

3.] Given:- We have a third degree polynomial

$$y = ax^3 + bx^2 + cx + d + v$$

$$\Rightarrow y = W^T b(x) + v$$

$$\text{where, } W = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \quad b(x) = \begin{bmatrix} x^3 \\ x^2 \\ x \\ 1 \end{bmatrix}$$

$$\text{and } v \sim \mathcal{N}(0, \sigma^2)$$

$$\text{Prior of } W \Rightarrow W \sim \mathcal{N}(0, \gamma^2 I)$$

W_{true} are the true parameters of y .

\rightarrow Estimate the MAP function parameter W .

Solution:- $y = W^T b(x) + v$

From the linearity property $x = Az + b$,
we know $y \sim \mathcal{N}(W^T b(x), \sigma^2)$

To estimate W , we have our MAP estimator:

$$W_{\text{MAP}} = \underset{W}{\operatorname{argmax}} p(W; y | x)$$

Applying Bayes Rule and disregarding the evidence;

$$W_{\text{MAP}} = \underset{W}{\operatorname{argmax}} \underbrace{p(y | x; W)}_{\text{likelihood}} \times \underbrace{p(W)}_{\text{prior}}$$

Taking log on both sides:

$$\ln W_{\text{MAP}} = \underset{W}{\operatorname{argmax}} \sum_{i=1}^K \ln p(y_i | x_i; W) + \ln p(W)$$

(Considering i samples)

Solving each term independently :-

$$\begin{aligned} \ln p(y_i | x_i; W) &= \ln \frac{1}{\sqrt{2\pi} \sigma} \times e^{-\frac{1}{2} \frac{(y_i - W^T b(x_i))^2}{\sigma^2}} \\ &= \underbrace{\ln \frac{\sigma^{-1}}{\sqrt{2\pi}}}_{\text{Constant}} + \frac{1}{2} \frac{(y_i - W^T b(x_i))^2}{\sigma^2} \end{aligned}$$

$$\begin{aligned} \ln p(W) &= \ln \frac{|Y^2 I|^{-1/2}}{2\pi} \times e^{-\frac{1}{2} W^T |Y^2 I|^{-1} W} \\ &= \underbrace{\ln \frac{|Y^2 I|^{-1/2}}{2\pi}}_{\text{Constant}} + \left(-\frac{1}{2}\right) W^T |Y^2 I|^{-1} W \end{aligned}$$

$$\therefore \ln W_{\text{MAP}} = \underset{W}{\operatorname{argmax}} \sum_{i=1}^K \left[-\frac{1}{2} \frac{(y_i - W^T b(x_i))^2}{\sigma^2} \right] - \frac{1}{2} W^T |Y^2 I|^{-1} W$$

$$\Rightarrow \ln W_{\text{MAP}} = \underset{W}{\operatorname{argmin}} \sum_{i=1}^K \frac{(y_i - W^T b(x_i))^2}{\sigma^2} - W^T |Y^2 I|^{-1} W$$

To minimize the RHS, we take a gradient at W_{MAP} .

$$\nabla_{W=W_{MAP}} \Rightarrow \frac{2}{\sigma^2} \sum_{i=1}^K (y_i - W_{MAP}^T b(x_i)) b(x_i)^T + (-2)(\gamma^2 I)^{-1} W_{MAP} = 0$$

$$\Rightarrow \frac{1}{\sigma^2} \sum_{i=1}^K b(x_i) y_i - \frac{1}{\sigma^2} \sum_{i=1}^K W_{MAP}^T b(x_i) b(x_i)^T +$$

$$(-1)(\gamma^2 I)^{-1} W_{MAP} = 0$$

Multiplying by σ^2 :

$$\sum_{i=1}^K b(x_i) y_i = \sum_{i=1}^K b(x_i) b(x_i)^T W_{MAP} + \sigma^2 (\gamma^2 I)^{-1} W_{MAP}$$

$$\therefore W_{MAP} = \left[\sum_{i=1}^K b(x_i) b(x_i)^T + \sigma^2 (\gamma^2 I)^{-1} \right]^{-1} \sum_{i=1}^K b(x_i) y_i$$

This is the MAP estimate of the parameter W