

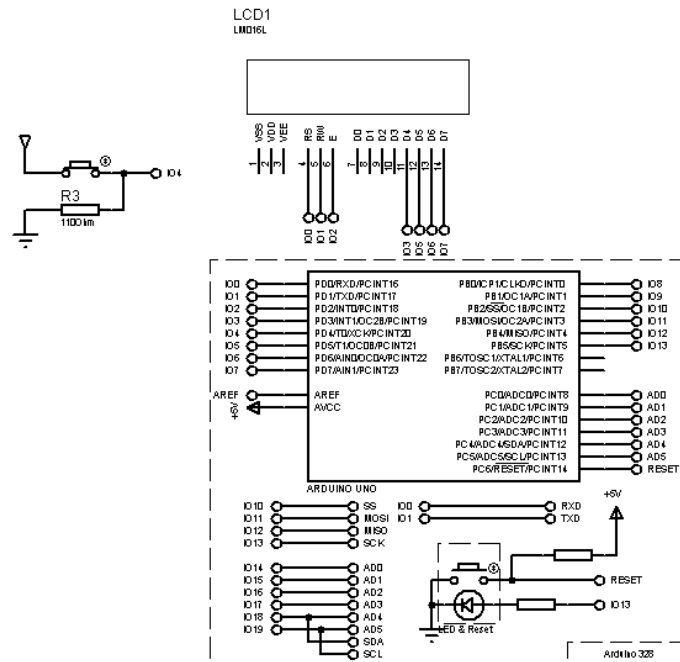
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NIM : 081711733002

Mata Kuliah : Embedded System

1. Timer CTC mode 0

a. Proteus



b. Code

```
/*  
 * pewaktuCTC.c  
 *  
 * Created: 5/5/2020 11:00:55 PM  
 * Author: Thoriqul Aziz  
 */
```

```
#include <io.h>  
#include <alcd.h>  
#include <stdlib.h>
```

```
unsigned char lup=0;  
unsigned char temp[6];  
int waktu;
```

```

interrupt [TIM0_OVF] void_timer0_ovf_isr(void)
{
    TCNT0=0x69;
    lup++;
    if (lup>=100) {
        waktu++;
        lup=0;
    };
}
void main(void)
{
    TCCR0A=0x00;
    TCCR0B=0x05;
    TCNT0=0x4F;
    OCR0A=0x4E;
    OCR0B=0x00;
    // OCR0A=0xF9;
    TIMSK0=0x01;
    //TIFR0=0x01;
    #asm("sei")

    lcd_init(16);
    while (1)
    {

        if(waktu==60)
        {
            lcd_clear();
            waktu=0;
        };

        lcd_gotoxy(0,0);
        lcd_putsf("Waktu : ");
        itoa(waktu,temp);
        lcd_gotoxy(0,1);
        lcd_puts(temp);
    }
}

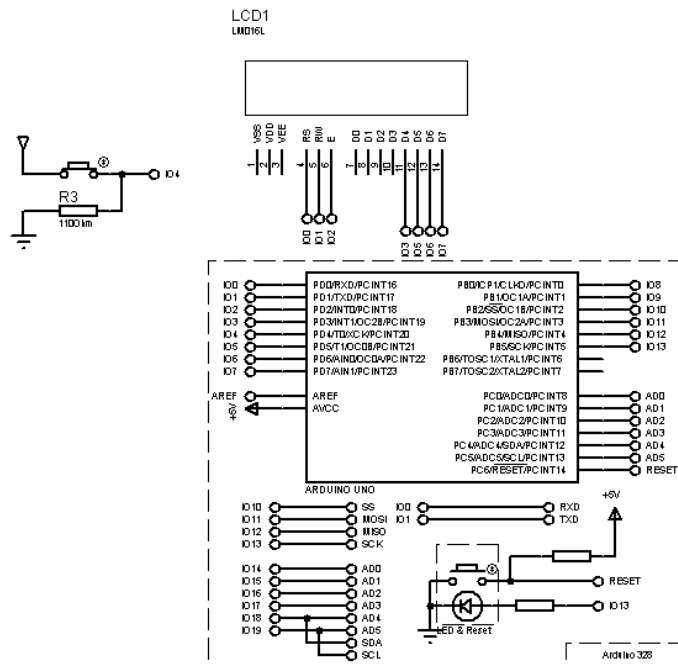
```

c. Status

FAILED

2. Timer Normal mode 1

a. Proteus



b. Code

```
/*
 * PewaktuTimer1.c
 *
 * Created: 5/6/2020 2:28:26 AM
 * Author: Thoriqul Aziz
 */
```

```
#include <io.h>
#include <alcd.h>
#include <stdlib.h>
```

```
unsigned char temp[6];
int waktu;
interrupt [TIM1_OVF] void timer1_ovf_isr(void) {
    TCNT1H=0xC2F7 >> 8;
    TCNT1L=0xC2F7 & 0xff;
    waktu++;
}
```

```

}

void main(void)
{
    TCCR1A=0x00;
    TCCR1B=0x05;
    TCNT1H=0xC2;
    TCNT1L=0xF7;
    ICR1H=0x00;
    ICR1L=0x00;
    OCR1AH=0x00;
    OCR1AL=0x00;
    OCR1BH=0x00;
    OCR1BL=0x00;

    TIMSK1=0x01;
    lcd_init(16);
    #asm("sei")
    while (1)
    {
        if(waktu==100)
        {
            lcd_clear();
            waktu=0;
        };

        lcd_gotoxy(0,0);
        lcd_putsf("Waktu : ");
        itoa(waktu,temp);
        lcd_gotoxy(0,1);
        lcd_puts(temp);
    }
}

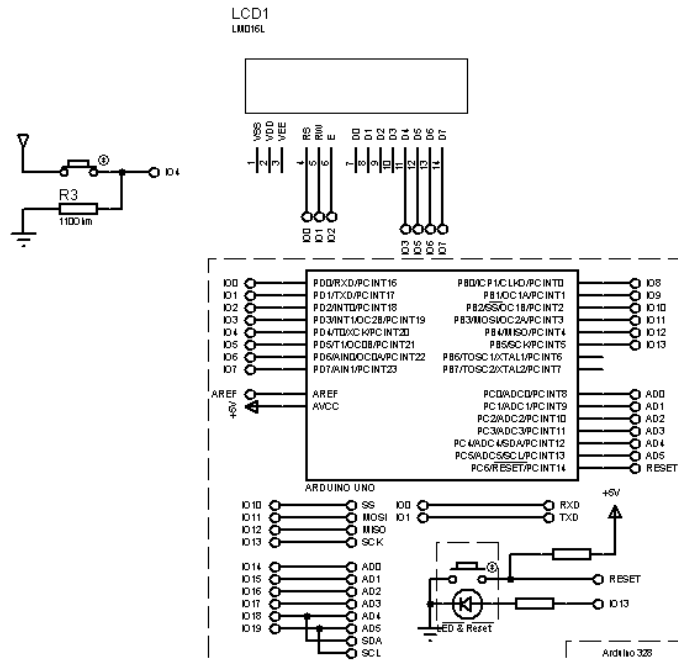
```

c. Status

WORK!!

3. Counter normal mode 0

a. Proteus



b. Code

```

/*
 * lagi.c
 *
 * Created: 5/7/2020 11:41:44 AM
 * Author: Thoriqul Aziz
 */

#include <io.h>
#include <alcd.h>
#include <stdlib.h>

int data;
unsigned char temp[6];
interrupt [TIMO_OVF] void timer0_int0_isr(void)
{
    data = TCNT0;
}

void main(void)
{

```

```
PORTD=0x10;
DDRD=0x10;
TCCR0A=0x00;
TCCR0B=0x07;
TCNT0=0x00;
OCR0A=0x00;
TIMSK0=0x01;
asm("sei")
lcd_init(16);
while (1)
{
    if (data>=256) {
        lcd_clear();
    }
    lcd_gotoxy(0,0);
    lcd_putsf("timer");
    itoa(data,temp); //menampilkan di
    lcd_gotoxy(0,1);
    lcd_puts(temp);
}
```

c. Status

FAILED