

Linear Algebra – Distance, Hyperplanes and Halfspaces, Eigenvalues, Eigenvectors

Review

- So far we have discussed linear algebra and matrix theory from a data science perspective
- We will provide some geometric interpretations now
- This section covers the following
 - Vectors
 - Notion of distance
 - Projections
 - Hyperplanes
 - Halfspaces
 - Eigenvalues and eigenvectors

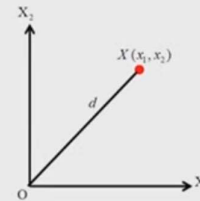
Vectors and lengths

- Consider

$$\mathbf{X} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

- \mathbf{X} is a data point in a 2 dimensional plane with x_1 and x_2 as the distances along the \mathbf{X}_1 and \mathbf{X}_2 axes respectively.
- \mathbf{X} can also be considered as a vector between the origin and the data point
- The length (magnitude) of this vector is

$$d = \sqrt{x_1^2 + x_2^2}$$



Vectors and lengths: Example

- Consider the point $A = (3,4)$ in a two dimensional plane

$$A = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$d = \sqrt{3^2 + 4^2} = 5 \text{ units}$$

- Important: Geometric concepts are easier to visualize in 2D or 3D
- Difficult to do so in the higher dimensions
- However, the fundamental mathematics remain the same irrespective of the dimension of the vector



Vectors and distances

- Consider another example with two points X^1 and X^2

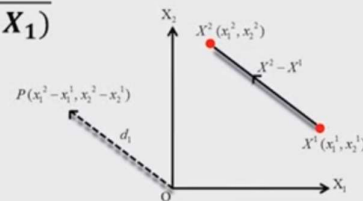
$$\mathbf{X}^1 = \begin{bmatrix} x_1^1 \\ x_2^1 \end{bmatrix} \quad \mathbf{X}^2 = \begin{bmatrix} x_1^2 \\ x_2^2 \end{bmatrix}$$

- The distance between these two can be calculated

$$l = \|\mathbf{X}^2 - \mathbf{X}^1\|_2$$

$$l = \sqrt{(x_1^2 - x_1^1)^2 + (x_2^2 - x_2^1)^2}$$

$$l = \sqrt{(\mathbf{X}_2 - \mathbf{X}_1)^T (\mathbf{X}_2 - \mathbf{X}_1)}$$



Vectors and distances: Example

- What is the distance between points A and B , where A is $(2,7)$ and B is $(5,3)$
- Using the concept of distance introduced before

$$A = \begin{bmatrix} 2 \\ 7 \end{bmatrix}, B = \begin{bmatrix} 5 \\ 3 \end{bmatrix}$$

$$l = \sqrt{(5 - 2)^2 + (3 - 7)^2}$$

$$l = 5 \text{ units}$$

Unit vector

- A unit vector is a vector with magnitude 1 (distance from origin)
- Unit vectors are used to define directions in a coordinate system
- Any vector can be written as a product of a unit vector and a scalar magnitude

$$A = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$\text{Magnitude of A: } |A| = \sqrt{3^2 + 4^2} = 5$$

$$\hat{a} = \frac{A}{|A|} = \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}$$



Orthogonal vectors

- Two vectors are orthogonal to each other when their dot product is 0
- Dot product (scalar product) of two n dimensional vectors A and B

$$A \cdot B = \sum_{i=1}^n a_i b_i$$

- Thus the vectors A and B are orthogonal to each other if and only if

$$A \cdot B = \sum_{i=1}^n a_i b_i = A^T B = 0$$



Orthogonal vectors: Example

- Consider the vectors v_1 and v_2 in 3D space. Identify if they are orthogonal to each other

$$v_1 = \begin{bmatrix} 1 \\ -2 \\ 4 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} 2 \\ 5 \\ 2 \end{bmatrix}$$

R Code
`v1=c(1,-2,4)`
`v2=c(2,5,2)`
`N=t(v1)%*%v2`

Console Output
`> N`
`[,1]`
`[1,] 0`

- Taking the dot product of the vectors

$$v_1 \cdot v_2 = V_1^T V_2 = [1 \ -2 \ 4] \begin{bmatrix} 2 \\ 5 \\ 2 \end{bmatrix} = 0$$

- Hence, the vectors are orthogonal

Orthonormal vectors

- Orthonormal vectors are orthogonal vectors with unit magnitude
- Example

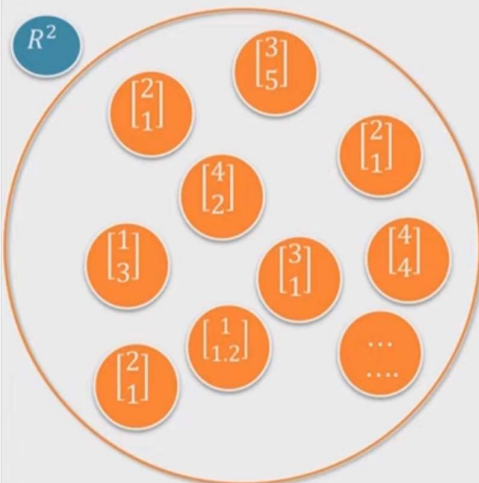
$$v_1 = \begin{bmatrix} 1 \\ -2 \\ 4 \end{bmatrix} / \sqrt{1^2 + (-2)^2 + 4^2}$$

$$v_2 = \begin{bmatrix} 2 \\ 5 \\ 2 \end{bmatrix} / \sqrt{2^2 + 5^2 + 2^2}$$

- Note that we have taken the vectors from the previous example and converted them into unit vectors by dividing them with their magnitudes.
- All orthonormal vectors are orthogonal



Basis vectors



Let us consider two vectors $v_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$$\begin{bmatrix} 2 \\ 1 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 2v_1 + 1v_2$$

$$\begin{bmatrix} 4 \\ 4 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 4 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 4v_1 + 4v_2$$

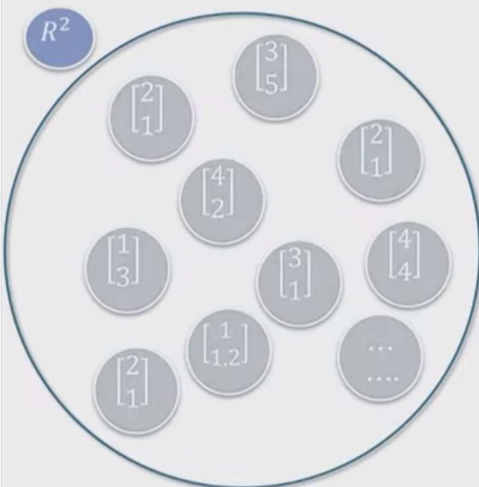
$$\begin{bmatrix} 1 \\ 3 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 1v_1 + 3v_2$$

v_1 and v_2 are the basis vectors for R^2

Basis vectors

- Basis vectors are set of vectors that are independent and span the space
- Example:
 - Two vectors $v_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$
 - Can span R^2 and are independent and hence form the basis for the R^2 space.

Basis vectors are not unique



Consider two vectors $v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

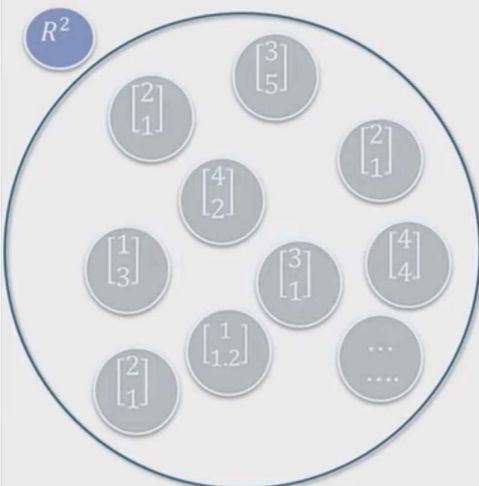
$$\begin{bmatrix} 2 \\ 1 \end{bmatrix} = 1.5 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + (+0.5) \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 1.5v_1 + (+0.5)v_2$$

$$\begin{bmatrix} 4 \\ 4 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 4v_1 + 0v_2$$

$$\begin{bmatrix} 1 \\ 3 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + (-1) \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 2v_1 + (-1)v_2$$

Hence, this v_1 and v_2 are also basis vectors for R^2

Basis vectors are not unique



Consider two vectors $v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

$$\begin{bmatrix} 2 \\ 1 \end{bmatrix} = 1.5 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + (+0.5) \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 1.5v_1 + (+0.5)v_2$$

$$\begin{bmatrix} 4 \\ 4 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 4v_1 + 0v_2$$

$$\begin{bmatrix} 1 \\ 3 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + (-1) \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 2v_1 + (-1)v_2$$

Hence, this v_1 and v_2 are also basis vectors for R^2

Basis vectors

$$\begin{bmatrix} 6 \\ 5 \\ 8 \\ 11 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 9 \\ 4 \\ 7 \\ 10 \end{bmatrix}, \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 14 \\ 7 \\ 12 \\ 17 \end{bmatrix}, \begin{bmatrix} 11 \\ 8 \\ 13 \\ 18 \end{bmatrix}, \begin{bmatrix} 7 \\ 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ -4 \\ -5 \end{bmatrix}, \begin{bmatrix} 7 \\ 7 \\ 11 \\ 15 \end{bmatrix}, \dots$$

Consider two vectors $v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 4 \\ 1 \\ 2 \\ 3 \end{bmatrix}$

$$\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} + 0 \begin{bmatrix} 4 \\ 1 \\ 2 \\ 3 \end{bmatrix} = 1v_1 + 0v_2$$

$$\begin{bmatrix} 7 \\ 7 \\ 11 \\ 15 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} + 1 \begin{bmatrix} 4 \\ 1 \\ 2 \\ 3 \end{bmatrix} = 3v_1 + 1v_2$$

Finding basis vectors

$$\begin{bmatrix} 6 \\ 5 \\ 8 \\ 11 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 9 \\ 4 \\ 7 \\ 10 \end{bmatrix}, \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 14 \\ 7 \\ 12 \\ 17 \end{bmatrix}, \begin{bmatrix} 11 \\ 8 \\ 13 \\ 18 \end{bmatrix}, \begin{bmatrix} 7 \\ 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ -4 \\ -5 \end{bmatrix}, \begin{bmatrix} 7 \\ 7 \\ 11 \\ 15 \end{bmatrix}$$

To find basis vectors of the given set of vectors, arrange the vectors as shown below

$$\begin{bmatrix} 6 & 1 & 9 & -3 & 3 & 14 & 11 & 7 & 2 & 7 \\ 5 & 2 & 4 & 1 & -1 & 7 & 8 & 0 & -3 & 7 \\ 8 & 3 & 7 & 1 & -1 & 12 & 13 & 1 & -4 & 11 \\ 11 & 4 & 10 & 1 & -1 & 17 & 18 & 2 & -5 & 15 \end{bmatrix}$$

$$\begin{bmatrix} 6 \\ 5 \\ 8 \\ 11 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 9 \\ 4 \\ 7 \\ 10 \end{bmatrix}, \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ -1 \\ -1 \end{bmatrix},$$

$$\begin{bmatrix} 14 \\ 7 \\ 12 \\ 17 \end{bmatrix}, \begin{bmatrix} 11 \\ 8 \\ 13 \\ 18 \end{bmatrix}, \begin{bmatrix} 7 \\ 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ -4 \\ -5 \end{bmatrix}, \begin{bmatrix} 7 \\ 7 \\ 11 \\ 15 \end{bmatrix}$$

$$\begin{bmatrix} 6 \\ 5 \\ 8 \\ 11 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 9 \\ 4 \\ 7 \\ 10 \end{bmatrix}, \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ -1 \\ -1 \end{bmatrix},$$

2 basis $8(2 \times 4)$
 $198 \times 2 \quad 396$
404

$$\begin{bmatrix} 6 & 1 & 9 & -3 & 3 & 14 & 11 & 7 & 2 & 7 \\ 5 & 2 & 4 & 1 & -1 & 7 & 8 & 0 & -3 & 7 \\ 8 & 3 & 7 & 1 & -1 & 12 & 13 & 1 & -4 & 11 \\ 11 & 4 & 10 & 1 & -1 & 17 & 18 & 2 & -5 & 15 \end{bmatrix}$$