

# Classes and objects

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Programming, Data Structures and Algorithms using Python  
Week 1

# Classes and objects

- Abstract datatype

- Stores some information
- Designated functions to manipulate the information
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- Template for a data type
- How data is stored
- How public functions manipulate data

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## ■ Class

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- How data is stored
- How public functions manipulate data

## ■ Object

- Concrete instance of template

## Example: 2D points

- A point has coordinates  $(x, y)$ 
  - `__init__()` initializes internal values `x, y`
  - First parameter is always `self`
  - Here, by default a point is at  $(0, 0)$

```
class Point:  
    def __init__(self, a=0, b=0):  
        self.x = a  
        self.y = b
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- Translation: shift a point by  $(\Delta x, \Delta y)$ 
  - $(x, y) \mapsto (x + \Delta x, y + \Delta y)$

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class Point:
    def __init__(self, a=0, b=0):
        self.x = a
        self.y = b

    def translate(self, deltax, deltay):
        self.x += deltax
        self.y += deltay
```

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- Distance from the origin
  - $d = \sqrt{x^2 + y^2}$

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class Point:
    def __init__(self, a=0, b=0):
        self.x = a
        self.y = b

    def translate(self, deltax, deltay):
        self.x += deltax
        self.y += deltay

    def odistance(self):
        import math
        d = math.sqrt(self.x*self.x +
                       self.y*self.y)
        return(d)
```



# Polar coordinates

- $(r, \theta)$  instead of  $(x, y)$ 
  - $r = \sqrt{x^2 + y^2}$
  - $\theta = \tan^{-1}(y/x)$

```
import math
class Point:
    def __init__(self, a=0, b=0):
        self.r = math.sqrt(a*a + b*b)
        if a == 0:
            self.theta = math.pi/2
        else:
            self.theta = math.atan(b/a)
```

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        else:
            self.theta = math.atan(b/a)

    def odistance(self):
        return(self.r)
```

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  - $r = \sqrt{x^2 + y^2}$
  - $\theta = \tan^{-1}(y/x)$
- Distance from origin is just  $r$
- Translation
  - Convert  $(r, \theta)$  to  $(x, y)$
  - $x = r \cos \theta, y = r \sin \theta$
  - Recompute  $r, \theta$  from  $(x + \Delta x, y + \Delta y)$

```
def translate(self, deltax, deltay):  
    x = self.r*math.cos(self.theta)  
    y = self.r*math.sin(self.theta)  
    x += deltax  
    y += deltay  
    self.r = math.sqrt(x*x + y*y)  
    if x == 0:  
        self.theta = math.pi/2  
    else:  
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- Translation
  - Convert  $(r, \theta)$  to  $(x, y)$
  - $x = r \cos \theta, y = r \sin \theta$
  - Recompute  $r, \theta$  from  $(x + \Delta x, y + \Delta y)$
- Interface has not changed
  - User need not be aware whether representation is  $(x, y)$  or  $(r, \theta)$

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def translate(self, deltax, deltay):  
    x = self.r*math.cos(self.theta)  
    y = self.r*math.sin(self.theta)  
    x += deltax  
    y += deltay  
    self.r = math.sqrt(x*x + y*y)  
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# Special functions

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- `__str__()` — convert object to string
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  - Implicitly invoked by `print()`

```
class Point:  
  
    ...  
  
    def __str__(self):  
        return(  
            '('+str(self.x)+', '  
            +str(self.y)+')'  
        )
```

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  - Implicitly invoked by `print()`
- `__add__()`
  - Implicitly invoked by `+`

```
class Point:
```

```
...
```

```
def __str__(self):
```

```
    return(
```

```
        '('+str(self.x)+','
```

```
        +str(self.y)+')
```

```
    )
```

```
def __add__(self,p):
```

```
    return(Point(self.x + p.x,
```

```
               self.y + p.y))
```

# Special functions

- `__init__()` — constructor
- `__str__()` — convert object to string
  - `str(o) == o.__str__()`
  - Implicitly invoked by `print()`
- `__add__()`
  - Implicitly invoked by `+`
- Similarly
  - `__mult__()` invoked by `*`
  - `__lt__()` invoked by `<`
  - `__ge__()` invoked by `>=`
  - ...

```
class Point:
    ...

    def __str__(self):
        return(
            '('+str(self.x)+', '
            +str(self.y)+')'
        )

    def __add__(self,p):
        return(Point(self.x + p.x,
                      self.y + p.y))
```