

Geometry of General Relativity

Workshop 3 Hand-In

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Problem (WS3 Problem 6). Let T be a $(1, 1)$ tensor field, λ a covector field and X, Y vector fields.

- a)** Using the inner Leibniz rule write down an expression for $(\nabla_X T)(\lambda, Y)$. Prove that this does indeed define a $(1, 1)$ tensor field $\nabla_X T$.
- b)** Prove that $\nabla_a f^b = -\Gamma_{ca}^b f^c$, where $\{f^a\}$ and $\{e_a\}$ are dual bases of covector and vector fields. Hence show that the components of the $(1, 2)$ tensor ∇T are

$$\nabla_c T^a_b = e_c(T^a_b) + \Gamma_{dc}^a T^d_b - \Gamma_{bc}^d T^a_d.$$

Deduce the Kronecker delta tensor is covariantly constant; i.e., $\nabla \delta = 0$.

- c)** Repeat part (a) for the Lie derivative and hence write down the components of $\mathcal{L}_X T$ in a coordinate basis. Evaluate $\mathcal{L}_X \delta$.

Solution to a). According to the inner Leibniz rule,

$$\nabla_X(T(\lambda, Y)) = (\nabla_X T)(\lambda, Y) + T(\nabla_X \lambda, Y) + T(\lambda, \nabla_X Y), \quad (\spadesuit)$$

so that

$$(\nabla_X T)(\lambda, Y) = \nabla_X(T(\lambda, Y)) - T(\nabla_X \lambda, Y) - T(\lambda, \nabla_X Y).$$

Now to demonstrate that $\nabla_X T$ is indeed a $(1, 1)$ tensor field, we must show C^∞ -bilinearity.¹ Let Ψ be any smooth function. Then,

$$\begin{aligned} (\nabla_X T)(\Psi \lambda, Y) &= \nabla_X(T(\Psi \lambda, Y)) - T(\nabla_X(\Psi \lambda), Y) - T(\Psi \lambda, \nabla_X Y) \\ &= \nabla_X(\Psi T(\lambda, Y)) - T(\nabla_X(\Psi \lambda), Y) - \Psi T(\lambda, \nabla_X Y) && \text{(Bilinearity of } T) \\ &= X(\Psi)T(\lambda, Y) + \Psi \nabla_X(T(\lambda, Y)) - T(X(\Psi)\lambda + \Psi \nabla_X \lambda, Y) - \Psi T(\lambda, \nabla_X Y) && \text{(Leibniz of } \nabla_X) \\ &= X(\Psi)T(\lambda, Y) + \Psi \nabla_X(T(\lambda, Y)) - X(\Psi)T(\lambda, Y) - \Psi T(\nabla_X \lambda, Y) - \Psi T(\lambda, \nabla_X Y) \\ &= \Psi \nabla_X(T(\lambda, Y)) - \Psi T(\nabla_X \lambda, Y) - \Psi T(\lambda, \nabla_X Y) \\ &= \Psi [\nabla_X(T(\lambda, Y)) - T(\nabla_X \lambda, Y) - T(\lambda, \nabla_X Y)] \\ &= \Psi (\nabla_X T)(\lambda, Y). \end{aligned}$$

A similar calculation shows C^∞ linearity on the contravariant slot.

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Proof of b). For vector fields X, Y and covector field λ , the Leibniz rule gives us

$$\nabla_X(\lambda \otimes Y) = (\nabla_X \lambda) \otimes Y + \lambda \otimes \nabla_X Y.$$

¹In fact, we show linearity in one slot only, since by the way $\nabla_X T$ is defined, if linearity holds on either slot, it will obviously hold on the other.

Then applying the contraction $C(\lambda \otimes Y) = \langle \lambda, Y \rangle$ and using the commutativity of ∇_X with contractions, we get

$$\nabla_X \langle \lambda, Y \rangle = \langle \nabla_X \lambda, Y \rangle + \langle \lambda, \nabla_X Y \rangle,$$

or

$$\langle \nabla_X \lambda, Y \rangle = \nabla_X \langle \lambda, Y \rangle - \langle \lambda, \nabla_X Y \rangle. \quad (\clubsuit)$$

Now letting $X = e_a$, $Y = e_b$, and $\lambda = f^c$ on (\clubsuit) , we get

$$\begin{aligned} \langle \nabla_a f^c, e_b \rangle &= \nabla_a \langle f^c, e_b \rangle - \langle f^c, \nabla_a e_b \rangle \\ &= \underbrace{\nabla_a \delta^c_b}_{=0} - \langle f^c, \Gamma_{ba}^r e_r \rangle \\ &= -\Gamma_{ba}^r \langle f^c, e_r \rangle \\ &= -\Gamma_{ba}^r \delta^c_r \\ &= -\Gamma_{ba}^c. \end{aligned}$$

This result implies that $\nabla_a f^c = -\Gamma_{da}^c f^d$, as desired.²

Now to determine the components $(\nabla T)_{c;a}^b = \nabla_a T_c^b$ of the $(1, 2)$ tensor ∇T , we put $X = e_a$, $\lambda = f^b$, and $Y = e_c$ on (\spadesuit) . Then,

$$\begin{aligned} \nabla_a (T(f^b, e_c)) &= \nabla_a T_c^b = (\nabla_a T)(f^b, e_c) + T(\nabla_a f^b, e_c) + T(f^b, \nabla_a e_c) \\ &= (\nabla_a T)_c^b + T(-\Gamma_{da}^b f^d, e_c) + T(f^b, \Gamma_{ca}^r e_r) \\ &= e_a(T_c^b) - \Gamma_{da}^b T_c^d + \Gamma_{ca}^r T_r^b. \end{aligned}$$

From this result we can easily see that $\nabla \delta = 0$: in components,

$$\begin{aligned} \nabla_a \delta^b_c &= (\nabla_a \delta)(f^b, e_c) + \delta(\nabla_a f^b, e_c) + \delta(f^b, \nabla_a e_c) \\ &= (\nabla_a \delta)_c^b + \delta(-\Gamma_{da}^b f^d, e_c) + \delta(f^b, \Gamma_{ca}^r e_r) \\ &= \underbrace{e_a(\delta_c^b)}_{=0} - \Gamma_{da}^b \delta_c^d + \Gamma_{ca}^r \delta_r^b \\ &= -\Gamma_{ca}^b + \Gamma_{ca}^b \\ &= 0. \end{aligned}$$

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Solution to c). Analogous to (\spadesuit) , we have

$$\mathcal{L}_X(T(\lambda, Y)) = (\mathcal{L}_X T)(\lambda, Y) + T(\mathcal{L}_X \lambda, Y) + T(\lambda, \mathcal{L}_X Y),$$

so that

$$(\mathcal{L}_X T)(\lambda, Y) = \mathcal{L}_X(T(\lambda, Y)) - T(\mathcal{L}_X \lambda, Y) - T(\lambda, \mathcal{L}_X Y).$$

In order to show that $\mathcal{L}_X T$ is a $(1, 1)$ tensor field, we show C^∞ bilinearity.³ Let Ξ be any smooth function; then

$$\begin{aligned} (\mathcal{L}_X T)(\Xi \lambda, Y) &= \mathcal{L}_X(T(\Xi \lambda, Y)) - T(\mathcal{L}_X(\Xi \lambda), Y) - T(\Xi \lambda, \mathcal{L}_X Y) \\ &= \mathcal{L}_X(\Xi T(\lambda, Y)) - T(X(\Xi) \lambda + \Xi \mathcal{L}_X \lambda, Y) - \Xi T(\lambda, \mathcal{L}_X Y) \\ &= X(\Xi) T(\lambda, Y) + \Xi \mathcal{L}_X(T(\lambda, Y)) - X(\Xi) T(\lambda, Y) - \Xi T(\mathcal{L}_X \lambda, Y) - \Xi T(\lambda, \mathcal{L}_X Y) \\ &= \Xi \mathcal{L}_X(T(\lambda, Y)) - \Xi T(\mathcal{L}_X \lambda, Y) - \Xi T(\lambda, \mathcal{L}_X Y) \\ &= \Xi [\mathcal{L}_X(T(\lambda, Y)) - T(\mathcal{L}_X \lambda, Y) - T(\lambda, \mathcal{L}_X Y)] \\ &= \Xi (\mathcal{L}_X T)(\lambda, Y). \end{aligned}$$

²Indeed, a quick check: $\langle -\Gamma_{da}^c f^d, e_b \rangle = -\Gamma_{da}^c \langle f^d, e_b \rangle = -\Gamma_{da}^c \delta^d_b = -\Gamma_{ba}^c$. \checkmark

³As before, showing linearity in one slot only will suffice.



A similar calculation shows C^∞ linearity on the contravariant slot.

Now to determine the components of $\mathcal{L}_X T$ in a coordinate basis, recall that (analogous to equation (2.74) from our course notes)

$$(\mathcal{L}_X T)(\lambda, Y) = X[T(\lambda, Y)] - T(\mathcal{L}_X \lambda, Y) - T(\lambda, [X, Y]). \quad (\heartsuit)$$

Thus, in a basis (putting $X = e_a$, $\lambda = f^b$, and $Y = e_c$), we get

$$\begin{aligned} (\mathcal{L}_a T)(f^b, e_c) &= \mathcal{L}_a(T(f^b, e_c)) - T(\mathcal{L}_a f^b, e_c) - T(f^b, \mathcal{L}_a e_c) \\ &= e_a(T^b_c) - T(\mathcal{L}_a f^b, e_c) - T(f^b, \underbrace{[e_a, e_c]}_{=0}) \\ &= e_a(T^b_c) - T(\mathcal{L}_a f^b, e_c). \end{aligned}$$

****Question to review on workshop: How can I simplify $T(\mathcal{L}_a f^b, e_c)$ further??****

As for $\mathcal{L}_X \delta$, recall that the $(1, 1)$ tensor field δ acting on a covector λ and a vector Y yields $\delta(\lambda, Y) = \langle \lambda, Y \rangle = \lambda(Y)$. Using this and (\heartsuit) we get

$$\begin{aligned} (\mathcal{L}_X \delta)(\lambda, Y) &= X(\delta(\lambda, Y)) - \delta(\mathcal{L}_X \lambda, Y) - \delta(\lambda, [X, Y]) \\ &= X(\lambda(Y)) - (\mathcal{L}_X \lambda)(Y) - \lambda([X, Y]) \\ &= X(\lambda(Y)) - X(\lambda(Y)) + \lambda([X, Y]) - \lambda([X, Y]) \\ &= 0, \end{aligned}$$

where on the third line we used

$$(\mathcal{L}_X \lambda)(Y) = X(\lambda(Y)) - \lambda([X, Y]),$$

which is a result we have derived previously in the course (cf. equation (2.72) from our course notes).

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