# Euclidean Heuristic Optimization

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## Introduction

#### Problem

- ► Improve the efficiency of finding shortest paths between arbitrary points in a search graph
- Example applications: road networks, virtual worlds

#### Approach

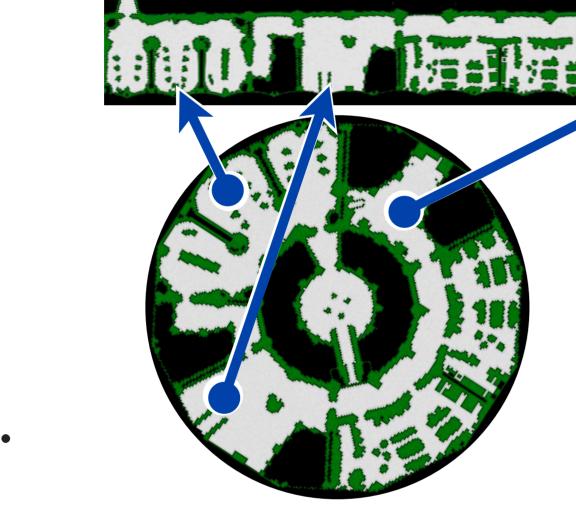
- Assign each state i in the input graph a point  $y_i \in \mathbb{R}^d$
- Use interpoint distances as heuristics for distances in the graph
- Arrange the points in such a way as to minimize the error between the estimated distances and the true distances

#### Contributions

- Link between heuristic construction and manifold learning
- Promising empirical results on a range of test domains

## Euclidean Heuristics

A Euclidean heuristic is a heuristic function *h* for any state pair that can be computed from distances between points:



$$h(i,j) = ||y_i - y_j||$$

The arrangement of the points Y defines h.

An optimal Euclidean heuristic minimizes the loss  $\mathcal{L}$  between the true distances  $\delta(i,j)$  and the heuristics given by the points Y:

minimize  $\mathcal{L}(Y)$ 

subject to Y is admissible and consistent

## Constraints

#### Theorem

Y is admissible between adjacent states

Y is admissible and consistent

Passino and Antsaklis, 1994

(one constraint per edge)

### The Loss Function

Favor larger errors by squaring terms, but admit a weight  $W_{ij}$  on the relative importance of each pair (i, j)

$$\mathcal{L}(Y) = \sum_{i,j} W_{ij} |\delta(i,j)^2 - ||y_i - y_j||^2|$$

Admissibility ( $\delta(i,j)^2 \ge ||y_i - y_j||^2$ ) permits a simpler loss:

$$\mathcal{L}(Y) = \sum_{i,j} W_{ij}(\delta(i,j)^2 - ||y_i - y_j||^2) \equiv -\sum_{i,j} W_{ij}||y_i - y_j||^2$$

The resulting optimization problem:

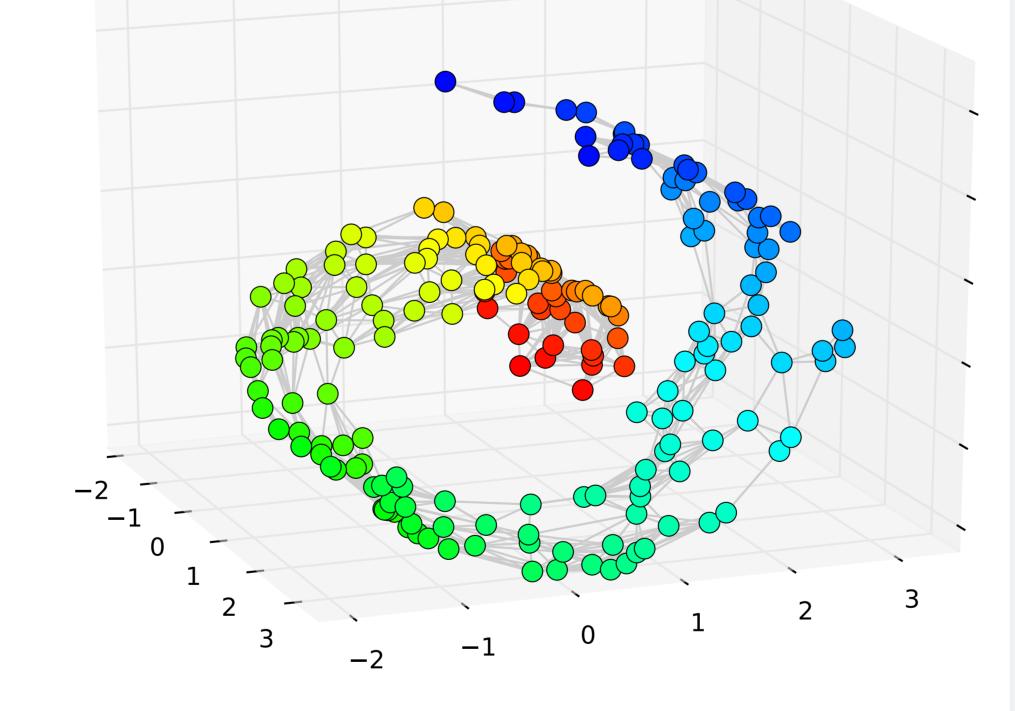
maximize 
$$\sum_{i,j} W_{ij} ||y_i - y_j||^2$$
 subject to  $\forall (i,j) \in E ||y_i - y_j|| \leq \delta(i,j)$ 

## Connections

#### Manifold Learning

This is a weighted generalization of MVU (Weinberger *et al.*)

- Nonlinear dimensionality reduction
- ► MVU's semidefinite reformulation renders the optimization tractable



#### Differential Heuristics

W can be parametrized to reproduce differential heuristics:

$$W_{\text{diff}} = \begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & \left(\frac{-1}{n-1}\right) & \left(\frac{-1}{n-1}\right) \\ 1 & \left(\frac{-1}{n-1}\right) & 0 & \left(\frac{-1}{n-1}\right) \\ 1 & \left(\frac{-1}{n-1}\right) & \left(\frac{-1}{n-1}\right) & 0 \end{bmatrix}$$

Suppose pivot is state 1:

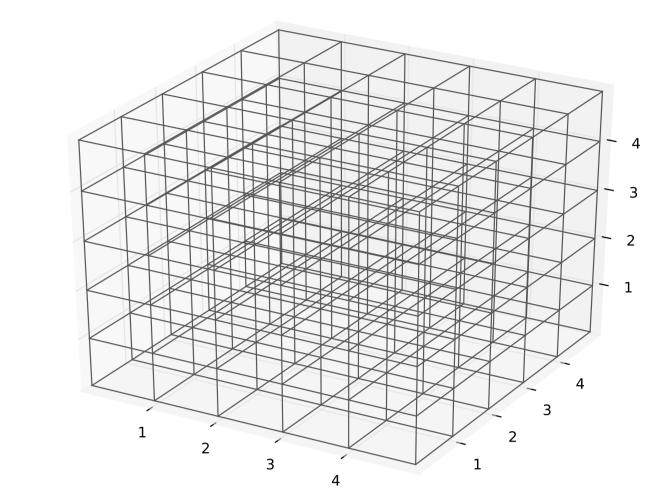
- Push points away from pivot
- Pull points into each other

# Experiments

Comparison against differential heuristics using A\*:

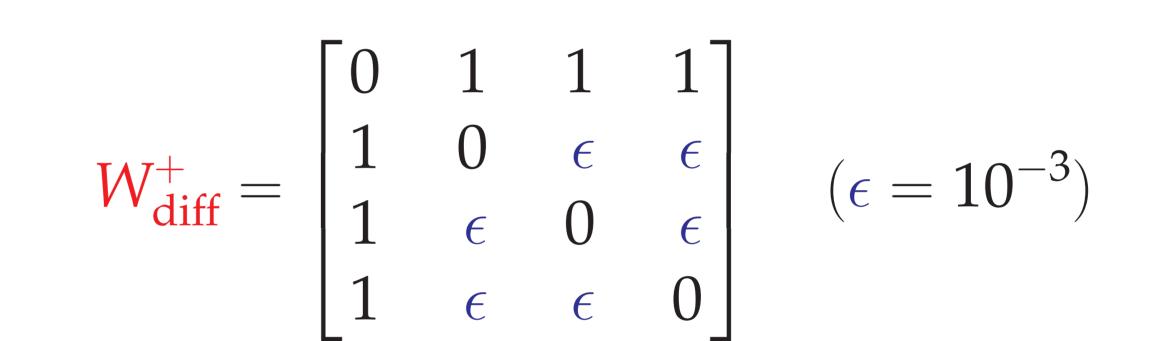
#### Cube World

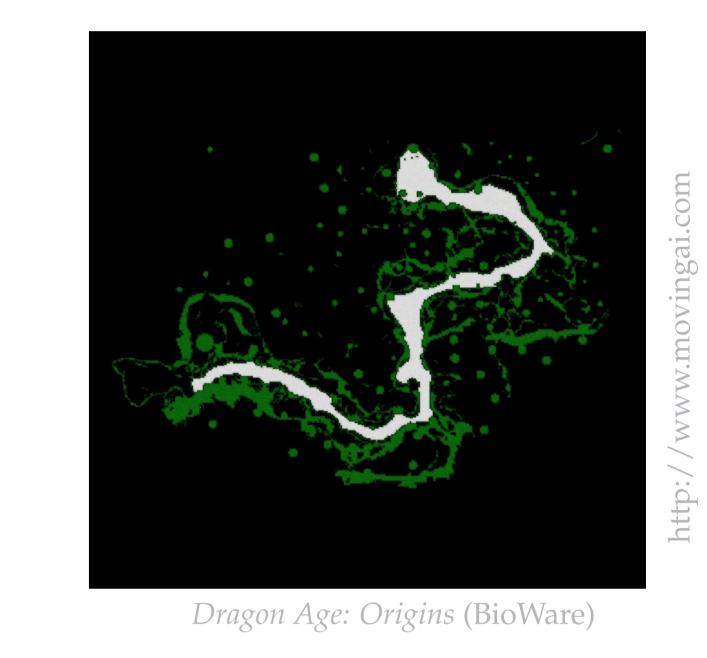
- ▶  $20 \times 20 \times 20 = 8,000$  states
- Agent increments any/all coordinates by 1;
   transition costs are the edge lengths
- Multi-dimensional search spaces target a weakness of differential heuristic



#### Video Game Maps

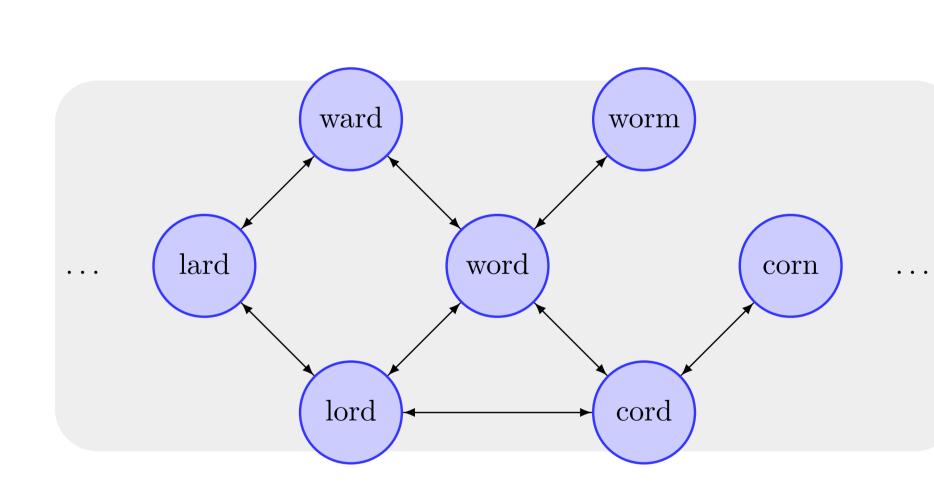
- ► 168–6,240 states
- Octile connectivity: diagonals cost 1.5
- ► Maps are like corridors to which differential heuristics are well suited; a competing W<sup>+</sup><sub>diff</sub> is introduced:

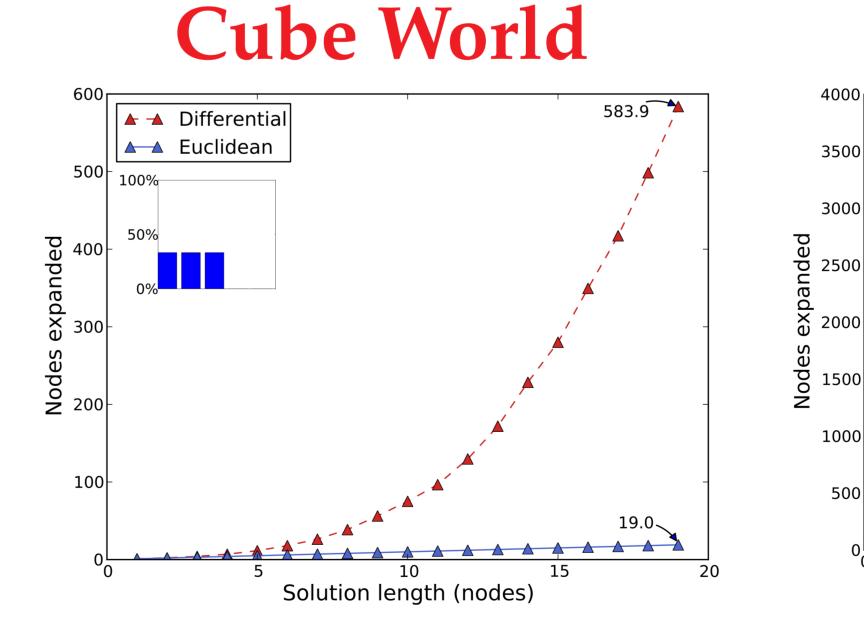


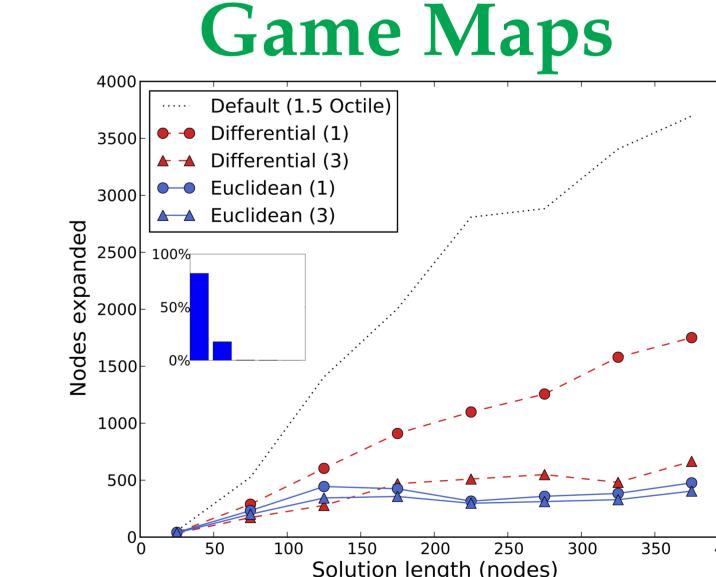


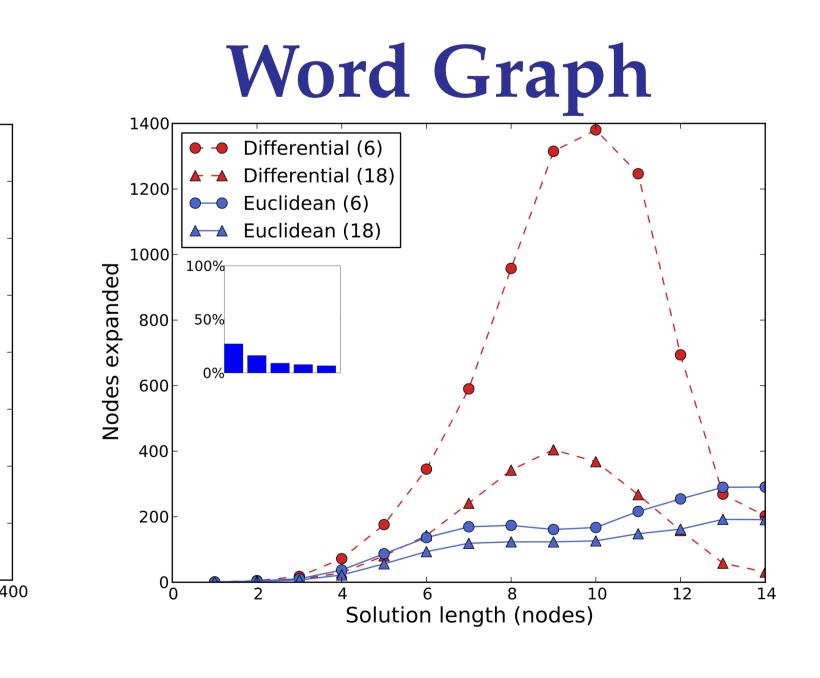
## Four-Letter Word Graph

- Connected graph of 4,820 words
- Agent changes 1 letter per step
- High dimensional domain









- ▶ Bar plots: variance in each dimension of the uniformly weighted embedding
- Optimal Euclidean heuristics show promise, storing more in less memory

Thank you Ariel Felner
Anonymous reviewers
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