# Elementary Graph Algorithms with Applications

Dr. Sachin Tripathi

Department of CSE, Indian School of Mines, Dhanbad.



#### Outline...

- 1 Representations of Graphs
- 2 Depth First Search
- 3 Topological Sort
- 4 Strongly Connected Components
- 5 Single Source DAG Shortest Path Problem and Application



## Adjacency-list and Adjacency-matrix Representation

#### Adjacency list

The adjacency-list representation of a graph G=(V,E) consists of an array Adj of |V| lists, one for each vertex in V. For each  $u\in V$ , the adjacency list Adj[u] contains all the vertices v such that there is an edge  $(u,v)\in E$ .

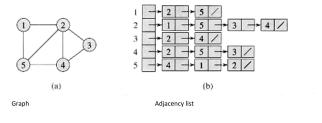
#### **Adjacency-matrix**

The adjacency-matrix representation of a graph G=(V,E), we assume that the vertices are numbered  $1,2,\ldots,|V|$  in some arbitrary manner. Then the adjacency-matrix representation of a graph G consists of a  $|V|\times |V|$  matrix  $A=(a_{ij})$  such that

$$(a_{ij}) = egin{cases} 1 & ext{if (i,j)} \in \mathsf{E} \\ 0 & ext{otherwise}. \end{cases}$$



## Representation of Undirected Graph

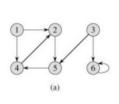


	1	2	3	4	5
1	0	1	0	0	1
2	1	0	l	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0
(c)					

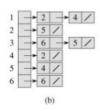
Adjacency matrix



## Representation of Directed Graph



graph



Adjacency list



Adjacency matrix



#### **Depth First Search**

```
DFS(G)
   for each vertex u \in G, V
       u.color = WHITE
       u.\pi = NIL
   time = 0
   for each vertex u \in G.V
       if u color == WHITE
           DFS-VISIT(G, u)
DFS-VISIT(G, u)
    time = time + 1
                                  // white vertex u has just been discovered
    u.d = time
    u.color = GRAY
    for each v \in G.Adi[u]
                                  // explore edge (u, v)
        if v.color == WHITE
             v.\pi = u
             DFS-VISIT(G, \nu)
   u.color = BLACK
                                  // blacken u: it is finished
    time = time + 1
```

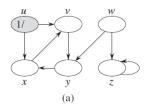
Run time complexity is  $\theta(V + E)$ 

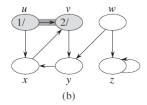


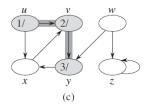
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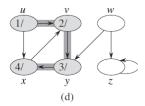
u.f = time

## DFS Example

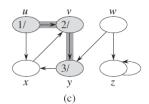


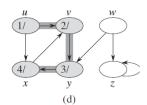


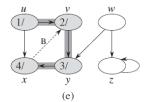


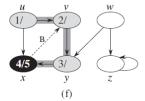




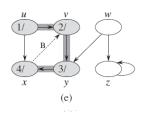


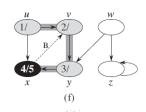


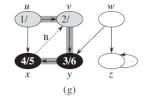


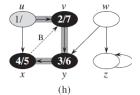




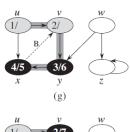


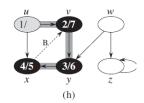


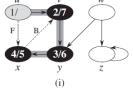


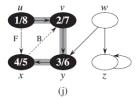




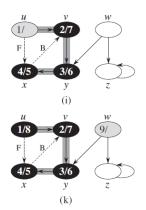


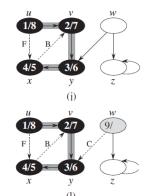




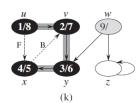


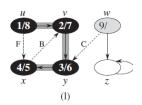


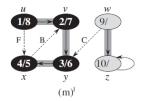


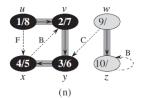




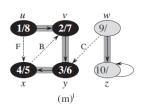


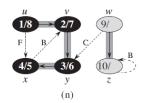


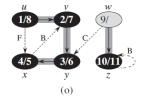


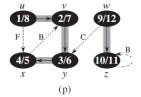










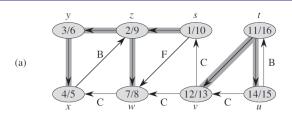


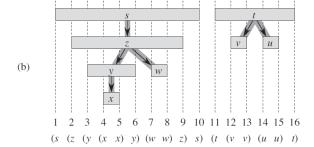


## Properties of Depth First Search

Depth-first search yields valuable information about the structure of a graph.

- DFS can be used to classify the edges of input graph G = (V, E), This edge classification can be used to glean important information about a graph. For Example:- Directed graph is acyclic iff DFS search yields no back edges.
  - Types of edges are Tree, Back, Forward and Cross
- If we represent the discovery of vertex u with a left parenthesis "(u" and represent its finishing by a right parenthesis "u)", then the history of discoveries and finishings makes a well-formed expression in the sense that the parentheses are properly nested. i.e.,

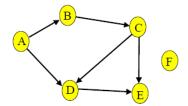






#### **Topological Sort**

**Topological sorting problem**: given digraph G = (V, E), find a linear ordering of vertices such that: for all edges (v, w) in E, v precedes w in the ordering





## Topological Sort Algorithm

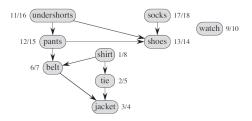
#### TOPOLOGICAL-SORT(G)

- 1 call DFS(G) to compute finishing times  $\nu$ . f for each vertex  $\nu$
- 2 as each vertex is finished, insert it onto the front of a linked list
  - 3 **return** the linked list of vertices

Time complexity is  $\theta(V + E)$ 



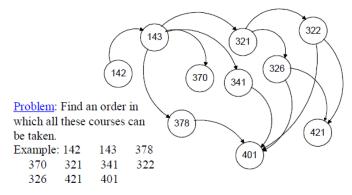
### Example 1:







#### Example 2:





## How we Define?

#### **Strongly Connected Component**

strongly connected component of a directed graph G = (V, E) is a maximal set of vertices  $C \subseteq V$  such that for every pair of vertices u and v in C, we have both  $u \to v$  and  $v \to u$ ; that is, vertices u and v are reachable from each other.



#### Observations.

- 1: Graph and Transpose of a graph have exactly the same strongly connected components. i.e., u and v are reachable from each other in G, iff they are reachable from each other in  $G^T$ .
- 2: The finishing time of each source in DFS forest is always greater than their descendant.



# Strongly Connected Components

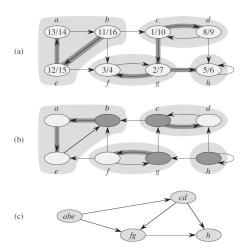
#### BFS(G,s)

- 1 call DFS(G) to compute finishing times u.f for each vertex u
- 2 compute  $G^T$
- 3 call DFS(G<sup>T</sup>) but in the main loop of DFS, consider the vertices in order of decreasing u.f (as computed in line 1)
- 4 output the vertices of each tree in the depth-first forest formed in line 3 as a separate strongly connected component

Time complexity is  $\theta(V + E)$ 



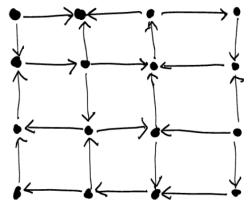
## Graph for Strongly Connected Components (Example 1)





# Example 2 (Tutorial)

Circle all of the strongly connected components of following directed graph.





## Single Source DAG Shortest Path

By relaxing the edges of a weighted dag (directed acyclic graph) G = (V, E) according to a topological sort of its vertices, we can compute shortest paths from a single source in  $\theta(V + E)$  time. The algorithm for this is:

DAG-SHORTEST-PATHS (G, w, s)

- 1 topologically sort the vertices of G
- 2 Initialize-Single-Source (G, s)
- 3 **for** each vertex u, taken in topologically sorted order
- 4 **for** each vertex  $v \in G.Adj[u]$
- 5 RELAX(u, v, w)



## INITIALIZE-SINGLE-SOURCE (G, s)

- 1 **for** each vertex  $v \in G.V$
- $v.d = \infty$
- $\nu.\pi = NIL$
- $4 \quad s.d = 0$

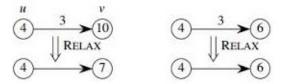


RELAX
$$(u, v, w)$$

1 **if** 
$$v.d > u.d + w(u, v)$$

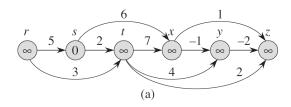
$$2 v.d = u.d + w(u, v)$$

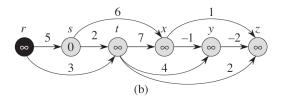
$$v.\pi = u$$



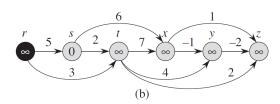


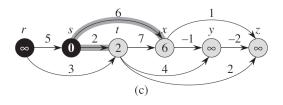
## Consider The Graph where 's' is the source



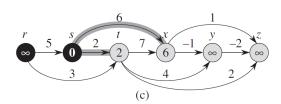


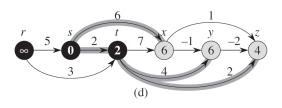




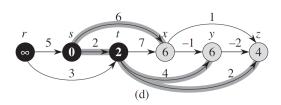


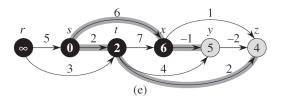




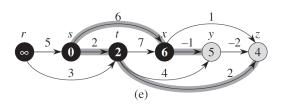


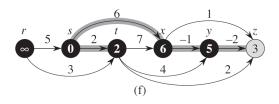




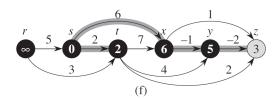


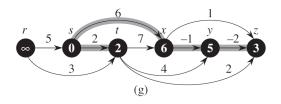














# Application (Critical path in PERT chart analysis)

**Critical Path:** It is the longest path through the DAG corresponding to the longest time perform an ordered sequence of jobs. It can be found either by:

- negating the edge weight and running DAG shortest path algorithm.
- Running DAG shortest path with the modification that replace  $\infty$  to  $-\infty$  in line two of the initialize single source algorithm and > by < in relax procedure.



# Thank you

