### Solving Linear Equations

Linear Algebra

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# Recap

- We have established the importance and usefulness of matrix theory and linear algebra in data sciences
- · Concepts covered previously
  - · Data representation using matrices
  - · Identifying linear relationships (if any) among attributes
- · How do we establish these linear relationships?
  - · Using null space
  - We will now focus on extracting solutions for matrix equations



# **SOLVING MATRIX EQUATIONS**



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### **Preliminaries**

• We consider the following set of equations

$$Ax = b$$

$$A(m \times n); x(n \times 1); b(m \times 1)$$

- Generalized linear equations can be represented in the above format.
- *m* and *n* are the number of equations and variables respectively.
- **b** is the general RHS commonly used



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## Categorization

- m = n
- · Number of equations and variables are the same
- · Easiest case to solve
- m > n
- · More equations than variables
- · Usually no solution
- m < n
- · Number of equations less than number of variables
- Usually multiple solutions

We look into these cases independently



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# Full row and column rank: Concepts

• Consider a matrix data matrix  $A(m \times n)$ 

#### Full Row Rank

- When all the rows of the matrix are linearly independent
- Data sampling does not present a linear relationship – samples are independent

#### Full Column Rank

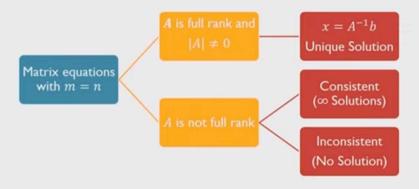
- When all the columns of the matrix are linearly independent
- Attributes are linearly independent

Row rank = Column rank



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### Case 1: m = n



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# Case 1: Example 1.1

$$\begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 7 \\ 10 \end{bmatrix}$$

R Code A=matrix(c(1,2,3,4),ncol=2, byrow=F) b=c(7,10) x=solve(A)%\*%b

$$|A| \neq 0$$
  
 $rank(A) = 2 = no. of columns$ 

. This implies that A is full rank

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}^{-1} \begin{bmatrix} 7 \\ 10 \end{bmatrix} = \begin{bmatrix} -2 & 1.5 \\ 1 & -0.5 \end{bmatrix} \begin{bmatrix} 7 \\ 10 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

• Thus, the solution for the given example is  $(x_1, x_2) = (1,2)$ 

Console output

[,1]

[1,] 1 [2,] 2



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# Case 1: Example 1.2

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 10 \end{bmatrix}$$

$$|A| = 0$$
;  $rank(A) = 1$ ;  $nullity = 1$ 

· Checking consistency

$$\begin{bmatrix} x_1 + 2x_2 \\ 2x_1 + 4x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 10 \end{bmatrix}$$

$$Row(2) = 2Row(1)$$

- The equations are consistent with only one linearly independent equation
- The solution set for  $(x_1, x_2)$  is infinite because we have only one linearly independent equation and 2 variables

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# Case 1: Example 1.3

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 9 \end{bmatrix}$$

$$|A| = 0$$
  
 $rank(A) = 1$   
 $nullity = 1$ 

Checking consistency

$$\begin{bmatrix} x_1 + 2x_2 \\ 2x_1 + 4x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 9 \end{bmatrix}$$

$$2Row(1) = 2x_1 + 4x_2 = 10 \neq 9$$

- · Thus the equations are inconsistent
- One cannot find a solution to  $(x_1, x_2)$

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### Case 2: m > n

- This is the case of not enough variables or attributes
- Since the number of equations is greater than the number of variables, in general, not all equations can be satisfied
- Hence it is sometimes termed as a no-solution case
- However, we can identify an appropriate solution by viewing this case from an optimization perspective



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# Case 2: An optimization perspective

- Instead of identifying a solution to Ax b = 0, one can identify an x such that (Ax b) is minimized
- Notice that (Ax b) is a vector
- There will be as many error terms as the number of equations
- Denote (Ax b) = e(mx1); there are m errors  $e_i$ , i = 1: m
- One could minimize all the errors collectively by minimizing  $\sum_{i=1}^{m} e_i^2$
- This is the same as minimizing  $(Ax b)^T (Ax b)$



# Case 2: An optimization perspective

· This optimization problem is

$$\min[(Ax - b)^{T}(Ax - b)]$$

$$= \min[(b^{T} - x^{T}A^{T})(Ax - b)]$$

$$= \min[(x^{T}A^{T}Ax - 2b^{T}Ax + b^{T}b) = f(x)]$$

- We observe that the optimization problem is a function of x
- Solving the optimization problem will result in a solution for x
- The solution to this optimization problem is obtained by differentiating f(x) with respect to x and setting the differential to zero

$$\nabla f(x) = 0$$



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# Case 2: An optimization perspective

• Differentiating f(x) and setting the differential to zero results in

$$2(A^T A)x - 2A^T b = 0$$
$$(A^T A)x = A^T b$$

· Assuming that all the columns are linearly independent

$$x = (A^T A)^{-1} A^T b$$

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