Learning Similarities for Linear Classification: Theoretical Foundations and Algorithms

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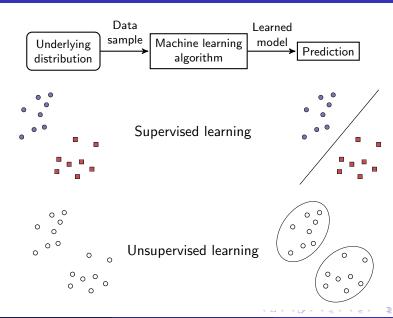




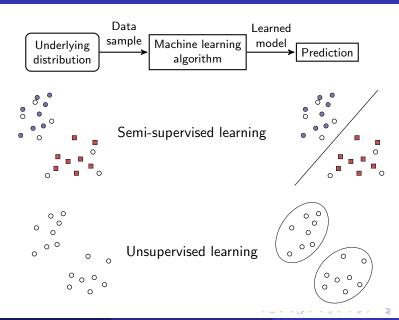


Scientific Context

Machine Learning



Machine Learning



Metric Learning

Performance depends on metrics

Most machine learning algorithms compare examples using a metric.



Adapting the metric to the problem

Learn a custom metric which better discriminates the examples.



Typically, it boils down to learning a new representation space.

Representation Learning

Importance

Representation learning is often key in machine learning algorithms.

Subfields of representation learning

- Kernel learning;
- Multiple kernel learning;
- Dictionary learning;
- Deep learning;
- Metric learning.

Differences come from:

- Orthogonality of the features;
- Implicit vs. explicit representation;
- Sparse vs. infinite representation space;
- Parametric vs. non parametric.

Background and Preliminaries

Supervised Learning

Binary Classification

Input

A **sample** of *n* labeled examples $S = \{z_i = (\mathbf{x}_i, y_i)\}_{i=1}^n$ independent and identically distributed (i.i.d.) according to an unknown distribution P.

Output

A model $h \in H$ that **best predicts** the labels of unseen examples.

Definition (True risk)

The expected loss suffered by h on the distribution P:

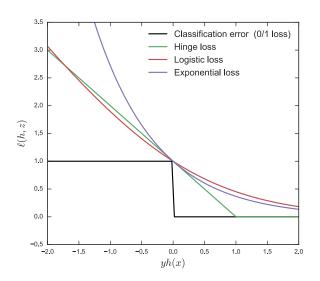
$$R_P^{\ell}(h) = \mathbb{E}_{z \sim P}[\ell(h, z)].$$

Definition (Empirical risk)

The average loss incurred by h on the sample \mathcal{S} : $R_{\mathcal{S}}^{\ell}(h) = \frac{1}{n} \sum_{i=1}^{n} \ell(h, z_i)$.

Supervised Learning

Loss Functions for Binary Classification



Supervised Learning

Generalization guarantees

Minimize an objective function of the form:

$$h_{\mathcal{S}} = \underset{h \in H}{\operatorname{arg min}} R_{\mathcal{S}}^{\ell}(h) + \lambda ||h||.$$

PAC bounds

Bound the deviation of the empirical risk from the true risk of a hypothesis h, i.e. its **capacity to generalize** to an unseen sample:

$$|R_P^{\ell}(h) - R_S^{\ell}(h)| \leq \mathcal{O}(complexity(h)/\sqrt{n}).$$

Theoretical frameworks

- Uniform convergence using VC dimension [VC71], Rademacher complexity [BM03] and other similar,
- Uniform stability [BE02],
- Algorithmic robustness [XM12].

Metric Learning



Mahalanobis distance learning

Find the positive semi-definite (PSD) matrix $\mathbf{M} \in \mathbb{R}^{d \times d}$ parameterizing a Mahalanobis distance $d^2_{\mathbf{M}}$ to best satisfy some constraints:

$$d_{\mathbf{M}}(\mathbf{x}, \mathbf{x}') = \sqrt{(\mathbf{x} - \mathbf{x}')^T \mathbf{M}(\mathbf{x} - \mathbf{x}')}.$$

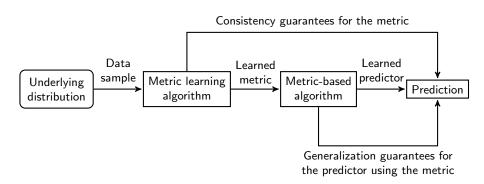
Similarity judgments (constraints)

- Pair-based: x and x' are (dis)similar;
- Triplet-based: x is more similar to x' than to x''.

Existing methods differ in the choice of the **metric**, the **constraints**, the **loss function** and the **regularizer**.

Generalization Guarantees in Metric Learning

The question of the generalization capacity can be asked at two levels: the **metric** and the **predictor** using it.



Only a few methods provide generalization guarantees for:

- the **learned metric** d_{M} itself [JWZ09, BT11, CGY12];
- the **performance** of the algorithm using it [BBS08].

 (ϵ, γ, τ) -Good Framework

(ϵ, γ, τ) -Good Similarity Functions

Some of the first results on how the properties of the **similarity function** influence its performance in **linear classification**.

Definition

[BBS08] $K \in [-1,1]$ is an (ϵ, γ, τ) -good similarity function in hinge loss for a learning problem P if there exists a random indicator function $R(\mathbf{x})$ defining a probabilistic set of landmarks such that the following conditions hold:

We have

$$\mathbb{E}_{(\mathbf{x},y)\sim P}\left[\left[1-yg(\mathbf{x})/\gamma\right]_{+}\right]\leq \epsilon,$$

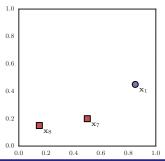
where $g(\mathbf{x}) = \mathbb{E}_{(\mathbf{x}', \mathbf{y}'), R(\mathbf{x}')} [\mathbf{y}' K(\mathbf{x}, \mathbf{x}') | R(\mathbf{x}')].$

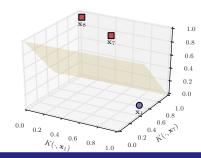
$$\epsilon, \gamma, \tau \in [0, 1]$$

[BBS08] Maria-Florina Balcan, Avrim Blum, and Nathan Srebro. Improved Guarantees for Learning via Similarity Functions. In *COLT*, 2008.

2 $\Pr_{\mathbf{x}'}(R(\mathbf{x}')) > \tau$.

Learning with (ϵ, γ, τ) -Good Similarity Functions





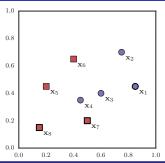
Theorem

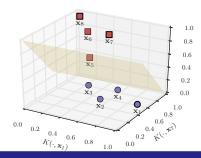
[BBS08] Given K is (ϵ, γ, τ) -good, there exists a linear separator α in the projection space that has error close to ϵ at margin γ .

Linear program (BBS)

$$\min_{\alpha} \left\{ \sum_{i=1}^{m} \left[1 - \sum_{j=1}^{n} \alpha_{j} y_{i} K(\mathbf{x}_{i}, \mathbf{x}_{j}) \right]_{+} : \sum_{j=1}^{n} |\alpha_{j}| \leq 1/\gamma \right\}$$

Learning with (ϵ, γ, τ) -Good Similarity Functions





Theorem

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Summary

Advantages

- Theoretical guarantees on α ;
- Semi-supervised framework.

Limitations

- Standard similarity functions might poorly satisfy the definition;
- No given method to find the suited similarity function.

Solution

- Learn the similarity function from a data sample;
- Directly optimize its empirical goodness;
- This implies guarantees for the linear classifier.

Contributions of the Thesis

- Optimize similarity functions instead of distances:
 - Less costly;
 - Gives access to a larger class of functions.
- Optimize the goodness of the similarities → generalization guarantees for the algorithm using the similarity.
- Derive consistency guarantees for the learned similarity.

More precisely

- Joint similarity and classifier learning for feature vectors.
- Similarity learning for multivariate time series classification.

Previous results using the (ϵ, γ, τ) -good framework

- String edit distance learning [BHS11];
- Learning a bilinear similarity for feature vectors [BHS12].

Joint Similarity and Classifier Learning for Feature Vectors

Optimizing the (ϵ, γ, τ) -Goodness in Metric Learning

(ϵ, γ, au) -Goodness Criterion

$$\mathbb{E}_{(\mathbf{x},y)\sim P}\left[\left[1-y\mathbb{E}_{(\mathbf{x}',y'),R(\mathbf{x}')}\left[yy'K_{\mathbf{M}}(\mathbf{x},\mathbf{x}'))|R(\mathbf{x}')\right]/\gamma\right]_{+}\right]\leq \epsilon.$$

To be satisfied on average.

Linear program (BBS)

$$\min_{\alpha} \left\{ \sum_{i=1}^{m} \left[1 - \sum_{j=1}^{n} \alpha_{j} y_{i} K(\mathbf{x}_{i}, \mathbf{x}_{j}) \right]_{+} : \sum_{j=1}^{n} |\alpha_{j}| \leq 1/\gamma \right\}$$

Landmarks labels are not used.

Problem Formulation

Joint Similarity Learning (JSL)

$$\min_{\boldsymbol{\alpha}, \mathbf{M}} \quad \sum_{i=1}^{m} \left[1 - \sum_{j=1}^{n} \alpha_{j} y_{i} K_{\mathbf{M}}(\mathbf{x}_{i}, \mathbf{x}_{j}) \right]_{+} + \lambda ||\mathbf{M} - \mathbf{R}||$$
s.t.
$$\sum_{j=1}^{n} |\alpha_{j}| \leq 1/\gamma$$

Properties

- ullet Semi-supervised setting o can use a small quantity of labeled data;
- Averaged constraints;
- Generic form of similarity and regularization;
- Convex for a large range of similarities and regularizers;
- ullet Solved by alternating optimization steps over lpha and $oldsymbol{\mathsf{M}}.$

Choice of Similarity and Regularization

Similarity functions

- $\bullet \ K_{\mathbf{M}}^{1}(\mathbf{x},\mathbf{x}') = \mathbf{x}^{T}\mathbf{M}\mathbf{x}';$
- $K_{\mathbf{M}}^{2}(\mathbf{x}, \mathbf{x}') = 1 (\mathbf{x} \mathbf{x}')^{T} \mathbf{M} (\mathbf{x} \mathbf{x}')$.

Regularizer $||\mathbf{M} - \mathbf{R}||$

- L_1 or L_2 norm;
- Value of $\mathbf{R} \in \mathbb{R}^{d \times d}$:
 - Identity matrix;
 - Empirical estimate of Kullback-Leibler divergence.

Theoretical Analysis using Rademacher Complexity

Rademacher average over ${\mathcal F}$

$$\hat{\mathfrak{R}}_{\mathcal{S}}(\mathcal{F}) := \mathbb{E}_{\sigma} \left[\sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^{n} \sigma_{i} f(z_{i}) \right]$$

Rademacher complexity

$$\mathfrak{R}_n(\mathcal{F}) := \mathbb{E}_{\mathcal{S}} \hat{\mathfrak{R}}_{\mathcal{S}}(\mathcal{F}), \forall n$$

where

- ullet \mathcal{F} is a class of uniformly bounded functions;
- $\{\sigma_i : i \in \{1, ..., n\}\}$ are independent Rademacher random variables, $\Pr(\sigma_i = 1) = \Pr(\sigma_i = -1) = \frac{1}{2}$.



Bounding True Risk with Rademacher Complexity

Definition $((\beta, c)$ -admissibility)

A similarity function $K_{\mathbf{M}}: \mathcal{X} \times \mathcal{X} \to [-1,1]$ parameterized by $\mathbf{M} \in \mathbb{R}^{d \times d}$ is (β,c) -admissible if, for any matrix norm $||\cdot||$, there exist $\beta,c \in \mathbb{R}$ s.t. $\forall \mathbf{x},\mathbf{x}' \in \mathcal{X}, |K_{\mathbf{M}}(\mathbf{x},\mathbf{x}')| \leq \beta + c \cdot ||\mathbf{x}'\mathbf{x}^T|| \cdot ||\mathbf{M}||$.

Theorem (Generalization bound)

Let $(\mathbf{M}_{\mathcal{S}}, \alpha_{\mathcal{S}})$ be the solution to JSL and $K_{\mathbf{M}}$ a (β, c) -admissible similarity function. Then, for any $0 < \delta < 1$, with probability at least $1 - \delta$, the following holds:

true risk

$$(\beta, c)$$
-admissibility of K_{M} $X_* = \sup_{\mathsf{x}, \mathsf{x}' \in \mathcal{X}} ||\mathsf{x}'\mathsf{x}^{\mathsf{T}}||_*$

$$|R_{\mathcal{P}}^{\ell}(\mathbf{M}_{\mathcal{S}}, \alpha_{\mathcal{S}}) - R_{\mathcal{S}}^{\ell}(\mathbf{M}_{\mathcal{S}}, \alpha_{\mathcal{S}})| \leq 4\mathfrak{R}_{m}\left(\frac{cd}{\gamma}\right) + \left(\frac{\beta + cX_{*}d}{\gamma}\right)\sqrt{\frac{2\ln\frac{1}{\delta}}{m}}.$$

empirical risk

Rademacher complexity convergence in $\mathcal{O}\left(\frac{1}{\sqrt{m}}\right)$

Experimental Setup

Methods:

- Linear classifiers:
 - Linear SVM with L₂ regularization;
 - BBS [BBS08];
 - SLLC [BHS12];
 - JSL;

- 2 Nearest neighbor approaches:
 - 3NN euclidean distance;
 - ITML [DKJ⁺07];
 - LMNN and LMNN-diag [WS08, WS09];
 - LRML [HLC10], semi-supervised setting.

Settings:

- Small quantities of labeled data: 5, 10, 20 examples per class;
- 15 unlabeled examples, or the whole training set.

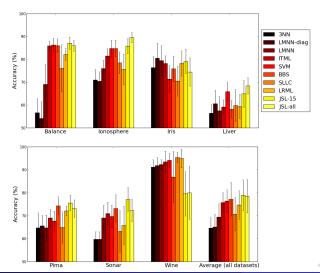
Datasets:

	Balance	Ionosphere	Iris	Liver	Pima	Sonar	Wine
# Instances	625	351	150	345	768	208	178
# Dimensions	4	34	4	6	8	60	13
# Classes	3	2	3	2	□ →2 ∢ 🗇	→ 42 →	4 ≣ 3 ■

Experimental Results

Accuracy Comparison

5 labeled points per class



Experimental Results

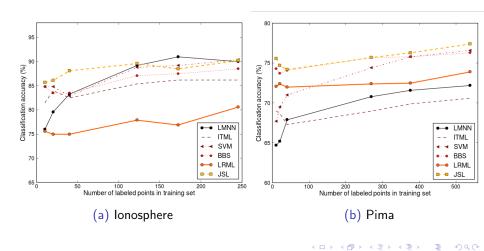
Overall Accuracy Comparison

Method	5 pts./cl.	10 pts./cl.	20 pts./cl.
3NN	64.6±4.6	68.5±5.4	70.4±5.0
LMNN-diag	65.1±5.5	68.2 ± 5.6	71.5 ± 5.2
LMNN	69.4±5.9	70.9 ± 5.3	73.2 ± 5.2
ITML	75.8±4.2	$76.5 {\pm} 4.5$	76.3 ± 4.8
SVM	76.4±4.9	76.2 ± 7.0	77.7 ± 6.4
BBS	77.2±7.3	77.0 ± 6.2	77.3 ± 6.3
SLLC	70.5±7.2	75.9 ± 4.5	75.8 ± 4.8
LRML	74.7±6.2	75.3 ± 5.9	75.8 ± 5.2
JSL-15	78.9 ±6.7	77.6 ±5.5	77.7 ± 6.4
JSL-all	78.2±7.3	76.6 ± 5.8	78.4 \pm 6.7

Experimental Results

Impact of the Amount of Labeled Data

15 unlabeled landmarks



Summary of JSL

- New semi-supervised metric learning framework;
- Joint learning of a metric and a global separator;
- General similarity function and regularizer;
- Theoretical guarantees using Rademacher complexity and algorithmic robustness.

Publications

- M.-I. Nicolae, É. Gaussier, A. Habrard, and M. Sebban. Joint semi-supervised similarity learning for linear classification. In ECML/PKDD, 2015a.
- M.-I. Nicolae, M. Sebban, A. Habrard, É. Gaussier, and M.-R. Amini. Algorithmic Robustness for Semi-Supervised (ϵ, γ, τ) -Good Metric Learning. In *ICONIP*, pages 253–263, 2015b.
- M.-I. Nicolae, M. Sebban, A. Habrard, É. Gaussier, and M.-R. Amini. Algorithmic Robustness for Learning via (ϵ, γ, τ) -Good Similarity Functions. In *ICLR Workshop*, 2015.

Learning Similarities for Time Series Classification

Motivation

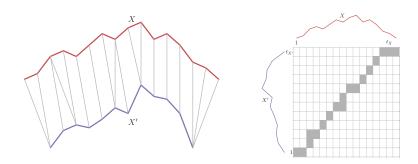
Time series

Vast presence of time series in real-world applications.

Metric learning for time series

- Little work in this field.
- Most of it focused on adapting known methods to the univariate case.

Dynamic Time Warping



Find the optimal alignment between two time series based on a cost matrix:

- Quadratic complexity in the length of the time series;
- Univariate case: often Euclidean distance;
- Multivariate case: need a measure for comparing time moments with multiple features.

Bilinear Similarity for Time Series

Time series **alignment** of length t_{AB} using DTW:

$$\mathbf{Y}_{\mathbf{A}\mathbf{B}} = \mathsf{DTW}(\mathbf{A}, \mathbf{B}).$$

Affinity for aligning time moments $0 < i \le t_A$ and $0 < j \le t_B$ between series **A** and **B**:

$$C_{M}(A,B)_{i,j} = a_{i}^{T} \cdot M \cdot b_{j}.$$

Affinity matrix under metric $\mathbf{M} \in \mathbb{R}^{d \times d}$ for computing the cost of alignment:

$$C_{M}(A, B) = A \cdot M \cdot B^{T}$$
.

Bilinear similarity

Let $K_{\mathbf{M}}: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ of form:

$$K_{\mathsf{M}}(\mathsf{A},\mathsf{B}) = \mathsf{Tr}(\mathsf{C}_{\mathsf{M}}(\mathsf{A},\mathsf{B})^T \cdot \mathsf{Y}_{\mathsf{AB}})/t_{\mathsf{AB}}.$$

Computes the score for aligning **A** and **B** under metric **M**.

Learning the Similarity

Improve the (ϵ, γ, τ) -goodness of $K_{\mathbf{M}}$:

$$\mathbb{E}_{(\mathbf{A},y)}\left[\left[1-\mathbb{E}_{(\mathbf{B},y'),R(\mathbf{B})}\left[yy'K_{\mathbf{M}}(\mathbf{A},\mathbf{B}))|R(\mathbf{B})\right]/\gamma\right]_{+}\right] \leq \epsilon.$$

But we do not have access to expected values.

Similarity Learning for Time Series (SLTS)

Optimize the empirical value of the goodness criterion over sample $\mathcal S$ w.r.t. the set of landmarks $\mathcal L$:

$$\min_{\mathbf{M}} \frac{1}{m} \sum_{(\mathbf{A}, y) \in \mathcal{S}} \left[1 - \frac{1}{n\gamma} \sum_{(\mathbf{B}, y') \in \mathcal{L}} yy' K_{\mathbf{M}}(\mathbf{A}, \mathbf{B}) \right]_{+} + \lambda ||\mathbf{M}||_{\mathcal{F}}^{2}.$$

Properties

- Convex formulation;
- ullet Based on landmarks o does not need to compute DTW and the similarity for all pairs.

Theoretical Analysis

Uniform Stability [BE02]

An algorithm is **stable** if its output is robust to small changes in its input. Uniform stability allows the derivation of generalization bounds.

Lemma

Given a training sample $\mathcal S$ of m examples drawn i.i.d. from P, our algorithm SLTS has uniform stability in κ/m with $\kappa=\frac{4d}{\gamma^2\lambda}$, that is:

$$\sup_{(\mathbf{A}, I) \sim P} |\ell(\mathbf{M}, (\mathbf{A}, I)) - \ell(\mathbf{M}^i, (\mathbf{A}, I))| \leq \frac{\kappa}{m},$$

where \mathbf{M}^{i} is obtained by learning on S after replacing the ith example with a new one.

Bounding True Risk with Uniform Stability

Theorem (Generalization bound)

For any $0 < \delta < 1$, with probability $1 - \delta$, for any matrix **M** learned with SLTS. we have:

features
$$4d 1 2d$$

$$|R_P^{\ell}(\mathbf{M}) - R_{\mathcal{S}}^{\ell}(\mathbf{M})| \leq \frac{4d}{\gamma^2 \lambda m} + \left(\frac{4d}{\gamma^2 \lambda} + \frac{1}{\gamma} \sqrt{\frac{2d}{\lambda}}\right) \sqrt{\frac{2\log\frac{2}{\delta}}{m}}.$$

empirical risk

margin

convergence in $\mathcal{O}\left(\frac{1}{\sqrt{m}}\right)$

Independence from the length of the time series and the alignments.

Experimental Setup

Methods:

Nearest neighbor approaches:

- 1NN
- LDMLT

Linear classifiers:

- L₂ regularized SVM
- BBS
- SLTS.

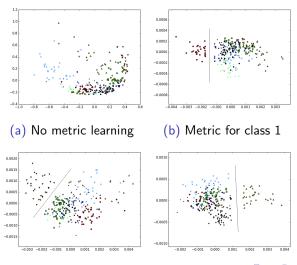
UCI Datasets [Lic13]:

Dataset	#Instances	Length	#Feat.	#Classes
Japanese vowels	640	7-29	12	9
Auslan	675	47-95	22	25
Arabic digits	8800	4-93	13	10
Robot execution failure				
LP1	88	15	6	4
LP2	47	15	6	5
LP3	47	15	6	4
LP4	117	15	6	3
LP5	164	15	6	5

Experimental Results

Similarity Space Visualization

2D PCA on Japanese Vowels



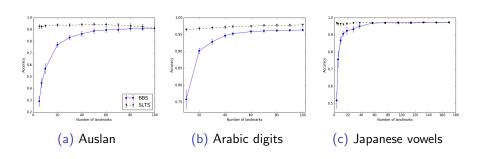
Experimental Results

Classification Accuracy (%)

Method	Japanese vowels	Auslan	Arabic digits	Robot failure	Avg.
1NN LDMLT L ₂ SVM BBS	93.8 97.3 97.8±0.1 97.1+0.5	77.8 ± 2.1 95.0 ± 1.3 92.6 ± 0.1 91.1 ± 1.6	94.7 96.9 93.3±0.0 96.4+0.3	68.8±7.5 71.9±7.0 60.6±6.5 66.9±10.6	92.1 95.6 92.2 94.7
SLTS	97.1±0.4	91.1 ± 1.0 91.1 ± 2.7	97.9 ± 0.4	67.0 ± 7.8	95.8

- SLTS has comparable performance to the other methods;
- It has theoretical guarantees and does not need to compute all the alignments.

Classification accuracy for SLTS and BBS



Summary of SLTS

- Novel method for learning similarities for multivariate time series classification.
- Metric consistency based on uniform stability.
- First method with theoretical guarantees for time series.

Publications

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• Introduce nonlinearity by learning multiple local metrics.

- Introduce nonlinearity by learning multiple local metrics.
- Challenge the learning pairs.

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- Goodness in similarity learning for local classification.

- Introduce nonlinearity by learning multiple local metrics.
- Challenge the learning pairs.
- Goodness in similarity learning for local classification.
- Metric learning for an unsupervised setting with generalization guarantees.

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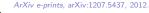
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