

## MATH 709 HW # 1

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**Problem 1 (Problem 1-1).** Let  $X$  be the set of all points  $z = (x, y) \in \mathbb{R}^2$  such that  $y = \pm 1$ , and let  $M$  be the quotient of  $X$  by the equivalence relation generated by  $(x, -1) \sim (x, 1)$  for all  $x \neq 0$ . Show that  $M$  is locally Euclidean and second-countable, but not Hausdorff. (This space is called the *line with two origins*.)

*Proof.* We start by showing that

$$M = X / \sim_{\forall x \neq 0}^{(x, -1) \sim (x, 1)} = (\mathbb{R} \setminus \{0\}) \cup \{-1, 1\}$$

is locally Euclidean and second countable. Let

$$\begin{aligned}\mathcal{U}_1 &= \{(x, 1) \mid x \neq 0\} \cup (0, 1) \\ \mathcal{U}_2 &= \{(x, -1) \mid x \neq 0\} \cup (0, -1).\end{aligned}$$

But now both  $\mathcal{U}_1$  and  $\mathcal{U}_2$  are naturally homeomorphic to  $\mathbb{R}$ . To see this note that, for instance, in the case of  $\mathcal{U}_1$ , we can define a map  $\varphi: \mathcal{U}_1 \subset \mathbb{R}^2 \rightarrow \mathbb{R}$  such that

$$\varphi(z) = \begin{cases} x & z \in \{(x, 1) \mid x \neq 0\}, \\ 0 & z = (0, 1). \end{cases}$$

Note that this map is clearly a homeomorphism (you can check this!). Similarly, we can define such a map for  $\mathcal{U}_2$  as well. Hence, since both  $\mathcal{U}_1$  and  $\mathcal{U}_2$  are homeomorphic to  $\mathbb{R}$ , they are locally Euclidean and second countable, and so is  $M = \mathcal{U}_1 \cup \mathcal{U}_2$ .

However  $M$  is not Hausdorff: for any two open sets  $U$  and  $V$  in  $M$  containing the two “origins”  $(0, 1) \in U$  and  $(0, -1) \in V$ , the intersection  $U \cap V$  is never empty.  $\square$

**Problem 2 (Problem 1-5).** Suppose  $M$  is a locally Euclidean Hausdorff space. Show that  $M$  is second-countable if and only if it is paracompact and has countably many connected components. (Hint: assuming  $M$  is paracompact, show that each component of  $M$  has a locally finite cover by precompact coordinate domains, and extract from this a countable subcover.)

*Proof.* ( $\Rightarrow$ ) Let  $x \in M$  be an arbitrary point and  $U_x$  be a corresponding neighborhood. We can assume that  $U_x \cap U_y = \emptyset$  whenever  $x \neq y$ , since  $M$  is Hausdorff. Assume that  $M$  is paracompact so that, for any open cover  $\chi$  of  $M$ , there exists an open refinement  $\{S_i\}$  of  $\chi$  such that each  $U_x \subset M$  intersects with only finitely many  $S_i$ , i.e.  $U_x \cap \{S_i\}$  is finite and open (being a finite intersection of open sets) for every  $x \in M$ . But then we are also assuming that  $M$  has countably many connected components  $\{\mathcal{C}_\alpha\}_{\alpha \in A}$ . Hence we define a collection  $\{V_\alpha\}_{\alpha \in A}$  such that

$$V_\alpha = \bigcup_{\substack{x \in U_x \\ U_x \subseteq \mathcal{C}_\alpha}} (U_x \cap \{S_i\}).$$

Note that this collection  $\{V_\alpha\}_{\alpha \in A}$  gives us a (countable) basis for  $M$ : Each  $V_\alpha$ , being the arbitrary union of open sets, is open. For each  $x \in M$ , there is obviously at least one basis element  $V_\alpha$  containing  $x$  (by construction). Moreover, we don't need to worry about intersections since, if  $x \in V_\alpha \cap V_\beta$ , then we must have that  $\alpha = \beta$  (by construction). Thus,  $M$  is a second-countable space, as desired.

( $\Leftarrow$ ) This direction is trivial, since if we assume that  $M$  locally Euclidean, Hausdorff, and second-countable, then  $M$  is a topological manifold by definition. Then by Theorem 1.15 from the text, we know that  $M$  is paracompact and from Proposition 1.11 part d), we have that  $M$  has countably many components. Notwithstanding, let's not be lazy and show some actual work instead of just calling on those propositions ☺:

First we show that  $M$  is paracompact. Since manifolds are locally compact, we can use the fact that second-countable, locally compact Hausdorff spaces admit an exhaustion by compact sets<sup>1</sup> (Proposition A.60 from the text). Now let  $\chi$  and  $\mathcal{B}$  be any arbitrary open cover and basis, respectively, for  $M$ , and let  $(K_j)_{j=1}^\infty$  be an exhaustion of  $M$  by compact sets. For each  $j$ , let

$$V_j = K_{j+1} \setminus \text{Int}(K_j) \quad \text{and} \quad W_j = \text{Int}(K_{j+2}) \setminus K_{j-1},$$

(where we interpret  $K_j$  as  $\emptyset$  if  $j \leq 1$ ). Then  $V_j$  is a compact set contained in the open subset  $W_j$ . Now, for each  $x \in V_j$ , there is some  $U_x \in \chi$  containing  $x$ , and because  $\mathcal{B}$  is a basis, there exists  $B_x \in \mathcal{B}$  such that  $x \in B_x \subseteq U_x \cap W_j$ . The collection of all such sets  $B_x$  as  $x$  ranges over  $V_j$  is an open cover of  $V_j$ , and thus has a finite subcover. The union of all such finite subcovers as  $j$  ranges over the positive integers is a countable open cover of  $M$  that refines  $\chi$ . Because the finite subcover of  $V_j$  consists of sets contained in  $W_j$ , and  $W_j \cap W_{j'} = \emptyset$  except when  $j-2 \leq j' \leq j+2$ , the resulting cover is locally finite. Thus we have shown that  $M$  is paracompact. In fact, we have demonstrated that given a topological manifold  $M$ , an open cover  $\chi$  of  $M$ , and any basis  $\mathcal{B}$  for the topology of  $M$ , there exists a countable, locally finite open refinement of  $\chi$  consisting of elements of  $\mathcal{B}$ .

Lastly, to show that  $M$  has countably many components, note that (by a previous proposition) each component is open in  $M$ , so the collection of components is an open cover of  $M$ . Because  $M$  is assumed to be second-countable, this cover must have a countable subcover. But since the components are all disjoint, the cover must have been countable to begin with, which is to say that  $M$  has only countably many components, as desired.  $\square$

**Problem 3 (Problem 1-6).** Let  $M$  be a nonempty topological manifold of dimension  $n \geq 1$ . If  $M$  has a smooth structure, show that it has uncountably many distinct ones. (Hint: first show that for any  $s > 0$ ,  $F_s(x) = |x|^{s-1}x$  defines a homeomorphism from  $\mathbb{B}^n$  to itself, which is a diffeomorphism if and only if  $s = 1$ .)

*Proof.* Suppose  $M$  has a smooth structure  $\mathcal{A}$  and fix a chart  $(U, \varphi)$  in  $\mathcal{A}$ . Assume WLOG that  $\varphi$  maps  $U$  onto the open unit ball  $\mathbb{B}^n$ . Let  $p = \varphi^{-1}(0)$  and define, for  $\alpha > 0$ ,  $f_\alpha: \mathbb{B}^n \rightarrow \mathbb{B}^n$  and its inverse  $f_\alpha^{-1}$  by

$$f_\alpha(x) = \frac{|x|^{1/\alpha}x}{|x|} \quad \text{and} \quad f_\alpha^{-1}(x) = \frac{|x|^\alpha x}{|x|},$$

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<sup>1</sup>Recall that a sequence  $(K_i)_{i=1}^\infty$  of compact subsets of a topological space  $X$  is called an **exhaustion of  $X$  by compact sets** if  $X = \bigcup_i K_i$  and  $K_i \subseteq \text{Int}(K_{i+1})$  for each  $i$ .

so that both  $f_\alpha$  and  $f_\alpha^{-1}$  are everywhere continuous (i.e.  $f_\alpha$  is a homeomorphism.) Also note that for  $\alpha = 1$  this is just the identity, whereas for  $\alpha > 1$  the map is not smooth at the origin. Hence  $f_\alpha$  is a diffeomorphism if and only if  $\alpha = 1$ .

We now construct uncountably many smooth structures  $\{\hat{\mathcal{A}}_\alpha\}_{\alpha \in I}$ . Let  $\mathcal{A}_\alpha$  be an atlas containing the chart with coordinate map  $f_\alpha \circ \varphi$ . Observe that for any chart  $(V, \psi) \in \mathcal{A}$ , if  $p = \varphi^{-1}(0) \notin V$  then  $\psi$  is smoothly compatible with  $f_\alpha \circ \varphi$ . With that in mind, we take a closed ball  $B$  about 0 in  $\varphi(U)$ . Then  $\varphi^{-1}(B)$  is a closed set in  $M$  with  $p$  in its interior. Now for every chart  $(V, \psi) \in \mathcal{A}$ , let  $\mathcal{A}_\alpha$  contain  $\psi|_{(\varphi^{-1}(B))^c}$  (that is, we restrict all the other charts to the complement of our closed coordinate ball in  $M$ .) These maps  $\psi|_{(\varphi^{-1}(B))^c}$  are then smoothly compatible with  $f_\alpha \circ \varphi$  because they do not overlap at  $p$ . Thus  $\mathcal{A}_\alpha$  is a smooth atlas, and it can be extended to a smooth structure. Let us call the induced smooth structure  $\hat{\mathcal{A}}_\alpha$ . Thus we have uncountably many smooth structures  $\{\hat{\mathcal{A}}_\alpha\}_{\alpha \in I}$ , one for each choice of  $\alpha$ .

Now we show that our uncountably many smooth structures are distinct. Given any  $\alpha, \beta \geq 1$ , assume WLOG that  $\alpha > \beta$ . The charts with coordinate maps  $f_\alpha \circ \varphi \in \mathcal{A}_\alpha$  and  $f_\beta \circ \varphi \in \mathcal{A}_\beta$  have the transition map

$$f_\alpha \circ \varphi \circ (f_\beta \circ \varphi)^{-1} = f_\alpha \circ \varphi \circ \varphi^{-1} \circ f_\beta^{-1} = f_\alpha \circ f_\beta^{-1},$$

which is  $x \mapsto (|x|^{\beta/\alpha}x)/|x|$ . This map is not differentiable at 0, and both coordinate maps send  $p$  to 0, so they are not smoothly compatible and as a consequence they must induce distinct smooth structures. Hence all of the  $\hat{\mathcal{A}}_\alpha$  are distinct smooth structures, as desired.  $\square$

**Problem 4** (Problem 1-7). Let  $N$  denote the **north pole**  $(0, \dots, 0, 1) \in \mathbb{S}^n \subseteq \mathbb{R}^{n+1}$ , and let  $S$  denote the **south pole**  $(0, \dots, 0, -1)$ . Define the **stereographic projection**  $\sigma: \mathbb{S}^n \setminus \{N\} \rightarrow \mathbb{R}^n$  by

$$\sigma(x^1, \dots, x^{n+1}) = \frac{(x^1, \dots, x^n)}{1 - x^{n+1}}.$$

Let  $\tilde{\sigma}(x) = -\sigma(-x)$  for  $x \in \mathbb{S}^n \setminus \{S\}$ . Then,

- a) For any  $x \in \mathbb{S}^n \setminus \{N\}$ , show that  $\sigma(x) = u$  where  $(u, 0)$  is the point where the line through  $N$  and  $x$  intersects the linear subspace where  $x^{n+1} = 0$  (see Figure 1 below). Similarly, show that  $\tilde{\sigma}(x)$  is the point where the line through  $S$  and  $x$  intersects the same subspace. (For this reason,  $\tilde{\sigma}$  is called the **stereographic projection from the south pole**.)

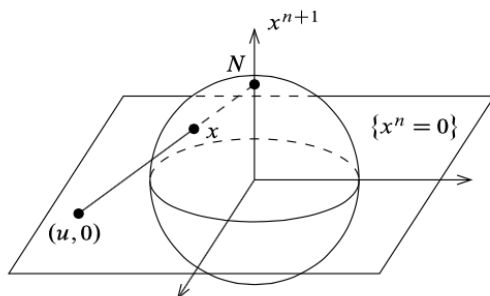


FIGURE 1. Stereographic projection

- b) Show that  $\sigma$  is bijective, and

(♣) 
$$\sigma^{-1}(u^1, \dots, u^n) = \frac{(2u^1, \dots, 2u^n, |u|^2 - 1)}{|u|^2 + 1}.$$

- c) Compute the transition map  $\tilde{\sigma} \circ \sigma^{-1}$  and verify that the atlas consisting of the two charts  $(\mathbb{S}^n \setminus \{N\}, \sigma)$  and  $(\mathbb{S}^n \setminus \{S\}, \tilde{\sigma})$  defines a smooth structure on  $\mathbb{S}^n$ . (The coordinates defined by  $\sigma$  or  $\tilde{\sigma}$  are called **stereographic coordinates**.)
- d) Show that this smooth structure is the same as the **standard smooth structure**, which is defined on Example 1.31, Page 20, Lee's Smooth Manifolds.

*Proof of a).* The line through  $x$  and the north pole  $N$  is given by

$$\begin{aligned}\ell(t) &= (x - N)t + N \\ &= [(x^1, \dots, x^{n+1}) - (0, \dots, 0, 1)]t + (0, \dots, 0, 1) \\ &= (x^1, \dots, x^{n+1} - 1)t + (0, \dots, 0, 1) \\ &= (x^1 \cdot t, \dots, (x^{n+1} - 1) \cdot t + 1).\end{aligned}$$

The  $(n+1)^{st}$  component  $(x^{n+1} - 1) \cdot t + 1$  is equal to 0 when  $t = t_0 = \frac{1}{1-x^{n+1}}$  so that

$$\ell(t_0) = \frac{1}{1-x^{n+1}}(x^1, \dots, x^n, 0) = \sigma(x).$$

Similarly the statement about  $\tilde{\sigma}$  follows in the same way. □

*Proof of b).* By inspection we can see that  $\sigma$  is well defined on all of  $\mathbb{S}^n \setminus \{N\}$  as well as is  $\sigma^{-1}$  on all of  $\mathbb{R}^n$ . Hence showing that  $\sigma \circ \sigma^{-1} = \text{Id}_{\mathbb{R}^n}$  and  $\sigma^{-1} \circ \sigma = \text{Id}_{\mathbb{S}^n \setminus \{N\}}$  is sufficient to establish that  $\sigma$  is a bijection and that the  $\sigma^{-1}$  given in () is indeed its inverse. So here goes nothing:

$$\begin{aligned}\sigma \circ \sigma^{-1}(u) &= \sigma \left( \frac{2u^1}{|u|^2 + 1}, \dots, \frac{2u^n}{|u|^2 + 1}, \frac{|u|^2 - 1}{|u|^2 + 1} \right) \\ &= \frac{\left( \frac{2u^1}{|u|^2 + 1}, \dots, \frac{2u^n}{|u|^2 + 1} \right)}{1 - \frac{|u|^2 - 1}{|u|^2 + 1}} \\ &= \frac{(2u^1, \dots, 2u^n)}{|u|^2 + 1 - |u|^2 + 1} \\ &= \frac{2(u^1, \dots, u^n)}{2} \\ &= u \\ &= \text{Id}_{\mathbb{R}^n}.\end{aligned}$$

But this holds for all  $u \in \mathbb{R}^n$ , thus  $\sigma \circ \sigma^{-1} = \text{Id}_{\mathbb{R}^n}$ .

Similarly, we have

$$\begin{aligned}\sigma^{-1} \circ \sigma(x) &= \sigma^{-1} \left( \frac{x^1}{1-x^{n+1}}, \dots, \frac{x^n}{1-x^{n+1}} \right) \\ &= \frac{\left( \frac{2x^1}{1-x^{n+1}}, \dots, \frac{2x^n}{1-x^{n+1}}, \frac{(x^1)^2 + \dots + (x^n)^2}{(1-x^{n+1})^2} - 1 \right)}{\frac{(x^1)^2 + \dots + (x^n)^2}{(1-x^{n+1})^2} + 1}\end{aligned}$$

But  $x \in \mathbb{S}^n \setminus \{N\}$ , thus we can rewrite  $(x^1)^2 + \dots + (x^n)^2$  as  $1 - (x^{n+1})^2$ . So we continue the computation:

$$\begin{aligned} \sigma^{-1} \circ \sigma(x) &= \frac{\left(2x^1, \dots, 2x^n, \frac{1-(x^{n+1})^2-1+2x^{n+1}-(x^{n+1})^2}{1-x^{n+1}}\right)}{\frac{1-(x^{n+1})^2+1-2x^{n+1}+(x^{n+1})^2}{1-x^{n+1}}} \\ &= \frac{\left(2x^1, \dots, 2x^n, \frac{2x^{n+1}(1-x^{n+1})}{1-x^{n+1}}\right)}{\frac{2(1-x^{n+1})}{1-x^{n+1}}} \\ &= \text{Id}_{\mathbb{S}^n \setminus \{N\}}(x). \end{aligned}$$

Since this holds for all  $x \in \mathbb{S}^n \setminus \{N\}$  we may conclude that  $\sigma^{-1} \circ \sigma = \text{Id}_{\mathbb{S}^n \setminus \{N\}}$ . Therefore  $\sigma$  is bijective and has inverse  $\sigma^{-1}$  as defined on  $(\clubsuit)$ , as desired.  $\square$

*Proof of c).* Let us compute  $\tilde{\sigma} \circ \sigma^{-1}$ :

$$\begin{aligned} \tilde{\sigma} \circ \sigma^{-1}(u) &= \tilde{\sigma} \left( \frac{2u^1}{|u|^2+1}, \dots, \frac{2u^n}{|u|^2+1}, \frac{|u|^2-1}{|u|^2+1} \right) \\ &= \frac{\left( \frac{2u^1}{|u|^2+1}, \dots, \frac{2u^n}{|u|^2+1} \right)}{1 + \frac{|u|^2-1}{|u|^2+1}} \\ &= \frac{u}{|u|^2}, \end{aligned}$$

which is a smooth rational function.

Now notice that

$$\tilde{\sigma} \circ (-\sigma^{-1}(-x)) = -\sigma \circ \sigma^{-1}(-x) = -\text{Id}_{\mathbb{R}^n}(-x) = -(-x) = x = \text{Id}_{\mathbb{R}^n}(x)$$

for all  $x \in \mathbb{R}^n$ , so that  $\tilde{\sigma}^{-1}(x) = -\sigma^{-1}(-x)$ . Therefore

$$\begin{aligned} \sigma \circ \tilde{\sigma}^{-1}(u) &= \sigma(-\sigma^{-1}(-u)) \\ &= -(-\sigma(-\sigma^{-1}(-u))) \\ &= -\tilde{\sigma}(\sigma^{-1}(-u)) \\ &= -\left( \frac{-u}{|-u|^2} \right) \\ &= \frac{u}{|u|^2}, \end{aligned}$$

which is also a smooth rational function.

Finally, note that  $\mathbb{S}^n = (\mathbb{S}^n \setminus \{N\}) \cup (\mathbb{S}^n \setminus \{S\})$ . Thus the atlas  $\mathcal{A} = \{(\mathbb{S}^n \setminus \{N\}, \sigma), (\mathbb{S}^n \setminus \{S\}, \tilde{\sigma})\}$  defines a smooth structure on  $\mathbb{S}^n$ , as we set out to prove.  $\square$

Before I proceed to prove part d), I will derive the standard smooth structure for  $\mathbb{S}^n$  for my own study purposes. The grader may want to skip this and jump right into the actual proof, which can be found below.

*Preliminaries for proof of d).* For each integer  $n > 0$ , the unit  $n$ -sphere  $\mathbb{S}^n$  is Hausdorff and second-countable because it is a topological subspace of  $\mathbb{R}^{n+1}$ . To show that it is locally Euclidean, for each index  $i = 1, \dots, n+1$  let  $U_i^+$  denote the subset of  $\mathbb{R}^{n+1}$  where the  $i^{\text{th}}$  coordinate is positive:

$$U_i^+ = \{(x^1, \dots, x^{n+1}) \in \mathbb{R}^{n+1} \mid x^i > 0\}.$$

Similarly,  $U_i^-$  is the set where  $x^i < 0$  (see Figure 2 below.)

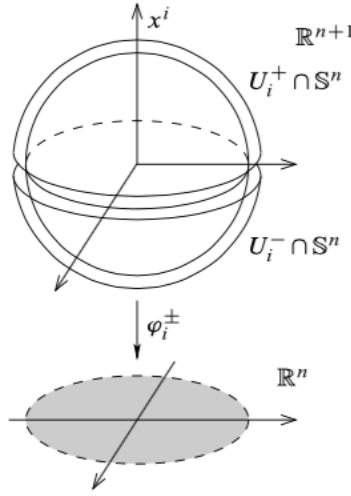


FIGURE 2. Charts for  $\mathbb{S}^n$ .

Now let  $f: \mathbb{B}^n \rightarrow \mathbb{R}$  be the continuous function

$$f(u) = \sqrt{1 - |u|^2}.$$

Then for each  $i = 1, \dots, n+1$ , it is easy to check that  $U_i^+ \cap \mathbb{S}^n$  is the graph of the function

$$x^i = f(x^1, \dots, \hat{x}^i, \dots, x^{n+1}),$$

where the hat indicates that  $x^i$  is omitted. Similarly,  $U_i^- \cap \mathbb{S}^n$  is the graph of

$$x^i = -f(x^1, \dots, \hat{x}^i, \dots, x^{n+1}).$$

Thus, each subset  $U_i^\pm \cap \mathbb{S}^n$  is locally Euclidean of dimension  $n$ , and the maps  $\varphi_i^\pm: U_i^\pm \cap \mathbb{S}^n \rightarrow \mathbb{B}^n$  given by

$$\varphi_i^\pm(x^1, \dots, x^{n+1}) = (x^1, \dots, \hat{x}^i, \dots, x^{n+1})$$

are graph coordinates for  $\mathbb{S}^n$ . Since each point of  $\mathbb{S}^n$  is in the domain of at least one of these  $2n+2$  charts,  $\mathbb{S}^n$  is a topological  $n$ -manifold.

Now we put a smooth structure on  $\mathbb{S}^n$  as follows. For each  $i = 1, \dots, n+1$  let  $(U_i^\pm, \varphi_i^\pm)$  denote the graph coordinate charts we constructed above. Then for any distinct indices  $i$  and  $j$ , the transition map  $\varphi_i^\pm \circ (\varphi_j^\pm)^{-1}$  can be easily computed. In the case when  $i < j$ , we get

$$\varphi_i^\pm \circ (\varphi_j^\pm)^{-1}(u^1, \dots, u^n) = (u^1, \dots, \underbrace{\hat{u}^i}_{i^{\text{th}} \text{ slot}}, \dots, \underbrace{\pm \sqrt{1 - |u|^2}}_{j^{\text{th}} \text{ slot}}, \dots, u^n),$$

and a similar formula holds when  $i > j$ . When  $i = j$ , an even simpler computation gives

$$\varphi_i^+ \circ (\varphi_i^-)^{-1} = \varphi_i^- \circ (\varphi_i^+)^{-1} = \text{Id}_{\mathbb{B}^n}.$$

Thus, the collection of charts  $\{(U_i^\pm, \varphi_i^\pm)\}$  is a smooth atlas, and so defines a smooth structure on  $\mathbb{S}^n$ . We call this its **standard smooth structure**.  $\square$

*Proof of d).* Now equipped with all the machinery from the above discussion, we can finally set out to prove that the standard smooth atlas on  $\mathbb{S}^n$   $\mathcal{A}' = \{(U_i^\pm, \varphi_i^\pm)\}$  is in fact the same as the atlas  $\mathcal{A} = \{(\mathbb{S}^n \setminus \{N\}, \sigma), (\mathbb{S}^n \setminus \{S\}, \tilde{\sigma})\}$  defined on part c). But by a previous lemma we know that this is equivalent to showing that  $\mathcal{A} \cup \mathcal{A}'$  is an atlas <sup>2</sup>. Since  $\mathcal{A}$  and  $\mathcal{A}'$  independently define smooth structures on  $\mathbb{S}^n$ , we know that  $\mathcal{A} \cup \mathcal{A}'$  will cover  $\mathbb{S}^n$  and that the transition functions from both  $\mathcal{A}$  and  $\mathcal{A}'$  are smooth. Thus it suffices to show that

$$\sigma \circ (\varphi_i^\pm)^{-1}, \quad \tilde{\sigma} \circ (\varphi_i^\pm)^{-1}, \quad \varphi_i^\pm \circ \sigma^{-1}, \quad \text{and} \quad \varphi_i^\pm \circ \tilde{\sigma}^{-1}$$

are smooth on their domain of definition. Thus let us roll up our sleeves and start computing:

$$\begin{aligned} \sigma \circ (\varphi_i^\pm)^{-1}(u) &= \begin{cases} \frac{u}{1 \mp \sqrt{1-|u|^2}} & \text{if } i = n, \\ \frac{(u^1, \dots, u^{i-1}, \pm \sqrt{1-|u|^2}, \dots, u^{n-1})}{1 - u^n} & \text{otherwise.} \end{cases} \\ \tilde{\sigma} \circ (\varphi_i^\pm)^{-1}(u) &= \begin{cases} \frac{u}{1 \pm \sqrt{1-|u|^2}} & \text{if } i = n, \\ \frac{(u^1, \dots, u^{i-1}, \pm \sqrt{1-|u|^2}, \dots, u^{n-1})}{1 + u^n} & \text{otherwise.} \end{cases} \\ \varphi_i^\pm \circ \sigma^{-1} &= \begin{cases} \frac{2u}{|u|^2 + 1} & \text{if } i = n + 1, \\ \frac{(2u^1, \dots, 2u^i, \dots, 2u^n, |u|^2 - 1)}{|u|^2 + 1} & \text{otherwise.} \end{cases} \\ \varphi_i^\pm \circ \tilde{\sigma}^{-1} &= \begin{cases} \frac{2u}{|u|^2 + 1} & \text{if } i = n + 1, \\ \frac{(2u^1, \dots, 2u^i, \dots, 2u^n, 1 - |u|^2)}{|u|^2 + 1} & \text{otherwise.} \end{cases} \end{aligned}$$

We can see that all of these transition maps are indeed smooth, hence  $\mathcal{A}$  and  $\mathcal{A}'$  determine the same smooth structure on  $\mathbb{S}^n$ , as desired.  $\square$

**Problem 5 (Problem 1-8).** By identifying  $\mathbb{R}^2$  with  $\mathbb{C}$ , we can think of the unit circle  $\mathbb{S}^1$  as a subset of the complex plane. An **angle function** on a subset  $U \subseteq \mathbb{S}^1$  is a continuous function  $\theta: U \rightarrow \mathbb{R}$  such that  $e^{i\theta(z)} = z$  for all  $z \in U$ . Show that there exists an angle function  $\theta$  on an open subset  $U \subseteq \mathbb{S}^1$  if and only if  $U \neq \mathbb{S}^1$ . For any such angle function, show that  $(U, \theta)$  is a smooth coordinate chart for  $\mathbb{S}^1$  with its standard smooth structure.

*Proof.*  $(\Rightarrow)$  We prove this direction by contradiction. Suppose that  $U = \mathbb{S}^1$  and there exists a continuous  $\theta: U \rightarrow \mathbb{R}$  such that  $e^{i\theta(z)} = z$  for all  $z \in U$ . Then it is easy to check that  $\theta$  is injective. Furthermore, since  $\mathbb{S}^1$  is compact and  $\mathbb{R}$  is Hausdorff, we must have that  $\theta$  is actually a homeomorphism and  $\theta(U)$  is compact and thus a closed bounded interval of  $\mathbb{R}$ . But  $\theta$  cannot possibly be a homeomorphism since removing an interior point of  $\theta(U) \subset \mathbb{R}$  gives a disconnected space while removing a point from  $U = \mathbb{S}^1$  still results in a connected space.  $(\Rightarrow \Leftarrow)$

<sup>2</sup>Just to recall, the lemma states that two smooth atlases for  $M$  determine the same smooth structure iff their union is a smooth atlas.

( $\Leftarrow$ ) Conversely, if  $U \neq \mathbb{S}^1$ , then there exists some  $p \in \mathbb{S}^1 \setminus U$ . We can cut the complex plane through the origin and  $p$  and get a branch of a logarithmic function  $f$  which is continuous on  $U$ . Let  $\theta(z) = -if(z)$  for all  $z \in U$ . Then we have

$$e^{i\theta(p)} = e^{f(z)} = z.$$

Lastly, we show that for any such angle function  $\theta$  we have that  $(U, \theta)$  is a smooth coordinate chart for  $\mathbb{S}^1$  with its standard smooth structure. By problem 1-7 above, we know that the standard smooth structure on  $\mathbb{S}^1$  is the same as that given by  $\{(\mathbb{S}^1 \setminus \{N\}, \sigma), (\mathbb{S}^1 \setminus \{S\}, \tilde{\sigma})\}$ , where  $N$  and  $S$  are the north and the south pole, respectively, and  $\sigma$  and  $\tilde{\sigma}$  are their respective stereographic projections. Thus we proceed by rotating  $\mathbb{R}^2$  appropriately, assuming that  $N = (0, 1) \notin U$ . Then let  $\sigma: \mathbb{S}^1 \setminus \{N\} \rightarrow \mathbb{R}$  be the stereographic projection given by  $\sigma(x^1, x^2) = x^1/(1 - x^2)$ . We can then compute

$$\sigma \circ \theta^{-1}(\alpha) = \frac{\cos \alpha}{1 - \sin \alpha},$$

which is a diffeomorphism on  $\theta(U)$ . Hence  $(U, \theta)$  is a smooth coordinate chart, as desired.  $\square$

**Problem 6 (Problem 1-10).** Let  $k$  and  $n$  be integers satisfying  $0 < k < n$ , and let  $P, Q \subseteq \mathbb{R}^n$  be the linear subspaces spanned by  $(e_1, \dots, e_k)$  and  $(e_{k+1}, \dots, e_n)$ , respectively, where  $e_i$  is the  $i^{\text{th}}$  standard basis vector for  $\mathbb{R}^n$ . For any  $k$ -dimensional subspace  $S \subseteq \mathbb{R}^n$  that has trivial intersection with  $Q$ , show that the coordinate representation  $\varphi(S)$  constructed on Example 1.36 (Grassmann manifolds, Pages 22–24, Lee's Smooth Manifolds) is the unique  $(n - k) \times k$  matrix  $B$  such that  $S$  is spanned by the columns of the matrix  $\begin{pmatrix} I_k \\ B \end{pmatrix}$ , where  $I_k$  denotes the  $k \times k$  identity matrix.

*Proof.* Let  $\mathcal{B} = \{e_1, \dots, e_k\}$ . The matrix of  $\varphi(S)$  represents the linear map  $(\pi_Q|_S) \circ (\pi_P|_S)^{-1}$ . Since  $\pi_P|_S$  is an isomorphism, the vectors  $(\pi_P|_S)^{-1}(\mathcal{B})$  form a basis for  $S$ . But then

$$\begin{aligned} (\text{Id}_{\mathbb{R}^n}|_S \circ (\pi_P|_S)^{-1})(\mathcal{B}) &= ((\pi_P|_S + \pi_Q|_S) \circ (\pi_P|_S)^{-1})(\mathcal{B}) \\ &= (\text{Id}_P + \pi_Q|_S \circ (\pi_P|_S)^{-1})(\mathcal{B}) \end{aligned}$$

is a basis for  $S$ . This is precisely the desired result.  $\square$