

CONTACT
INFORMATIONEmail : rishkumar2345@gmail.comWebsite : <https://rishav.github.io/>

EDUCATION

B.E. Computer Science, Birla Institute of Technology & Science, Pilani*Aug'16 - Jul'20*PROFESSIONAL
EXPERIENCE**Augmented Vision, DFKI***Kaiserslautern, Germany**Research Engineer**Feb'21-Present*

- Working with [Prof. Dr. Didier Stricker](#) on real time algorithms for precision agriculture. The work involves estimating the precise amount of herbicide/fertilizer needed for crop/weed.
- Status : Designed algorithms for unsupervised cross-spectral stereo matching and growth-stage invariant semantic segmentation. Increased the speed from 1.3 fps to 24 fps on NVIDIA AGX using quantization and knowledge distillation.

Wells Fargo EGS*Hyderabad, India**Software Engineer**Aug'20-Feb'21*

- Worked with capital markets team of Wells Fargo. Developed an automated real-time tool for monitoring of ETL jobs which previously needed to be monitored manually. *Stack : ReactJS & SpringBoot*
- Coordinated the EPL migration of the trading platform of Wells Fargo.

PUBLICATIONS

[1] [Rishav*](#), Ramy Battrawy*, et. al. [DeepLiDARFlow: A Deep Learning Architecture For Scene Flow Estimation Using Monocular Camera and Sparse LiDAR](#). In *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS-2020)*.

[2] [Rishav*](#), René Schuster*, et. al. [ResFPN: Residual Skip Connections in Multi-Resolution Feature Pyramid Networks for Accurate Dense Pixel Matching](#). In *IEEE International Conference on Pattern Recognition (ICPR-2020)*, **Oral (top 6%)**.

INTERNSHIPS

Chloropy Tech, Singapore*Research Intern**May'20-Jul'20*

- Developed an unsupervised learning algorithm for estimating crop depth (height) using drone videos.
- Assisted in curating the dataset for training the algorithm and later used cross sequence depth consistency to generate quality depth maps.

Augemented Vision, DFKI, Germany*Research Intern**Jun'19-Dec'19*

- Worked on deep learning for end-to-end prediction of scene flow using monocular images and sparse LiDAR measurements.
- The algorithm utilized sparse LiDAR and RGB information and via mutual improvement and significantly improved the performance in regions difficult to match using RGB only. Work was presented at IROS-2020.

Pixxel, Bengaluru*Research Intern**May'18-Aug'18*

- Worked on Deep Learning algorithms for cleaning of bands in hyperspectral images, used google BigQuery for accessing LANDSAT (multispectral) data. Implemented HSID-CNN for denoising hyperspectral images and deployed on google cloud.

IMPLEMENTATION
PROJECTS

- Compiler Construction : Compiler for a given language specification in C [\[code\]](#)
- CycleGAN for unsupervised cross spectral stereo matching [\[code\]](#)
- HSID-CNN : 3D CNN based architecture for denoising hyperspectral images [\[code\]](#)

PROFESSIONAL
ACTIVITIES

- Head Teaching Assistant for Neural Networks and Fuzzy Logic for spring semester 2019-2020.
- Team Leader for Project Gyanbodh by Nirmaan Organisation for promoting creative learning amongst kids (2018-2020).
- Senior Member at BITS-ACM, the ACM student chapter at BITS Pilani. (2017-2020)