(end-2) ) / ( N(end-1) - N(end-2) );
4 slope_linf = ( normlinf_vec(end-1) - normlinf_vec(end-2) ) / ( N(end-1) - N(end-2) );

```

This yields the slopes

```

1 slope_l1 = -6.6480e-05
2 slope_l2 = -1.4082e-05
3 slope_linf = -4.0000e-06

```

There are both unexpected and expected results here. Firstly, I was not expecting to find lower errors for $n = 24$ than for $n = 49$. This rather surprising behavior is consistent for all three norms tested. On the other hand, the way in which the norms compare with one another for a fixed number of grid points n was indeed expected, since we know that $\|\mathbf{x}\|_\infty \leq \|\mathbf{x}\|_2 \leq \|\mathbf{x}\|_1$ for all $\mathbf{x} \in \mathbb{R}^m$. Proof: Let $i \in [1, m]$ be the index that maximizes $|x_i|$; that is,

$$\|\mathbf{x}\|_\infty = \max_{1 \leq i \leq m} |x_i| = |x_i|.$$

Then,

$$\|x\|_2 = \left(\sum_{i=1}^m |x_i|^2 \right)^{1/2} = \left(|x_i|^2 + \sum_{i \neq i} |x_i|^2 \right)^{1/2} \geq |x_i| = \|x\|_\infty. \quad \checkmark$$

As for the other inequality, note that

$$\|x\|_2^2 = \sum_{i=1}^m |x_i|^2 \leq \sum_{i=1}^m |x_i|^2 + 2 \sum_{i \neq j} |x_i| |x_j| = \|x\|_1^2 \implies \|x\|_2 \leq \|x\|_1. \quad \checkmark \quad \square$$

Solution to e). The following code solves the system for $n \in \{9, 49, 99, 999, 4999, 9999\}$, and documents the CPU times (in seconds):

```

1 %Set constants:
2 a = -1;
3 b = 1;
4 alph = 5;
5 bet = 7;
6 N = [9, 49, 99, 999, 4999, 9999];
7
8 for n = N
9
10     %Start CPU clock
11     tStart = cputime;
12
13     h = (b-a)/(n+1);
14
15     %Generate the matrix A (size nxn):
16     A = zeros(n); %initialize nxn matrix
17     for i = 1:n
18         for j = 1:n
19             if i == j
20                 A(i,i) = -2/h^2;
21             elseif (j == i+1) || (i == j+1)
22                 A(i,j) = 1/h^2;
23             end
24         end
25     end
26
27     %define the x grid:
28     x = linspace(a,b,n+2); %size n+2 (n interior pts + 2 BCs)
29
30     %define function vector f:
31     f = zeros(n,1); %initialize nx1 vector
32     for i = 1:n
33         if i==1
34             f(i) = 1 - abs(x(i+1)) - alph/h^2;
35         elseif i == n
36             f(i) = 1 - abs(x(i+1)) - bet/h^2;
37         else
38             f(i) = 1 - abs(x(i+1));
39         end
40     end
41
42     %Use linear solver to solve Au=f for u:
43     u = linsolve(A,f);
44     usol = [alph; u; bet]; %extend solution to include BCs
45
46     tEnd = cputime - tStart;
47     %displays the cpu time
48     cpu_display = ['For n= ', num2str(n), ' the CPU time was ', num2str(tEnd), ' seconds.'
49 ];
50     disp(cpu_display)
51 end

```

The results were as follows:

```

1 For n= 9 the CPU time was 0.01 seconds.
2 For n= 49 the CPU time was 0 seconds.

```

```

3 For n= 99 the CPU time was 0.01 seconds.
4 For n= 999 the CPU time was 0.16 seconds.
5 For n= 4999 the CPU time was 3.03 seconds.
6 For n= 9999 the CPU time was 19.56 seconds.

```

I do not understand how MATLAB claims that it took "0" seconds to run the code for $n = 49$... Not sure how reliable this cputime function really is... \square

Problem 4. Use the centered finite difference scheme to approximate solutions to the linear BVP

$$u'' = u + \frac{2}{3}e^x, \quad u(0) = 0, \quad u(1) = \frac{1}{3}e. \quad (8)$$

- *a) Specify the entries of the $n \times n$ matrix A and the vector F in the linear system $AU = F$ resulting from the approximation.*
- *b) Plot the approximate solution for $n = 69$ (number of interior grid points) together with the exact solution $u(x) = 1/3 xe^x$.*
- *c) Plot the absolute error as a function of x in a semi-log plot (i.e. x_i vs. $\log|e(x_i)| = \log|U_i - u(x_i)|$). You can use MATLAB's semilogy to produce the plot.*

Solution to a). The centered discretization of the BVP (8) is of the form

$$\begin{aligned}
 & \frac{u_{i-1} - 2u_i + u_{i+1}}{h^2} - u_i = \frac{2}{3}e^x \\
 \Rightarrow & \frac{u_{i-1} - 2u_i + u_{i+1} - h^2 u_i}{h^2} = \frac{2}{3}e^x \\
 \Rightarrow & \frac{u_{i-1} - (2 + h^2)u_i + u_{i+1}}{h^2} = \frac{2}{3}e^x \quad i = 1, \dots, n.
 \end{aligned}$$

In matrix form,

$$\frac{1}{h^2} \underbrace{\begin{bmatrix} -(2+h^2) & 1 & & & \\ 1 & -(2+h^2) & 1 & & \\ & 1 & -(2+h^2) & 1 & \\ & & \ddots & \ddots & \ddots \\ & & & 1 & -(2+h^2) & 1 \\ & & & & 1 & -(2+h^2) \end{bmatrix}}_A \underbrace{\begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_i \\ \vdots \\ u_n \end{bmatrix}}_U = \underbrace{\begin{bmatrix} 2/3 e^{x_1} \\ 2/3 e^{x_2} \\ \vdots \\ \vdots \\ 2/3 e^{x_{n-1}} \\ 2/3 e^{x_n} - e/(3h^2) \end{bmatrix}}_F. \quad \square$$

Solution to b). The following MATLAB code solves this linear system for U and plots the numerical and exact solutions:

```

1 %Set constants:
2 a = 0;
3 b = 1;
4 alph = 0;
5 bet = (1/3)*exp(1);
6 n = 69;
7 h = (b-a)/(n+1);
8

```

```

9 %Generate the matrix A (size nxn):
10 A = zeros(n); %initialize nxn matrix
11 for i = 1:n
12     for j = 1:n
13         if i == j
14             A(i,i) = -(2+h^2)/h^2;
15         elseif (j == i+1) || (i == j+1)
16             A(i,j) = 1/h^2;
17         end
18     end
19 end
20
21 %define the x-grid:
22 x = linspace(a,b,n+2); %size n+2 (n interior pts + 2 BCs)
23
24 %define function vector f:
25 f = zeros(n,1); %initialize nx1 vector
26 for i = 1:n
27     if i==n
28         f(i) = (2/3)*exp(x(i)) - exp(1)/(3*h^2);
29     else
30         f(i) = (2/3)*exp(x(i));
31     end
32 end
33
34 %Use linear solver to solve Au=f for u:
35 u = linsolve(A,f);
36 usol = [alph; u; bet]; %extend solution to include BCs
37
38
39 %generate vector of errors and vector of exact solution:
40 abserror_vec = zeros(n,1);
41 funct_vec = zeros(n,1);
42 funct = @(t) (1/3)*t*exp(t); %closed-form solution
43 for i = 1:n
44     funct_vec(i) = funct (x(i));
45     abserror_vec(i) = abs( usol(i) - funct_vec(i) );
46 end
47
48 %extend exact solution vector to include BCs
49 funct_vec = [alph; funct_vec; bet];
50
51 %generate vector of errors
52 abserror_vec = zeros(n,1);
53 funct = @(t) (1/3)*t*exp(t); %closed-form solution
54 for i = 1:n
55     abserror_vec(i) = abs( usol(i) - funct(x(i)) );
56 end
57
58 %extend abs error vector to include BCs
59 abserror_vec = [0; abserror_vec; 0];
60
61 %Semilog plot of the absolute error vs x:
62 semilog(x,abserror_vec, "m+")
63 ylabel('Error')
64 xlabel('x')
65 exportgraphics(gcf,'abserror_Prob4.pdf')
66 close
67
68
69 %Plot results:
70 plot(x,usol, "r*")
71 hold on
72 plot(x,funct_vec, "g+-", "LineWidth",2)
73 ylabel('u(x)')
74 xlabel('x')
75 legend("Numerical Solution", "Exact Solution", 'Location','northwest')
76 exportgraphics(gcf,'BVP_Prob4.pdf')
77 close

```

Here is the resulting plot of the numerical and exact solutions:

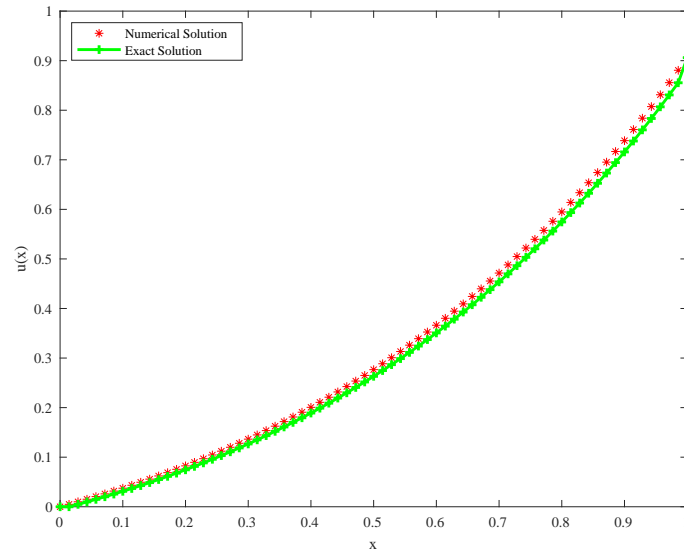


Figure 4: Exact and numerical solutions (for $n = 69$ grid points) of the BVP (8).

□

Solution to c). Here is the resulting semi-log plot from the code presented in 6):

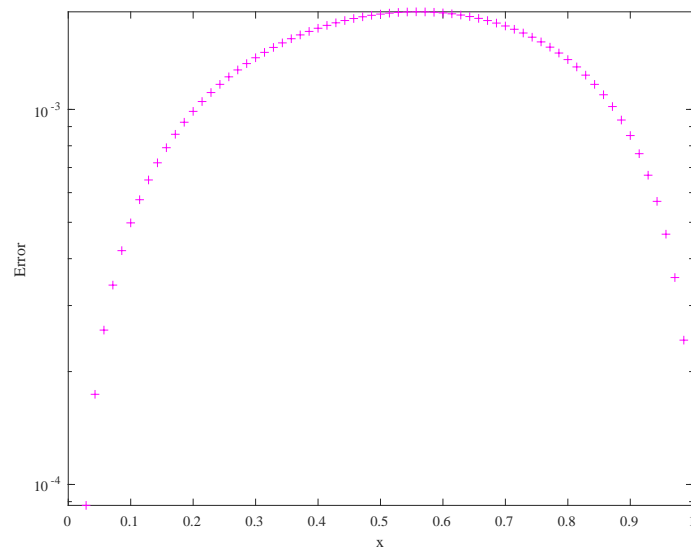


Figure 5: Semilog plot of the absolute error as a function of x .

□

Problem 5. Repeat the Problem 4 for the linear BVP

$$u'' = (2 + 4x^2)u, \quad u(0) = 1, \quad u(1) = e \quad (9)$$

with the exact solution $u(x) = e^{x^2}$.

Solution to a). In what follows we shall use the notation

$$h\Psi_i \equiv h^2 (2 + 4x_i^2).$$

Now, the centered discretization of the BVP (9) is of the form

$$\begin{aligned} \frac{u_{i-1} - 2u_i + u_{i+1}}{h^2} - (2 + 4x_i^2) u_i &= 0 \\ \Rightarrow \frac{u_{i-1} - 2u_i + u_{i+1} - h\Psi_i u_i}{h^2} &= 0 \\ \Rightarrow u_{i-1} - (2 + h\Psi_i) u_i + u_{i+1} &= 0 \quad i = 1, \dots, n. \end{aligned}$$

In matrix form,

$$\underbrace{\begin{bmatrix} -(2 + h\Psi_1) & 1 & & & & \\ & 1 & -(2 + h\Psi_2) & 1 & & \\ & & 1 & -(2 + h\Psi_3) & 1 & \\ & & & \ddots & \ddots & \ddots \\ & & & & 1 & -(2 + h\Psi_{n-1}) & 1 \\ & & & & & 1 & -(2 + h\Psi_n) \end{bmatrix}}_A \underbrace{\begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_i \\ \vdots \\ u_n \end{bmatrix}}_U = \underbrace{\begin{bmatrix} -1 \\ 0 \\ \vdots \\ 0 \\ -e \end{bmatrix}}_F. \quad \square$$



Solution to b). The following MATLAB code solves this linear system for U and plots the numerical and exact solutions:

```
1 %Set constants:
2 a = 0;
3 b = 1;
4 alph = 1;
5 bet = exp(1);
6 n = 69;
7 h = (b-a)/(n+1);
8
9 %define the x-grid
10 %size n (n interior pts only for now; 2 bd pts will be added later):
11 x = linspace(a+h,b-h,n);
12
13 % %define the Psi vector
14 Psi = zeros(n,1); %initialize nx1 vector
15 for i = 1:n
16     Psi(i) = h^2 * (2 + 4*x(i)^2);
17 end
18
19 %Generate the matrix A (size nxn):
20 A = zeros(n); %initialize nxn matrix
21 for i = 1:n
22     for j = 1:n
23         if i == j
24             A(i,i) = - ( 2 + Psi(i) );
25         elseif (j == i+1) || (i == j+1)
26             A(i,j) = 1;
27         end
28     end
29 end
30
31 %define function vector f:
32 f = zeros(n,1); %initialize nx1 vector
33 for i = 1:n
34     if i==1
35         f(i) = - 1;
36     elseif i == n
37         f(i) = - exp(1);
38     end
39 end
```

```

39     end
40 end
41
42
43 %Use linear solver to solve Au=f for u:
44 u = linsolve(A,f);
45 usol = [alph; u; bet]; %extend solution to include BCs
46
47
48 %redefine x to include bd pts
49 x = linspace(a,b,n+2); %size n+2 (n interior pts + 2 BCs)
50
51
52 %generate vector of errors and vector of exact solution:
53 abserror_vec = zeros(n,1);
54 funct_vec = zeros(n,1);
55 funct = @(t) exp(t^2); %closed-form solution
56 for i = 1:n
57     funct_vec(i) = funct (x(i));
58     abserror_vec(i) = abs( usol(i) - funct_vec(i) );
59 end
60
61 %extend abs error vector to include BCs
62 abserror_vec = [0; abserror_vec; 0];
63
64 %Semilog plot of the absolute error vs x:
65 semilogy(x,abserror_vec, "m+")
66 ylabel('Error')
67 xlabel('x')
68 exportgraphics(gcf,'abserror_Prob5.pdf')
69 close
70
71
72 %extend exact solution vector to include BCs
73 funct_vec = [alph; funct_vec; bet];
74
75 %Plot results:
76 plot(x,usol, "b*")
77 hold on
78 plot(x,funct_vec, "m-o", "LineWidth",2)
79 ylabel('u(x)')
80 xlabel('x')
81 legend("Numerical Solution", "Exact Solution", 'Location','northwest')
82 exportgraphics(gcf,'BVP_Prob5.pdf')
83 close

```

Here is the resulting plot of the numerical and exact solutions:

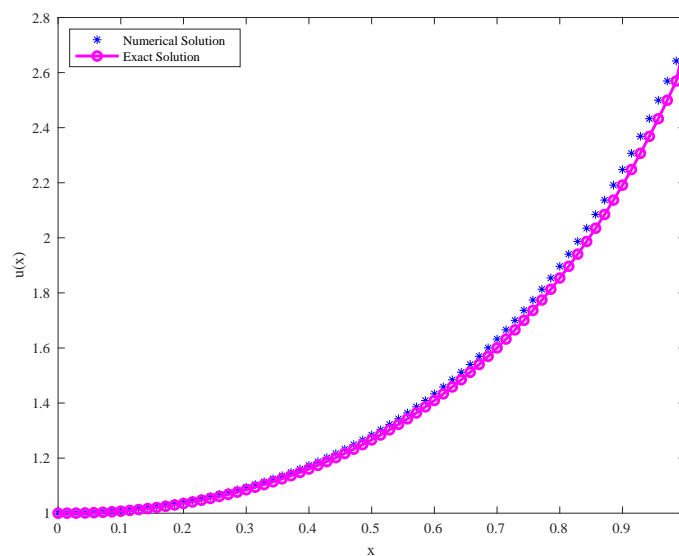


Figure 6: Exact and numerical solutions (for $n = 69$ grid points) of the BVP (9).

□

Solution to c). Here is the resulting semi-log plot from the code presented in b):

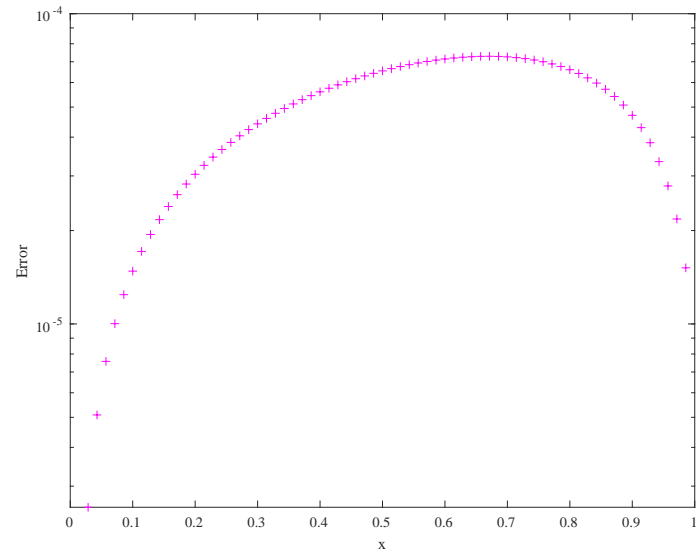


Figure 7: Semilog plot of the absolute error as a function of x .

□