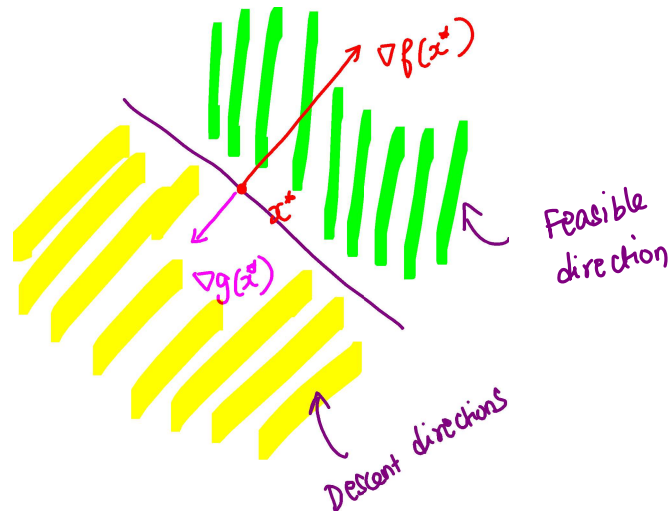


Every descent direction is also feasible!

$\Rightarrow x^*$ cannot be optimal for the configuration above.

$$\begin{aligned} \min_x \quad & f(x) \\ \text{s.t.} \quad & g(x) \leq 0 \end{aligned}$$

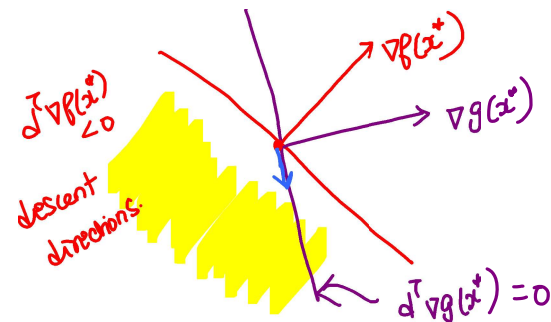


Necessary Condition
for optimality of x^* .

$$\nabla f(x^*) = -\lambda \nabla g(x^*)$$

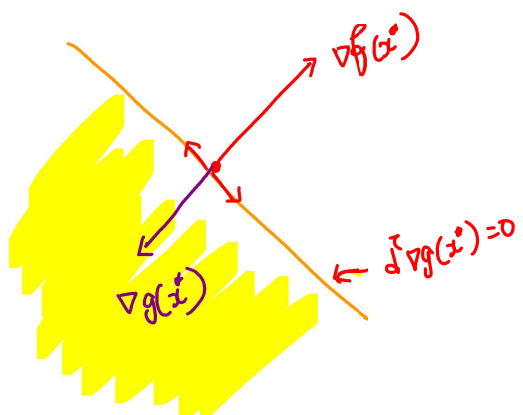
positive scalar.

$$\begin{aligned} \min_x \quad & f(x) \\ \text{s.t.} \quad & g(x) = 0 \end{aligned}$$

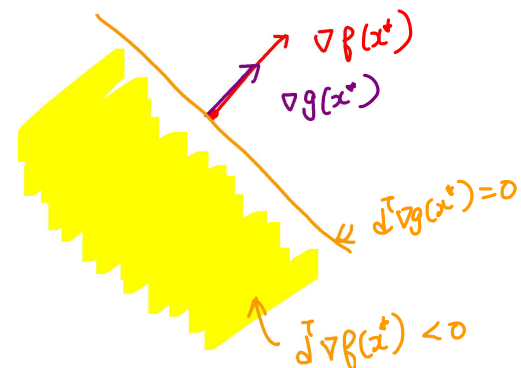


$$\begin{aligned} g(x^*) &= 0 \\ g(x^* + \eta d) &\approx g(x^*) + \eta d^T \nabla g(x^*) \\ 0 &\approx 0 + \eta d^T \nabla g(x^*) \end{aligned}$$

$$d^T \nabla g(x^*) = 0$$



Additionally



$$\nabla f(x^*) = -\underline{\lambda} \nabla g(x^*)$$

can be any
arbitrary
scalar.

Lagrange multiplier