Fast Approximation of Betweenness Centrality through Sampling

M. Riondato and E. Kornaropoulos



Brown University Computer Science

Boston University - October 18th, 2013



Why is it interesting?



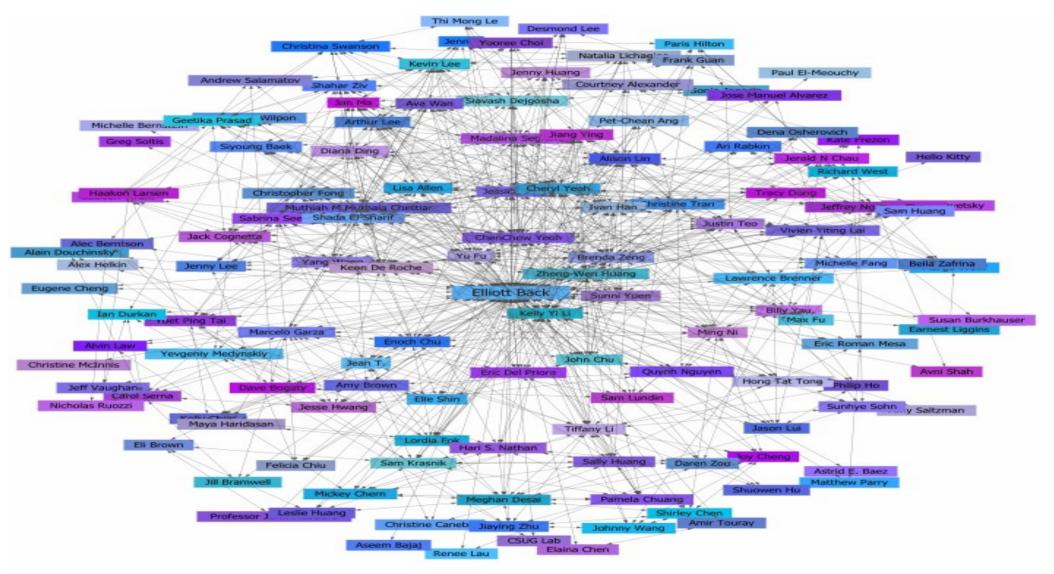


Online Social Networks





Relationship Graph





- Prolification of online social networks
- •Social Network Analysis pre-existed them
- •Core task:
 - Find the most important players



- Prolification of online social networks
- •Social Network Analysis pre-existed them
- •Core task:
 Find the most important players
- •Why?
 To target them (rumors, connectivity,
 marketing, promotions, ...)



- Prolification of online social networks
- •Social Network Analysis pre-existed them
- •Core task:
 Find the most important players
- •Why?
 To target them (rumors, connectivity,
 marketing, promotions, ...)
- •Not just social networks: road networks
 (used in GPS navs), computer networks
 (Autonomous Systems), protein networks



- Prolification of online social networks
- •Social Network Analysis pre-existed them
- •Core task:
 Find the most important players
- •Why?
 To target them (rumo
 marketing, promotion Not well defined.
 what is "important"?
- Not just social networks.

 (used in GPS navs), computer networks

 (Autonomous Systems), protein networks



Centrality Indices

- •Centrality indices measure the relative importance of vertices in a graph
- •Introduced in sociology literature, '70s



Centrality Indices

- •Centrality indices measure the relative importance of vertices in a graph
- •Introduced in sociology literature, '70s
- Different flavours of importance
 Many definitions of centrality indices
- Most are based on shortest paths
 Intuition: information "spreads" along shortest paths (probably not true)
- Can be extended to include routing info



Computing Centrality

- •Today's networks have 10^8 vertices
- •Exact computation requires many runs of Single Source Shortest Paths (SSSP) + Aggregation
- •Too expensive, despite tricks to speed up the aggregation [Brandes01]



Computing Centrality

- •Today's networks have 10^8 vertices
- •Exact computation requires many runs of Single Source Shortest Paths (SSSP) + Aggregation
- •Too expensive, despite tricks to speed up the aggregation [Brandes01]
- •Sampling can help:
 trade-off accuracy for speed



Outline

- •Motivation
- Definition and settings
- Exact and simple sampling algorithms
- Our result: a fast sampling algorithm
- •Better approximation for the top-K vertices
- Experiments
- Conclusions

Graph

- •Graph G = (V, E)
 - $\bullet |V| = n$, |E| = m
 - •Can be weighted: $w_e \ge 0, e \in E$
 - ·Can be directed
 - •No self-loops
 - No multiple edges between a pair of vertices



(Shortest) Paths

- •Path $p = (v_1, \dots, v_{|p|})$ ordered tuple of vertices
- •End points of p: $\{v_1,v_{|p|}\}$
- •Internal vertices: $Int(p) = p \setminus \{v_1, v_{|p|}\}$
- S_{uv} : Set of shortest paths from u to v
- $ullet \sigma_{uv} = |\mathcal{S}_{uv}|$ no. of shortest paths from u to v
- $ullet \mathbb{S}_G = igcup_{(u,v) \in V imes V, u
 eq v} \mathcal{S}_{uv}$: all shortest paths in G



Betweenness Centrality

•The betweenness centrality of a vertex $v \in V$ measures (roughly) the fraction of shortest paths going through v



Betweenness Centrality

- •The betweenness centrality of a vertex $v \in V$ measures (roughly) the fraction of shortest paths going through v
- •Let $\mathcal{T}_v = \{ p \in \mathbb{S}_G : v \in Int(p) \}$
- •Betweenness centrality of v

$$\mathbf{b}(v) = \frac{1}{n(n-1)} \sum_{p_{uw} \in \mathbb{S}_G} \frac{1_{\mathcal{T}_v}(p_{uw})}{\sigma_{uw}} = \frac{1}{n(n-1)} \sum_{p_{uw} \in \mathcal{T}_v} \frac{1}{\sigma_{uw}}$$

•k-betweenness: local variant, consider only shortest paths of length up to k



Outline

- •Motivation
- Definition and settings
- Exact and simple sampling algorithm
- Our result: a fast sampling algorithm
- •Better approximation for the top-K vertices
- Experiments
- Conclusions



Exact Algorithm

- •Naïve exact algorithm for betweenness:
 - •All Pairs Shortest Paths + Aggregation
 - The aggregation part dominates
 - •Complexity: $\Theta(n^3)$



Exact Algorithm

- •Naïve exact algorithm for betweenness:
 - •All Pairs Shortest Paths + Aggregation
 - The aggregation part dominates
 - •Complexity: $\Theta(n^3)$
- •[Brandes01]:
 - •split aggregation in smaller parts by considering partial contributions
 - •Complexity: O(nm) or $O(nm + n^2 \log n)$



Exact Algorithm

- •Naïve exact algorithm for betweenness:
 - •All Pairs Shortest Paths + Aggregation
 - The aggregation part dominates
 - •Complexity: $\Theta(n^3)$
- •[Brandes01]:
 - •split aggregation in small
 considering partial contri
 - •Complexity: O(nm) or $O(nm + n^2 \log n)$

This is still too much for large networks



Sampling to the Rescue

- •Solution: use sampling!
- Trade off accuracy for speed



Can guarantee high quality approximations with high confidence

...especially when the analysis is tight!



Sampling to the Rescue

- •Solution: use sampling!
- ·Trade off accuracy to speed



•Can guarantee high quality with high confidence Key questions:

...especially when the

is tight!

What should we sample?How much should we sample?

Riondato et al. - Fast Approximation of Betweenness Centrality Through Sampling



Guarantees

•We want (probabilistic) guarantees on the approximation

Guarantees

- •We want (probabilistic) guarantees on the approximation
- •An (ε, δ) -approximation for the betweenness is a set of estimations $\tilde{\mathbf{b}}(v)$ for all $v \in V$ such that $\Pr\left(\exists v \in V : |\tilde{\mathbf{b}}(v) \mathbf{b}(v)| > \varepsilon\right) < \delta$
- ε controls the accuracy
- δ controls the confidence
- •Trade-off: Higher accuracy and/or confidence requires more samples!

- [BrandesPich07] inspired by [EppsteinWang01]
- •The algorithm:

```
For r times do sample random vertex v
```

Compute SSSP from v

Perform partial computation for $\tilde{b}(w), w \in V$

- [BrandesPich07] inspired by [EppsteinWang01]
- •The algorithm:

For r times do Sample random vertex v Like exact algorithm [Brandes01] Compute SSSP from v Perform partial computation for $\tilde{\mathbf{b}}(w), w \in V$

- [BrandesPich07] inspired by [EppsteinWang01]
- •The algorithm:

For r times do sample random vertex v

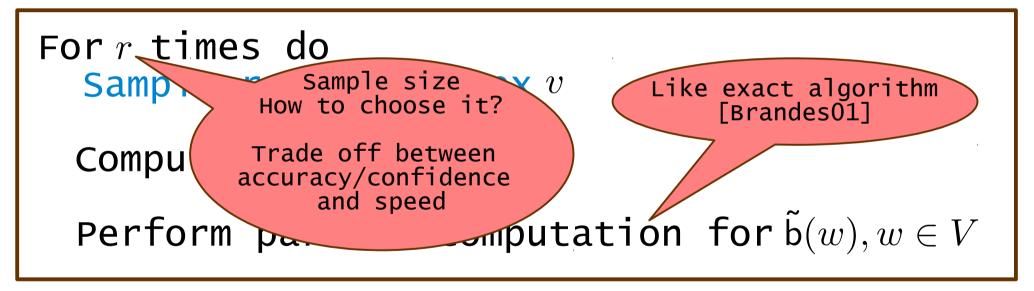
Compute SSSP from \boldsymbol{v}

Perform partial computation for $\tilde{\mathbf{b}}(w), w \in V$

Like exact algorithm [Brandes01]

•At each step, the algorithm computes many shortest paths (at least n-1 for a connected, undirected graph)

- [BrandesPich07] inspired by [EppsteinWang01]
- •The algorithm:



•At each step, the algorithm computes many shortest paths (at least n-1 for a connected, undirected graph)



•How to compute r?



- •How to compute r?
- •Use Hoeffding bound (method of bounded differences) to bound deviation of estimated betweenness from exact value for a single vertex:

$$\Pr(|\mathbf{\tilde{b}}(v) - \mathbf{b}(v)| > \varepsilon) < 2e^{-2r\varepsilon^2}$$



- •How to compute r?
- •Use Hoeffding bound (method of bounded differences) to bound deviation of estimated betweenness from exact value for a single vertex:

$$\Pr(|\mathbf{\tilde{b}}(v) - \mathbf{b}(v)| > \varepsilon) < 2e^{-2r\varepsilon^2}$$

•Use union bound over all n vertices



- •How to compute r?
- •Use Hoeffding bound (method of bounded differences) to bound deviation of estimated betweenness from exact value for a single vertex:

$$\Pr(|\mathbf{\tilde{b}}(v) - \mathbf{b}(v)| > \varepsilon) < 2e^{-2r\varepsilon^2}$$

- •Use union bound over all n vertices
- •Sample size r for (ε, δ) -approximation:

$$r \ge \frac{1}{2\varepsilon^2} \left(\ln n + \ln 2 + \ln \frac{1}{\delta} \right)$$



Drawbacks

- •The sample size depends on $\ln n$
 - •Obtained from the union bound: loose!



Drawbacks

- •The sample size depends on $\ln n$
 - •Obtained from the union bound: loose!
 - Is this the right quantity?We believe not
 - •It should be a characteristic quantity of the graph



Drawbacks

- •The sample size depends on $\ln n$
 - •Obtained from the union bound: loose!
 - Is this the right quantity?We believe not
 - •It should be a characteristic quantity of the graph
- •At each sample, "heavy" computation (SSSP)
 - •Touch a lot of edges, has low "locality"



Outline

- •Motivation
- Definition and settings
- Exact and simple sampling algorithms
- Our result: a fast sampling algorithm
- •Better approximation for the top-K vertices
- Experiments
- •Conclusions



Fast Sampling Algorithm

- •Our algorithm solves the drawbacks:
 - Does not use the union bounduse VC-dimension
 - Its sample size depends on a characteristic quantity of the graph (the vertex-diameter)
 - •Not on number of vertices
 - •Performs a single s-t shortest path computation per sample
 - Fewer edges touched, better locality



Fast Sampling Algorithm

•The algorithm:

For r times do Sample a random pair of vertices (u,v)

Compute \mathcal{S}_{uv} , all shortest paths from u to v

Select a path p uniformly at random from \mathcal{S}_{uv}

For each $w \in Int(p)$

$$\tilde{\mathbf{b}}(w) \leftarrow \tilde{\mathbf{b}}(w) + 1/r$$



Vertex Diameter

•The vertex diameter VD(G) of G is the maximum size of a shortest path between a pair of vertices of G:

$$VD(G) = \max\{|p| : p \in S_G\}$$

- •If the graph is not weighted: $VD(G) = \Delta_G + 1$
- •No relationship in general if G is weighted



Analysis

•Theorem:

Given
$$\varepsilon, \delta \in (0,1)$$
, if
$$r \geq \frac{1}{\varepsilon^2} \left(\lfloor \log_2(\mathsf{VD}(G) - 2) \rfloor + 1 + \ln \frac{1}{\delta} \right)$$
 then $\Pr\left(\exists v \in V \ : \ |\mathbf{\tilde{b}}(v) - \mathbf{b}(v)| > \varepsilon \right) < \delta$

•We have an (ε, δ) -approximation



Analysis

•Theorem:

Given
$$\varepsilon,\delta\in(0,1)$$
, if
$$r\geq\frac{1}{\varepsilon^2}\left(\lfloor\log_2(\mathsf{VD}(G)-2)\rfloor+1+\ln\frac{1}{\delta}\right)$$
 then $\Pr\left(\exists v\in V\ :\ |\tilde{\mathsf{b}}(v)-\mathsf{b}(v)|\right)$ Always less than n

•We have an (ε, δ) -approximation



Analysis

•Theorem:

Given
$$\varepsilon, \delta \in (0,1)$$
, if
$$r \geq \frac{1}{\varepsilon^2} \left(\lfloor \log_2(\mathsf{VD}(G) - 2) \rfloor + 1 + \ln \frac{1}{\delta} \right)$$
 then $\Pr\left(\exists v \in V \ : \ |\tilde{\mathsf{b}}(v) - \mathsf{b}(v)| > \delta \right)$

- •We have an (ε, δ) -approximation
- •For the proof, we use VC-Dimension



VC-Dimension

- [VapnikChervonenkis71]
- •Combinatorial property of a collection of subsets from a domain
- •Measures the "richness", "expressivity" of the subsets



VC-Dimension

- [VapnikChervonenkis71]
- •Combinatorial property of a collection of subsets from a domain
- •Measures the "richness", "expressivity" of the subsets
- •Given a probability distribution on the domain, if we know the VC-dim of a collection of subsets, we can compute the sample size sufficient to approximate the probability mass of each subset using a sample and the empirical average



Range Sets

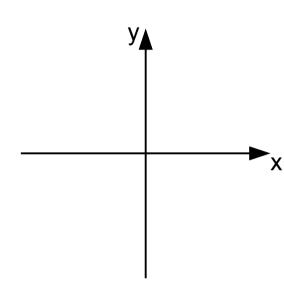
- VC-Dimension is defined on range sets
- B: Domain
- • \mathcal{R} : collection of subsets from B (ranges)
- •No restrictions:
 - Bcan be infinite
 - R can be infinite
 - \mathcal{R} can contain infinitely-large subsets of B

VC-Dimension

- •Range set ${\cal R}$ on domain B
- •For any $C \subseteq B$, define $P_C = \{C \cap F : F \in \mathcal{R}\}$
- C is shattered if $P_C = 2^C$
- •The VC-Dimension of $\mathcal R$ is the size of the largest shattered subset of $\mathcal B$



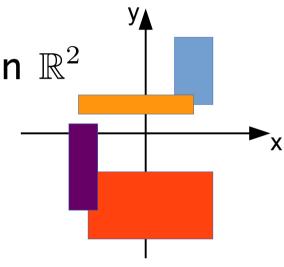
•
$$B = \mathbb{R}^2$$





•
$$B = \mathbb{R}^2$$

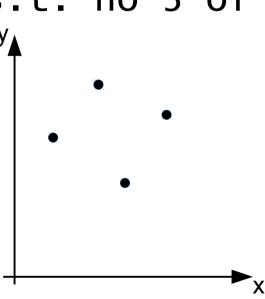
 $oldsymbol{\cdot}$ $\mathcal{R}=$ all axis-aligned rectangles in \mathbb{R}^2





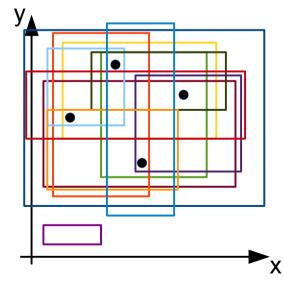
- $B = \mathbb{R}^2$
- $ullet \mathcal{R} = \mathsf{all} \; \mathsf{axis-aligned} \; \mathsf{rectangles} \; \mathsf{in} \; \mathbb{R}^2$
- •Shattering 4 points: Easy
 - -Take any 4 points s.t. no 3 of them are aligned y

 | Take any 4 points s.t. no 3 of





- $B = \mathbb{R}^2$
- $ullet \mathcal{R} = \mathsf{all} \; \mathsf{axis-aligned} \; \mathsf{rectangles} \; \mathsf{in} \; \mathbb{R}^2$
- •Shattering 4 points: Easy
 - -Take any 4 points s.t. no 3 of
 - them are aligned



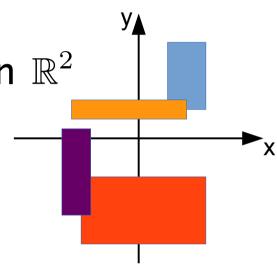
Need 16 rectangles to shatter them



•
$$B = \mathbb{R}^2$$

 $oldsymbol{\cdot}$ $\mathcal{R}=$ all axis-aligned rectangles in \mathbb{R}^2

•Shattering 5 points?

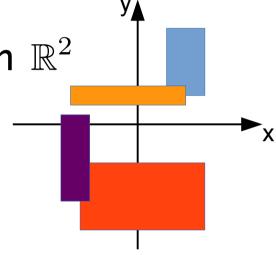




•
$$B = \mathbb{R}^2$$

 $oldsymbol{\cdot}$ $\mathcal{R}=$ all axis-aligned rectangles in \mathbb{R}^2

•Shattering 5 points: impossible

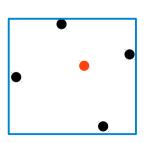




- $B = \mathbb{R}^2$
- $ullet \mathcal{R} = \mathsf{all} \; \mathsf{axis-aligned} \; \mathsf{rectangles} \; \mathsf{in} \; \mathbb{R}^2$



- -Take any 5 points
- -One of them that is contained in all rectangles containing the other four
- -Impossible to find a rectangle containing only the other four
- $VC(\mathcal{R}) = 4$





VC-Dimension

- [VapnikChervonenkis71]
- •Combinatorial property of a collection of subsets from a domain
- •Measures the "richness", "expressivity" of the subsets
- •Given a probability distribution on the domain, if we know the VC-dim of a collection of subsets, we can compute the sample size sufficient to approximate the probability mass of each subsets using a sample and the empirical average



Sample Theorem

- •Let \mathcal{R} have $VC(\mathcal{R}) \leq d$
- •Let π be a probability distribution on B
- •Let $\pi(A)$ be the probability mass of $A \subseteq B$
- •Given $\varepsilon,\delta\in[0,1]$,let S be a collection of samples from π
- •If

$$|S| \ge \frac{1}{\varepsilon^2} \left(\frac{\mathbf{d}}{\mathbf{d}} + \ln \frac{1}{\delta} \right)$$

then,

$$\Pr\left(\exists A \in \mathcal{R} : \left| \pi(A) - \frac{1}{|S|} \sum_{s \in S} 1_A(s) \right| > \varepsilon\right) < \delta$$



Sample Theorem

- •Let \mathcal{R} have $VC(\mathcal{R}) \leq d$
- •Let π be a probability distribution on B
- •Let $\pi(A)$ be the probability mass of $A \subseteq B$
- •Given $\varepsilon, \delta \in [0,1]$, let S be a collection of samples from π
- •If

$$|S| \ge \frac{1}{\varepsilon^2} \left(\frac{\mathbf{d}}{\mathbf{d}} + \ln \frac{1}{\delta} \right)$$

Empirical Average

then,

$$\Pr\left(\exists A \in \mathcal{R} : \left| \pi(A) - \frac{1}{|S|} \sum_{s \in S} 1_A(s) \right| > \varepsilon \right) < \delta$$



Sample Theorem

- •Let \mathcal{R} have $VC(\mathcal{R}) \leq d$
- •Let π be a probability distribution on B
- •Let $\pi(A)$ be the probability π
- •Given $\varepsilon, \delta \in [0,1]$, let S be then neither does $|\mathbf{S}|$!!!
- samples from π
- •If

$$|S| \ge \frac{1}{\varepsilon^2} \left(\frac{d + \ln \frac{1}{\delta}}{\delta} \right)$$

Empirical Average

then,

$$\Pr\left(\exists A \in \mathcal{R} : \left| \pi(A) - \frac{1}{|S|} \sum_{s \in S} 1_A(s) \right| > \varepsilon \right) < \delta$$



Roadmap

- •We are going to build a range set for the problem and show an upper bound to its VC-dimension
- •We define a probability distribution and use it to sample elements of the domain
- •The sample theorem gives us the amount of samples we need to draw to obtain a good approximation of the betweenness of all vertices



Shortest Path Range Set

- •Range set \mathcal{R}_G associated to shortest paths
- •Domain: \mathbb{S}_G , all shortest paths in G
- $\mathcal{R}_G = \{\mathcal{T}_v, v \in V\}$
- •Contains one range per vertex



Shortest Path Range Set

- •Range set \mathcal{R}_G associated to shortest paths
- •Domain: \mathbb{S}_G , all shortest paths in G is internal to
- $\mathcal{R}_G = \{\mathcal{T}_v, v \in V\}$
- Contains one range per vertex



Shortest Path Range Set

- •Range set \mathcal{R}_G associated to shortest paths
- •Domain: \mathbb{S}_G , all sho<u>rtest paths</u> in GAll shortest paths v is internal to • $\mathcal{R}_G = \{\mathcal{T}_v, v \in V\}$
- Contains one range per vertex
- •Sampling probability distribution on \mathbb{S}_G

$$\pi_G(p_{uv}) = \frac{1}{n(n-1)} \frac{1}{\sigma_{uv}}$$

•The algorithm samples paths according to π_G



•Theorem: $VC(\mathcal{R}_G) \leq \lfloor \log_2 VD(G) - 2 \rfloor + 1$



•Theorem: $VC(\mathcal{R}_G) \leq \lfloor \log_2 VD(G) - 2 \rfloor + 1$

•Proof:



•Theorem: $VC(\mathcal{R}_G) \leq \lfloor \log_2 VD(G) - 2 \rfloor + 1$

•Proof: To shatter a set A of paths, |A| = d, we need 2^d different ranges $\mathcal{T}_v \in \mathcal{R}_G$



- •Theorem: $VC(\mathcal{R}_G) \leq \lfloor \log_2 VD(G) 2 \rfloor + 1$
- •Proof: To shatter a set A of paths, |A| = d, we need 2^d different ranges $\mathcal{T}_v \in \mathcal{R}_G$
 - •Any $p \in A$ must appear in 2^{d-1} different ranges



- •Theorem: $VC(\mathcal{R}_G) \leq \lfloor \log_2 VD(G) 2 \rfloor + 1$
- •Proof: To shatter a set A of paths, |A|=d, we need 2^d different ranges $\mathcal{T}_v \in \mathcal{R}_G$
 - •Any $p \in A$ must appear in 2^{d-1} different ranges
 - p appears only in the \mathcal{T}_v 's of the $v \in \operatorname{Int}(p)$



- •Theorem: $VC(\mathcal{R}_G) \leq \lfloor \log_2 VD(G) 2 \rfloor + 1$
- •Proof: To shatter a set A of paths, |A| = d, we need 2^d different ranges $\mathcal{T}_v \in \mathcal{R}_G$
 - •Any $p \in A$ must appear in 2^{d-1} different ranges
 - p appears only in the \mathcal{T}_v 's of the $v \in \operatorname{Int}(p)$
 - p appears in $|\operatorname{Int}(p)| \leq \operatorname{VD}(G) 2$ ranges \mathcal{T}_v



- •Theorem: $VC(\mathcal{R}_G) \leq \lfloor \log_2 VD(G) 2 \rfloor + 1$
- •Proof: To shatter a set A of paths, |A| = d, we need 2^d different ranges $\mathcal{T}_v \in \mathcal{R}_G$
 - •Any $p \in A$ must appear in 2^{d-1} different ranges
 - p appears only in the \mathcal{T}_v 's of the $v \in \operatorname{Int}(p)$
 - p appears in $|Int(p)| \leq VD(G) 2$ ranges \mathcal{T}_v
 - •For A to be shattered, must be $2^{d-1} \leq VD(G) 2$
 - Implies the thesis



Back to the algorithm

•Recall the algorithm:

```
For r times do Sample a random pair of vertices (u,v)
```

Compute \mathcal{S}_{uv} , all shortest paths from u to v

Select a path p uniformly at random from \mathcal{S}_{uv}

For each $w \in Int(p)$

$$\tilde{\mathbf{b}}(w) \leftarrow \tilde{\mathbf{b}}(w) + 1/r$$



Back to the algorithm

•Recall the algorithm:

```
For r times do Sample a random pair of vertices (u,v)
```

Compute S_{uv} , all shortest paths from u to v

Select a path p uniformly at random from \mathcal{S}_{uv}

For each $w \in Int(p)$

$$\tilde{\mathbf{b}}(w) \leftarrow \tilde{\mathbf{b}}(w) + 1/r$$

Sampling from $\boldsymbol{\pi}$

 $\tilde{\mathsf{b}}(w) \leftarrow \tilde{\mathsf{b}}(w) + 1/r$



Back to the algorithm

•Recall the algorithm:

```
For r times do Sample a random pair of vertices (u,v)
```

Compute S_{uv} , all shortest paths from u to v

Select a path p uniformly at random from S_{uv}

For each $w \in Int(p)$

$$\tilde{\mathbf{b}}(w) \leftarrow \tilde{\mathbf{b}}(w) + 1/r$$

Sampling from π

Empirical Average



Correctness

•From the sample theorem we get that if

$$r \ge \frac{1}{\varepsilon^2} \left(\lfloor \log_2(\mathsf{VD}(G) - 2) \rfloor + 1 + \ln \frac{1}{\delta} \right)$$

then the returned collection of $\tilde{b}(v)$ is an (ε, δ) -approximation:

$$\Pr\left(\exists v \in V : |\tilde{\mathsf{b}}(v) - \mathsf{b}(v)| > \varepsilon\right) < \delta$$



•From the sample theorem we get that if

$$r \ge \frac{1}{\varepsilon^2} \left(\lfloor \log_2(\mathsf{VD}(G) - 2) \rfloor + 1 + \ln \frac{1}{\delta} \right)$$

 $\Pr\left(\exists v \in V : | \tilde{\mathbf{b}}(v) \right)$ Definitively smaller than n

then the returned collection in real world social networks, (ε,δ) -approximation: the diameter is usually very small (small world phenomenon)



Corollaries

•If there is a unique shortest path for each pair of vertices then $VC(\mathcal{R}_G) \leq 3$



Corollaries

- •If there is a unique shortest path for each pair of vertices then $VC(\mathcal{R}_G) \leq 3$
 - •This "collapse" of the VC-dimension to a constant is somewhat surprising
 - •Suggests that there may be other characteristic quantities of the graph that control the VC-Dimension



Corollaries

- •If there is a unique shortest path for each pair of vertices then $VC(\mathcal{R}_G) \leq 3$
 - •This "collapse" of the VC-dimension to a constant is somewhat surprising
 - •Suggests that there may be other characteristic quantities of the graph that control the VC-Dimension
- •k-betweenness: if we only consider shortest paths of size up to k, then

$$VC(\mathcal{R}_G) \le |\log_2 k - 1| + 1$$



Diameter Approximation

- •Computing VD(G) exactly would require APSP
 - Defeat the purpose of sampling



Diameter Approximation

- •Computing VD(G) exactly would require APSP
 - Defeat the purpose of sampling
- •We need an approximation of VD(G)
- •Can be constant approx, we use log anyway!



Diameter Approximation

- •Computing $\mathsf{VD}(G)$ exactly would require APSP
 - Defeat the purpose of sampling
- •We need an approximation of VD(G)
- ·Can be constant approx, we use log anyway!
- •Undirected && unweighted:2-approx using BFS
- •All other cases: ???
 - •Return the size of the largest WCC (<= n)</p>



- Often interest is top-K players in the network, and in their ranking
- •Let $b^{(K)}$ be the K^{th} highest betweenness (ties broken arbitrarily)

•Goal:

find the set T(K,G):

$$T(K,G) = \{ v \in V : b(v) \ge b^{(K)} \}$$



•Often interest is top-K players in the network, and in their ranking

•Let $b^{(K)}$ be the K^{th} highest betweenness (ties

broken arbitrarily)

•Goal:

find the set T(K,G):

$$T(K,G) = \{ v \in V : b(v) \ge b^{(K)} \}$$

Similar to definition of top-K Frequent Itemsets



•"Two phases" sampling algorithm for highquality approximation of the betweenness of the top-K vertices



- •"Two phases" sampling algorithm for highquality approximation of the betweenness of the top-K vertices
 - •1st phase: compute lower bound to $\mathbf{b}^{(K)}$ sing "standard" sample theorem
 - •2nd phase: Use relative variant of the sample theorem to compute superset of T(K,G)



- •"Two phases" sampling algorithm for highquality approximation of the betweenness of the top-K vertices
 - **•1**st phase: compute lower bound to $\mathbf{b}^{(K)}$ sing "standard" sample theorem
 - •2nd phase: Use relative variant of the sample theorem to compute superset of T(K,G)
- •For all vertices v in output we have

$$(1 - \varepsilon)b(v) \le \tilde{b}(v) \le (1 + \varepsilon)b(v)$$

with probability at least $1-\delta$



- "Two phases" sampling algorithm for high-quality approximation of the betweenness of the top-K vertices
 - $oldsymbol{\cdot 1^{st}}$ phase: compute lower bound to $\mathbf{b}^{(K)}$ sing "standard" sample theorem
 - •2nd phase: Use relative va (rather than addictive) sample theorem to compute $\sup \mathcal{E}$ of T(K,G)
- For all vertices v in output v have $(1-\varepsilon)\mathbf{b}(v) \leq \tilde{\mathbf{b}}(v) \leq (1+\varepsilon)\mathbf{b}(v)$

$$(1 - \varepsilon)\mathsf{b}(v) \le \tilde{\mathsf{b}}(v) \le (1 + \varepsilon)\mathsf{b}(v)$$

with probability at least $1-\delta$



·We proved the upper bound

$$VC(\mathcal{R}_G) \le \lfloor \log_2(VD(G) - 2) \rfloor + 1$$

•Is it tight?

•We proved the upper bound

$$VC(\mathcal{R}_G) \le \lfloor \log_2(VD(G) - 2) \rfloor + 1$$

- •Is it tight?
- ·YES!
- ·There are graphs with

$$VC(\mathcal{R}_G) = \lfloor \log_2(VD(G) - 2) \rfloor + 1$$

·We proved the upper bound

$$VC(\mathcal{R}_G) \le \lfloor \log_2(VD(G) - 2) \rfloor + 1$$

- •Is it tight?
- ·YES!
- ·There are graphs with

$$VC(\mathcal{R}_G) = \lfloor \log_2(VD(G) - 2) \rfloor + 1$$

•Example:

·We proved the upper bound

$$VC(\mathcal{R}_G) \le \lfloor \log_2(VD(G) - 2) \rfloor + 1$$

- •Is it tight?
- ·YES!
- ·There are graphs with

$$VC(\mathcal{R}_G) = \lfloor \log_2(VD(G) - 2) \rfloor + 1$$

- •Example:
 - VD(G) = 9

·We proved the upper bound

$$VC(\mathcal{R}_G) \le \lfloor \log_2(VD(G) - 2) \rfloor + 1$$

- •Is it tight?
- ·YES!
- ·There are graphs with

$$VC(\mathcal{R}_G) = \lfloor \log_2(VD(G) - 2) \rfloor + 1$$

- •Example:
 - VD(G) = 9
 - $VC(\mathcal{R}_G) = 3$



Outline

- •Motivation
- Definition and settings
- Exact and simple sampling algorithms
- Our result: a fast sampling algorithm
- Better approximation for the top-K vertices
- •Experiments
- •Conclusions



Experimental Evaluation

•Goals:

- •Evaluate accuracy of our algorithms
- Compare running time, accuracy, and locality with exact and simple sampling algorithms



Experimental Evaluation

•Goals:

- •Evaluate accuracy of our algorithms
- Compare running time, accuracy, and locality with exact and simple sampling algorithms
- •Implementation:
 - c extension of igraph (igraph.sf.net)
 - •Exposed through Python3 API
 - •Available from GitHub (not yet)



Experimental Evaluation

•Goals:

- •Evaluate accuracy of our algorithms
- Compare running time, accuracy, and locality with exact and simple sampling algorithms

•Implementation:

- c extension of igraph (igraph.sf.net)
- •Exposed through Python3 API
- •Available from GitHub (not yet)

•Datasets:

•Real networks (social, road, citation, ...) from SNAP (snap.stanford.edu)



Accuracy Results

- •Always within ε from real value
- Accuracy even better than guaranteed



Speedup Results

•Almost 1 order of magnitude faster than simple sampling algorithm



Scalability Results

•Scales much better than simple sampling algorithm



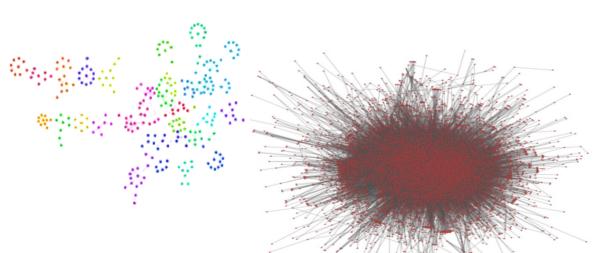
Conclusions

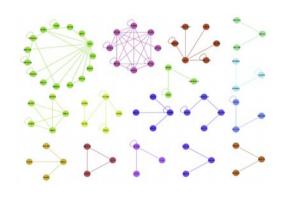
- •We presented two sampling-based randomized algorithms to approximate the betweenness of (top-K) vertices in huge graphs
- •The algorithms offer probabilistic guarantees on the accuracy of the approximations, using much fewer samples and performing fewer computations than previous available algorithms
- •Experimental evaluation shows that the algorithm outperforms previous works in terms of execution time and accuracy



The End

- •Questions or comments?
- •matteo@cs.brown.edu
- •http://bigdata.cs.brown.edu
- •http://database.cs.brown.edu









Bibliography

- •[Brandes01] *A faster algorithm for betweenness centrality*, J. Math. Sociol., 2001
- •[BrandesPich07] *Centrality estimation in large networks*, Intl. J. Bifurc. Chaos, 2007
- •[EppsteinWang01] Fast approximation of centrality, J. Graph Alg. and App., 2001
- •[VapnikChervonenkis71] On the uniform convergence of relative frequencies of events to their probabilities, Th. Prob. and its Appl., 1971