

# Polynomial and FFT

# Outline

- Polynomials
  - Algorithms to add, multiply and evaluate polynomials
  - Coefficient and point-value representation
- Fourier Transform
  - Discrete Fourier Transform (DFT) and inverse DFT to translate between polynomial representations
  - “A Short Digression on Complex Roots of Unity”
  - Fast Fourier Transform (FFT) is a divide-and-conquer algorithm based on properties of complex roots of unity

# Polynomials

- A polynomial in the variable  $x$  is a representation of a function

$$A(x) = a_{n-1}x^{n-1} + \dots + a_2x^2 + a_1x + a_0$$

as a formal sum  $A(x) = \sum_{j=0}^{n-1} a_j x^j$ .

- We call the values  $a_0, a_1, \dots, a_{n-1}$  the **coefficients** of the polynomial
- $A(x)$  is said to have **degree**  $k$  if its highest nonzero coefficient is  $a_k$ .
- Any integer strictly greater than the degree of a polynomial is a **degree-bound** of that polynomial

# Examples

- $A(x) = x^3 - 2x - 1$ 
  - $A(x)$  has degree 3
  - $A(x)$  has degree-bounds 4, 5, 6, ... or all values  $>$  degree
  - $A(x)$  has coefficients  $(-1, -2, 0, 1)$
- $B(x) = x^3 + x^2 + 1$ 
  - $B(x)$  has degree 3
  - $B(x)$  has degree bounds 4, 5, 6, ... or all values  $>$  degree
  - $B(x)$  has coefficients  $(1, 0, 1, 1)$

# Coefficient Representation

- A **coefficient representation** of a polynomial

$A(x) = \sum_{j=0}^{n-1} a_j x^j$  of degree-bound  $n$  is a vector of coefficients  $a = (a_0, a_1, \dots, a_{n-1})$ .

- More examples

- $A(x) = 6x^3 + 7x^2 - 10x + 9$   $(9, -10, 7, 6)$

- $B(x) = -2x^3 + 4x - 5$   $(-5, 4, 0, -2)$

- The operation of **evaluating** the polynomial  $A(x)$  at point  $x_0$  consists of computing the value of  $A(x_0)$ .
- Evaluation takes time  $\Theta(n)$  using Horner's rule
  - $A(x_0) = a_0 + x_0(a_1 + x_0(a_2 + \dots + x_0(a_{n-2} + x_0(a_{n-1}))) \dots)$

# Adding Polynomials

- **Adding** two polynomials represented by the coefficient vectors  $a=(a_0,a_1,\dots,a_{n-1})$  and  $b=(b_0,b_1,\dots,b_{n-1})$  takes time  $\Theta(n)$ .
- Sum is the coefficient vector  $c=(c_0,c_1,\dots,c_{n-1})$ , where  $c_j=a_j+b_j$  for  $j=0,1,\dots,n-1$ .
- Example

$A(x) = 6x^3 + 7x^2 - 10x + 9$	$(9, -10, 7, 6)$
$B(x) = -2x^3 + 4x - 5$	$(-5, 4, 0, -2)$
<hr/>	
$C(x) = 4x^3 + 7x^2 - 6x + 4$	$(4, -6, 7, 4)$

# Multiplying Polynomials

- For **polynomial multiplication**, if  $A(x)$  and  $B(x)$  are polynomials of degree-bound  $n$ , we say their **product**  $C(x)$  is a polynomial of degree-bound  $2n-1$ .
- Example

$$\begin{array}{r}
 6x^3 + 7x^2 - 10x + 9 \\
 - 2x^3 + \phantom{7x^2} + 4x - 5 \\
 \hline
 - 30x^3 - 35x^2 + 50x - 45 \\
 24x^4 + 28x^3 - 40x^2 + 36x \\
 - 12x^6 - 14x^5 + 20x^4 - 18x^3 \\
 \hline
 - 12x^6 - 14x^5 + 44x^4 - 20x^3 - 75x^2 + 86x - 45
 \end{array}$$

# Multiplying Polynomials

- **Multiplication** of two degree-bound  $n$  polynomials  $A(x)$  and  $B(x)$  takes time  $\Theta(n^2)$ , since each coefficient in vector  $a$  must be multiplied by each coefficient in vector  $b$ .
- Another way to express the product  $C(x)$  is  $\sum_{j=0}^{2n-1} c_j x^j$ , where  $c_j = \sum_{k=0}^j a_k b_{j-k}$
- The resulting coefficient vector  $c = (c_0, c_1, \dots, c_{2n-1})$  is also called the **convolution** of the input vectors  $a$  and  $b$ , denoted as  $c = a \otimes b$ .



# Point-Value Representation

- A **point-value representation** of a polynomial  $A(x)$  of degree-bound  $n$  is a set of  $n$  **point-value pairs**

$$\{(x_0, y_0), (x_1, y_1), \dots, (x_{n-1}, y_{n-1})\}$$

such that all of the  $x_k$  are distinct and  $y_k = A(x_k)$  for  $k=0, 1, \dots, n-1$ .

- Example  $A(x) = x^3 - 2x + 1$

$$\begin{array}{l} \bullet -x_k \quad 0, 1, 2, 3 \\ \bullet -A(x_k) \quad 1, 0, 5, 22 \end{array} \quad \left. \vphantom{\begin{array}{l} \bullet -x_k \quad 0, 1, 2, 3 \\ \bullet -A(x_k) \quad 1, 0, 5, 22 \end{array}} \right\} \{(0, 1), (1, 0), (2, 5), (3, 22)\}$$

- Using Horner's method,  **$n$ -point evaluation** takes time  $\Theta(n^2)$ .

# Point-Value Representation

- The inverse of evaluation is called **interpolation**
  - determines coefficient form of polynomial from point-value representation
  - For any set  $\{(x_0, y_0), (x_1, y_1), \dots, (x_{n-1}, y_{n-1})\}$  of  $n$  point-value pairs such that all the  $x_k$  values are distinct, there is a **unique** polynomial  $A(x)$  of degree-bound  $n$  such that  $y_k = A(x_k)$  for  $k=0, 1, \dots, n-1$ .

- Lagrange's formula

$$A(x) = \sum_{k=0}^{n-1} y_k \frac{\prod_{j \neq k} (x - x_j)}{\prod_{j \neq k} (x_k - x_j)}$$

- Using Lagrange's formula, interpolation takes time  $\Theta(n^2)$ .

# Example

- Using Lagrange's formula, we interpolate the point-value representation  $\{(0,1),(1,0),(2,5),(3,22)\}$ .

- $$1 \frac{(x-1)(x-2)(x-3)}{(0-1)(0-2)(0-3)} = \frac{x^3-6x^2+11x-6}{-6} = \frac{-x^3+6x^2-11x+6}{-6}$$

- $$0 \frac{(x-0)(x-2)(x-3)}{(1-0)(1-2)(1-3)} = 0$$

- $$5 \frac{(x-0)(x-1)(x-3)}{(2-0)(2-1)(2-3)} = 5 \frac{x^3-4x^2+3x}{-2} = \frac{-15x^3+60x^2-45x}{6}$$

- $$22 \frac{(x-0)(x-1)(x-2)}{(3-0)(3-1)(3-2)} = 22 \frac{x^3-3x^2+2x}{6} = \frac{22x^3-66x^2+44x}{6}$$

- $$\frac{1}{6} (6x^3+0x^2-12x+6)$$

- $$x^3-2x+1$$

# Adding Polynomials

- In point-value form, addition  $C(x)=A(x)+B(x)$  is given by  $C(x_k)=A(x_k)+B(x_k)$  for any point  $x_k$ .
  - $A:\{(x_0,y_0),(x_1,y_1),\dots,(x_{n-1},y_{n-1})\}$
  - $B:\{(x_0,y'_0),(x_1,y'_1),\dots,(x_{n-1},y'_{n-1})\}$
  - $C:\{(x_0, y_0+y'_0),(x_1, y_1+y'_1),\dots,(x_{n-1}, y'_{n-1}+y_{n-1})\}$
- $A$  and  $B$  are evaluated for the **same**  $n$  points.
- The time to add two polynomials of degree-bound  $n$  in point-value form is  $\Theta(n)$ .

# Example

- We add  $C(x)=A(x)+B(x)$  in point-value form
  - $A(x)=x^3-2x+1$
  - $B(x)=x^3+x^2+1$
  - $x_k=(0,1,2,3)$
  - $A: \{(0,1),(1,0),(2,5),(3,22)\}$
  - $B: \{(0,1),(1,3),(2,13),(3,37)\}$
  - $C: \underline{\{(0,2),(1,3),(2,18),(3,59)\}}$

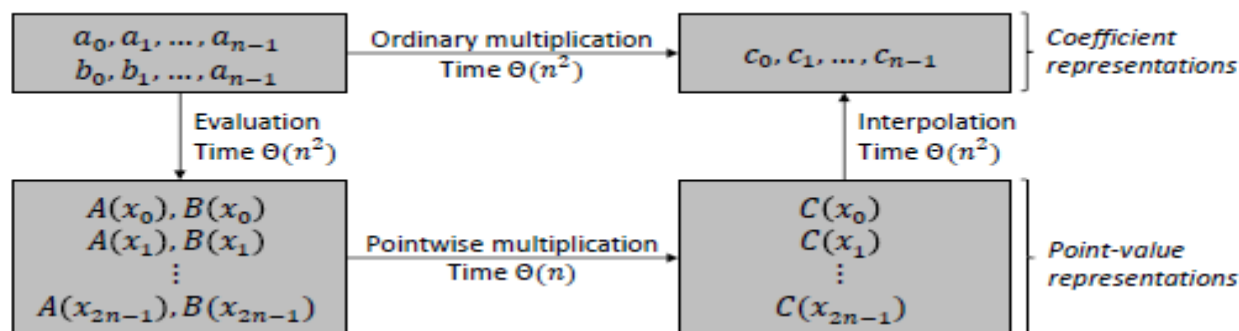
# Multiplying Polynomials

- In point-value form, multiplication  $C(x) = A(x)B(x)$  is given by  $C(x_k) = A(x_k)B(x_k)$  for any point  $x_k$ .
- **Problem:** if  $A$  and  $B$  are of degree-bound  $n$ , then  $C$  is of degree-bound  $2n$ .
- Need to start with “extended” point-value forms for  $A$  and  $B$  consisting of  $2n$  point-value pairs each.
  - $A: \{(x_0, y_0), (x_1, y_1), \dots, (x_{2n-1}, y_{2n-1})\}$
  - $B: \{(x_0, y'_0), (x_1, y'_1), \dots, (x_{2n-1}, y'_{2n-1})\}$
  - $C: \{(x_0, y_0 y'_0), (x_1, y_1 y'_1), \dots, (x_{n-1}, y'_{n-1} y'_{n-1})\}$
- The time to multiply two polynomials of degree-bound  $n$  in point-value form is  $\Theta(n)$ .

# Example

- We multiply  $Cx = Ax B(x)$  in point-value form
  - $A(x) = x^3 - 2x + 1$
  - $B(x) = x^3 + x^2 + 1$
  - $x_k = (-3, -2, -1, 0, 1, 2, 3)$       We need 7 coefficients!
  - $A: \{(-3, -17), (-2, -3), (-1, 1), (0, 1), (1, 0), (2, 5), (3, 22)\}$
  - $B: \{(-3, -20), (-2, -3), (-1, 2), (0, 1), (1, 3), (2, 13), (3, 37)\}$
  - $C: \{(-3, 340), (-2, 9), (-1, 2), (0, 1), (1, 0), (2, 65), (3, 814)\}$

# Road So far



- Can we do better?
  - Using Fast Fourier Transform (FFT) and its inverse, we can do evaluation and interpolation in time  $\Theta(n \log n)$ .
- The product of two polynomials of degree-bound  $n$  can be computed in time  $\Theta(n \log n)$ , with both the input and output in coefficient form.



# Fourier Transform

- Fourier Transforms originate from **signal processing**
  - Transform signal from **time domain** to **frequency domain**



- Input signal is a function mapping time to amplitude
- Output is a weighted sum of phase-shifted sinusoids of varying frequencies

# Fast Multiplication of Polynomials

- Using complex roots of unity
  - Evaluation by taking the Discrete Fourier Transform (DFT) of a coefficient vector
  - Interpolation by taking the “inverse DFT” of point-value pairs, yielding a coefficient vector
  - Fast Fourier Transform (FFT) can perform DFT and inverse DFT in time  $\Theta(n \log n)$
- Algorithm
  1. Add  $n$  higher-order zero coefficients to  $A(x)$  and  $B(x)$
  2. Evaluate  $A(x)$  and  $B(x)$  using FFT for  $2n$  points
  3. Pointwise multiplication of point-value forms
  4. Interpolate  $C(x)$  using FFT to compute inverse DFT

# Complex Roots of Unity

- A **complex  $n^{\text{th}}$  root of unity** (1) is a complex number  $\omega$  such that  $\omega^n = 1$ .
- There are exactly  $n$  complex  $n^{\text{th}}$  root of unity

$$e^{2\pi ik/n} \text{ for } k = 0, 1, \dots, n-1$$

where  $e^{iu} = \cos(u) + i \sin(u)$ . Here  $u$  represents an angle in **radians**.

- Using  $e^{2\pi ik/n} = \cos(2\pi k/n) + i \sin(2\pi k/n)$ , we can check that it is a root

$$\left(e^{2\pi ik/n}\right)^n = e^{2\pi ik} = \underbrace{\cos(2\pi k)}_1 + i \underbrace{\sin(2\pi k)}_0 = 1$$

# Examples

- The complex 4<sup>th</sup> roots of unity are

$$1, -1, i, -i$$

where  $\sqrt{-1} = i$ .

- The complex 8<sup>th</sup> roots of unity are all of the above, plus four more

$$\frac{1}{\sqrt{2}} + \frac{i}{\sqrt{2}}, \frac{1}{\sqrt{2}} - \frac{i}{\sqrt{2}}, -\frac{1}{\sqrt{2}} + \frac{i}{\sqrt{2}}, \text{ and } -\frac{1}{\sqrt{2}} - \frac{i}{\sqrt{2}}$$

- For example

$$\left( \frac{1}{\sqrt{2}} + \frac{i}{\sqrt{2}} \right)^2 = \frac{1}{2} + \frac{2i}{2} + \frac{i^2}{2} = i$$

# Principal nth Root of unity

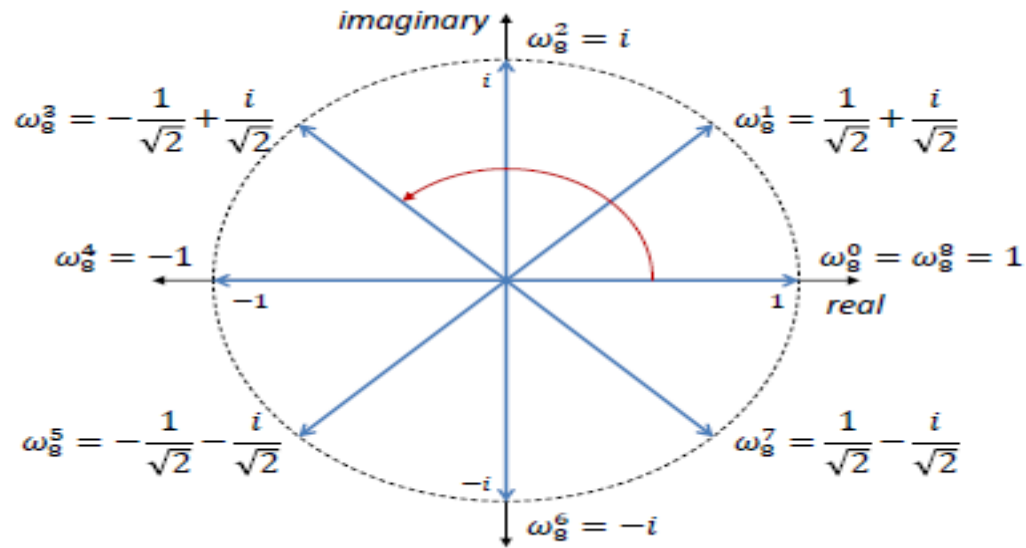
- The value

$$\omega_n = e^{2\pi i/n}$$

is called the **principal  $n^{\text{th}}$  root of unity**.

- All of the other complex  $n^{\text{th}}$  roots of unity are powers of  $\omega_n$ .
- The  $n$  complex  $n^{\text{th}}$  roots of unity,  $\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}$ , form a group under multiplication that has the same structure as  $(\mathbb{Z}_n, +)$  modulo  $n$ .
- $\omega_n^n = \omega_n^0 = 1$  implies
  - $\omega_n^j \omega_n^k = \omega_n^{j+k} = \omega_n^{(j+k) \bmod n}$
  - $\omega_n^{-1} = \omega_n^{n-1}$

# Visualizing 8 complex 8<sup>th</sup> Roots of Unity



# Cancellation Lemma

- For any integers  $n \geq 0$ ,  $k \geq 0$ , and  $b > 0$ ,

$$\omega_{dn}^{dk} = \omega_n^k.$$

- Proof

$$\omega_{dn}^{dk} = \left(e^{2\pi i/dn}\right)^{dk} = \left(e^{2\pi i/n}\right)^k = \omega_n^k$$

- For any even integer  $n > 0$ ,  $\omega_n^{n/2} = \omega_2 = -1$ .
- Example  $\omega_{24}^6 = \omega_4$

$$- \omega_{24}^6 = \left(e^{2\pi i/24}\right)^6 = e^{2\pi i \frac{6}{24}} = e^{2\pi i/4} = \omega_4$$

# Halving Lemma

- If  $n > 0$  is even, then the squares of the  $n$  complex  $n^{\text{th}}$  roots of unity are the  $n/2$  complex  $n/2^{\text{th}}$  roots of unity.
- Proof
  - By the cancellation lemma, we have  $(\omega_n^k)^2 = \omega_{n/2}^k$  for any nonnegative integer  $k$ .
- If we square all of the complex  $n^{\text{th}}$  roots of unity, then each  $n/2^{\text{th}}$  root of unity is obtained exactly twice
  - $(\omega_n^{k+n/2})^2 = \omega_n^{2k+n} = \omega_n^{2k} \omega_n^n = \omega_n^{2k} = (\omega_n^k)^2$
  - Thus,  $\omega_n^k$  and  $\omega_n^{k+n/2}$  have the **same square**



# Summation Lemma

- For any integer  $n \geq 1$  and nonzero integer  $k$  not divisible by  $n$ ,  $\sum_{j=0}^{n-1} (\omega_n^k)^j = 0$ .
- Proof
  - Geometric series  $\sum_{j=0}^{n-1} x^j = \frac{x^n - 1}{x - 1}$
  - $\sum_{j=0}^{n-1} (\omega_n^k)^j = \frac{(\omega_n^k)^n - 1}{\omega_n^{k-1} - 1} = \frac{(\omega_n^n)^k - 1}{\omega_n^{k-1} - 1} = \frac{(1)^k - 1}{\omega_n^{k-1} - 1} = 0$
  - Requiring that  $k$  not be divisible by  $n$  ensures that the denominator is not 0, since  $\omega_n^k = 1$  only when  $k$  is divisible by  $n$

# Discrete Fourier Transform

- Evaluate a polynomial  $A(x)$  of degree-bound  $n$  at the  $n$  complex  $n^{\text{th}}$  roots of unity,  $\omega_n^0, \omega_n^1, \omega_n^2, \dots, \omega_n^{n-1}$ .
  - assume that  $n$  is a power of 2
  - assume  $A$  is given in coefficient form  $a = (a_0, a_1, \dots, a_{n-1})$
- We define the results  $y_k$ , for  $k = 0, 1, \dots, n - 1$ , by

$$y_k = A(\omega_n^k) = \sum_{j=0}^{n-1} a_j \omega_n^{kj}.$$

- The vector  $y = (y_0, y_1, \dots, y_{n-1})$  is the **Discrete Fourier Transform (DFT)** of the coefficient vector  $a = (a_0, a_1, \dots, a_{n-1})$ , denoted as  $y = \text{DFT}_n(a)$ .

# Fast Fourier Transform

- **Fast Fourier Transform (FFT)** takes advantage of the special properties of the complex roots of unity to compute  $\text{DFT}_n(a)$  in time  $\Theta(n \log n)$ .
- Divide-and-conquer strategy
  - define two new polynomials of degree-bound  $n/2$ , using even-index and odd-index coefficients of  $A(x)$  separately
  - $A^{[0]}(x) = a_0 + a_2x + a_4x^2 + \dots + a_{n-2}x^{n/2-1}$
  - $A^{[1]}(x) = a_1 + a_3x + a_5x^2 + \dots + a_{n-1}x^{n/2-1}$
  - $A(x) = A^{[0]}(x^2) + xA^{[1]}(x^2)$

# Continued

- The problem of evaluating  $A(x)$  at  $\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}$  reduces to
  1. evaluating the degree-bound  $n/2$  polynomials  $A^{[0]}(x)$  and  $A^{[1]}(x)$  at the points  $(\omega_n^0)^2, (\omega_n^1)^2, \dots, (\omega_n^{n-1})^2$
  2. combining the results by  $A(x) = A^{[0]}(x^2) + xA^{[1]}(x^2)$
- Why bother?
  - The list  $(\omega_n^0)^2, (\omega_n^1)^2, \dots, (\omega_n^{n-1})^2$  does not contain  $n$  distinct values, but  $n/2$  complex  $n/2^{\text{th}}$  roots of unity
  - Polynomials  $A^{[0]}$  and  $A^{[1]}$  are recursively evaluated at the  $n/2$  complex  $n/2^{\text{th}}$  roots of unity
  - Subproblems have exactly the same form as the original problem, but are half the size

# Example

- $A(x) = a_0 + a_1x + a_2x^2 + a_3x^3$  of degree-bound 4
  - $A(\omega_4^0) = A(1) = a_0 + a_1 + a_2 + a_3$
  - $A(\omega_4^1) = A(i) = a_0 + a_1i - a_2 - a_3i$
  - $A(\omega_4^2) = A(-1) = a_0 - a_1 + a_2 - a_3$
  - $A(\omega_4^3) = A(-i) = a_0 - a_1i + a_2 + a_3i$
- Using  $A(x) = A^{[0]}(x^2) + xA^{[1]}(x^2)$ 
  - $A(x) = a_0 + a_2x^2 + x(a_1 + a_3x^2)$
  - $A(\omega_4^0) = A(1) = a_0 + a_2 + 1(a_1 + a_3)$
  - $A(\omega_4^1) = A(i) = a_0 - a_2 + i(a_1 - a_3)$
  - $A(\omega_4^2) = A(-1) = a_0 + a_2 - 1(a_1 + a_3)$
  - $A(\omega_4^3) = A(-i) = a_0 - a_2 - i(a_1 - a_3)$

# Recursive FFT

RECURSIVE-FFT( $a$ )

```
1  $n \leftarrow \text{length}[a]$ 
2 if  $n = 1$ 
3   then return  $a$ 
4  $\omega_n \leftarrow e^{2\pi i/n}$ 
5  $\omega \leftarrow 1$ 
6  $a^{[0]} \leftarrow (a_0, a_2, \dots, a_{n-2})$ 
7  $a^{[1]} \leftarrow (a_1, a_3, \dots, a_{n-1})$ 
8  $y^{[0]} \leftarrow \text{RECURSIVE-FFT}(a^{[0]})$ 
9  $y^{[1]} \leftarrow \text{RECURSIVE-FFT}(a^{[1]})$ 
10 for  $k \leftarrow 0$  to  $n/2 - 1$ 
11   do  $y_k \leftarrow y_k^{[0]} + \omega y_k^{[1]}$ 
12      $y_{k+(n/2)} \leftarrow y_k^{[0]} - \omega y_k^{[1]}$ 
13      $\omega \leftarrow \omega \omega_n$ 
14 return  $y$ 
```

$n$  is a power of 2

basis of recursion

$\omega_n$  is principal  $n^{\text{th}}$  root of unity

$$y_k^{[0]} = A^{[0]}(\omega_{n/2}^k) = A^{[0]}(\omega_n^{2k})$$
$$y_k^{[1]} = A^{[1]}(\omega_{n/2}^k) = A^{[1]}(\omega_n^{2k})$$

since  $-\omega_n^k = \omega_n^{k+(n/2)}$   
compute  $\omega_n^k$  iteratively

# Why does it work?

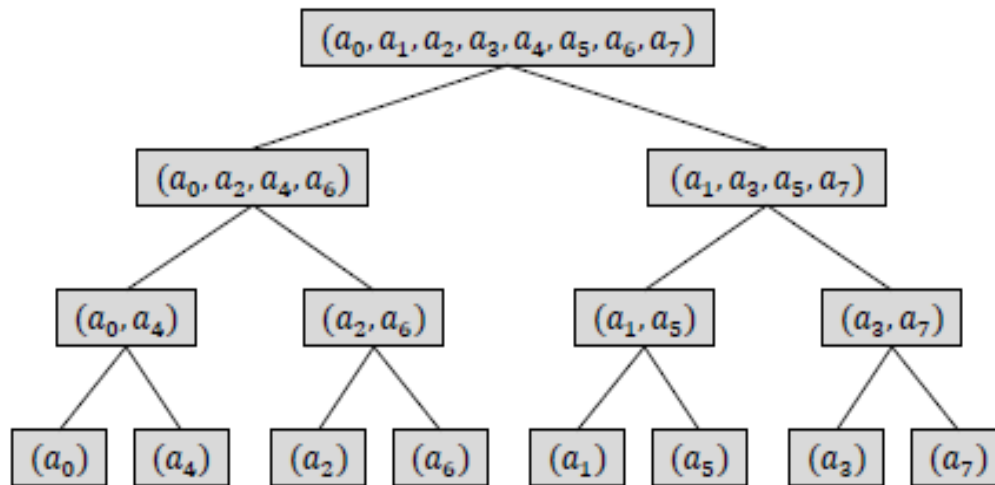
- For  $y_0, y_1, \dots, y_{n/2-1}$  (line 11)

$$\begin{aligned} y_k &= y_k^{[0]} + \omega_n^k y_k^{[1]} \\ &= A^{[0]}(\omega_n^{2k}) + \omega_n^k A^{[1]}(\omega_n^{2k}) \\ &= A(\omega_n^k) \end{aligned}$$

- For  $y_{n/2}, y_{n/2+1}, \dots, y_{n-1}$  (line 12)

$$\begin{aligned} y_{k+n/2} &= y_k^{[0]} - \omega_n^k y_k^{[1]} \\ &= y_k^{[0]} + \omega_n^{k+(n/2)} y_k^{[1]} && \text{since } -\omega_n^k = \omega_n^{k+(n/2)} \\ &= A^{[0]}(\omega_n^{2k}) + \omega_n^{k+(n/2)} A^{[1]}(\omega_n^{2k}) \\ &= A^{[0]}(\omega_n^{2k+n}) + \omega_n^{k+(n/2)} A^{[1]}(\omega_n^{2k+n}) \\ &&& \text{since } \omega_n^{2k+n} = \omega_n^{2k} \\ &= A(\omega_n^{k+(n/2)}) \end{aligned}$$

# Input Vector Tree of $\text{RECURSIVEFFT}(a)$





# Interpolation

- Interpolation by computing the inverse DFT, denoted by  $a = \text{DFT}_n^{-1}(y)$ .
- By modifying the FFT algorithm, we can compute  $\text{DFT}_n^{-1}$  in time  $\Theta(n \log n)$ .
  - switch the roles of  $a$  and  $y$
  - replace  $\omega_n$  by  $\omega_n^{-1}$
  - divide each element of the result by  $n$