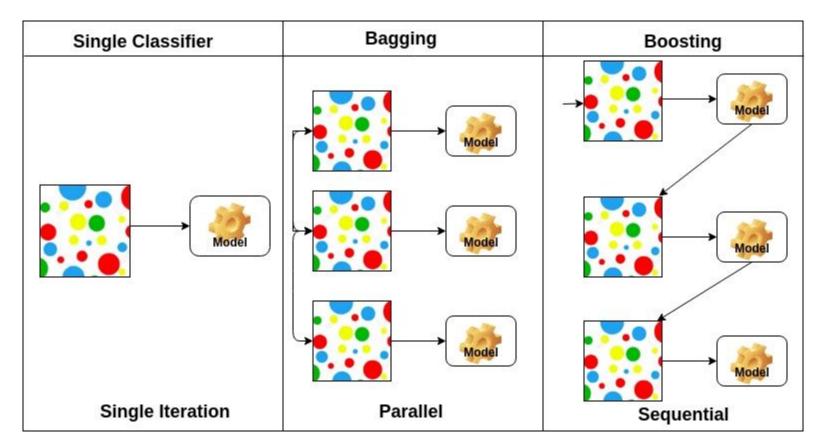
# **Boosting Algorithms**

that are tree-based

Tomasz Kajdanowicz



ex. Random Forest

# Sequential Decision Tree Building

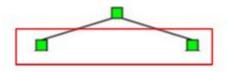
#### The building process

#### For each leaf node:

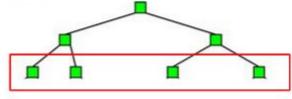
#### For each feature:

- Sort the instances in the node by the feature value
- Linear scan to decide the best split on the feature

#### Take the best split and do it

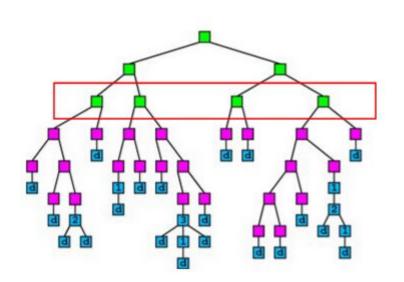


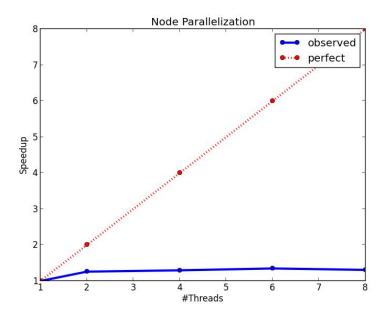




# Parallelize Node Building at Each Level

- parallelize node building at each level
- workload imbalance problem (number of leafs)





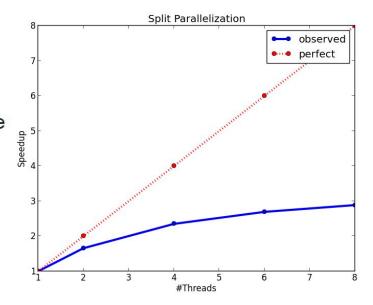
## Parallelize Split Finding on Each Node

too much overhead for small nodes.

#### 1. For each feature:

- Sort the instances by the feature value
- Linear scan to decide the best split on the feature

#### 2. Take the best split and do it



#### Parallelize Split Finding at Each Level by Features

For each feature:

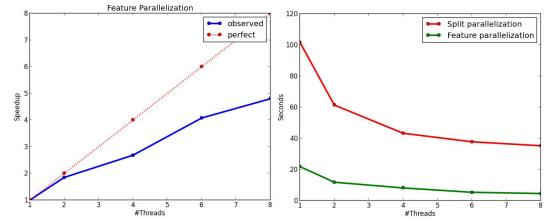
**>** 

For each leaf node:

Can sort globally first!

- Sort the instances of the node by the feature value
- Linear scan to decide the best split on the feature

Take the best split for each node and do it



#### Advantages:

- workload totally balanced number of instances for each
  feature is the same, the
  workload for different jobs is
  the same
- overhead for parallelization is small split finding at the whole level rather than a single node

# AdaBoost.PL

#### Output: The classifier (H)Output: The classifier (H)**Procedure: Procedure:** 1: $w^1 \leftarrow (\frac{1}{n}, ..., \frac{1}{n})$ 1: **for** $p \leftarrow 1$ to M **do** 2: $H^p \leftarrow ADABOOST(D_{np}^p, T)$ 2: **for** $t \leftarrow 1$ to T **do** 3: $H^{p^*} \leftarrow$ the weak classifiers in $H^p$ sorted w.r.t. $\alpha^{p(t)}$ 3: $h^{(t)} \leftarrow \text{LearnWeakClassifier}(w^t)$ 4: end for $\epsilon_{-} \leftarrow \sum_{i=1}^{n} w_{i}^{t} I \left\{ h^{(t)} \left( x_{i} \right) \neq y_{i} \right\}$ $\alpha^{t} \leftarrow \frac{1}{2} \ln \left( \frac{1 - \epsilon_{-}}{\epsilon_{-}} \right)$ 5: for $t \leftarrow 1$ to T do 6: $h^{(t)} \leftarrow \text{MERGE}(h^{1^*(t)}, ..., h^{M^*(t)})$ 7: $\alpha^t \leftarrow \frac{1}{M} \sum_{p=1}^{M} \alpha^{p^*(t)}$ for $i \leftarrow 1$ to n do if $h^{(t)}(x_i) \neq y_i$ then $w_i^{t+1} \leftarrow \frac{w_i^t}{2\epsilon}$ 8: end for 9: return $H = \sum_{t=1}^{T} \alpha^t h^{(t)}$ else $w_i^{t+1} \leftarrow \frac{w_i^t}{2(1-\epsilon_-)}$ 10: end if 11: end for 12: 13: end for 14: return $H = \sum_{t=1}^{T} \alpha^{t} h^{(t)}$

**Algorithm 1** ADABOOST $(D_n, T)$ 

**Input:** Training set of n examples  $(D_n)$ 

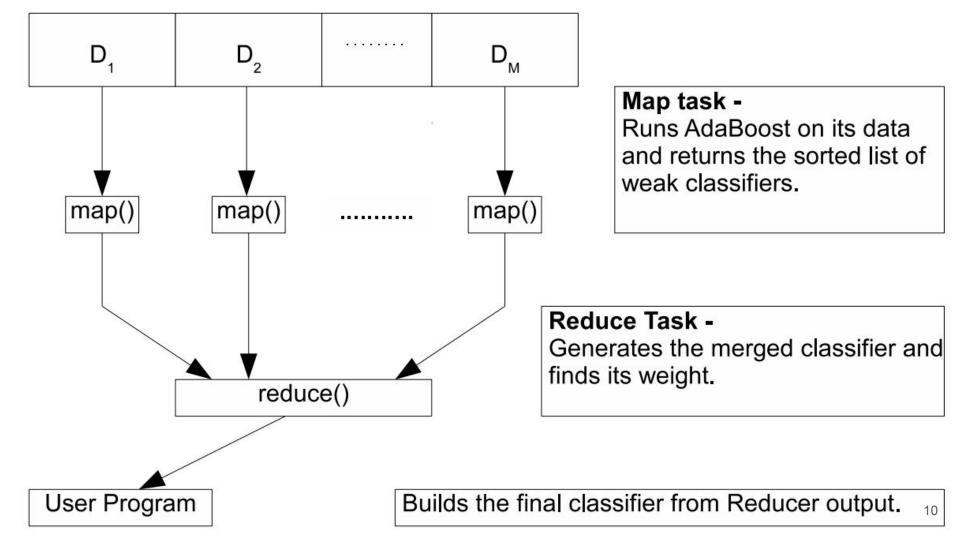
Number of boosting iterations (T)

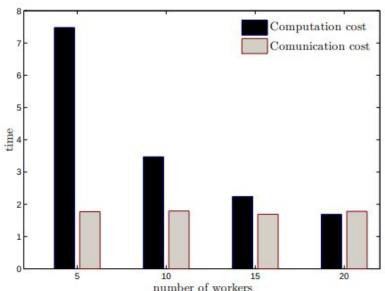
Palit, Indranil, and Chandan K. Reddy. "Parallelized boosting with map-reduce." 2010 IEEE International Conference on Data Mining Workshops. IEEE, 2010.

**Algorithm 2** ADABOOST.PL $(D_{n^1}^1, ..., D_{n^M}^M, T)$ 

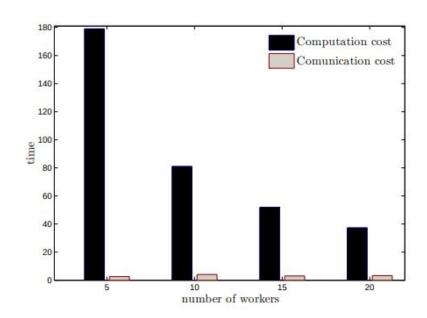
Number of boosting iterations (T)

**Input:** The training sets of M workers  $(D_{n_1}^1,...,D_{n_M}^M)$ 





number of workers			
dataset	instances	attributes	
musk	6598	167	
swsequence	3527	6349	



# Gradient boosting machines (GBMs)

#### How to understand GBMs?

additive modeling

intuition behind gradient boosting

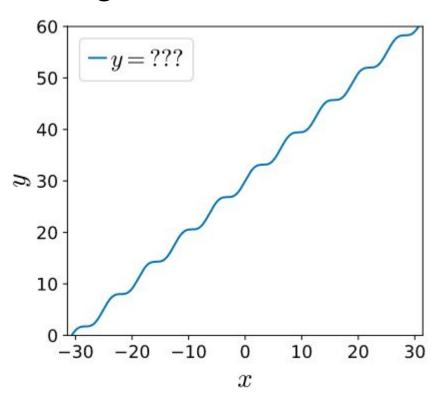
Example

Performance

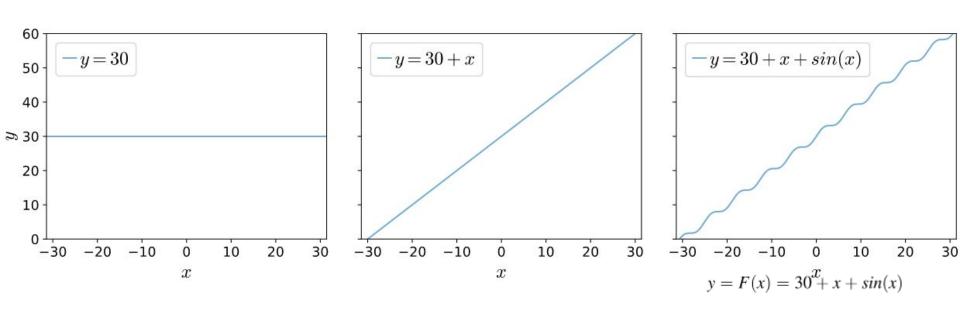
Hyper-parameters

L2 loss optimizing algorithm

# Additive modeling



# Additive modeling



$$F_M(\mathbf{x}) = f_1(\mathbf{x}) + \dots + f_M(\mathbf{x}) = \sum_{m=1}^M f_m(\mathbf{x})$$

#### Greedy approach

Our aim: 
$$\hat{y} = \sum_{m=1}^{M} f_m(\mathbf{x})$$

Gradient boosting machines use additive modeling to gradually nudge an approximate model with greedy approach:

$$F_m(\mathbf{x}) = F_{m-1}(\mathbf{x}) + f_m(\mathbf{x})$$

# Intuition behind gradient boosting

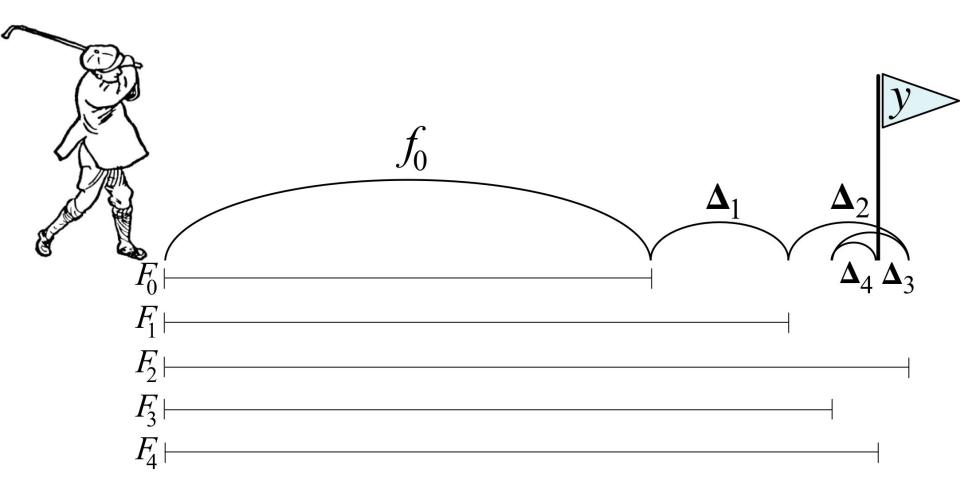
 $f_0(x)$  - initial model (predicts y given x)

then, let's gradually nudge the model towards the known target value y by adding one or more tweaks

$$\hat{\mathbf{y}} = f_0(\mathbf{x}) + \Delta_1(\mathbf{x}) + \Delta_2(\mathbf{x}) + \dots + \Delta_M(\mathbf{x})$$

$$= f_0(\mathbf{x}) + \sum_{m=1}^{M} \Delta_m(\mathbf{x})$$

$$= F_M(\mathbf{x})$$



$rac{ ext{Stage}}{m}$	$egin{aligned} \mathbf{Boosted} \\ \mathbf{Model} \end{aligned}$	$\begin{array}{c} \mathbf{Model} \\ \mathbf{Output} \; \hat{y} \end{array}$	Train $\Delta_m$ on $y - F_{m-1}$	$egin{aligned} \mathbf{Noisy} \ \mathbf{Prediction} \ \Delta_m \end{aligned}$
0	$F_0$	70		
1	$F_1 = F_0 + \Delta_1$	70 + 15 = 85	100-70=30	$\Delta_1 = 15$
2	$F_2 = F_1 + \Delta_2$	85 + 20 = 105	100-85=15	$\Delta_2 = 20$
3	$F_3 = F_2 + \Delta_3$	105 - 10 = 95	100 - 105 = -5	$\Delta_3 =$ -10
4	$F_4 = F_3 + \Delta_4$	95 + 5 = 100	100-95=5	$\Delta_4 = 5$

#### **REMARK!**

- Direction vector and residuals vector
- There will be so-called **learning rate**, that speeds up or slows down the overall approach of predicted y to real y, which helps to reduce the likelihood of overfitting

Example	sqfeet	rent
	750	1160
<u>Data:</u>	800	1200
	850	1280
	900	1450
	950	2000

Notation: X - feature vectors, y - rent vector,  $F_m(x_i)$  - predicted value,  $F_m(X)$  - predicted target vector

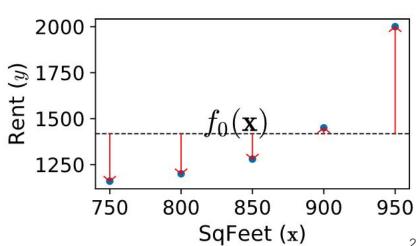
<u>Task:</u> predict rent price given square footage

Initial model: mean (average), then: regression tree stump

$\mathbf{sqfeet}$	$\mathbf{rent}$	$F_0$	$\mathbf{y} - F_0$
750	1160	1418	-258
800	1200	1418	-218
850	1280	1418	-138
900	1450	1418	32
950	2000	1418	582

 $y - F_m$  - called pseudo-responses

shows not only the direction but the magnitude



$$x < 925$$
 $x > = 925$ 
 $[-258, -218, -138, 32]$ 
 $[582]$ 
 $[582]$ 
 $[582]$ 
 $[582]$ 
 $[582]$ 

x < 825 x > 825

x < 925 x > = 925 [-20,20,-54.2,115.8] x > = 925 [-61.7] x = -61.7 x = -61.7

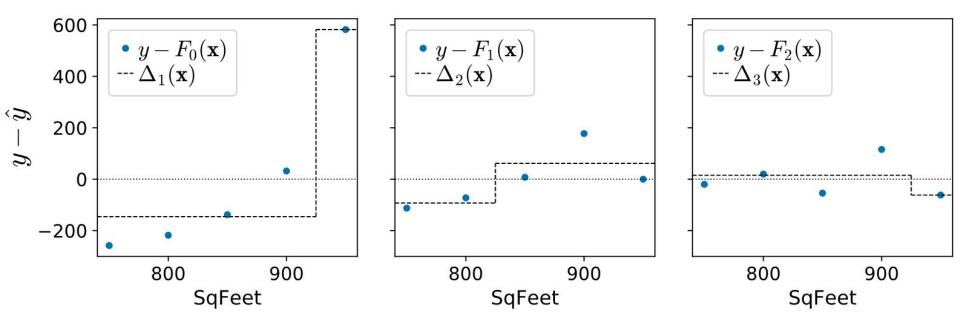
$$F_m(X) = F_{m-1}(X) + \eta \Delta_m(X)$$

$$\eta = 1.0$$

$$F_1 = F_0 + \Delta_1, F_2 = F_1 + \Delta_2$$

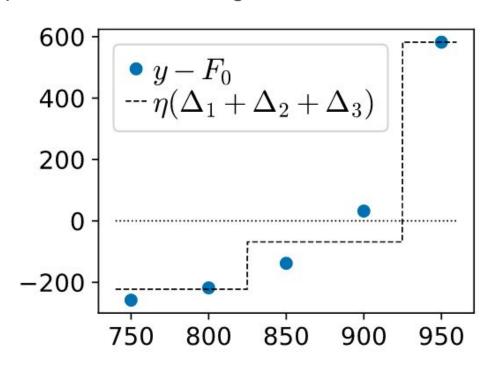
$\Delta_1$	$F_1$	$\mathbf{y}$ - $F_1$	$\Delta_2$	$F_2$	$\mathbf{y}$ - $F_2$	$\Delta_3$	$F_3$
-145.5	1272.5	-112.5	-92.5	1180	-20	15.4	1195.4
-145.5	1272.5	-72.5	-92.5	1180	20	15.4	1195.4
-145.5	1272.5	7.5	61.7	1334.2	-54.2	15.4	1349.6
-145.5	1272.5	177.5	61.7	1334.2	115.8	15.4	1349.6
582	2000	0	61.7	2061.7	-61.7	-61.7	2000

we are always training on the residual vector  $\mathbf{y} - \mathbf{F}_{m-1}$  but get imperfect model



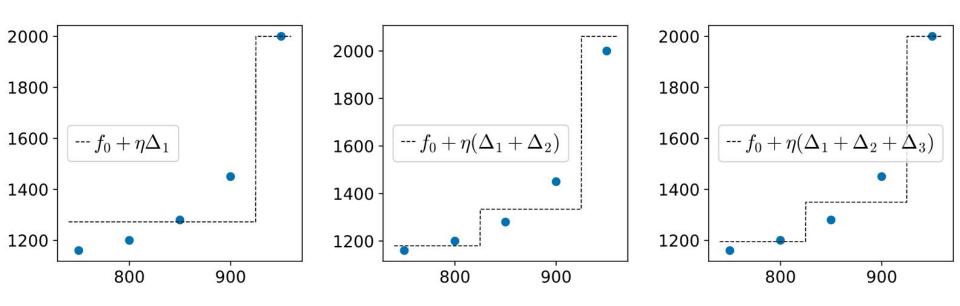
**blue dots** - residual vector elements used to train weak models, **dashed lines** - predictions made by weak models, **dotted line** - origin at 0

composite model sums together all of the weak models



blue dots - residual vector
elements used to train weak
models,
dashed lines - predictions made
by weak models,
dotted line - origin at 0

adding all of weak models to the initial average model



#### Measuring model performance

The loss across all **N** observations is just the average of all the individual observation losses:

$$L(\mathbf{y}, F_M(X)) = \frac{1}{N} \sum_{i=1}^{N} L(y_i, F_M(\mathbf{x}_i))$$

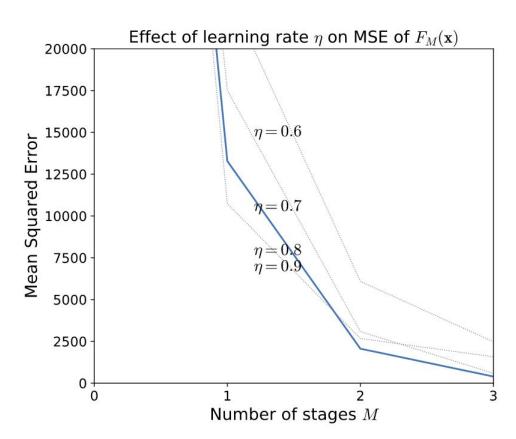
The mean squared error (MSE) is the most common, and what we are optimizing:

$$L(\mathbf{y}, F_M(X)) = \frac{1}{N} \sum_{i=1}^{N} (y_i - F_M(\mathbf{x}_i))^2$$

## Choosing hyper-parameters

number of stages M

the learning rate  $\,\eta\,$ 



# L2 loss optimizing algorithm

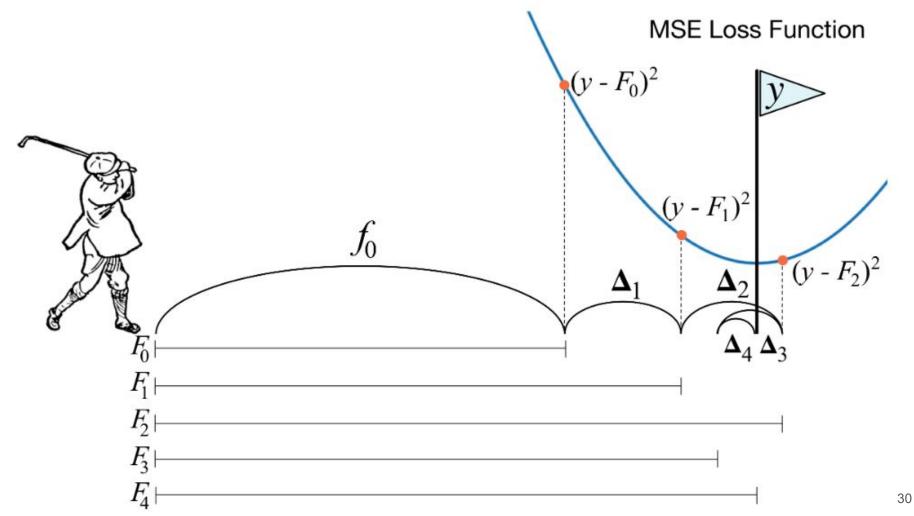
Algorithm:  $l2boost(X,y,M,\eta)$  returns model  $F_M$ Let  $F_0(X) = \frac{1}{N} \sum_{i=1}^{N} y_i$ , mean of target y across all observations for m = 1 to M do Let  $\mathbf{r}_{m-1} = \mathbf{y} - F_{m-1}(X)$  be the residual direction vector Train regression tree  $\Delta_m$  on  $\mathbf{r}_{m-1}$ , minimizing squared error  $F_m(X) = F_{m-1}(X) + \eta \Delta_m(X)$ end return  $F_M$ 

## Why **gradient** boosting?

a mathematician's favorite trick: showing how our current problem is just a flavor of another well-known problem for which we have lots of useful results

GBM training weak learners on residual vectors optimizes the mean squared error (MSE), the  $L_2$  loss, between the true target y and the intermediate predictions  $F_m(X)$ 

Is adding weak models  $\Delta_m$  to our GBM additive model  $F_m(X) = F_{m-1}(X) + \eta \Delta_m(X)$  performing gradient descent in some way?



To uncover the loss function optimized we just have to integrate the residuals  $y - F_m(X)$ 

$$L(\mathbf{y}, F_M(X)) = \frac{1}{N} \sum_{i=1}^{N} (y_i - F_M(\mathbf{x}_i))^2$$

$$L(\mathbf{y}, \hat{\mathbf{y}}) = \frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

since N is a constant once we start boosting, and f(x) and cf(x) have the same x minimum point, let's drop the 1/N constant

$$L(\mathbf{y}, \hat{\mathbf{y}}) = \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

taking the partial derivative of the loss function with respect to a specific

approximation 
$$\hat{y}_j$$
  $\frac{\partial}{\partial \hat{y}_j} L(\mathbf{y}, \hat{\mathbf{y}}) = \frac{\partial}{\partial \hat{y}_j} \sum_{i=1}^N (y_i - \hat{y}_i)^2$ 

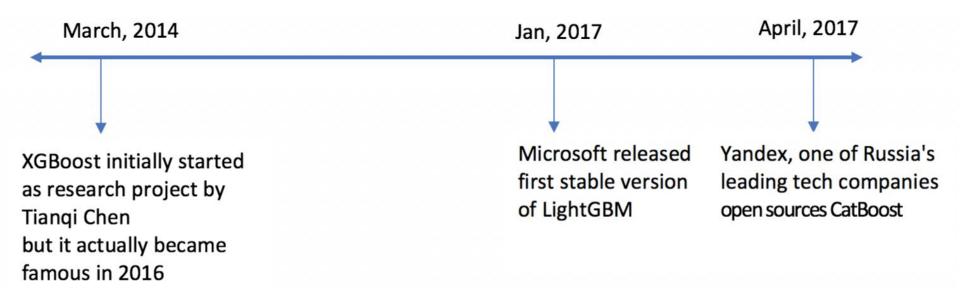
$$= \frac{\partial}{\partial \hat{y}_j} (y_j - \hat{y}_j)^2$$

$$= 2(y_j - \hat{y}_j) \frac{\partial}{\partial \hat{y}_j} (y_j - \hat{y}_j)$$

$$= -2(y_j - \hat{y}_j)$$

remove the summation because the partial derivative of *L* for *i*≠*j* is 0

$$\nabla_{\hat{\mathbf{y}}} L(\mathbf{y}, \hat{\mathbf{y}}) = -2(\mathbf{y} - \hat{\mathbf{y}})$$



# XGBoost

#### Difference between GBM and XGBoost?

- XGBoost and GBM follows the principle of gradient boosting
- XGBoost uses a more regularized model formalization to control complexity of the model and over-fitting, which gives it better performance.
- Objective Function : Training Loss + Regularization
- Regularization: complexity of the model

$$Obj = \sum_{i=1}^{n} l(y_i, \hat{y}_i) + \sum_{k=1}^{K} \Omega(f_k)$$

**Training Loss** measures how well model fit on training data

**Regularization**, measures complexity of trees

## Complexity of a tree

#### Taken into account:

- Number of leaves in tree T
- Leaf weigh penalty parameter  $\gamma$
- Tree size penalty parameter λ
- Score of a leaf w<sub>i</sub>

$$\Omega(F_t) = \gamma T + \frac{1}{2} \lambda \sum_{i=1}^T w_j^2$$

$$Obj(F_t) = -\frac{1}{2} \sum_{i=1}^T \frac{G_j^2}{H_j + \lambda} + \gamma T$$

$$G_{j} = \sum_{i \in I_{j}} \partial_{\hat{y}^{(t-1)}} l(y_{i}, \hat{y}^{(t-1)})$$

$$H_{j} = \sum_{i \in I_{j}} \partial_{\hat{y}^{(t-1)}}^{2} l(y_{i}, \hat{y}^{(t-1)})$$

$$I = \{i | q(x_{i}) = j\}$$

# LightGBM

## LightGBM

#### Gradient-based One-Side Sampling (GOSS):

- exclude a significant proportion of data instances with small gradients, and only use the rest to estimate the information gain
- since the data instances with larger gradients play a more important role in the computation of information gain, GOSS can obtain quite accurate estimation of the information gain with a much smaller data size -> FASTER

#### Exclusive Feature Bundling (EFB):

- bundle mutually exclusive features (i.e., they rarely take nonzero values simultaneously), to reduce the number of features
- finding the optimal bundling of exclusive features is NP-hard, but a greedy algorithm can achieve quite good approximation ratio

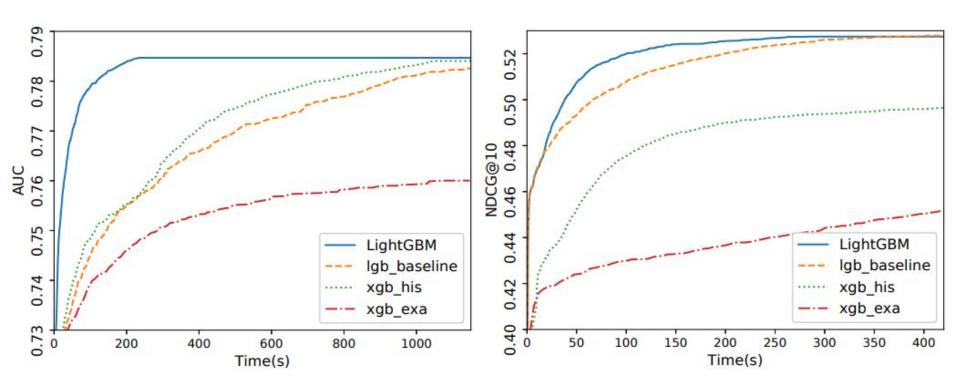


Figure 1: Time-AUC curve on Flight Delay.

Figure 2: Time-NDCG curve on LETOR.

# CatBoost

#### CatBoost

- ordered boosting a permutation-driven alternative to the classic algorithm
  - $\circ$  Adresses the **prediction shift** problem gradients used at each step are estimated using the target values of the same data points the current model  $F_{m-1}$  was built on
- an innovative algorithm for processing categorical features

Function	XGBoost	CatBoost	Light GBM
Important parameters which control overfitting	<ol> <li>learning_rate or eta         <ul> <li>optimal values lie</li> <li>between 0.01-0.2</li> </ul> </li> <li>max_depth</li> <li>min_child_weight:         <ul> <li>similar to min_child</li> <li>leaf; default is 1</li> </ul> </li> </ol>	1. Learning_rate 2. Depth - value can be any integer up to 16. Recommended - [1 to 10] 3. No such feature like min_child_weight 4. I2-leaf-reg: L2 regularization coefficient. Used for leaf value calculation (any positive integer allowed)	<ol> <li>learning_rate</li> <li>max_depth: default is 20. Important to note that tree still grows leaf-wise. Hence it is important to tune num_leaves (number of leaves in a tree) which should be smaller than 2^(max_depth). It is a very important parameter for LGBM</li> <li>min_data_in_leaf: default=20, alias= min_data, min_child_samples</li> </ol>
Parameters for categorical values	Not Available	<ol> <li>cat_features: It denotes the index of categorical features</li> <li>one_hot_max_size: Use one-hot encoding for all features with number of different values less than or equal to the given parameter value (max – 255)</li> </ol>	categorical_feature: specify the categorical features we want to use for training our model
Parameters for controlling speed	<ol> <li>colsample_bytree:         <ul> <li>subsample ratio of columns</li> </ul> </li> <li>subsample:         <ul> <li>subsample ratio of the training instance</li> </ul> </li> <li>n_estimators:         <ul> <li>maximum number of decision trees; high value can lead to overfitting</li> </ul> </li> </ol>	<ol> <li>rsm: Random subspace method. The percentage of features to use at each split selection</li> <li>No such parameter to subset data</li> <li>iterations: maximum number of trees that can be built; high value can lead to overfitting</li> </ol>	<ol> <li>feature_fraction: fraction of features to be taken for each iteration</li> <li>bagging_fraction: data to be used for each iteration and is generally used to speed up the training and avoid overfitting</li> <li>num_iterations: number of boosting iterations to be performed; default=100</li> </ol>

## Conclusions