

MATH 710 HW # 6

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Exercise 1 (Exercise 2-2 [DoCarmo]). Let X and Y be differentiable vector fields on a Riemannian manifold M . Let $p \in M$ and let $c: I \rightarrow M$ be an integral curve of X through p , i.e. $c(t_0) = p$ and $dc/dt = X(c(t))$. Prove that the Riemannian connection of M is

$$(\nabla_X Y)(p) = \left. \frac{d}{dt} \right|_{t=t_0} (P_{c,t_0,t}^{-1}(Y(c(t)))),$$

where $P_{c,t_0,t}: T_{c(t_0)}M \rightarrow T_{c(t)}M$ is the parallel transport along c , from t_0 to t (this shows how the connection can be re-obtained from the concept of parallelism).

Proof. Let $(e_i)_{i=1}^n$ be an orthonormal basis for $T_p M$, with $e_i(t) = P_{c,t_0,t} e_i$, i.e. $\nabla_{c'(t)} e_i(t) = 0$, so that $(e_i(t))_{i=1}^n$ is an orthonormal basis for $T_{c(t)} M$. Indeed,

$$\begin{aligned} \nabla_{c'(t)} \langle e_i(t), e_j(t) \rangle &= \langle \nabla_{c'(t)} e_i(t), e_j(t) \rangle + \langle e_i(t), \nabla_{c'(t)} e_j(t) \rangle = 0 \\ \implies \langle e_i(t), e_j(t) \rangle &= \langle e_i, e_j \rangle = \delta_i^j. \end{aligned}$$

Now we can write

$$Y(c(t)) = Y^i(t) e_i(t),$$

and then the following computation follows

$$\begin{aligned} \left. \frac{d}{dt} \right|_{t=t_0} (P_{c,t_0,t}^{-1}(Y(c(t)))) &= \left. \frac{d}{dt} \right|_{t=t_0} (P_{c,t_0,t}^{-1}(Y^i(t) e_i(t))) \\ &= \left. \frac{d}{dt} \right|_{t=t_0} (Y^i(t) e_i) \\ &= \left. \frac{d}{dt} \right|_{t=t_0} (Y^i(t)) e_i \\ &= \nabla_{c'(t)} (Y^i(t) e_i(t)) \Big|_{t=t_0} \\ &= \nabla_{c'(t)} (Y^i(t) e_i(t)) \Big|_{t=t_0} \\ &= (\nabla_X Y)(p). \end{aligned}$$

□

Exercise 2 (Exercise 2-3 [DoCarmo]). Let $f: M^n \rightarrow \overline{M}^{n+k}$ be an immersion of a smooth manifold M into a Riemannian manifold \overline{M} . Assume that M has the Riemannian metric induced by f (c.f. Example 2.5, Chapter 1). Let $p \in M$ and let $U \subset M$ be a neighborhood of p such that $f(U) \subset \overline{M}$ is a submanifold of \overline{M} . Further, suppose that X, Y are smooth vector fields on $f(U)$ which extend to smooth vector fields $\overline{X}, \overline{Y}$ on an open set of \overline{M} . Define $(\nabla_X Y)(p)$ = the tangential component of $(\overline{\nabla}_{\overline{X}} \overline{Y})(p)$, where $\overline{\nabla}$ is the Riemannian connection of \overline{M} . Prove that ∇ is the Riemannian connection of M .

Proof. We have that $(\nabla_X Y)(p)$ is the tangential component of $(\overline{\nabla}_{\overline{X}} \overline{Y})(p)$; let us denote that by $\nabla_X Y = (\overline{\nabla}_{\overline{X}} \overline{Y})^t$. Using the Riemannian metric \langle, \rangle induced by f , we have the following:

- ∇ is compatible with the metric on M . For all $p \in M$, we get

$$\begin{aligned} X\langle Y, Z \rangle(p) &= \overline{X}\langle \overline{Y}, \overline{Z} \rangle(p) \\ &= \langle \overline{\nabla_X Y}, \overline{Z} \rangle(p) + \langle \overline{Y}, \overline{\nabla_X Z} \rangle(p) \\ &= \langle \overline{\nabla_X Y}, Z \rangle(p) + \langle Y, \overline{\nabla_X Z} \rangle(p) \\ &= \langle \nabla_X Y, Z \rangle(p) + \langle Y, \nabla_X Z \rangle(p). \end{aligned}$$

- ∇ is symmetric. For all $p \in M$, we get

$$\begin{aligned} (\clubsuit) \quad (\nabla_X Y - \nabla_Y X)(p) &= (\overline{\nabla_X Y} - \overline{\nabla_Y X})^t(p) \\ &= [\overline{X}, \overline{Y}]^t(p) = [X, Y](p). \end{aligned}$$

To get this last equality (\clubsuit), note that in local coordinates, we have

$$\begin{aligned} (\heartsuit) \quad [\overline{X}, \overline{Y}]^t(p) &= \left(\sum_{i,j=1}^{n+k} \left\{ \overline{X}^i \frac{\partial \overline{Y}^j}{\partial x^i} - \overline{Y}^i \frac{\partial \overline{X}^j}{\partial x^i} \right\} \frac{\partial}{\partial x^j} \right)^t(p) \\ &= \left(\sum_{i=1}^n \sum_{j=1}^{n+k} \left\{ X^i \frac{\partial Y^j}{\partial x^i} - Y^i \frac{\partial X^j}{\partial x^i} \right\} \frac{\partial}{\partial x^j} \right)^t(p) \\ &= \left(\sum_{i,j=1}^n \left\{ X^i \frac{\partial Y^j}{\partial x^i} - Y^i \frac{\partial X^j}{\partial x^i} \right\} \frac{\partial}{\partial x^j} \right)(p) \\ &= [X, Y](p). \end{aligned}$$

This third equality (\heartsuit) holds because $\nabla_X Y(p)$ depends only on $X(p)$ and $Y(c(t))$ (where $c(t)$ is an integral curve for X through p).

Thus we have shown that ∇ is the Riemannian connection of M . \square

Exercise 3 (Exercise 2-8 [DoCarmo]). Consider the upper half-plane

$$\mathbb{R}_+^2 = \{(x, y) \in \mathbb{R}^2 \mid y > 0\}$$

with the metric given by $g_{11} = g_{22} = 1/y^2$, and $g_{12} = 0$ (metric of Lobatchevski's non-Euclidean geometry).

a) Show that the Christoffel symbols of the Riemannian connection are

$$\Gamma_{11}^1 = \Gamma_{12}^2 = \Gamma_{22}^1 = 0, \quad \Gamma_{11}^2 = \frac{1}{y}, \quad \Gamma_{12}^1 = \Gamma_{22}^2 = -\frac{1}{y}.$$

b) Let $v_0 = (0, 1)$ be a tangent vector at the point $(0, 1) \in \mathbb{R}_+^2$ (v_0 is the unit vector on the y -axis with origin at $(0, 1)$). Let $v(t)$ be the parallel transport of v_0 along the curve $x = t$, $y = 1$. Show that $v(t)$ makes an angle t with the direction of the y -axis, measured in the clockwise sense.

Proof of a). We have the following:

$$\begin{aligned}\Gamma_{ij}^k &= \frac{1}{2} g^{kl} \left(\frac{\partial g_{il}}{\partial x^j} + \frac{\partial g_{lj}}{\partial x^i} - \frac{\partial g_{ij}}{\partial x^l} \right) \\ &= \frac{y^2}{2} \left(\frac{\partial g_{ik}}{\partial x^j} + \frac{\partial g_{kj}}{\partial x^i} - \frac{\partial g_{ij}}{\partial x^k} \right) \\ &= \frac{y^2}{2} \cdot \frac{-2}{y^3} \left(\frac{\partial x^2}{\partial x^j} \delta_{ik} + \frac{\partial x^2}{\partial x^i} \delta_{kj} - \frac{\partial x^2}{\partial x^k} \delta_{ij} \right).\end{aligned}$$

Thus we have the desired values for the Christoffel symbols

$$\Gamma_{11}^1 = \Gamma_{12}^2 = \Gamma_{22}^1 = 0,$$

$$\Gamma_{11}^2 = \frac{1}{y},$$

$$\Gamma_{12}^1 = \Gamma_{22}^2 = -\frac{1}{y}.$$

□

Proof of b). Let $v(t) = (a(t), b(t))$ be the parallel field along the curve $x = t, y = 1$ with

$$v(0) = (0, 1), \quad v'(0) = v_0 = (0, 1).$$

Then, from the geodesic equations, we have

$$\begin{aligned}\frac{da}{dt} + \Gamma_{12}^1 b &= 0, \\ \frac{db}{dt} + \Gamma_{11}^2 a &= 0.\end{aligned}$$

Now, taking $a = \cos \theta(t)$ and $b = \sin \theta(t)$ (we can make this assumption since parallel transports preserve inner products), the above equations imply that $d\theta/dt = -1$. We have that $v_0 = (0, 1)$, so

$$\theta_0 = \frac{\pi}{2} \quad \text{and thus} \quad \theta = \frac{\pi}{2} - t,$$

as desired.

□