18: Explain about I/O programming.

Ilo post perogramming is an essential aspect of working with the

soss microcartalles.

The 8051 microcontroller has four ports:

Bat 0 (PO)

Post 1 (P1)

Post 2 (P2)

Post 3 (P3)

These posts can be used for both enput and output operations, allowing you to enterface with external devices such as sensons,

displays, and other perphenals.

Common Oberapare for I/O bory brodrammend:

Configuring I/O Posts:

Before mind I/O bony don used to contiders of ar eights subnit on ambig.

Each part per can be endivedually confequed as exput (loger high

empendance) or output (logic low empendance) using corresponding tells in post's associated register.

Existo configure P1 as output and P2 as Proput.

MON 67, # OXEE

MON 65, #0x00

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11) Reading from Irput Posts:

To nead statue of Proput pans of a post, you can use post's associated neglisten.

>> The values sead from siegistes indicate logic level of pins.

A logic high(1) indicates pin is necreving high voltage, while a logic low(0) indicates low voltage.

Ex: To read status of P3 and store an accumulator (A).

MONA, P3

ing Marked to ontbut bonts:

To see the output values of pans on output post, you can use post's associated segistes. Summer of has all of willing of mineral

Waithough a logic highles to part sets at to a high vallage level and logic lowlow and rest to low voltage level.

Ex: To set PO to high and PI to low.

MOV PO, #0xFF MOV PI, #0x00

in Manspulating Indiredual Ans:

Sometimes, we need to manipulate individual pans of posts, while keeping others unchanged.

We can acheeve their using bit wise operations such as AND, OR, and bit shifteng.

Ex: To topple state pin of P2.3 while keeping other pins of P2 unchanged.

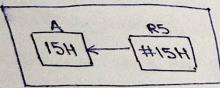
CPL P2.3

- We External Pull-UplDown Resistors:
 - The 8051 mRcocontroller doesn't have enternal Pull-UplDown resistors.
- If you want to use external pull-upldown restistors for Phput pins.

 The you need to consect them externally to the corresponding
- Rh Walte about addressing modes of 8051.
- Addressing modes is defined as way of specifying operand in an instruction
- >> In 8051 there are 6 types of addressing modes:
 - 1/2 Immediate addressing mode
 - Pip Register addressing made
 - Piil Draect addressing mode
 - Puls Register Indirect addressing made
 - up Indexed Addressing mode
 - vib Impleed addressing mode
 - Immediate addressing made:
 - In this, data is provided in instruction etself. The data is provided immediately after operate. Data constant value.

-> & mmedrate data " of inchist & DPTR-> data pornier pornis external data memory locatear.

In this, source on destination data should be present in 28 to plan grosselle hade stail to pure en Louisburg 30000



Regseles to Register transfer.

Pup

>>

Draect addressing modess

In this, source on destination data is specified by 8-624 data Presouction.

Only enternal memory can be used in this made.

Example:

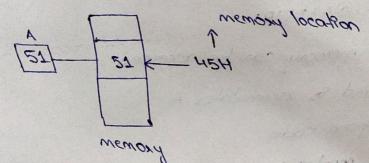
1/2 MOV 80H, RG

MOV R2, 45H

MOV RO, OSH

2/2 MON RO, 45H

ADD A, 51H



Register indirect addressing mades:

In thes, source or destration address es given en register.

By using this, internal on external addresses can be addressed.

The Ro and RI are used for 8-694 addresses and OPTR 95

used for 16-694 addresses, no other negisters can be used for

addressed barboses.

Examples

MOU A, @ Ro

@ -> points address

