

# Math Refresher: Basic Calculus

## Introduction

This is a refresher on basic calculus. It is not meant to be a substitute for a full course on calculus, but rather a quick review of the basic concepts and techniques that will be used in this semester.

## Limits

The limit of a function  $f(x)$  as  $x$  approaches  $a$  is the value that  $f(x)$  approaches as  $x$  gets closer and closer to  $a$ . We write this as:

$$\lim_{x \rightarrow a} f(x) = L$$

In this case, the limit of the function  $f(x)$  as  $x$  approaches  $a$  is  $L$ . For example, consider the function  $f(x) = x^2$ . The limit of  $f(x)$  as  $x$  approaches 2 is 4:

## Limits to Derivatives

Limits can also be used to estimate derivatives. The derivative of a function  $f(x)$  is the slope of the function at a given point. The derivative of  $f(x)$  at  $x = a$  is written as  $f'(a)$ . The derivative of  $f(x)$  is defined as:

$$f'(a) = \lim_{h \rightarrow 0} \frac{f(a+h) - f(a)}{h}$$

In other words, the derivative is the slope of a function at a particular point  $a$ . This can be proxied using derivatives, by choosing a very small value for  $h$ .

For example, consider the function  $f(x) = x^2$ . The derivative of  $f(x)$  at  $x = a$  is:

$$\begin{aligned}
f'(a) &= \lim_{h \rightarrow 0} \frac{f(a+h) - f(a)}{h} \\
&= \lim_{h \rightarrow 0} \frac{(a+h)^2 - (a)^2}{h} \\
&= \lim_{h \rightarrow 0} \frac{a^2 + 2ah + h^2 - a^2}{h} \\
&= \lim_{h \rightarrow 0} 2a + h = 2a
\end{aligned}$$

If anything else fails, one can always rely on numerical differentiation.

## Derivative of common functions

For most common functions, the derivative can be calculated using the following rules:

- The derivative of a constant is zero
- The derivative of  $x^n$  is  $nx^{n-1}$
- The derivative of  $\ln(x)$  is  $\frac{1}{x}$
- The derivative of  $e^x$  is  $e^x$
- The derivative of  $a^x$  is  $a^x \ln a$

There are other rules for derivatives, but these are the ones that will be used most often.

## Derivative of composite functions

The derivative of a composite function  $f(g(x))$  is given by the chain rule:

$$\frac{d}{dx}f(g(x)) = f'(g(x))g'(x)$$

For example, consider the function  $f(x) = \ln(x^2)$ . The derivative of  $f(x)$  is:

$$\begin{aligned}
\frac{d}{dx} \ln(x^2) &= \frac{1}{x^2} \frac{d}{dx} x^2 \\
&= \frac{1}{x^2} 2x \\
&= \frac{2}{x}
\end{aligned}$$

## Derivative of sums and products

The derivative of a sum of functions is the sum of the derivatives of the functions.

$$\frac{d}{dx}(f(x) + g(x)) = \frac{d}{dx}f(x) + \frac{d}{dx}g(x)$$

The derivative of a product of functions is given by the product rule:

$$\frac{d}{dx}(f(x)g(x)) = f'(x)g(x) + f(x)g'(x)$$

The derivative of a quotient of functions is given by the quotient rule:

$$\frac{d}{dx} \frac{f(x)}{g(x)} = \frac{f'(x)g(x) - f(x)g'(x)}{g(x)^2}$$

Which is a special case of the product rule.

## Maximization and Minimization

Derivatives can be used to identify the maximum and minimum values of a function. Consider a function  $f(x)$ .

To find the maximum (or minimum) value of  $f(x)$ , we can take the derivative of  $f(x)$  and set it equal to zero. This is called the first order condition. The idea is that at the maximum (or minimum) value of  $f(x)$  shouldn't change anymore (should be flat). Thus the derivative of  $f(x)$  should be zero.

For example, consider the function  $f(x) = 5x^2 - 4x + 2$ . The derivative of  $f(x)$  is:

$$\begin{aligned} f'(x) &= 10x - 4 = 0 \\ x &= \frac{4}{10} = 0.4 \end{aligned}$$

So when  $x$  is equal to 0.4, the function  $f(x)$  does not change anymore. This, however, is insufficient to determine if the function is at a maximum or a minimum. To determine this, we can take the second derivative of  $f(x)$ , or second order condition:

$$f''(x) = 10 > 0$$

Because the second derivative is positive, we know that  $f(x)$  is at a minimum when  $x = 0.4$ . If the second derivative was negative, we would know that  $f(x)$  is at a maximum when  $x = 0.4$ .

why is this the case

- $f'(x)$  measures the changes in  $f(x)$  along  $x$ . when  $f'(x) = 0$ ,  $f(x)$  is not changing anymore.
- $f''(x)$  measures the changes in  $f'(x)$  (changes in those changes). Because its positive, we know that  $f'(x)$  is increasing. This means that at  $x = 0.4$  the changes if  $f(x)$  were going from negative to positive. Thus indicating a minimum.

## Optimization with multiple variables

When considering multiple variables, we also need to rely on the first and second order conditions to find minimum and maximum values. Consider a function  $f(x, y)$ . The first order conditions are:

$$\begin{aligned}\frac{\partial}{\partial x} f(x, y) &= 0 \\ \frac{\partial}{\partial y} f(x, y) &= 0\end{aligned}$$

This conditions now say that, in the direction of  $x$  and  $y$ , the function  $f(x, y)$  is not changing anymore. Thus we have a potential maximum or minimum. Now, to identify a minimum, we need second order conditions to be:

$$H = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{xy} & f_{yy} \end{bmatrix}$$

If  $\text{Det}(H) > 0$  and  $f_{xx} > 0$  then we have a minimum. If  $\text{Det}(H) > 0$  and  $f_{xx} < 0$  then we have a maximum. If  $\text{Det}(H) < 0$  then we have a saddle point. And if  $\text{Det}(H) = 0$  then we have an inconclusive result.

## Optimization with constraints

When optimizing a function with constraints, we can use the method of Lagrange multipliers. Consider a function  $f(x, y)$  subject to the constraint  $g(x, y) = z$ . The Lagrangian is:

$$L(x, y, \lambda) = f(x, y) + \lambda(z - g(x, y))$$

Notice that the Lagrangian is the function  $f(x, y)$  plus the constraint  $g(x, y)$  multiplied by a constant  $\lambda$ . The constant  $\lambda$  is called the Lagrange multiplier. The constrain is written as the difference between the constant  $z$  and the function  $g(x, y)$ . The Lagrangian is then optimized with respect to  $x$ ,  $y$ , and  $\lambda$ . This are the equivalent of the first order conditions:

$$\begin{aligned}\frac{\partial}{\partial x}L(x, y, \lambda) &= 0 \\ \frac{\partial}{\partial y}L(x, y, \lambda) &= 0 \\ \frac{\partial}{\partial \lambda}L(x, y, \lambda) &= z - g(x, y) = 0\end{aligned}$$

The last condition is the constraint, and it implies that the constraint must be satisfied. The second order conditions are the same as before.