Fast Approximation of Betweenness Centrality through Sampling

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Why is it interesting?



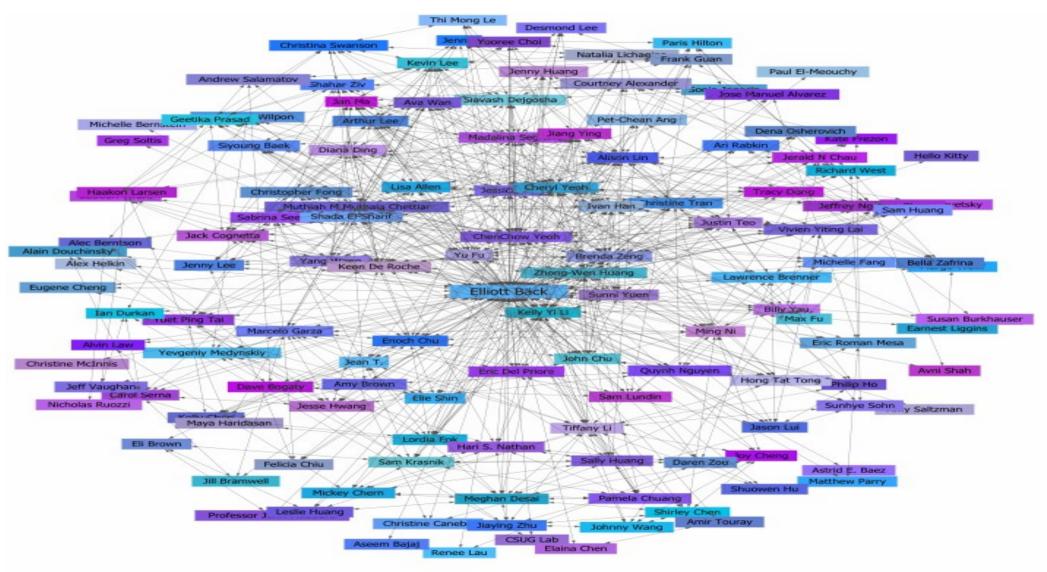


Online Social Networks





Relationship Graph





- Prolification of online social networks
- Social Network Analysis pre-existed them
- •Core task:
 - Find the most important players



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 Find the most important players
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 To target them (rumors, connectivity,
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- Prolification of online social networks
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- •Core task:
 Find the most important players
- •Why?
 To target them (rumc
 marketing, promotion Not well defined.
 What is "important"?
- •Not just social networks.

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 (Autonomous Systems), protein networks



Centrality Indices

- Centrality indices measure the relative importance of vertices in a graph
- •Introduced in sociology literature, '70s



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- •Introduced in sociology literature, '70s
- Different flavours of importance
 Many definitions of centrality indices
- Most are based on shortest pathsIntuition: information "spreads" along shortest paths (probably not true)
- Can be extended to include routing info



Computing Centrality

- •Today's networks have 10^8 vertices
- •Exact computation requires many runs of Single Source Shortest Paths (SSSP) + Aggregation
- •Too expensive, despite tricks to speed up the aggregation [Brandes01]



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- •Exact computation requires many runs of Single Source Shortest Paths (SSSP) + Aggregation
- •Too expensive, despite tricks to speed up the aggregation [Brandes01]
- Sampling can help: trade-off accuracy for speed



Outline

- •Motivation√
- Definition and settings
- Exact and simple sampling algorithms
- •Our result: a fast sampling algorithm
- •Better approximation for the top-K vertices
- Experiments
- Conclusions

Graph

- •Graph G = (V, E)
 - $\bullet |V| = n$, |E| = m
 - •Can be weighted: $w_e \geq 0, e \in E$
 - Can be directed
 - •No self-loops
 - No multiple edges between a pair of vertices



(Shortest) Paths

- •Path $p = (v_1, \ldots, v_{|p|})$ ordered tuple of vertices
- •End points of p: $\{v_1,v_{|p|}\}$
- •Internal vertices: $Int(p) = p \setminus \{v_1, v_{|p|}\}$
- • S_{uv} : Set of shortest paths from u to v
- $ullet \sigma_{uv} = |\mathcal{S}_{uv}|$: no. of shortest paths from u to v
- $ullet \mathbb{S}_G = igcup_{(u,v) \in V imes V, u
 eq v} \mathcal{S}_{uv}$: all shortest paths in G



Betweenness Centrality

•The betweenness centrality of a vertex $v \in V$ measures (roughly) the fraction of shortest paths going through v



Betweenness Centrality

- •The betweenness centrality of a vertex $v \in V$ measures (roughly) the fraction of shortest paths going through v
- •Let $\mathcal{T}_v = \{ p \in \mathbb{S}_G : v \in Int(p) \}$
- •Betweenness centrality of v

$$\mathbf{b}(v) = \frac{1}{n(n-1)} \sum_{p_{uw} \in \mathbb{S}_G} \frac{1_{\mathcal{T}_v}(p_{uw})}{\sigma_{uw}} = \frac{1}{n(n-1)} \sum_{p_{uw} \in \mathcal{T}_v} \frac{1}{\sigma_{uw}}$$

•k-betweenness: local variant, consider only shortest paths of length up to k



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Exact Algorithm

- •Naïve exact algorithm for betweenness:
 - •All Pairs Shortest Paths + Aggregation
 - The aggregation part dominates
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 - •split aggregation in smaller parts by considering partial contributions
 - •Complexity: O(nm) or $O(nm + n^2 \log n)$



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This is still too much for large networks



Sampling to the Rescue

- •Solution: use sampling!
- Trade off accuracy for speed



Can guarantee high quality approximations with high confidence

...especially when the analysis is tight!



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Key questions:What should we sample?How much should we sample?



Guarantees

•We want (probabilistic) guarantees on the approximation



Guarantees

- •We want (probabilistic) guarantees on the approximation
- •An (ε, δ) -approximation for the betweenness is a set of estimations $\tilde{\mathbf{b}}(v)$ for all $v \in V$ such that $\Pr\left(\exists v \in V : |\tilde{\mathbf{b}}(v) \mathbf{b}(v)| > \varepsilon\right) < \delta$
- ε controls the accuracy
- δ controls the confidence
- •Trade-off: Higher accuracy and/or confidence requires more samples!

- [BrandesPich07] inspired by [EppsteinWang01]
- •The algorithm:

```
For r times do sample random vertex v
```

Compute SSSP from v

Perform partial computation for $\tilde{b}(w), w \in V$

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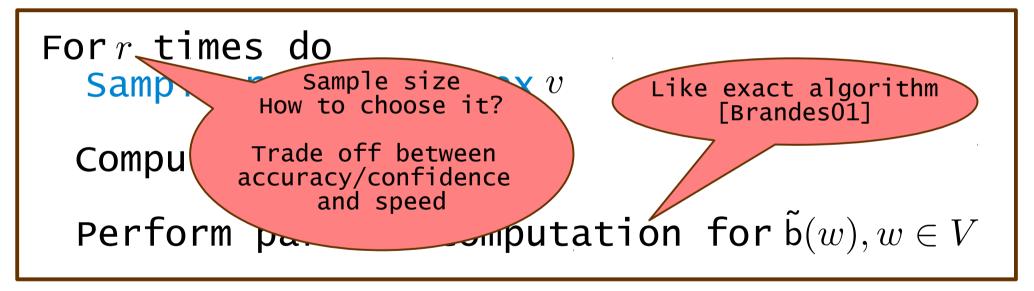
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•At each step, the algorithm computes many shortest paths (at least n-1 for a connected, undirected graph)

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- Use Hoeffding bound (method of bounded differences) to bound deviation of estimated betweenness from exact value for a single

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$$\Pr(|\mathbf{\tilde{b}}(v) - \mathbf{b}(v)| > \varepsilon) < 2e^{-2r\varepsilon^2}$$



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- •Use union bound over all n vertices
- •Sample size r for (ε, δ) -approximation:

$$r \ge \frac{1}{2\varepsilon^2} \left(\ln n + \ln 2 + \ln \frac{1}{\delta} \right)$$



Drawbacks

- •The sample size depends on $\ln n$
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Drawbacks

- •The sample size depends on $\ln n$
 - •Obtained from the union bound: loose!
 - •Is this the right quantity?
 - •We believe not
 - •It should be a characteristic quantity of the graph
- •At each sample, "heavy" computation (SSSP)
 - •Touch a lot of edges, has low "locality"



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Fast Sampling Algorithm

- •Our algorithm solves the drawbacks:
 - Does not use the union bounduse VC-dimension
 - Its sample size depends on a characteristic quantity of the graph (the vertex-diameter)
 - Not on number of vertices
 - Performs a single s-t shortest path computation per sample
 - Fewer edges touched, better locality



Fast Sampling Algorithm

•The algorithm:

For r times do Sample a random pair of vertices (u,v)

Compute \mathcal{S}_{uv} , all shortest paths from u to v

Select a path p uniformly at random from \mathcal{S}_{uv}

For each $w \in Int(p)$

$$\tilde{\mathbf{b}}(w) \leftarrow \tilde{\mathbf{b}}(w) + 1/r$$



Vertex Diameter

•The vertex diameter VD(G) of G is the maximum size of a shortest path between a pair of vertices of G:

$$VD(G) = \max\{|p| : p \in S_G\}$$

- •If the graph is not weighted: $VD(G) = \Delta_G + 1$
- •No relationship in general if G is weighted



Analysis

•Theorem:

Given
$$\varepsilon, \delta \in (0,1)$$
, if
$$r \geq \frac{1}{\varepsilon^2} \left(\lfloor \log_2(\mathsf{VD}(G) - 2) \rfloor + 1 + \ln \frac{1}{\delta} \right)$$
 then $\Pr\left(\exists v \in V \ : \ |\mathbf{\tilde{b}}(v) - \mathbf{b}(v)| > \varepsilon \right) < \delta$

•We have an (ε, δ) -approximation



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- •We have an (ε, δ) -approximation
- •For the proof, we use VC-Dimension



VC-Dimension

- [VapnikChervonenkis71]
- •Combinatorial property of a collection of subsets from a domain
- •Measures the "richness", "expressivity" of the subsets
- •Given a probability distribution on the domain, if we know the VC-dim of a collection of subsets, we can compute the sample size sufficient to approximate the probability mass of each subsets using a sample and the empirical average



Range Sets

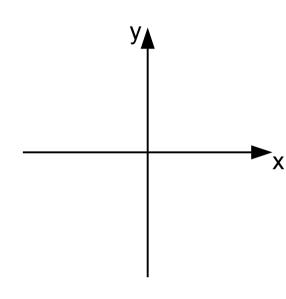
- VC-Dimension is defined on range sets
- B: Domain
- • \mathcal{R} : collection of subsets from B (ranges)
- •No restrictions:
 - B can be infinite
 - R can be infinite
 - \mathcal{R} can contain infinitely-large subsets of B

VC-Dimension

- •Range set ${\cal R}$ on domain B
- •For any $C \subseteq B$, define $P_C = \{C \cap F : F \in \mathcal{R}\}$
- C is shattered if $P_C = 2^C$
- •The VC-Dimension of $\mathcal R$ is the size of the largest shattered subset of $\mathcal B$

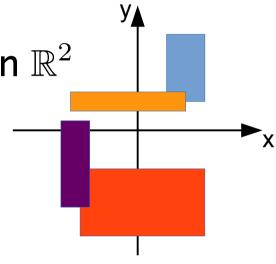


$$\bullet B = \mathbb{R}^2$$



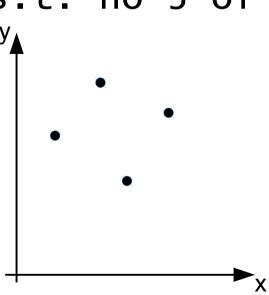


- $\bullet B = \mathbb{R}^2$
- $\mathcal{R}=$ all axis-aligned rectangles in \mathbb{R}^2



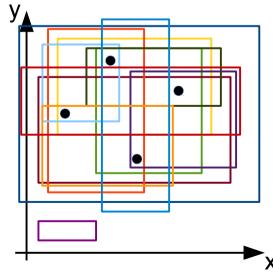


- $B = \mathbb{R}^2$
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- •Shattering 4 points: Easy
 - -Take any 4 points s.t. no 3 of them are aligned y





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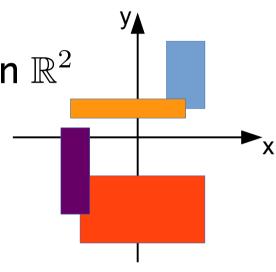
Need 16 rectangles to shatter them



•
$$B = \mathbb{R}^2$$

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•Shattering 5 points?

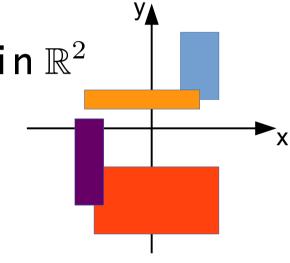




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•Shattering 5 points: impossible

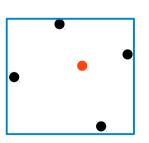




- $\bullet B = \mathbb{R}^2$
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- -Take any 5 points
- -One of them that is contained in all rectangles containing the other four
- -Impossible to find a rectangle containing only the other four
- $VC(\mathcal{R}) = 4$





VC-Dimension

- [Vapnik and Chervonenkis 71]
- Combinatorial property of a collection of subsets from a domain
- •Measures the "richness", "expressivity" of the subsets
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Sample Theorem

- •Let \mathcal{R} have $VC(\mathcal{R}) \leq d$
- •Let π be a probability distribution on B
- •Let $\pi(A)$ be the probability mass of $A \subseteq B$
- •Given $\varepsilon, \delta \in [0,1]$, let S be a collection of samples from π
- •If

$$|S| \ge \frac{1}{\varepsilon^2} \left(\frac{\mathbf{d}}{\mathbf{d}} + \ln \frac{1}{\delta} \right)$$

then,

$$\Pr\left(\exists A \in \mathcal{R} : \left| \pi(A) - \frac{1}{|S|} \sum_{s \in S} 1_A(s) \right| > \varepsilon\right) < \delta$$



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- Samples 110
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Roadmap

- •We are going to build a range set for the problem and show an upper bound to its VC-dimension
- •We define a probability distribution and use it to sample elements of the domain
- •The sample theorem gives us the amount of samples we need to draw to obtain a good approximation of the betweenness of all vertices



Shortest Path Range Set

- •Range set \mathcal{R}_G associated to shortest paths
- •Domain: \mathbb{S}_G , all shortest paths in G
- $\bullet \mathcal{R}_G = \{\mathcal{T}_v, v \in V\}$
- •Contains one range per vertex



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- Contains one range per vertex
- •Sampling probability distribution on \mathbb{S}_G

$$\pi_G(p_{uv}) = \frac{1}{n(n-1)} \frac{1}{\sigma_{uv}}$$

•The algorithm samples paths according to π_G



•Theorem: $VC(\mathcal{R}_G) \leq \lfloor \log_2 VD(G) - 2 \rfloor + 1$



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- •Proof: To shatter a set A of paths, |A| = d, we need 2^d different ranges $\mathcal{T}_v \in \mathcal{R}_G$



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 - p appears only in the \mathcal{T}_v 's of the $v \in \operatorname{Int}(p)$
 - p appears in $|Int(p)| \leq VD(G) 2$ ranges \mathcal{T}_v
 - •For A to be shattered, must be $2^{d-1} \leq VD(G) 2$
 - Implies the thesis



Back to the algorithm

•Recall the algorithm:

```
For r times do Sample a random pair of vertices (u,v)
```

Compute \mathcal{S}_{uv} , all shortest paths from u to v

Select a path p uniformly at random from \mathcal{S}_{uv}

For each $w \in Int(p)$

$$\tilde{\mathbf{b}}(w) \leftarrow \tilde{\mathbf{b}}(w) + 1/r$$



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Correctness

•From the sample theorem we get that if

$$r \ge \frac{1}{\varepsilon^2} \left(\lfloor \log_2(\mathsf{VD}(G) - 2) \rfloor + 1 + \ln \frac{1}{\delta} \right)$$

then the returned collection of $\tilde{\mathbf{b}}(v)$ is an (ε, δ) -approximation:

$$\Pr\left(\exists v \in V : |\tilde{\mathsf{b}}(v) - \mathsf{b}(v)| > \varepsilon\right) < \delta$$



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 $\Pr\left(\exists v \in V : | \tilde{\mathbf{b}}(v) \right)$ Definitively smaller than n

then the returned coller (ε, δ)-approximation: the diameter is usually very small (small wold phenomenon)



Corollaries

•If there is a unique shortest path for each pair of vertices then $VC(\mathcal{R}_G) \leq 3$



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- •If there is a unique shortest path for each pair of vertices then $VC(\mathcal{R}_G) \leq 3$
 - •This "collapse" of the VC-dimension to a constant is somewhat surprising
 - •Suggests that there may be other characteristic quantities of the graph that control the VC-Dimension



Corollaries

- •If there is a unique shortest path for each pair of vertices then $VC(\mathcal{R}_G) \leq 3$
 - •This "collapse" of the VC-dimension to a constant is somewhat surprising
 - •Suggests that there may be other characteristic quantities of the graph that control the VC-Dimension
- •k-betweenness: if we only consider shortest paths of size up to k, then

$$VC(\mathcal{R}_G) \le |\log_2 k - 1| + 1$$



Diameter Approximation

- •Computing VD(G) exactly would require APSP
 - Defeat the purpose of sampling



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Diameter Approximation

- •Computing VD(G) exactly would require APSP
 - Defeat the purpose of sampling
- •We need an approximation of VD(G)
- •Can be constant approx, we use log anyway!
- •Undirected && unweighted:2-approx using BFS
- •All other cases: ???
 - •Return the size of the largest WCC (<= n)</pre>



- •Often interest is top-K players in the network, and in their ranking
- •Let $b^{(K)}$ be the K^{th} highest betweenness (ties broken arbitrarily)
- •Goal: find the set T(K,G):

$$T(K,G) = \{ v \in V : b(v) \ge b^{(K)} \}$$



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Similar to definition of top-K Frequent Itemsets



 "Two phases" sampling algorithm for highquality approximation of the betweenness of the top-K vertices



- "Two phases" sampling algorithm for highquality approximation of the betweenness of the top-K vertices
 - •1st phase: compute lower bound to $\mathbf{b}^{(K)}$ using "standard" sample theorem
 - •2nd phase: Use relative variant of the sample theorem to compute superset of T(K,G)



- •"Two phases" sampling algorithm for highquality approximation of the betweenness of the top-K vertices
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- •For all vertices v in output we have

$$(1 - \varepsilon)b(v) \le \tilde{b}(v) \le (1 + \varepsilon)b(v)$$

with probability at least $1-\delta$



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$$(1 - \varepsilon)b(v) \le \tilde{b}(v) \le (1 + \varepsilon)b(v)$$

with probability at $least 1-\delta$



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Experimental Evaluation

•Goals:

- •Evaluate accuracy of our algorithms
- Compare running time, accuracy, and locality with exact and simple sampling algorithms



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 - Compare running time, accuracy, and locality with exact and simple sampling algorithms
- •Implementation:
 - c extension of igraph (igraph.sf.net)
 - •Exposed through Python3 API
 - Available from GitHub (not yet)



Experimental Evaluation

- •Goals:
 - Evaluate accuracy of our algorithms
 - Compare running time, accuracy, and locality with exact and simple sampling algorithms
- •Implementation:
 - c extension of igraph (igraph.sf.net)
 - Exposed through Python3 API
 - •Available from GitHub (not yet)
- •Datasets:
 - •Real networks (social, road, citation, ...) from SNAP (snap.stanford.edu)



Results

- •Very preliminary results
- •>3x speedup compared to simple sampling
- •>10x speedup compared to exact algorithm
- •Always within ε from real value
- Accuracy even better than guaranteed, better than simple sampling algorithm



•We proved the upper bound

$$VC(\mathcal{R}_G) \le \lfloor \log_2(VD(G) - 2) \rfloor + 1$$

•Is it tight?

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- •Example:
 - VD(G) = 9

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- •Example:
 - VD(G) = 9
 - $VC(\mathcal{R}_G) = 3$



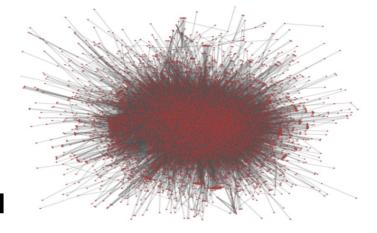
Conclusions

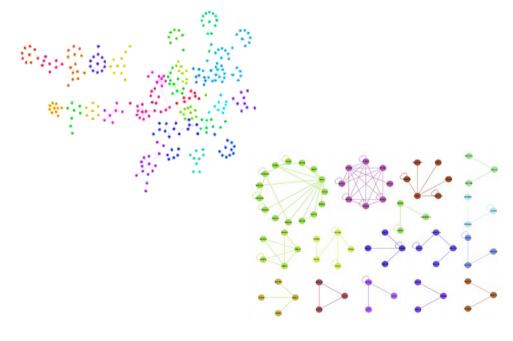
- •We presented two sampling-based randomized algorithms to approximate the betweenness of (top-K) vertices in huge graphs
- •The algorithms offer probabilistic guarantees on the accuracy of the approximations, using much fewer samples and performing fewer computations than previous available algorithms
- •Experimental evaluation shows that the algorithm outperforms previous works in terms of execution time and accuracy

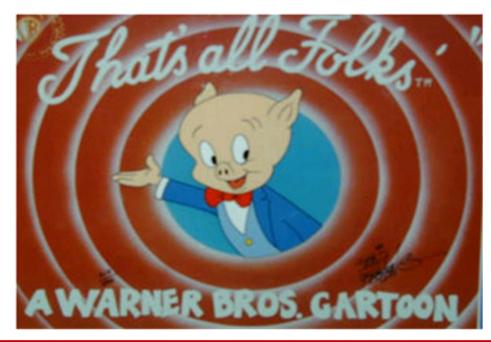


The End

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