### Rasterization & The Graphics Pipeline

Fast Approximations for Real-Time Graphics

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## Introduction



Valorant - 120 FPS Gaming



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 $\boldsymbol{Up}$  - 30 hours per frame

• Real-time constraint: Games need 60-120 FPS







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Valorant - 120 FPS Gaming



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- Trade-off: Sacrifice physical accuracy for speed



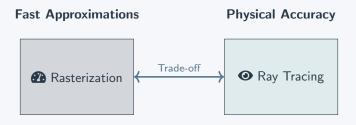
Valorant - 120 FPS Gaming



**Up** - 30 hours per frame

- Real-time constraint: Games need 60-120 FPS
- Interactive experience: User input must feel responsive
- Trade-off: Sacrifice physical accuracy for speed
- Goal: Images that look good enough, delivered fast enough

### Rasterization vs Ray Tracing: The Fundamental Choice



#### Rasterization:

- 60-240 FPS
- · Clever approximations
- Hardware optimized
- "Good enough" quality

#### **Ray Tracing:**

- $\approx 0$  FPS
- Physical simulation
- Computationally heavy
- Photorealistic

### The Real-Time Graphics Challenge

#### Time Budget at 60 FPS

 $\frac{1}{60}=16.67$  milliseconds per frame

#### What needs to happen:

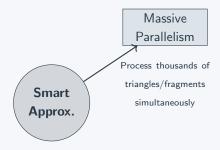
- Process input
- Update game logic
- Render graphics
- Present to screen

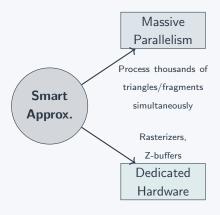
**Graphics budget:**  $\sim$ 10-12ms

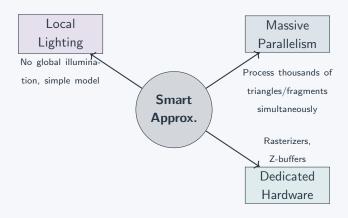
### 16.67ms

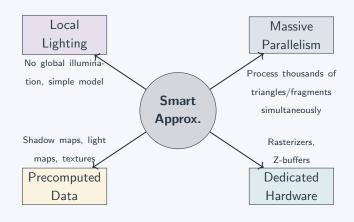












### **The Clever Approximations**

### What We Skip

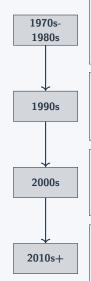
- Global illumination:
   No light bouncing
- Perfect shadows: Use shadow maps
- Perfect reflections:
   Use environment maps
- Complex materials: Simplified BRDFs

#### What We Gain

- Predictable performance: Linear with triangle count
- Hardware optimization:
   Purpose-built silicon
- Real-time interaction:
   Immediate feedback
- Scalable quality: Adjust for performance

# The GPU Evolution

### A Brief History



#### **Software Rendering**

- Everything done on CPU
- Frame rates: 1-10 FPS
- Wireframe graphics

#### **Fixed-Function GPUs**

- 3dfx Voodoo, NVIDIA Riva
- Hardware rasterization
- Fixed pipeline stages

#### **Programmable Shaders**

- DirectX 8.0, OpenGL
- Vertex & Fragment shaders
- Creative freedom

#### **Unified Architecture**

- CUDA, OpenCL
- Compute shaders
- General-purpose



3dfx Voodoo 3 - 1999



NVIDIA GeForce 5090 - 2025

#### **CPU**

4-16 complex cores Large caches Branch prediction Out-of-order execution

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Complex logic Branching Low latency

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Simple operations Same instruction High throughput

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#### **Parallel Tasks**

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### Perfect Match: Graphics + GPU

**Graphics pipeline stages** process thousands of vertices/fragments *independently* 

⇒ Ideal for massively parallel GPU architecture

### Modern GPU: The Graphics Powerhouse

#### Hardware Implementation

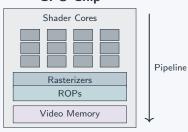
#### **GPU** handles entire pipeline:

- Vertex processing: Shader cores
- Rasterization: Fixed-function units
- Fragment processing: Shader cores
- Memory operations: ROPs

#### **GPU Driver handles:**

- Command submission
- State management
- Resource allocation

### **GPU Chip**



The Modern Graphics Pipeline

#### The Rasterization Process

 GPU process vast numbers of vertices and pixels every frame (millions per second)

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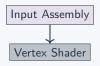
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### The Graphics Pipeline

The graphics pipeline is a sequence of stages that process vertices and fragments in parallel, transforming 3D models into 2D images.

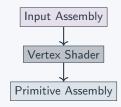
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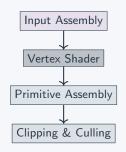
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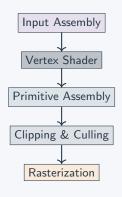
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# Pipeline Stages at a Glance



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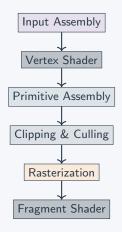
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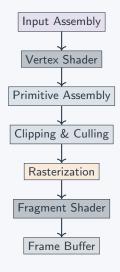
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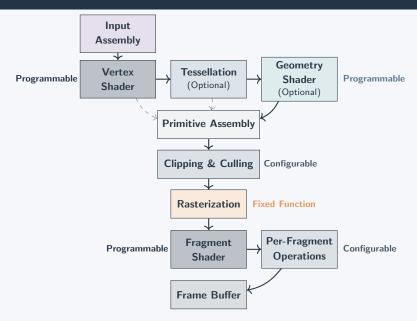
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Fragment Shader: Programmable stage — compute final color of each fragment.

Frame Buffer: Blend, depth-test, and write pixels to the screen.

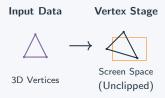
# **Modern Advanced Pipeline**

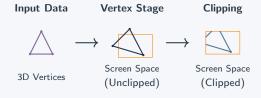


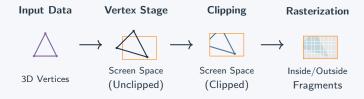
Input Data

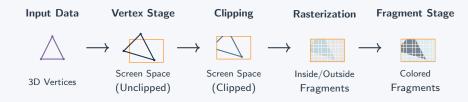


3D Vertices









# **Programmable vs Fixed Function Stages**

#### **Programmable Stages**

#### You write the code:

- Vertex Shader: Transform positions, compute lighting
- **Tessellation:** Subdivide surfaces adaptively
- Geometry Shader: Generate/modify primitives
- Fragment Shader:
   Compute final pixel colors

#### Maximum flexibility

# **Programmable vs Fixed Function Stages**

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Maximum flexibility

#### Fixed Function Stages

#### Hardware handles it:

- Primitive Assembly: Group vertices into triangles
- Clipping: Remove off-screen geometry
- Rasterization: Convert triangles to pixels
- **Depth Testing:** Z-buffer comparisons

Maximum performance

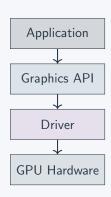
**APIs & Shading Languages** 

## **Graphics APIs Overview**

#### What is a Graphics API?

An **Application Programming Interface** that provides:

- Commands to control the GPU
- Abstraction over hardware differences
- Standard interface for graphics operations



#### OpenGL

#### **Open Graphics Library**

Perhaps the most widely used and most beginner-friendly graphics API. OpenGL was designed to be a cross-platform standard for rendering 2D and 3D graphics.

- Stable APIs
- High-level abstraction
- ♣, ➡, Support
- Two modes -
  - Immediate Mode Deprecated, fixed function (Used by iGraphics)
  - Retained Mode Modern OpenGL, uses shaders



#### Vulkan

Low-overhead, Cross-platform Graphics API Developed by the Khronos Group as a modern successor to OpenGL. Designed for high-performance, multi-threaded rendering.

- Low-level control over GPU
- Better CPU-GPU parallelism
- Explicit memory and resource management
- 🔬, 🛎, 🕊 Support
- Support via MoltenVK



#### DirectX (Direct3D)

# Microsoft's Graphics API for Windows and Xbox

A powerful API suite used primarily for game development on Windows platforms.

- Direct3D for 3D rendering
- Deep integration with Windows OS and drivers
- High performance with hardware vendor optimizations
- ■, Support only



#### Metal

#### Apple's Low-level Graphics API

Designed to maximize performance on Apple devices, replacing OpenGL on Apple platforms.

- Low-overhead, low-level access
- Unified graphics and compute
- Tight integration with Apple hardware
- Support only (macOS, iOS, iPadOS)



# **Shading Languages**

#### **Purpose**

Shading languages allow programmers to write code that runs on the GPU for:

- Vertex processing (transformations)
- Fragment processing (lighting, texturing, effects)
- Compute operations (general-purpose GPU computing)

#### Major Shading Languages:

- GLSL (OpenGL)
- HLSL (DirectX)
- MSL (Metal)
- SPIR-V (Vulkan)
   Can be compiled from GLSL or HLSL

# GLSL: OpenGL Shading Language

#### **GLSL Characteristics**

- C-like syntax
- Built-in vector/matrix types
- Version-specific features

#### **Data Types**

- float, int, bool
- vec2, vec3, vec4
- mat2, mat3, mat4
- sampler2D, samplerCube

```
#version 330 core
// Vertex shader inputs
layout (location = 0) in vec3 aPos;
layout (location = 1) in vec3 aNormal;
layout (location = 2) in vec2 aTexCoord;
// Outputs to fragment shader
out vec3 FragPos;
out vec3 Normal:
out vec2 TexCoord:
// Uniform variables
uniform mat4 model:
uniform mat4 view:
uniform mat4 projection;
void main() {
    FragPos = vec3(model * vec4(aPos, 1.0));
    Normal = mat3(transpose(inverse(model)))
              * aNormal:
    TexCoord = aTexCoord:
    gl_Position = projection
                  * view
                  * vec4(FragPos, 1.0):
```

### **GLSL** Qualifiers

#### Storage Qualifiers

- in Input from previous stage
- out Output to next stage
- uniform Buffer from CPU

#### **Layout Qualifiers**

Used to explicitly assign indices or binding points to resources.

- location Attribute/output index
- binding Texture/uniform buffer slot

```
#version 330 core
// Fragment shader
in vec3 FragPos;
in vec3 Normal;
in vec2 TexCoord:
out vec4 FragColor;
uniform vec3 lightPos;
uniform vec3 viewPos;
uniform sampler2D texture_diffuse1;
void main() {
    vec3 color = texture(texture diffuse1.
                          TexCoord).rgb;
    // Ambient
    vec3 ambient = 0.1 * color:
    // Diffuse
    vec3 norm = normalize(Normal):
    vec3 lightDir = normalize(
                      lightPos - FragPos):
    float diff = max(dot(norm, lightDir).
                      (0.0):
    vec3 diffuse = diff * color;
    // Result
    vec3 result = ambient + diffuse:
    FragColor = vec4(result, 1.0);
```

Input Assembly

# **Input Assembly Stage**

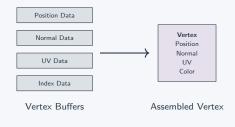
#### **Input Assembly**

**Input:** Vertex data from application

**Output:** Organized vertex streams for vertex shader

#### Purpose:

- Pull vertex data from memory
- Organize data into vertex attributes
- Handle indexed vs non-indexed drawing
- Set up primitive topology



#### Vertex Attributes

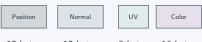
#### **Common Vertex Attributes**

- Position: 3D coordinates (vec3)
- Normal: Surface normal vector (vec3)
- Texture Coordinates: UV mapping (vec2)
- Color: Vertex color (vec3/vec4)

#### **Vertex Layout Example**

$$\mathsf{Vertex} = \begin{cases} \mathsf{Position:} & (x,y,z) \\ \mathsf{Normal:} & (n_x,n_y,n_z) \\ \mathsf{UV:} & (u,v) \\ \mathsf{Color:} & (r,g,b,a) \end{cases}$$

**Total size:** 
$$3 + 3 + 2 + 4 = 12$$
 floats = 48 bytes



12 bytes 12 bytes 8 bytes 16 bytes

# **Primitive Topology**

#### **Primitive Types**

#### Points: Individual vertices

- Used for particle systems
- Point sprites

#### Lines: Connected line segments

- Wireframe rendering
- Debug visualization

#### **Triangles:** Most common primitive

- Standard for 3D surfaces
- Hardware optimized

#### **Points**





### **Triangles**



# **Indexed vs Non-Indexed Drawing**

#### Non-Indexed Drawing

#### Direct vertex specification

Each vertex is specified multiple times for shared vertices.

#### Problem:

- Vertex duplication
- Increased memory usage
- Inefficient for complex meshes

#### **Indexed Drawing**

Vertices referenced by indices Each vertex is stored once, and indices specify how to connect them.

#### Benefits:

- No vertex duplication
- Lower memory usage
- Vertex cache friendly

Non-Indexed

33% less data

Vertices: A, B, C, B, C, D

Vertices: A, B, C, D

Indices: 0. 1. 2. 1. 2. 3

# Vertex Shader

# **Vertex Shader Stage**

#### **Vertex Shader**

**Input:** Individual vertices with attributes

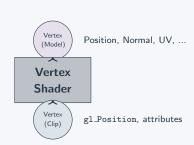
 $\begin{tabular}{lll} \textbf{Output:} & Transformed & vertices & in & clip \\ \end{tabular}$ 

space

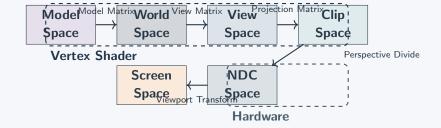
#### Purpose:

- Transform vertex positions through coordinate spaces
- Calculate per-vertex lighting (Gouraud shading)
- Pass attributes to next stage
- Apply animations and deformations

Programmable stage - you write the code!



# The Transformation Pipeline



### **Transformation Matrices**

#### **Model Matrix**

**Purpose:** Object-to-world transformation

$$\mathbf{M} = \mathbf{T} \cdot \mathbf{R} \cdot \mathbf{S}$$

- T: Translation
- R: Rotation
- **S**: Scale

Transforms from model's local coordinates to world coordinates.

#### **View Matrix**

**Purpose:** World-to-camera transformation

V = lookAt(eye, target, up)

Transforms from world coordinates to camera/eye coordinates.

Camera is at origin, looking down -Z axis.

#### **Transformation Matrices**

#### **Projection Matrix**

Purpose: Camera-to-clip space transformation

Perspective:

$$\mathbf{P}_{\mathsf{persp}} = egin{pmatrix} rac{1}{ an(\mathsf{fov}/2) \cdot \mathsf{aspect}} & 0 & 0 & 0 \ 0 & rac{1}{ an(\mathsf{fov}/2)} & 0 & 0 \ 0 & 0 & rac{f+n}{n-f} & rac{2fn}{n-f} \ 0 & 0 & -1 & 0 \end{pmatrix}$$

**Orthographic:** 

$$\mathbf{P}_{\text{ortho}} = \begin{pmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & \frac{-2}{f-n} & -\frac{f+n}{f-n} \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

# **Vertex Shader Example**

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    FragPos = vec3(model * vec4(aPos, 1.0));
    Normal = mat3(transpose(inverse(model)))
              * aNormal:
    TexCoord = aTexCoord:
    gl_Position = projection
                  * view
                  * vec4(FragPos, 1.0):
```

#### **Output Variables**

gl\_Position Clip space position

# **Gourand Shading**

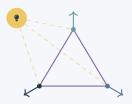
#### Gouraud (Per-Vertex) Shading

Compute lighting at vertices, interpolate across triangles

#### **Process:**

- Calculate lighting at each vertex
- 2. Output vertex color
- 3. Hardware interpolates colors across triangle

**Pros:** Fast, good for distant objects **Cons:** Poor specular highlights, faceted appearance





# **Questions & Discussion**

# Questions?



# References & Further Reading



Matt Pharr, Wenzel Jakob, and Greg Humphreys. *Physically Based Rendering: From Theory to Implementation (4th Edition)*. Morgan Kaufmann, 2023.

Availabe online

Peter Shirley. Ray Tracing in One Weekend. Self-published, 2016–2020.

Project Website

MIT OpenCourseWare: 6.837 Computer Graphics. ocw.mit.edu/6-837

Scratchapixel: Learn Computer Graphics Programming. scratchapixel.com