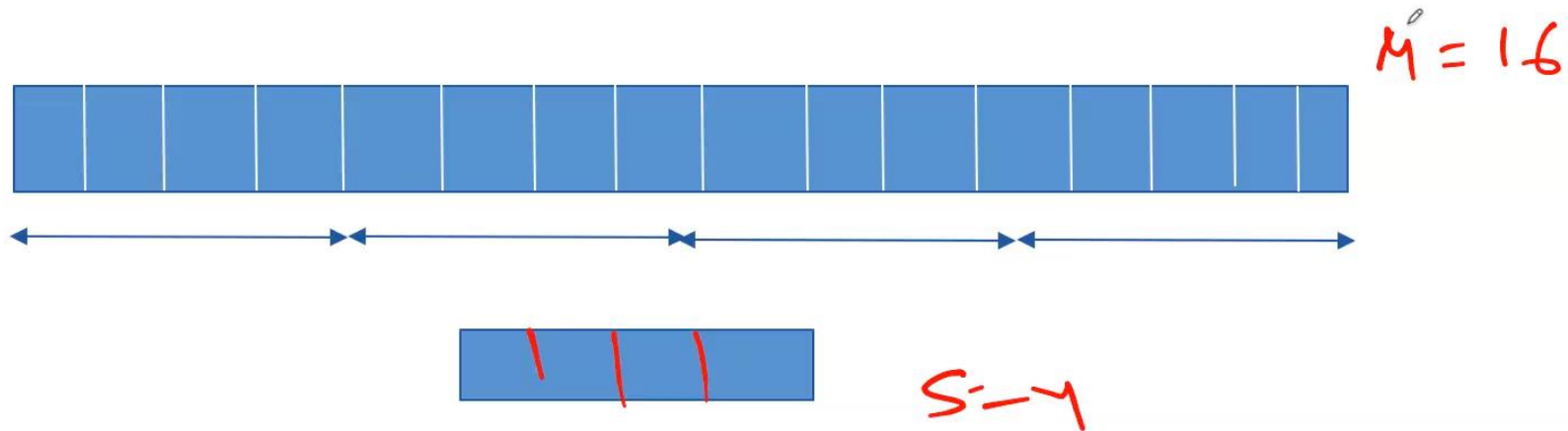
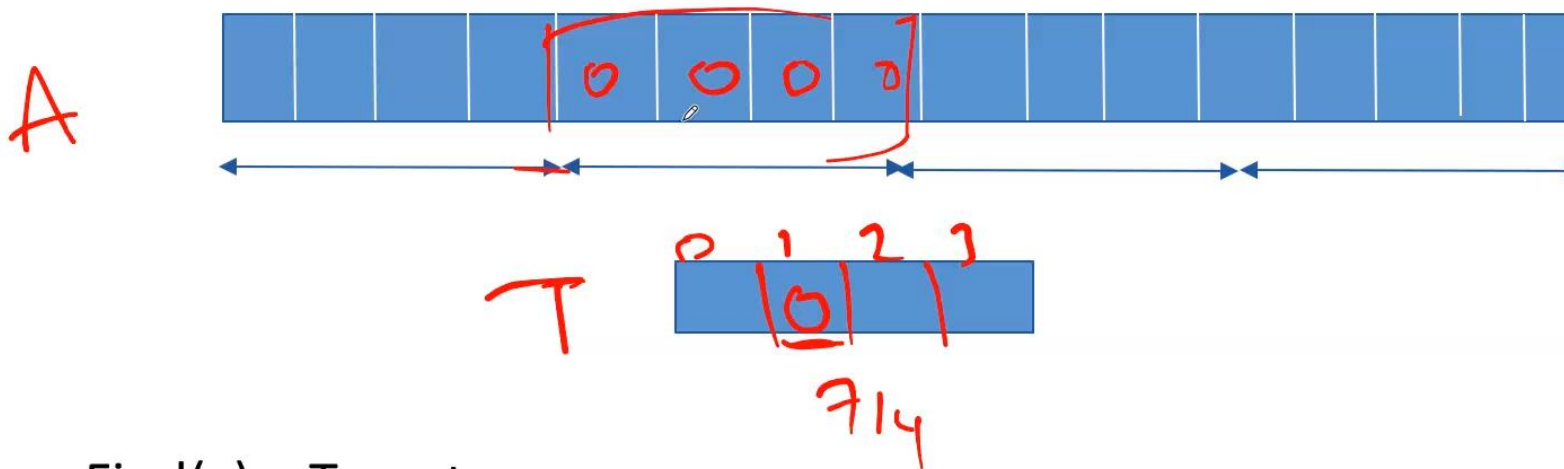


Tiered Bit Vectors



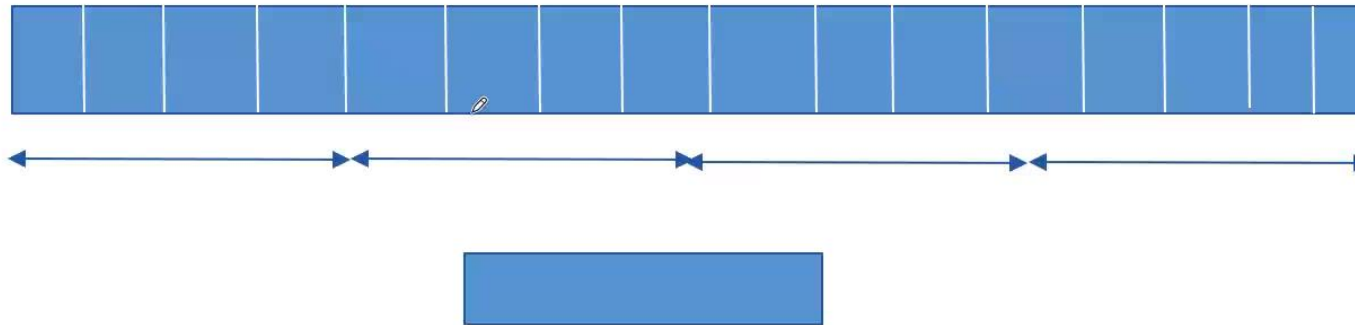
- Formally, let s be a parameter.
- The array A is partitioned into A/s pieces and the array T is of size s .

Operations on Tiered Bit Vectors



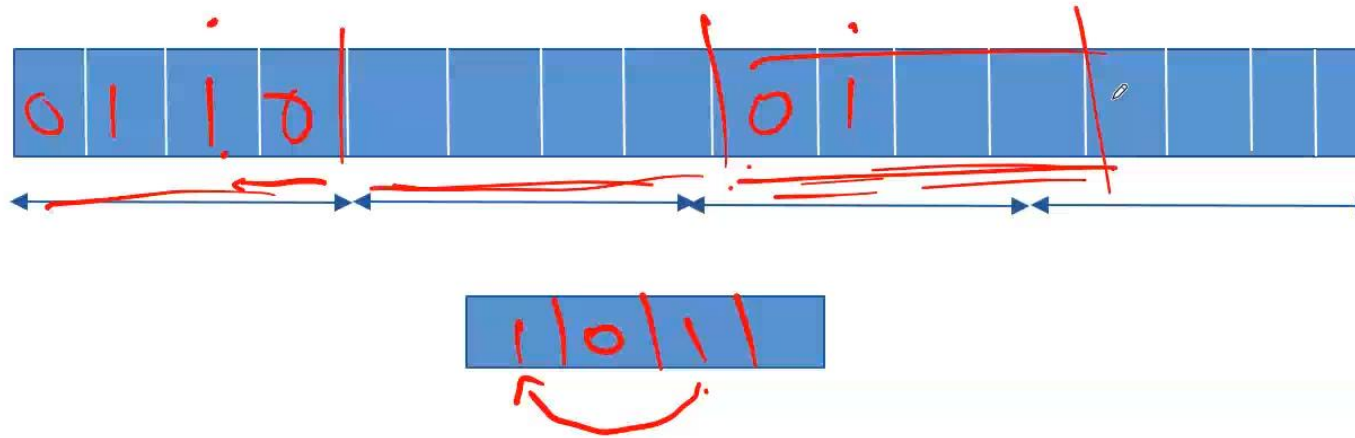
- Find(x) – Two steps
 - Otherwise, check for x in array $A_{x/s}$.
- Each Find(x) is therefore translated to one isempty() query and one find on a small array.

Operations on Tiered Bit Vectors



- $\text{Min}()$ should return the value of the smallest present element.
- Find the minimum value in the smaller vector, say j .
- Suggests that $T[j]$ is 1 and all other $T[i]$ if $i < j$ are 0.
- Find minimum in A
- In essence, $\text{Min}()$ translates to two $\text{Min}()$ operations on smaller vectors.

Operations on Tiered Bit Vectors

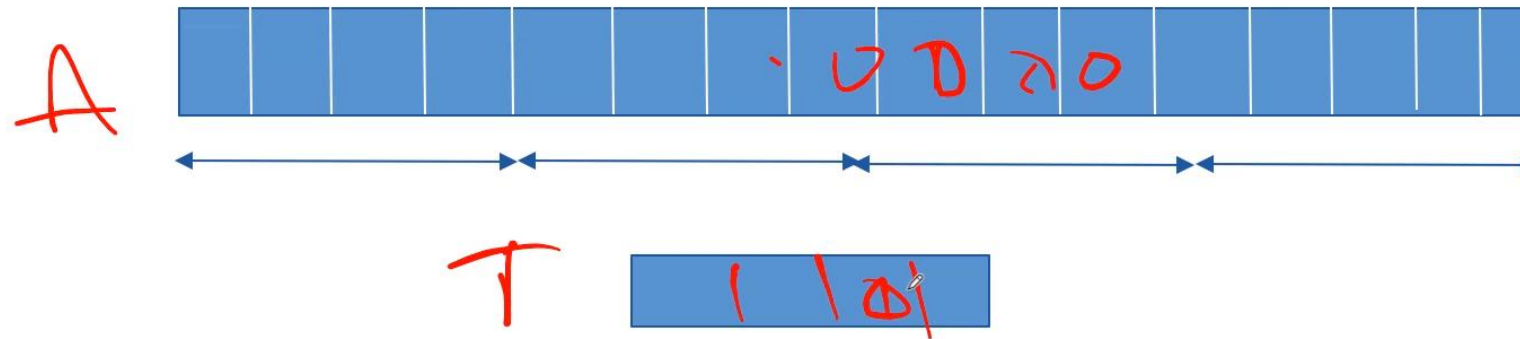


- Prev(x) – Again multiple steps on smaller vectors.

- Find Min() in the vector $A_{x/s}$.
- If the answer is different from x, return.
- Otherwise, find $j = \text{Prev}(x/s)$ in the smaller vector.
- Find Max() in A_j .

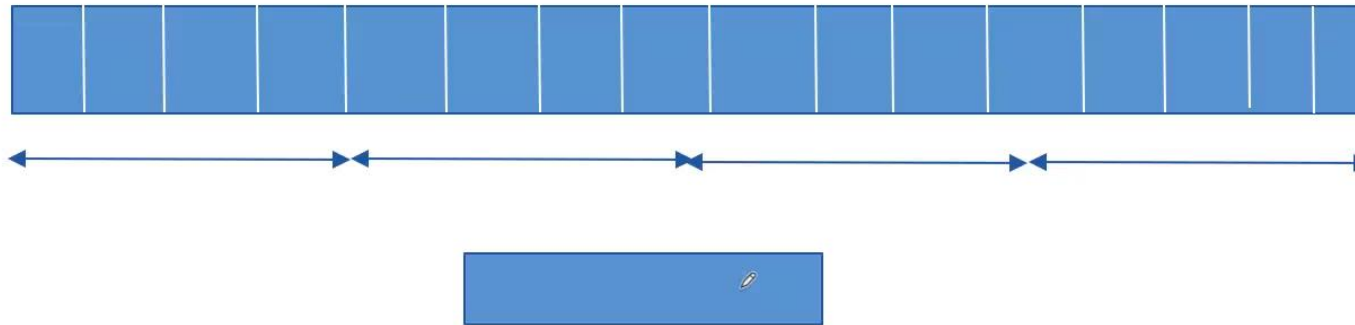
- Each Prev(x) is translated to two Prev() queries. Same with Next(x).

Operations on Tiered Bit Vectors



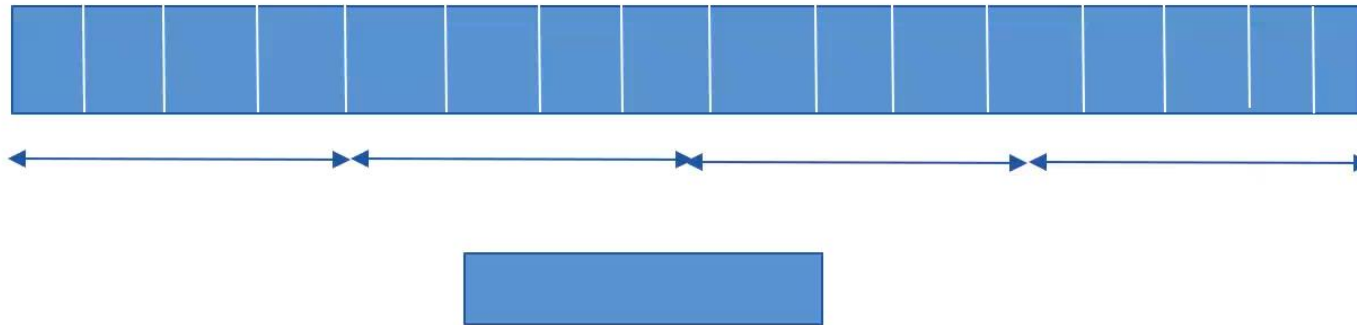
- Delete(x) – Again two steps
 - Mark $A[x]$ in $A_{x/s}$ as 0.
 - If all entries in $A_{x/s}$ are 0, then set $T[x/s]$ to 0.

Operations on Tiered Bit Vectors



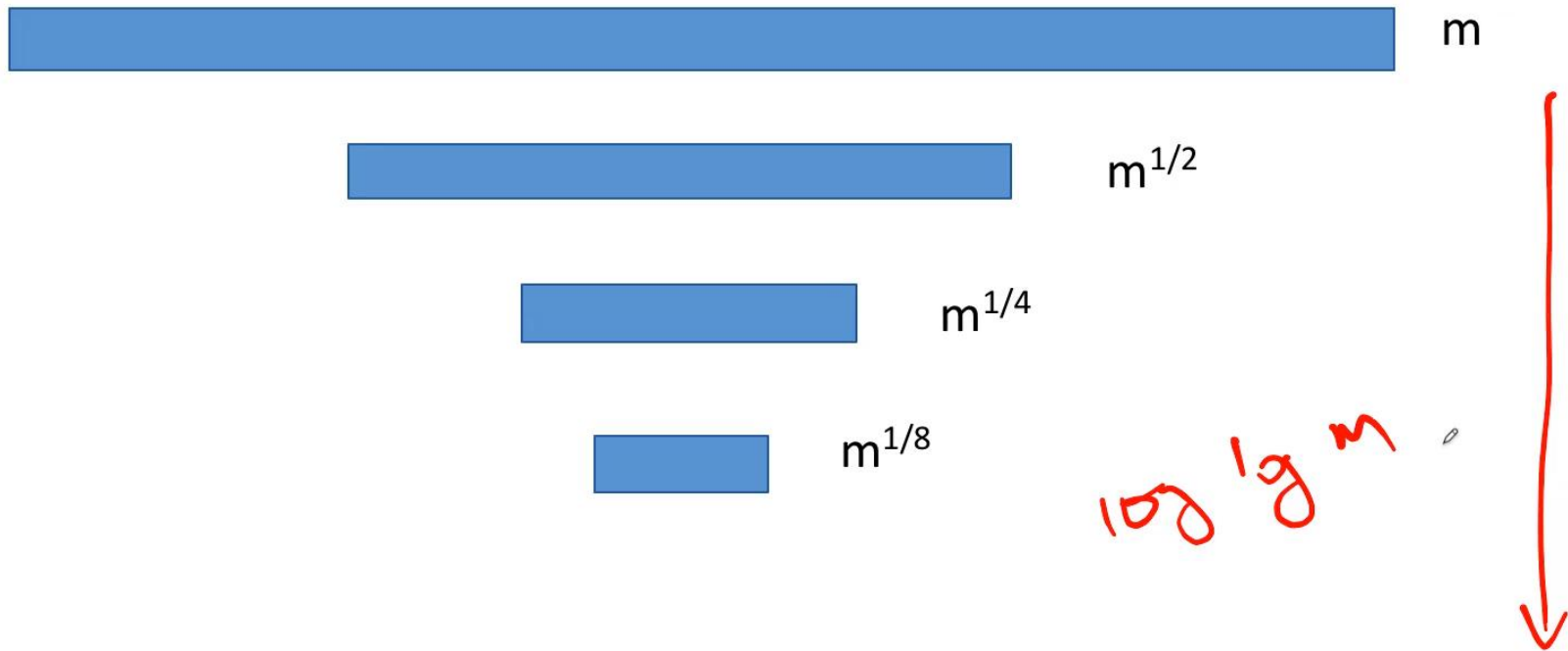
- Each operation turns into operations on smaller arrays as follows. Time taken is:
 - insert: 2x insert – $O(1)$
 - find : 1x lookup – $O(1)$
 - is-empty: 1x
 - min: 2x min – $O(s + m/s)$
 - next: 1x next, 1x max, 1x min – $O(s+m/s)$
 - delete: 2x delete, 1x is-empty – $O(s+m/s)$

Operations on Tiered Bit Vectors



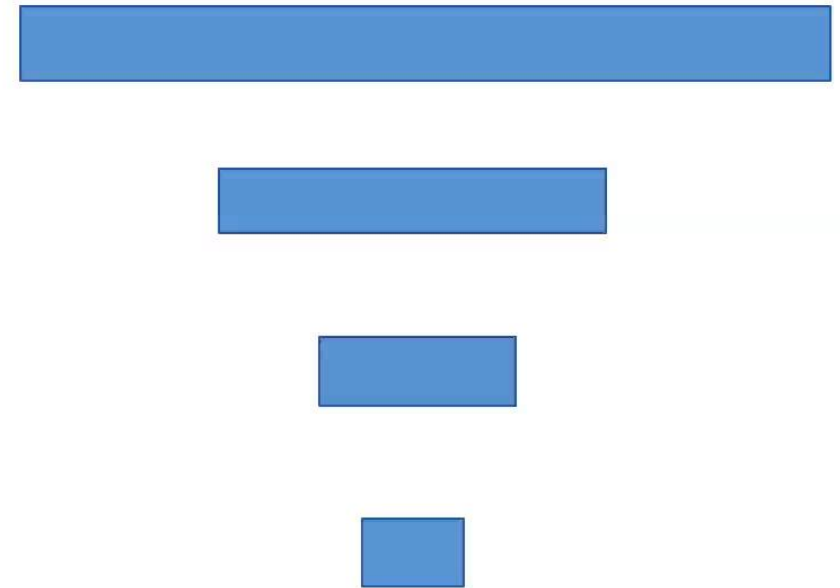
- Each operation turns into operations on smaller arrays as follows.
Time taken is:
 - The run time of $O(s+m/s)$ is seen to be minimized when $s = \sqrt{m}$.
 - In other words, all operations finish in time $O(\sqrt{m})$.
 - Some operations are much faster.
 - Not a good solution – BST much better.

Extending Tiered Bit Vectors



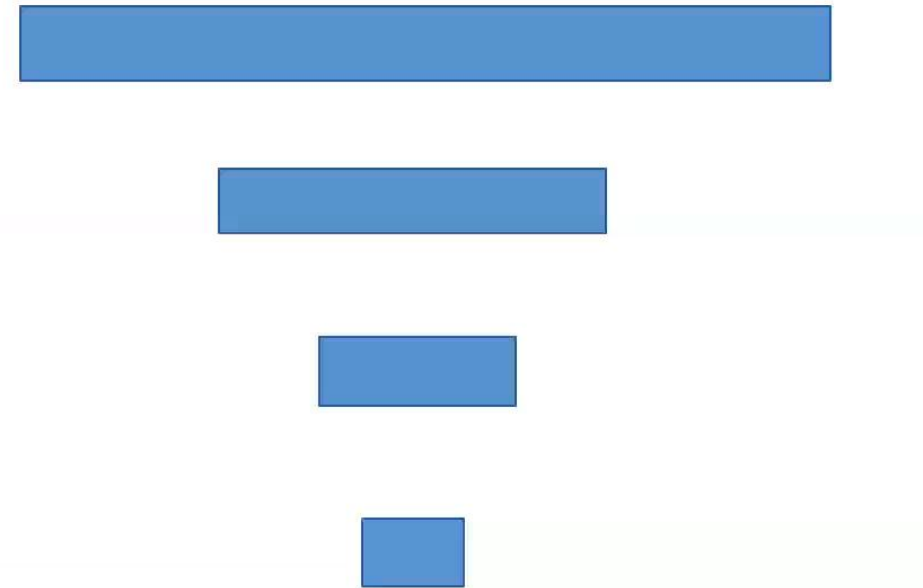
Extending Tiered Bit Vectors

- A helpful view is to see the two levels of the hierarchy as forming $1+m^{1/2^i}$ smaller vectors at level i .



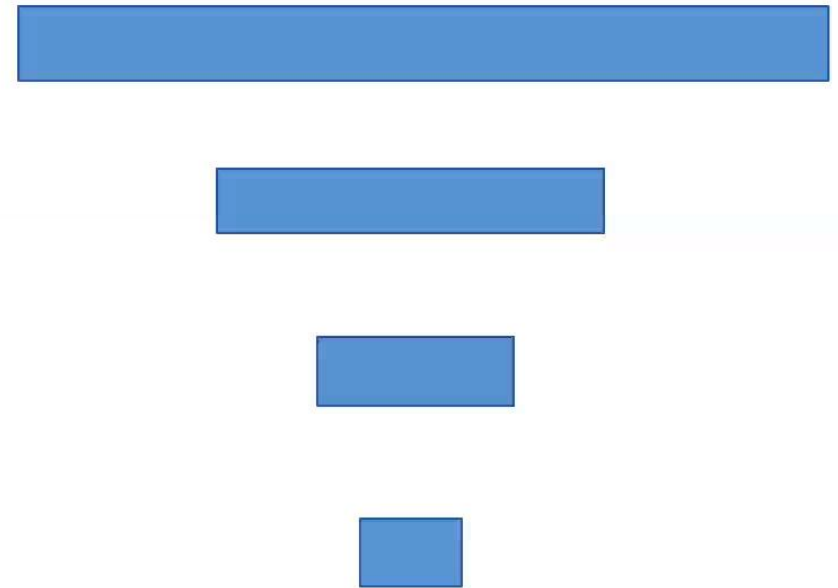
Operations on Extended Tiered Bit Vectors

- Consider the set of operations again.
 - Insert: 2x insert, at each recursive level.
 - Find : 1x lookup – but can say lookup in a smaller bit vector.
 - is-empty: 1x is-empty, but can say on a smaller bit vector
 - min: 2x min, one each at a smaller level
 - next: 1x next, 1x max, 1x min, at a smaller level
 - delete: 2x delete at a smaller level, 1x is-empty,



Operations on Extended Tiered Bit Vectors

- Consider the set of operations again.
 - Find : 1x lookup – but can say lookup in a smaller bit vector.
Time : $T(m) = T(\sqrt{m}) + O(1)$
Solution: $T(m) = O(\log \log m)$.



Extending Tiered Bit Vectors

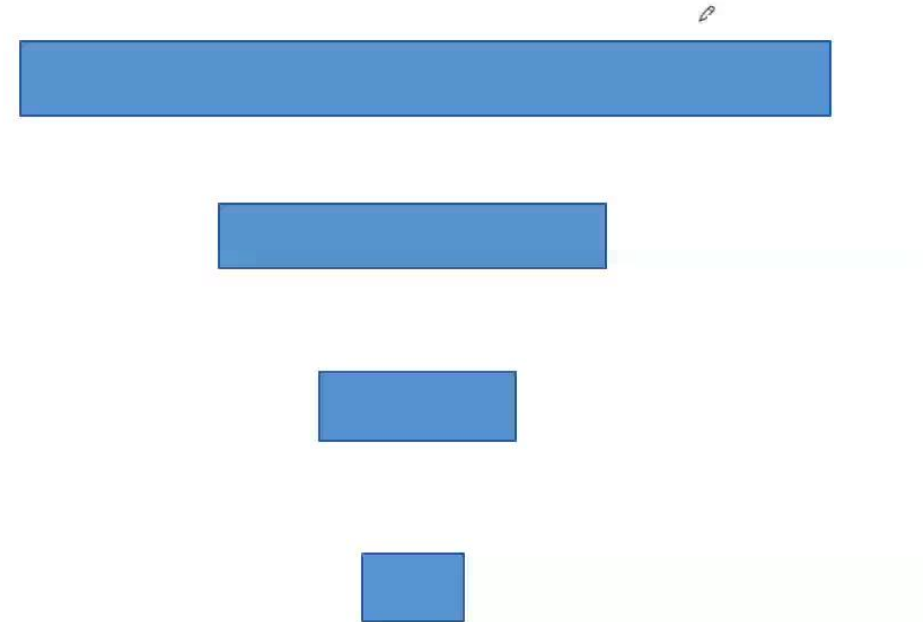
Proposition 1. $T(U) = T(\sqrt{U}) + O(1) = O(\log \log U)$.

Proof. Let $m = \log U \Rightarrow U = 2^m$. Our recurrence relation is now: $T(2^m) = T(2^{\frac{m}{2}}) + O(1)$. Let $S(m) = T(2^m)$, then we have that: $S(m) = S(\frac{m}{2}) + O(1)$. By case 2 of the master method, $S(m) = O(\log m)$. Therefore, $T(U) = T(2^m) = S(m) = O(\log m) = O(\log \log U)$. [?] \square



Operations on Extended Tiered Bit Vectors

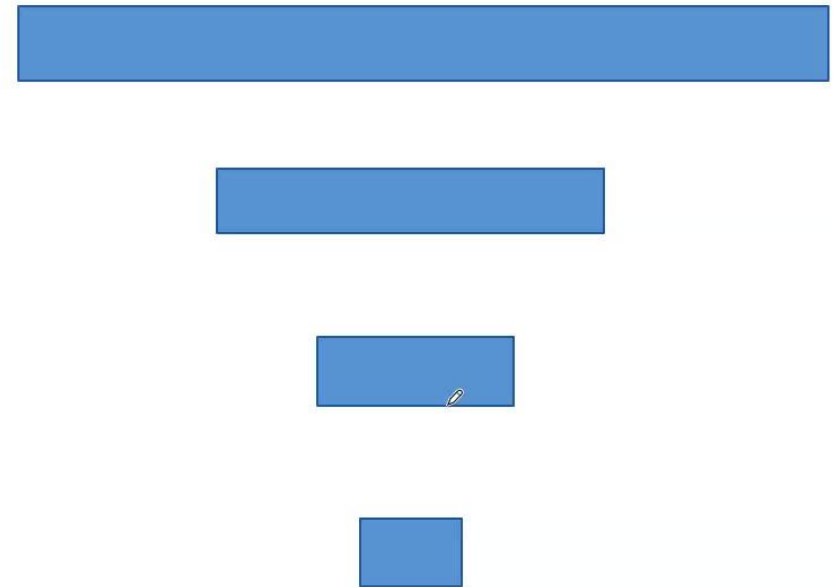
- Consider the set of operations again.
 - Insert: 2x insert, at each recursive level.
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 - is-empty: 1x is-empty, but can say on a smaller bit vector
 - min: 2x min, one each at a smaller level
 - next: 1x next, 1x max, 1x min, at a smaller level
 - delete: 2x delete at a smaller level, 1x is-empty,



Operations on Extended Tiered Bit Vectors

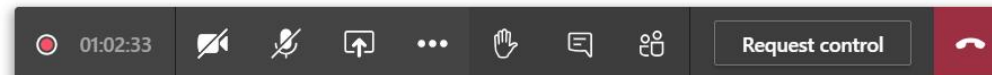
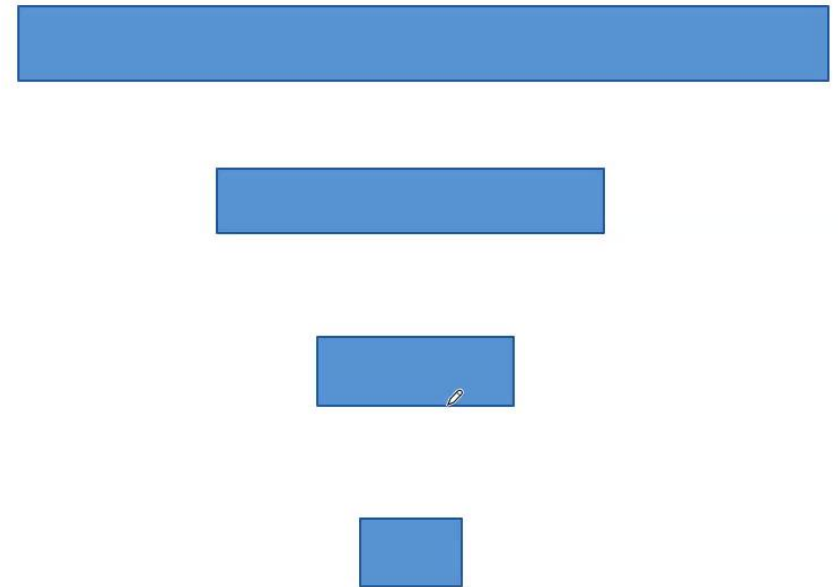
- Consider the set of operations again.
 - next: 1x next, 1x max, 1x min, at a smaller level
 - delete: 2x delete at a smaller level, 1x is-empty,

$$\begin{aligned}T(m) &= T(\sqrt{m}) + T(\max) + T(\min) \\&= T(\sqrt{m}) + O(\log m) \\&= O(\log m)\end{aligned}$$



Operations on Extended Tiered Bit Vectors

- Consider the set of operations again.
 - is-empty: 1x is-empty, but can say on a smaller bit vector
Time: $T(m) = T(\sqrt{m}) + O(1)$.
 - min: 2x min, one each at a smaller level
Time: $T(m) = 2T(\sqrt{m}) + O(1)$
Solution: From earlier, $T(m) = \log(m)$



Our Solution So Far

- We have a data structure, the tiered bit vector, where some operations are $O(\log \log m)$.
 - These are exponentially faster than using BSTs.
- Other operations are in $O(\log m)$.
 - These are worse than BST.
- Can we make all operations faster?
 - Let us identify some potential places for optimization.

