

```
#include <Wire.h>

#include <Adafruit_MLX90614.h>
#include <Adafruit_GFX.h>
#include <Adafruit_SSD1306.h>
#include "HX711.h"
#include <Servo.h>


// Pin Definitions
#define TRIG_PIN 6
#define ECHO_PIN 7
#define BUZZER_PIN 11
#define SERVO_PIN 10


#define COLOR_R_PIN A0
#define COLOR_G_PIN A1
#define COLOR_B_PIN A2 // If available


#define HX_DT 8
#define HX_SCK 9


// OLED config
#define SCREEN_WIDTH 128
#define SCREEN_HEIGHT 64
Adafruit_SSD1306 display(SCREEN_WIDTH, SCREEN_HEIGHT, &Wire, -1);


// Sensors and modules
Adafruit_MLX90614 mlx = Adafruit_MLX90614();
HX711 scale;
Servo myServo;


// Thresholds (You should calibrate these!)
int red_thresh = 500; // Adjust based on your RGB sensor readings
int green_thresh = 600;
```

```
int blue_thresh = 400;
```

```
void setup() {
```

```
  Serial.begin(9600);
```

```
  // RGB sensor pins
```

```
  pinMode(COLOR_R_PIN, INPUT);
```

```
  pinMode(COLOR_G_PIN, INPUT);
```

```
  pinMode(COLOR_B_PIN, INPUT);
```

```
  // Ultrasonic
```

```
  pinMode(TRIG_PIN, OUTPUT);
```

```
  pinMode(ECHO_PIN, INPUT);
```

```
  // Buzzer
```

```
  pinMode(BUZZER_PIN, OUTPUT);
```

```
  // OLED
```

```
  if (!display.begin(SSD1306_SWITCHCAPVCC, 0x3C)) {
```

```
    Serial.println("OLED failed");
```

```
    while (1);
```

```
  }
```

```
  display.clearDisplay();
```

```
  // MLX90614
```

```
  mlx.begin();
```

```
  // HX711
```

```
  scale.begin(HX_DT, HX_SCK);
```

```
  scale.set_scale(); // Calibrate this
```

```
  scale.tare();
```

```
  // Servo
```

```
myServo.attach(SERVO_PIN);  
myServo.write(90); // Neutral position  
}  
  
void loop() {  
  // Read RGB sensor  
  int red = analogRead(COLOR_R_PIN);  
  int green = analogRead(COLOR_G_PIN);  
  int blue = analogRead(COLOR_B_PIN);  
  
  // Classify Material (example logic)  
  bool isBiodegradable = (green > green_thresh && red < red_thresh);  
  
  // Read distance  
  digitalWrite(TRIG_PIN, LOW);  
  delayMicroseconds(2);  
  digitalWrite(TRIG_PIN, HIGH);  
  delayMicroseconds(10);  
  digitalWrite(TRIG_PIN, LOW);  
  long duration = pulseIn(ECHO_PIN, HIGH);  
  float distance = duration * 0.034 / 2;  
  
  // Read temperature  
  float tempC = mlx.readObjectTempC();  
  
  // Read weight  
  float weight = scale.get_units(5);  
  
  // Display values on OLED  
  display.clearDisplay();  
  display.setTextSize(1);  
  display.setTextColor(SSD1306_WHITE);
```

```
display.setCursor(0, 0);
display.print("Temp: "); display.print(tempC); display.println(" C");

display.print("Dist: "); display.print(distance); display.println(" cm");

display.print("Weight: "); display.print(weight); display.println(" g");

display.print("R: "); display.print(red);
display.print(" G: "); display.print(green);
display.print(" B: "); display.println(blue);

display.print("Class: ");
display.println(isBiodegradable ? "BIODEGRADABLE" : "NON-BIO");

display.display();
```

```
// Servo action
```

```
if (distance < 10 && weight > 5) {
  if (isBiodegradable) {
    myServo.write(150); // Rotate right
  } else {
    myServo.write(30); // Rotate left
  }
  tone(BUZZER_PIN, 1000, 300); // Beep
  delay(1000);
  myServo.write(90); // Reset to middle
}
```

```
delay(1000); // Wait before next reading
}
```