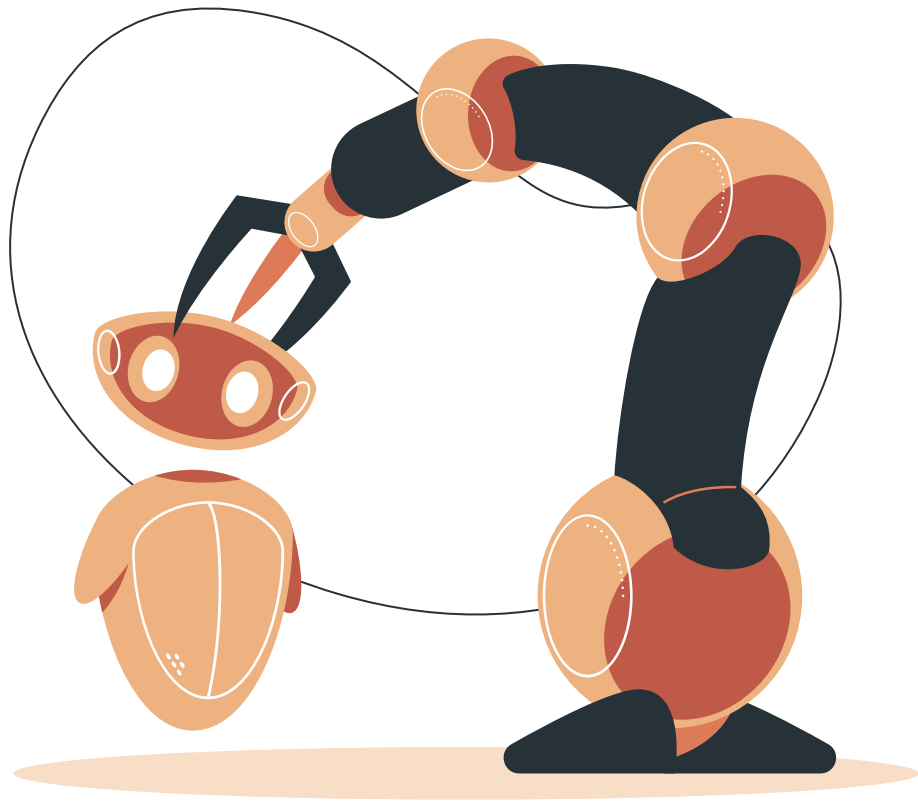


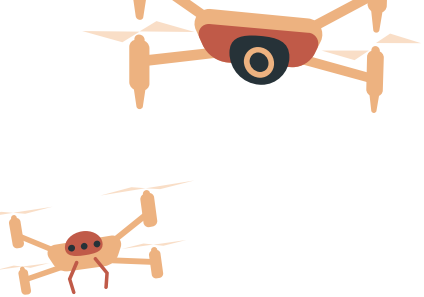
Laboratorio

02

Robótica Móvil [IIC2685]

- Alonso Rivera
- Mateo de la Cuadra
- Gustavo Blanco



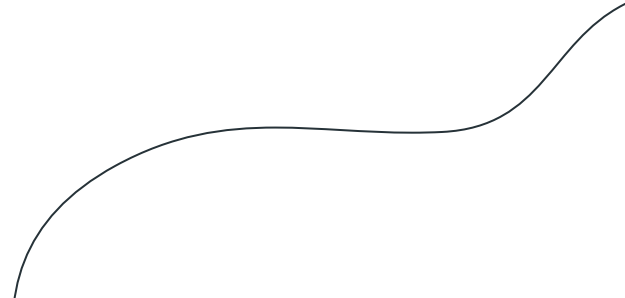


Lineal

$K_p = 8$

Angular

$K_p = 5.5$





Lineal

$K_p = 1.6$

$K_i = 0.8$

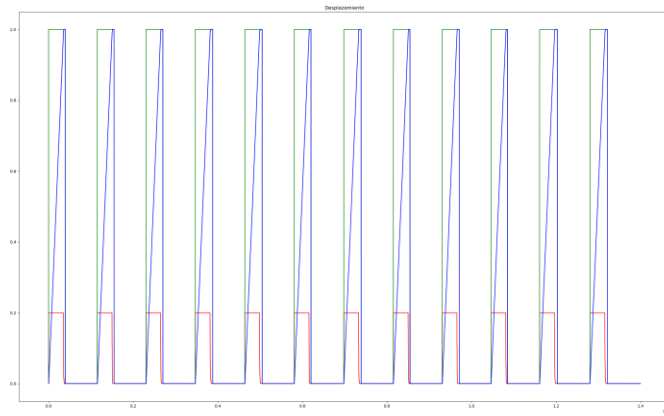
Angular

$K_p = 2$

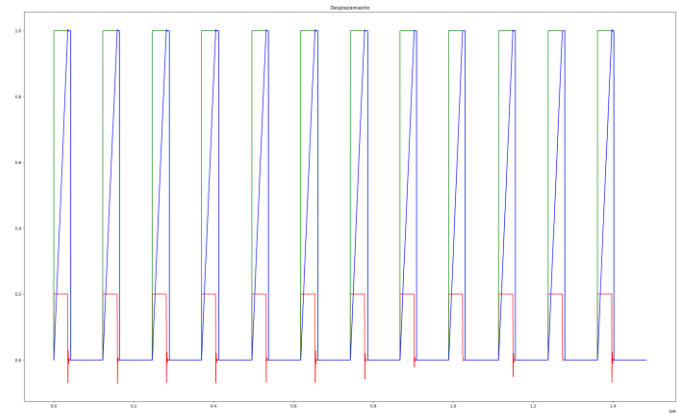
$K_i = 0.1$

Señales

Respuesta lineal



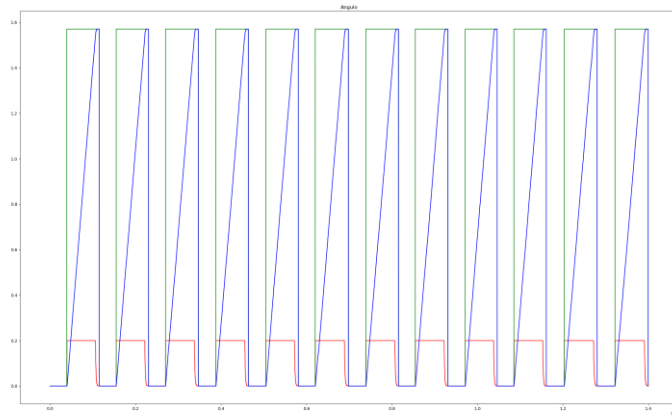
Control P



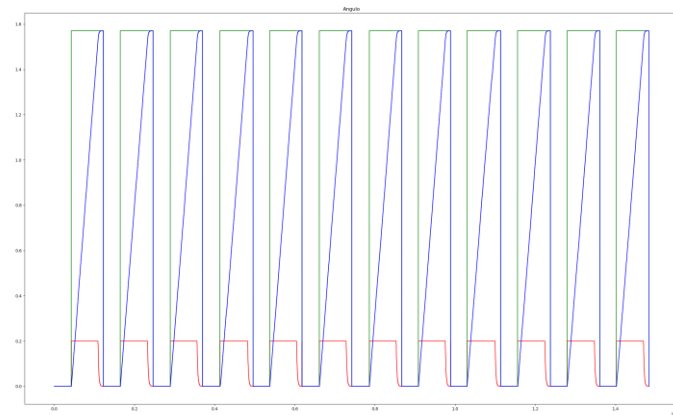
Control PI

Señales

Respuesta angular



Control P



Control PI



Gracias

Trayectoria

A thick orange horizontal bar with rounded ends is positioned below the title. In the top right corner, a thin black curved line arcs from the edge of the frame towards the center.

Sin Control

Control P

Control PI