abc	All-in-focus image without gradient addition
badpix1	Percentage pixels where disparity deviates by less than 0.01 pixels from the ground truth.
badpix3	Percentage pixels where disparity deviates by less than 0.03 pixels from the ground truth.
badpix7	Percentage pixels where disparity deviates by less than 0.07 pixels from the ground truth.
depth_Our	Proposed depth map
depth_output	Ground-truth depth map
disp_max	Max depth value in ground-truth depth map.
disp_min	Min depth value in ground-truth depth map.
FinalImg2	Disparity map. (Addition of FinalImg51 and FinalImg61 and refinement)
FinalImg51	Disparity map using octagonal patch shape 1.
FinalImg61	Disparity map using octagonal patch shape 2.
MAX	Max disparity value in proposed depth map.
Max_slope	Max depth value in proposed depth map.
MIN	Min disparity value in proposed depth map.
Min_slope	Min depth value in proposed depth map.
Slope	Difference depth values for focal stack generation.
t_depth_gen	Time taken for depth estimation
t_fstack_gen	Time taken for focal stack generation
t_initial_depth	Time taken for initial depth estiamtion
telapsed1	Total Algorithm time.
xyz	All-in-focus image with gradient addition