

# Ray Tracing & Ray Casting

Realistic Graphics Inspired by Nature

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Motivation

The Story of Light

Ray Casting: Foundation

The Mathematics of Rays

Camera Models in Ray Tracing

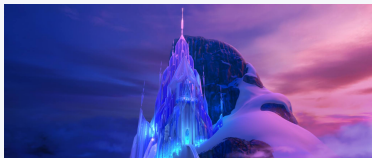
Ray-Object Intersections

# Motivation

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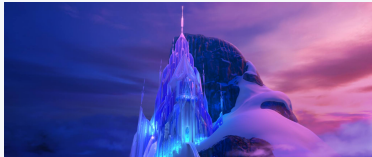
# Why Learn This?

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Elsa's Castle in Frozen

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Elsa's Castle in Frozen



Cyberpunk 2077 with RTX

- **Realistic graphics** of your favourite animated movies are the result of ground-breaking work in Ray Tracing by studios like Disney, Pixar, and DreamWorks. Do you know these films take years to render? 30 hours per frame!

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Elsa's Castle in Frozen



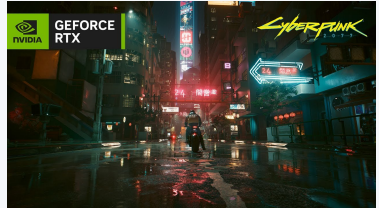
Cyberpunk 2077 with RTX

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- Lately, **RTX** is all the rage in gaming. New titles boast ray-tracing effects in real-time, not 30 hours per frame!

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Elsa's Castle in Frozen



Cyberpunk 2077 with RTX

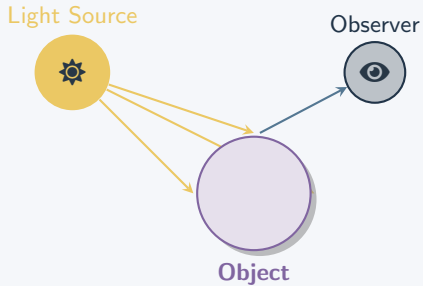
- **Realistic graphics** of your favourite animated movies are the result of ground-breaking work in Ray Tracing by studios like Disney, Pixar, and DreamWorks. Do you know these films take years to render? 30 hours per frame!
- Lately, **RTX** is all the rage in gaming. New titles boast ray-tracing effects in real-time, not 30 hours per frame!
- It's fun! You will know when you create your first ray-traced image!



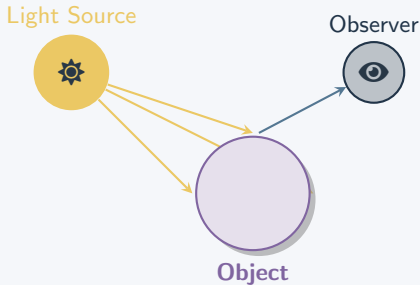
# The Story of Light

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# How Do We See?



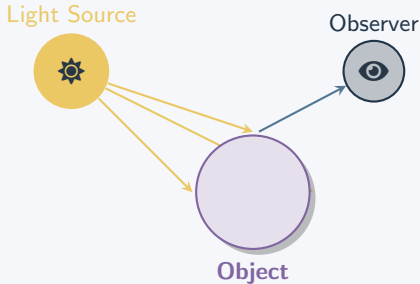
# How Do We See?



## Natural Process

1. Light travels from source
2. Light hits objects
3. Light bounces to our eyes
4. Our brain interprets the signal

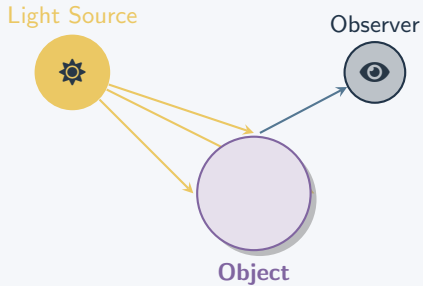
# How Do We See?



## Physical Process

1. Photon is emitted from source
2. Photon hits objects
3. Part of the photon is reflected or absorbed
4. The reflected photons reach our eyes
5. The rods and cones in our retina detect the photons
6. Our brain interprets the signal
7. **Colour:** The wavelength of the photons
8. **Brightness:** The number of photons

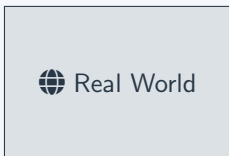
# How Do We See?



Question: How do we simulate this?

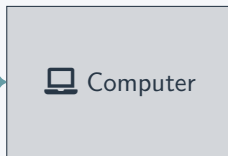
# The Computer Graphics Challenge

**Infinite Complexity**



Simulate

**Finite Pixels**



## Challenges:

- Infinite light rays/photons
- Complex physics
- High computational cost

# Ray Casting: Foundation

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# The Key Insight

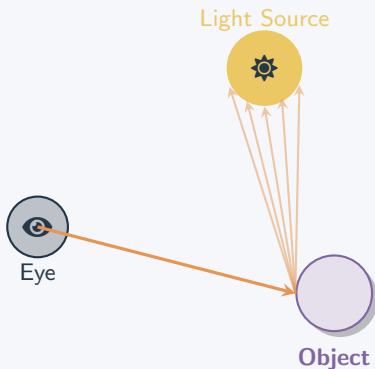
## 1. Reverse Engineering

Instead of following light rays from light sources —

**Let's trace backwards!**

**Shoot rays from the eye,**  
find where it hits and find out  
how much light reaches there.

This is the opposite of what happens in reality. **Why does this work?**





# The Key Insight

## 1. Reverse Engineering

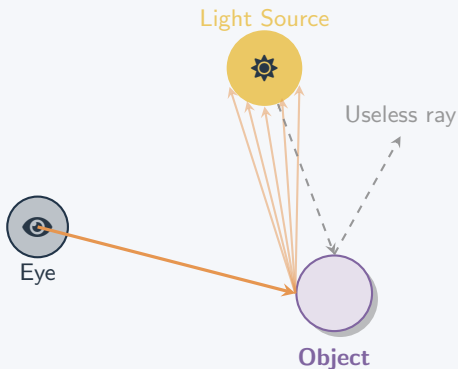
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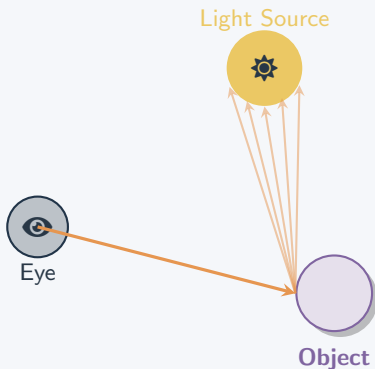
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This is the opposite of what happens in reality. **Why does this work?**

- Most light never reaches our eyes
- Only trace rays that matter
- Much more efficient!



# From Infinite Rays to Finite Pixels

## 2. Cutting Costs

Instead of tracing infinite rays —

**Trace one ray per pixel.**

This comes with little tradeoff, because:

# From Infinite Rays to Finite Pixels

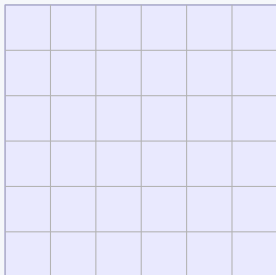
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- An image is just a grid of pixels



# From Infinite Rays to Finite Pixels

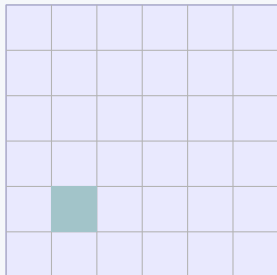
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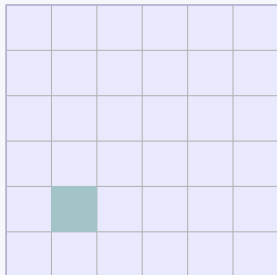
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- In the end, we just need to know the *color of each pixel*



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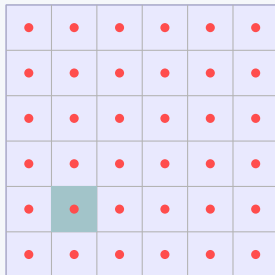
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- An image is just a grid of pixels
- Each pixel can only be of one color
- In the end, we just need to know the *color of each pixel*
- Hence, one ray from the mid-point of each pixel should be a good approximation\*

\* We will discuss more advanced techniques later that improve quality



# The Full Picture

Light Source



Eye



Object

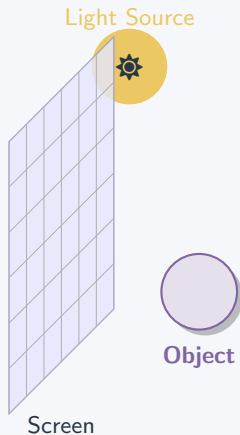


# The Full Picture

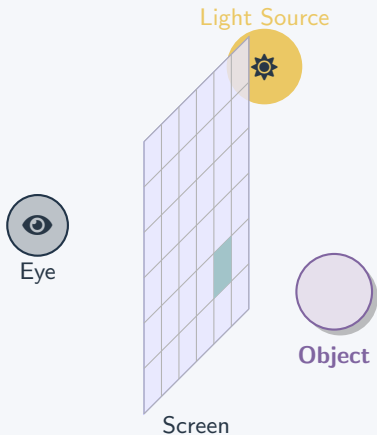
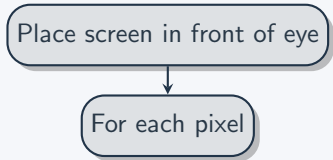
Place screen in front of eye



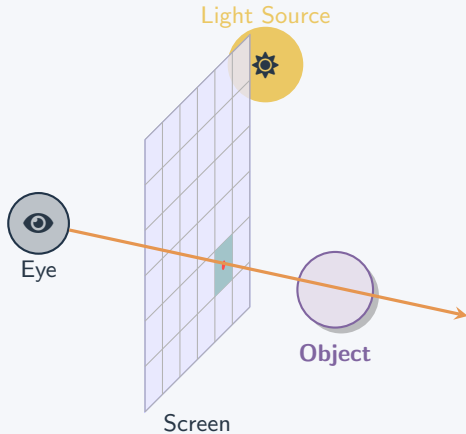
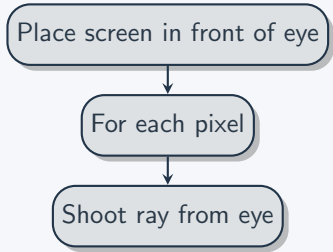
Eye



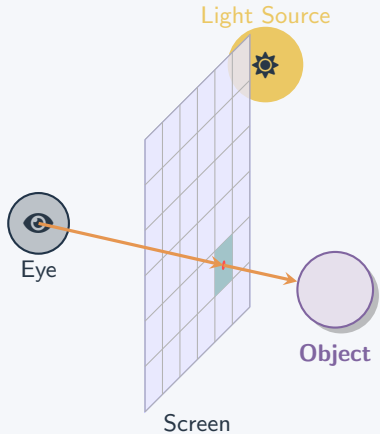
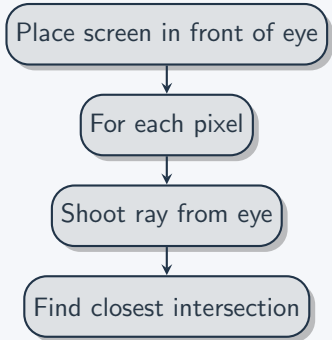
# The Full Picture



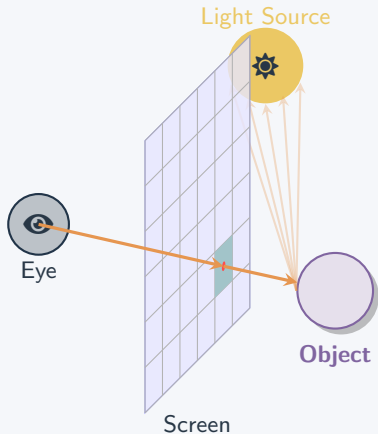
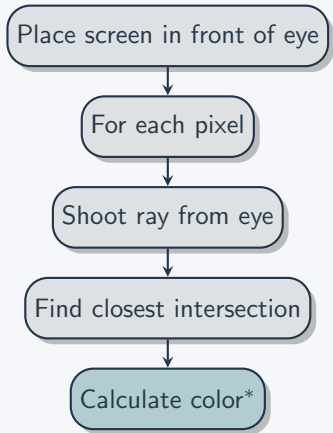
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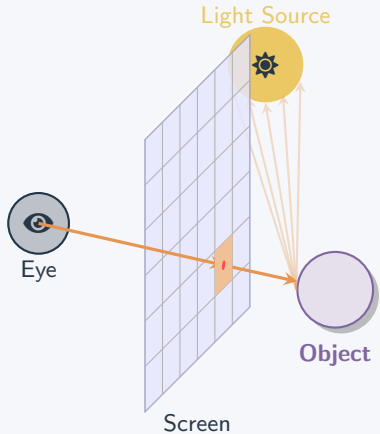
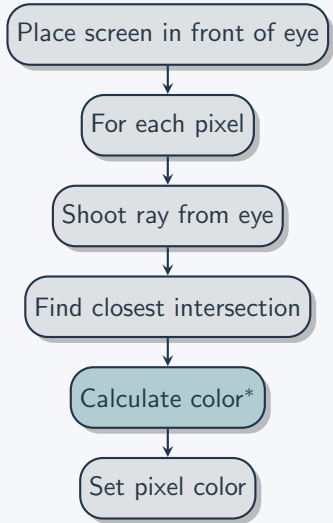
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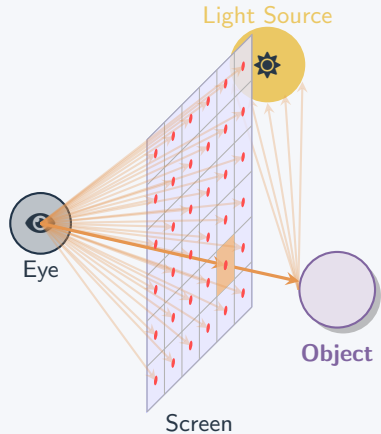
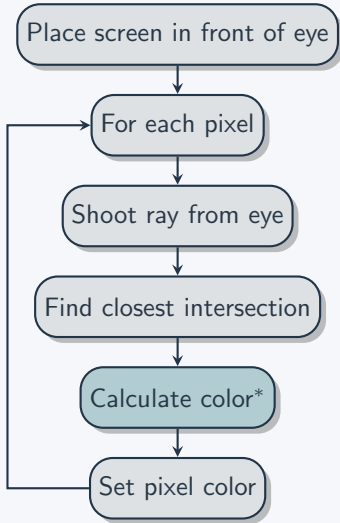
# The Full Picture



# The Full Picture



# The Full Picture



# The Mathematics of Rays

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# What is a Ray?

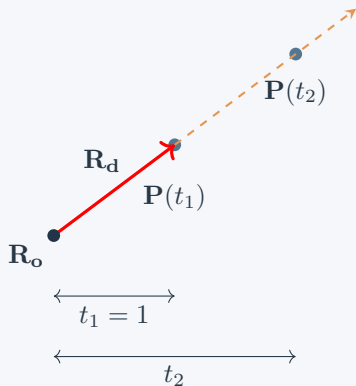
## Ray Representation

A ray is defined by:

$$\mathbf{P}(t) = \mathbf{R}_o + t \cdot \mathbf{R}_d \quad (1)$$

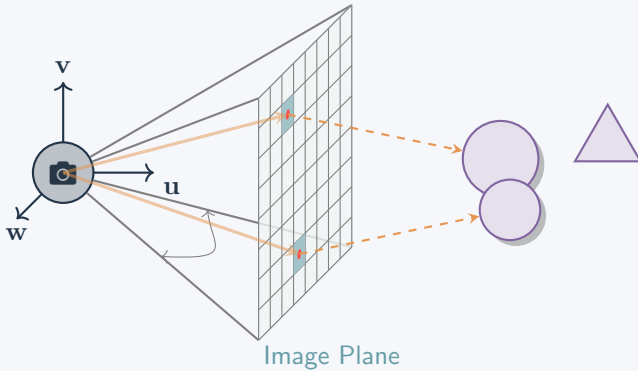
where:

- $\mathbf{R}_o$  = Origin point
- $\mathbf{R}_d$  = Direction vector
- $t$  = Parameter ( $t \geq 0$ )



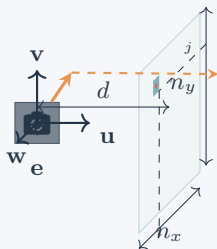
Check out here on desmos.

# Camera and Ray Generation



## Camera Parameters

**Camera Definition:** Eye point  $e$ , orthobasis  $\{u, v, w\}$ , field of view, image dimensions



## Ray Equation

For pixel  $(i, j)$ :

$$s = \frac{i + 0.5}{n_x} \quad (2)$$

$$t = \frac{j + 0.5}{n_y} \quad (3)$$

**Ray direction:**

$$\mathbf{d} = (s - 0.5) \cdot \text{FOV} \cdot \mathbf{u} \quad (4)$$

$$+ (t - 0.5) \cdot \text{FOV} \cdot \mathbf{v} \quad (5)$$

$$+ d \cdot \mathbf{w} \quad (6)$$

**Parametric ray:**

# Camera Models in Ray Tracing

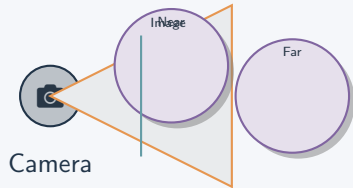
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# Why Camera Models Matter

## The Camera's Role

The camera determines:

- **Field of view** - What we see
- **Perspective** - How objects appear
- **Ray generation** - Where rays start
- **Image formation** - Final rendering



Different camera models = Different visual effects!

# The Pinhole Camera Model

## Pinhole Camera

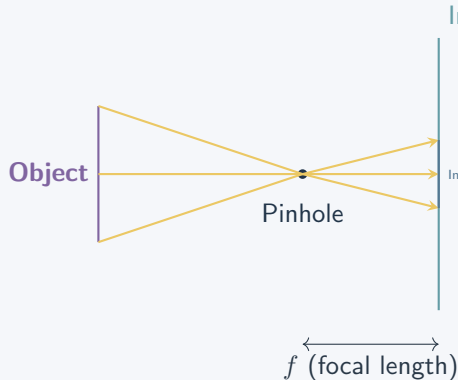
### Key Properties:

- Point aperture (no lens)
- Perfect focus everywhere
- Linear perspective
- No depth of field

### Ray Generation:

$$\mathbf{R}_o = \text{eye} \quad (8)$$

$$\mathbf{R}_d = \text{pixel} - \text{eye} \quad (9)$$



## Physical Reality

Real pinhole cameras exist! They create sharp images but require

# Simplified Pinhole Camera

## Simplification

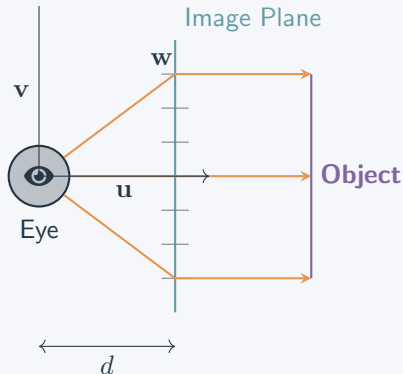
**Problem:** Real pinhole creates inverted image

**Solution:** Place image plane in front!

$$\text{pixel} = \text{eye} + d \cdot \mathbf{w} + u \cdot \mathbf{u} + v \cdot \mathbf{v} \quad (10)$$

where:

- $d$  = distance to image plane
- $u, v$  = pixel coordinates
- $\mathbf{u}, \mathbf{v}, \mathbf{w}$  = camera basis



## Advantage

# View Frustum

## Viewing Frustum

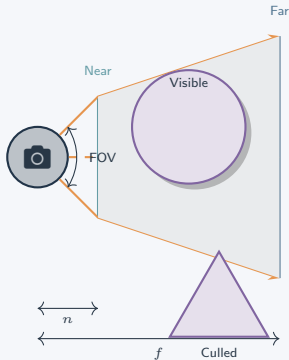
**Definition:** The 3D region visible to the camera

**Boundaries:**

- **Near plane** - Closest visible distance
- **Far plane** - Farthest visible distance
- **Left/Right** - Horizontal field of view
- **Top/Bottom** - Vertical field of view

**Field of View:**

$$\text{FOV} = 2 \arctan \left( \frac{h}{2d} \right)$$





# Orthographic Camera

## Orthographic Projection

### Key Properties:

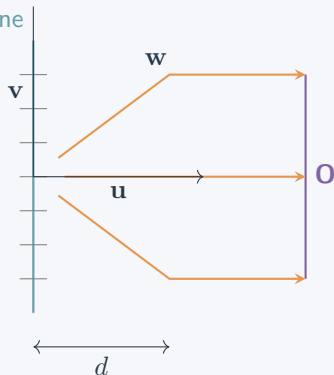
- No perspective distortion
- Parallel projection rays
- Objects same size regardless of distance
- Infinite focal length

### Ray Generation:

$$\mathbf{R}_o = \text{pixel} \quad (12)$$

$$\mathbf{R}_d = \mathbf{w} \text{ (constant)} \quad (13)$$

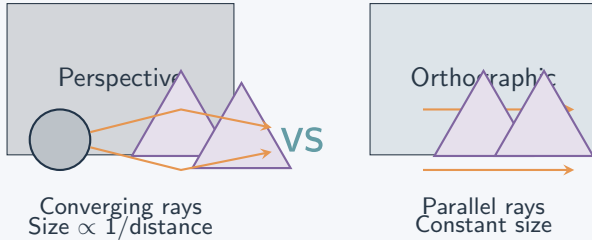
Image Plane



## Applications

Technical drawings, CAD software, 2D games, architectural

# Perspective vs Orthographic



## When to use Perspective

- Natural/realistic scenes
- Human vision simulation
- Games and films
- Depth perception important

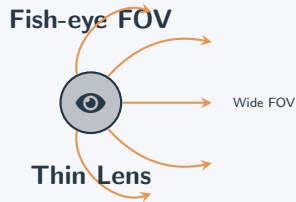
## When to use Orthographic

- Technical illustrations
- CAD/Engineering
- UI elements overlay
- Precise measurements

# Other Camera Types

## Fish-eye Camera

- Very wide field of view ( $\geq 180^\circ$ )
- Non-linear distortion
- Curved ray paths
- Surveillance, VR applications



## Thin Lens Camera

- Simulates real camera lens
- Depth of field effects
- Focal blur



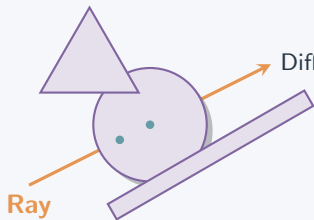
# Ray-Object Intersections

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## Finding Intersections

### Key Objects:

- **Planes** - Linear equations
- **Spheres** - Quadratic equations
- **Triangles** - Barycentric coordinates
- **General Quadrics** - Polynomial solving



**Challenge:** Find the **closest** intersection efficiently!

# Ray-Plane Intersection

## Plane Equation

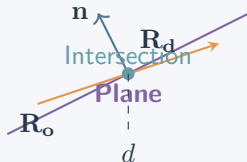
Implicit form:

$$\mathbf{n} \cdot \mathbf{P} + D = 0 \quad (14)$$

Substituting ray equation:

$$\mathbf{n} \cdot (\mathbf{R}_o + t\mathbf{R}_d) + D = 0 \quad (15)$$

$$t = -\frac{D + \mathbf{n} \cdot \mathbf{R}_o}{\mathbf{n} \cdot \mathbf{R}_d} \quad (16)$$



## Key Insight

**Explicit** ray equation meets **implicit** plane equation = Clean intersection formula!

# Ray-Sphere Intersection

## Sphere Equation

Implicit form (centered at origin):

$$\mathbf{P} \cdot \mathbf{P} - r^2 = 0 \quad (17)$$

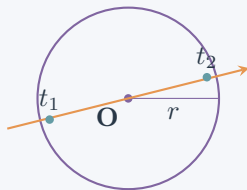
Substituting ray equation:

$$(\mathbf{R}_o + t\mathbf{R}_d) \cdot (\mathbf{R}_o + t\mathbf{R}_d) - r^2 = 0 \quad (18)$$

$$t^2 + 2(\mathbf{R}_d \cdot \mathbf{R}_o)t + (\mathbf{R}_o \cdot \mathbf{R}_o - r^2) = 0 \quad (19)$$

Quadratic formula:  $t =$

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$



Sphere

- $\Delta > 0$ : 2 roots
- $\Delta = 0$ : 1 root
- $\Delta < 0$ : no roots

# Ray-Triangle Intersection

## Barycentric Approach

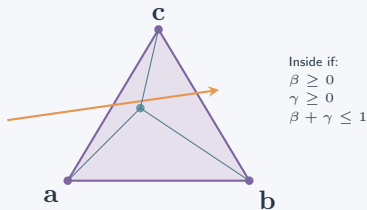
Triangle defined by vertices **a**,  
**b**, **c**:

$$\mathbf{P}(\beta, \gamma) = \mathbf{a} + \beta(\mathbf{b} - \mathbf{a}) + \gamma(\mathbf{c} - \mathbf{a}) \quad (20)$$

Set equal to ray equation:

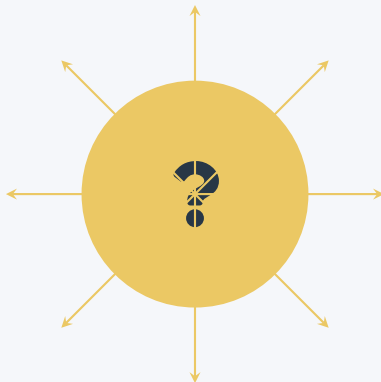
$$\mathbf{R}_o + t\mathbf{R}_d = \mathbf{a} + \beta(\mathbf{b} - \mathbf{a}) + \gamma(\mathbf{c} - \mathbf{a}) \quad (21)$$

Solve  $3 \times 3$  system for  $t, \beta, \gamma$





# Questions?



## References & Further Reading



Peter Shirley and Steve Marschner et al. *Fundamentals of Computer Graphics (4th Edition)*. CRC Press, 2016.

Available as PDF



Matt Pharr, Wenzel Jakob, and Greg Humphreys. *Physically Based Rendering: From Theory to Implementation (4th Edition)*. Morgan Kaufmann, 2023.

Available online



Peter Shirley. *Ray Tracing in One Weekend*. Self-published, 2016–2020.

Project Website



MIT OpenCourseWare: 6.837 Computer Graphics.  
[ocw.mit.edu/6-837](https://ocw.mit.edu/6-837)



Scratchapixel: Learn Computer Graphics Programming.  
[scratchapixel.com](https://scratchapixel.com)