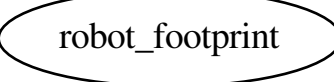


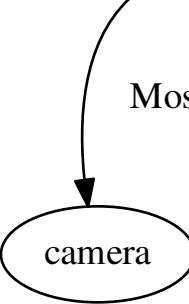
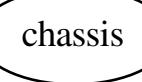
Broadcaster: /rtabmap/rtabmap
Average rate: 20.215 Hz
Most recent transform: 601.122 (-0.096 sec old)
Buffer length: 4.650 sec



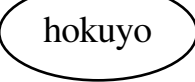
Broadcaster: /gazebo
Average rate: 5.227 Hz
Most recent transform: 600.885 (0.141 sec old)
Buffer length: 4.400 sec



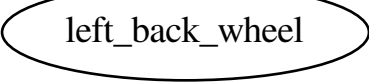
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (601.026 sec old)
Buffer length: 0.000 sec



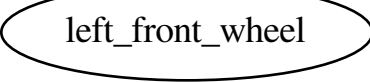
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (601.026 sec old)
Buffer length: 0.000 sec



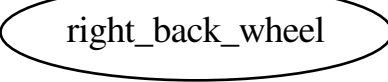
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (601.026 sec old)
Buffer length: 0.000 sec



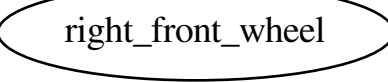
Broadcaster: /robot_state_publisher
Average rate: 10.213 Hz
Most recent transform: 601.002 (0.024 sec old)
Buffer length: 4.602 sec



Broadcaster: /robot_state_publisher
Average rate: 10.213 Hz
Most recent transform: 601.002 (0.024 sec old)
Buffer length: 4.602 sec



Broadcaster: /robot_state_publisher
Average rate: 10.213 Hz
Most recent transform: 601.002 (0.024 sec old)
Buffer length: 4.602 sec



Broadcaster: /robot_state_publisher
Average rate: 10.213 Hz
Most recent transform: 601.002 (0.024 sec old)
Buffer length: 4.602 sec