

Single Source Shortest Paths with Negative Weights

Madhavan Mukund

<https://www.cmi.ac.in/~madhavan>

Programming, Data Structures and Algorithms using Python
Week 5

Dijkstra's algorithm

- Recall the burning pipeline analogy

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- We keep track of the following
 - The vertices that have been burnt
 - The expected burn time of vertices

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- Initially
 - No vertex is burnt
 - Expected burn time of source vertex is 0
 - Expected burn time of rest is ∞

Initialization (assume source vertex 0)

- $B(i) = \text{False}$, for $0 \leq i < n$
 - $UB = \{k \mid B(k) = \text{False}\}$
- $EBT(i) = \begin{cases} 0, & \text{if } i = 0 \\ \infty, & \text{otherwise} \end{cases}$

Dijkstra's algorithm

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- We keep track of the following
 - The vertices that have been burnt
 - The expected burn time of vertices
- Initially
 - No vertex is burnt
 - Expected burn time of source vertex is 0
 - Expected burn time of rest is ∞
- While there are vertices yet to burn
 - Pick unburnt vertex with minimum expected burn time, mark it as burnt
 - Update the expected burn time of its neighbours

Initialization (assume source vertex 0)

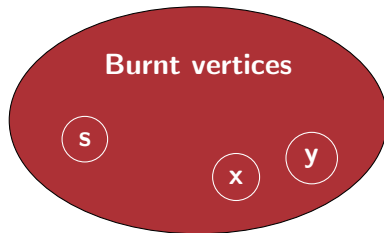
- $B(i) = \text{False}$, for $0 \leq i < n$
 - $UB = \{k \mid B(k) = \text{False}\}$
- $EBT(i) = \begin{cases} 0, & \text{if } i = 0 \\ \infty, & \text{otherwise} \end{cases}$

Update, if $UB \neq \emptyset$

- Let $j \in UB$ such that $EBT(j) \leq EBT(k)$ for all $k \in UB$
- Update $B(j) = \text{True}$, $UB = UB \setminus \{j\}$
- For each $(j, k) \in E$ such that $k \in UB$,
 $EBT(k) = \min(EBT(k), EBT(j) + W(j, k))$

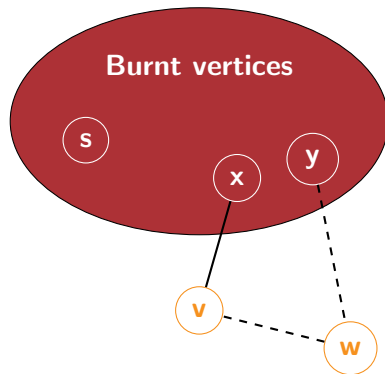
Correctness requires non-negative edge weights

- Each new shortest path we discover extends an earlier one
- By induction, assume we have found shortest paths to all vertices already burnt



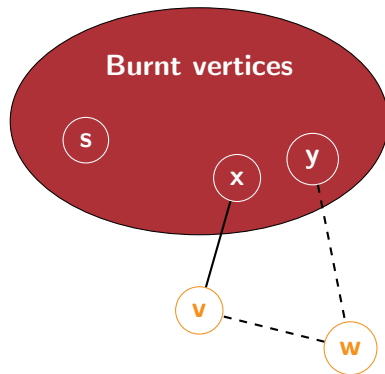
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- Next vertex to burn is \mathbf{v} , via \mathbf{x}
- Cannot find a shorter path later from \mathbf{y} to \mathbf{v} via \mathbf{w}
 - Burn time of $\mathbf{w} \geq$ burn time of \mathbf{v}
 - Edge from \mathbf{w} to \mathbf{v} has weight ≥ 0



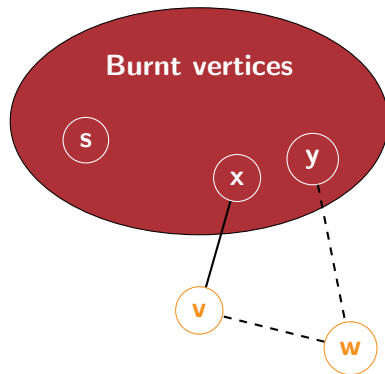
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 - Burn time of $\mathbf{w} \geq$ burn time of \mathbf{v}
 - Edge from \mathbf{w} to \mathbf{v} has weight ≥ 0
- This argument breaks down if edge (\mathbf{w}, \mathbf{v}) can have negative weight



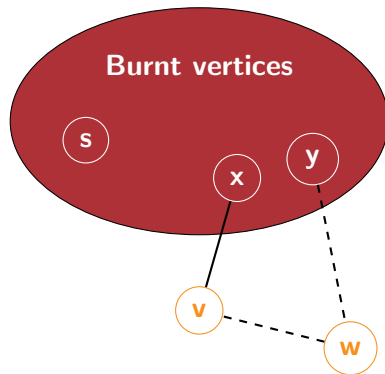
Extending to negative edge weights

- The difficulty with negative edge weights is that we stop updating the burn time once a vertex is burnt



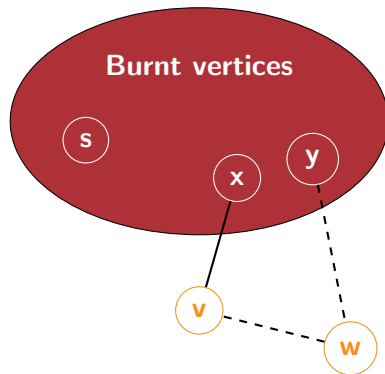
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- What if we allow updates even after a vertex is burnt?



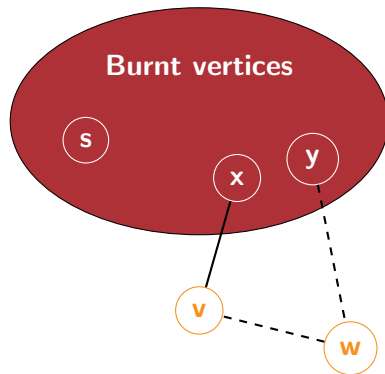
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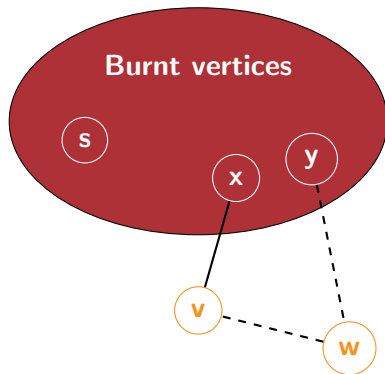
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- What if we allow updates even after a vertex is burnt?
- Recall, negative edge weights are allowed, but no negative cycles
- Going around a cycle can only add to the length
- Shortest route to every vertex is a path, no loops



Extending to negative edge weights

- Suppose minimum weight path from 0 to k is

$$0 \xrightarrow{w_1} j_1 \xrightarrow{w_2} j_2 \xrightarrow{w_3} \cdots \xrightarrow{w_{\ell-1}} j_{\ell-1} \xrightarrow{w_{\ell}} k$$

- Need not be minimum in terms of number of edges

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- Every prefix of this path must itself be a minimum weight path
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- Once we discover shortest path to $j_{\ell-1}$, next update will fix shortest path to k
- Repeatedly update shortest distance to each vertex based on shortest distance to its neighbours
 - Update cannot push this distance below actual shortest distance
- After ℓ updates, all shortest paths using $\leq \ell$ edges have stabilized
 - Minimum weight path to any node has at most $n-1$ edges
 - After $n-1$ updates, all shortest paths have stabilized

Bellman-Ford Algorithm

Initialization (source vertex 0)

- $D(j)$: minimum distance known so far to vertex j

- $$D(j) = \begin{cases} 0, & \text{if } j = 0 \\ \infty, & \text{otherwise} \end{cases}$$

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Repeat $n-1$ times

- For each vertex $j \in \{0, 1, \dots, n-1\}$,
for each edge $(j, k) \in E$,
 $D(k) = \min(D(k),$
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Works for directed and undirected graphs

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    infinity = np.max(WMat)*rows+1  
    distance = {}  
    for v in range(rows):  
        distance[v] = infinity  
  
    distance[s] = 0  
  
    for i in range(rows):  
        for u in range(rows):  
            for v in range(cols):  
                if WMat[u,v,0] == 1:  
                    distance[v] = min(distance[v],distance[u]  
                                        +WMat[u,v,1])  
    return(distance)
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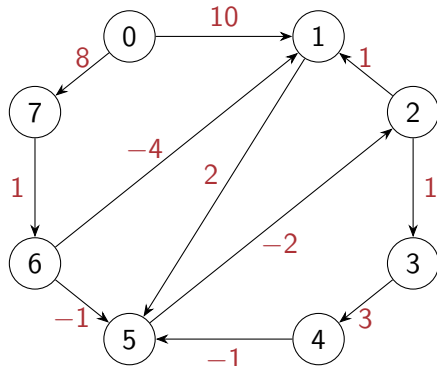
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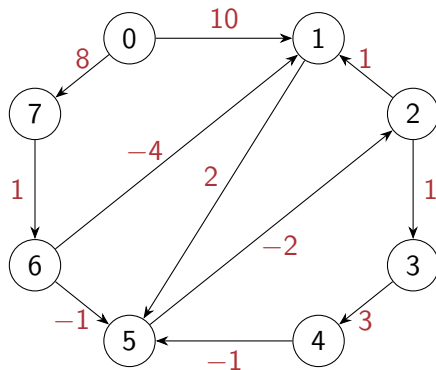
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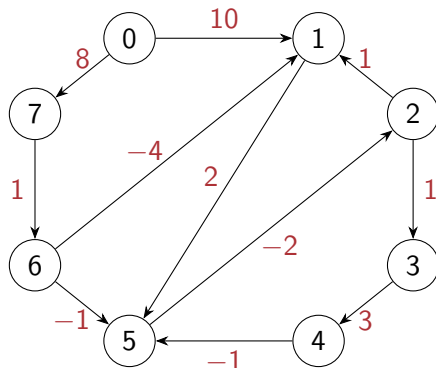
v	$D(v)$							
0								
1								
2								
3								
4								
5								
6								
7								



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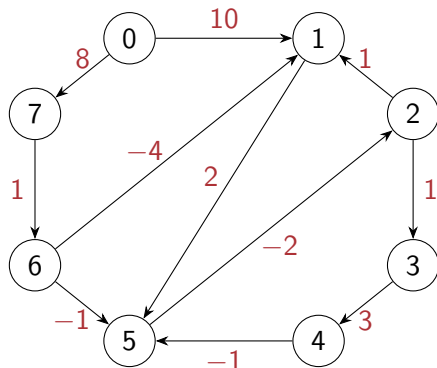
v	$D(v)$							
0	0							
1	∞							
2	∞							
3	∞							
4	∞							
5	∞							
6	∞							
7	∞							

- Initialize $D(0) = 0$



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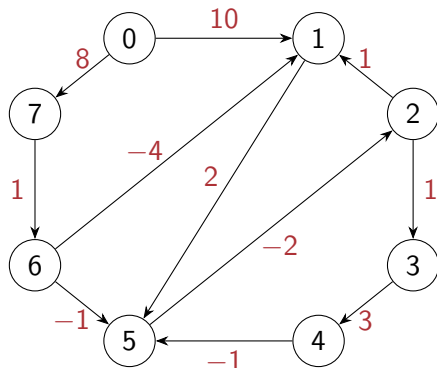
v	$D(v)$							
0	0	0						
1	∞	10						
2	∞	∞						
3	∞	∞						
4	∞	∞						
5	∞	∞						
6	∞	∞						
7	∞	8						



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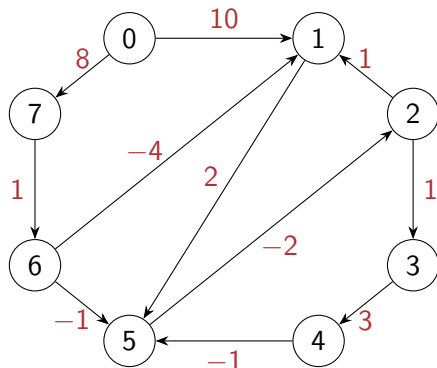
v	$D(v)$							
0	0	0	0					
1	∞	10	10					
2	∞	∞	∞					
3	∞	∞	∞					
4	∞	∞	∞					
5	∞	∞	12					
6	∞	∞	9					
7	∞	8	8					



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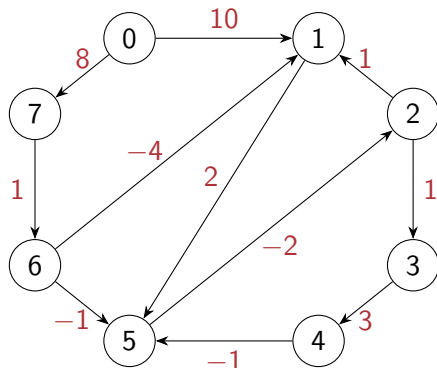
v	$D(v)$							
0	0	0	0	0				
1	∞	10	10	5				
2	∞	∞	∞	10				
3	∞	∞	∞	∞				
4	∞	∞	∞	∞				
5	∞	∞	12	8				
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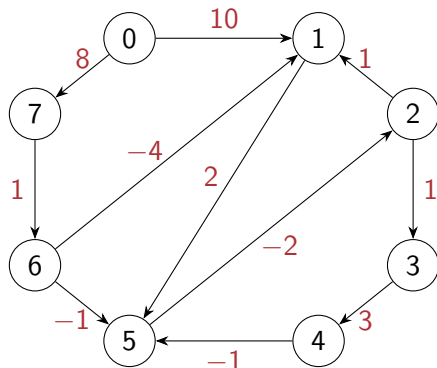
v	$D(v)$							
0	0	0	0	0	0			
1	∞	10	10	5	5			
2	∞	∞	∞	10	6			
3	∞	∞	∞	∞	11			
4	∞	∞	∞	∞	∞			
5	∞	∞	12	8	7			
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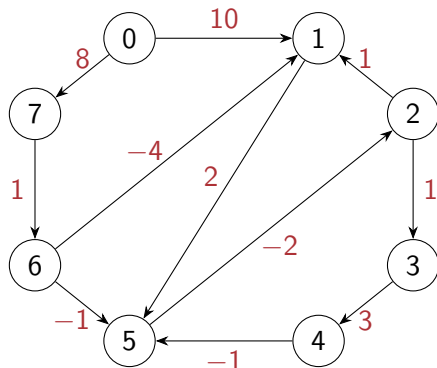
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3	∞	∞	∞	∞	11	7	
4	∞	∞	∞	∞	∞	14	
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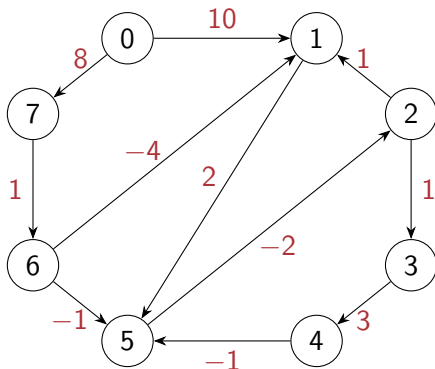
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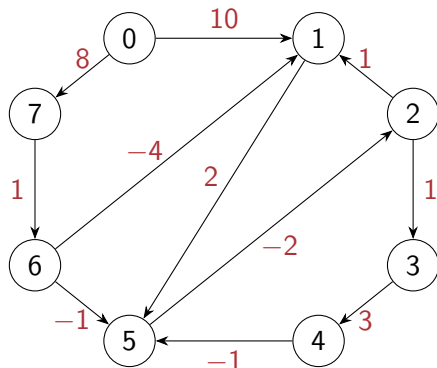
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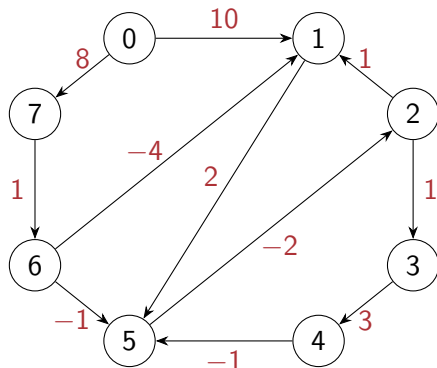
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- What if there was a negative cycle?

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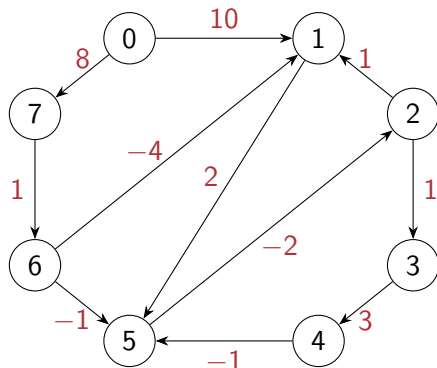
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- Distance would continue to decrease

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- What if there was a negative cycle?
- Distance would continue to decrease
- Check if update n reduces any $D(v)$

Complexity

- Initialing `infinity` takes $O(n^2)$ time

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    (rows,cols,x) = WMat.shape  
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    distance = {}  
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    for i in range(rows):  
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- In each iteration, we have to examine every edge in the graph
 - This take $O(n^2)$ for an adjacency matrix

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- Overall, $O(n^3)$
- If we shift to adjacency lists
 - Initializing `infinity` is $O(m)$
 - Scanning all edges in each update iteration is $O(m)$

```
def bellmanfordlist(WList,s):  
    infinity = 1 + len(WList.keys())*  
                max([d for u in WList.keys()  
                    for (v,d) in WList[u]])  
  
    distance = {}  
    for v in WList.keys():  
        distance[v] = infinity  
  
    distance[s] = 0  
  
    for i in WList.keys():  
        for u in WList.keys():  
            for (v,d) in WList[u]:  
                distance[v] = min(distance[v],distance[u] + d)  
    return(distance)
```


Complexity

- Initializing `infinity` takes $O(n^2)$ time
- The outer update loop runs $O(n)$ times
- In each iteration, we have to examine every edge in the graph
 - This takes $O(n^2)$ for an adjacency matrix
- Overall, $O(n^3)$
- If we shift to adjacency lists
 - Initializing `infinity` is $O(m)$
 - Scanning all edges in each update iteration is $O(m)$
- Now, overall $O(mn)$

```
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```

Summary

- Dijkstra's algorithm assumes non-negative edge weights
 - Final distance is frozen each time a vertex “burns”
 - Should not encounter a shorter route discovered later
- Without negative cycles, every shortest route is a path
- Every prefix of a shortest path is also a shortest path
- Iteratively find shortest paths of length $1, 2, \dots, n-1$
- Update distance to each vertex with every iteration — Bellman-Ford algorithm
- $O(n^3)$ time with adjacency matrix, $O(mn)$ time with adjacency list
- If Bellman-Ford algorithm does not converge after $n - 1$ iterations, there is a negative cycle