

# Report

Part 1)

## **Dataset:**

1. a gt.txt file
2. KITTI\_17\_images.zip
3. outputVideFile.mp4
4. sort-master.zip
5. TrackEval-master.zip

**Task:** Multi-object tracking with detection(MOT) to predict the positions of peoples/pedestrians with a given sequence of images provided in the [KITTI\\_17\\_images.zip](#) file (frames of the video) using SORT and a model Yolov5 to do object tracking and detection respectively.

## **Approach:**

Firstly, Iterates over a sequence of frames of the video with help of a function ``enumerate`` and then each frame is converted from PIL format image to OpenCV format image using ``cv2.cvtColor()`` function. Now, the yolov5 model is used to detect pedestrians using the ``yolov5_detector``. Object detections are filtered to keep it for the people/pedestrians only and object tracker is updated with the filtered detections using the ``obj_tracker.update()`` function and then tracked objects are drawn on the frame with help of bounding boxes and object\_ids using the ``cv2.rectangle()`` and ``cv2.putText()`` functions respectively. Also tracking information of each frame is written to a predict.txt file using the ``fptr_out.write`` function. A video with tracked pedestrians is saved after combining its tracked frames together using ``final_out.write()``. Finally, a tracked\_OutputVideo.mp4 releases using the function ``final_out.release()``.