

2.6 Exact Equations and Integrating Factors

If we have a differential equation:

$$M(x, y) + N(x, y)y' = 0$$

find a function $\psi(x, y)$ such that

$$\frac{\partial \psi}{\partial x}(x, y) = M(x, y), \quad \frac{\partial \psi}{\partial y}(x, y) = N(x, y)$$

Then,

$$M(x, y) + N(x, y)y' = \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} \frac{dy}{dx} = \frac{d}{dx} \psi[x, \phi(x)] = 0$$

where $y = \phi(x)$ is the solution. By integration we get

$$\psi(x, y) = c$$

which implicitly defines the solutions for the original differential equation. In this case the original differential equation is an **exact** differential equation.

THEOREM 2.6.1. *Let the functions M, N, M_y, N_x , where the subscripts denote partial derivatives be continuous in the rectangular region $R : \alpha < x < \beta, \gamma < y < \delta$. The differential equation*

$$M(x, y) + N(x, y)y' = 0$$

is an exact differential equation in R if and only if

$$M_y(x, y) = N_x(x, y)$$

for each point in R . That is, there exists a function ψ such that

$$\frac{\partial \psi}{\partial x}(x, y) = M(x, y), \quad \frac{\partial \psi}{\partial y}(x, y) = N(x, y)$$

if and only if M and N satisfy that constraint.

Proof. Computing M_y and N_x , we get,

$$M_y(x, y) = \psi_{xy}(x, y), \quad M_y(x, y) = \psi_{yx}(x, y)$$

and $\psi_{xy}(x, y) = \psi_{yx}(x, y)$ so if the equation is exact, then $M_y(x, y) = N_x(x, y)$. Now, we must prove the other way around.

We need to find a ψ so that

$$\psi_x(x, y) = M(x, y), \quad \psi_y(x, y) = N(x, y)$$

By integrating the first half the the equation above we get

$$\psi(x, y) = Q(x, y) + h(y)$$

where

$$Q(x, y) = \int_{x_0}^x M(s, y) ds$$

and $h(y)$ acts as a constant (with respect to x). Now we choose h to satisfy

$$\psi_y(x, y) = \frac{\partial Q}{\partial y}(x, y) + h'(y) = N(x, y)$$

So we have

$$h'(y) = N(x, y) - \frac{\partial Q}{\partial y}(x, y)$$

For this equation to be true the right side of the equation must be only a function of y , so the partial derivative with respect to x should be 0.

$$\frac{\partial N}{\partial x}(x, y) - \frac{\partial}{\partial x} \frac{\partial Q}{\partial y}(x, y) = 0$$

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And we know $\frac{\partial Q}{\partial x}(x, y) = \frac{\partial \psi}{\partial x}(x, y) = M(x, y)$. So,

$$\frac{\partial N}{\partial x}(x, y) - \frac{\partial M}{\partial y}(x, y) = 0$$

and

$$M_y(x, y) = N_x(x, y)$$

$h(y)$ can be found by integrating $N(x, y) - \frac{\partial Q}{\partial y}(x, y)$. □

Integrating Factors. Sometimes if an equation is not exact, then it is possible to use an integrating factor $\mu(x, y)$ to make it exact. If we have,

$$M(x, y) + N(x, y)y' = 0$$

and we multiply it by $\mu(x, y)$,

$$\mu(x, y)M(x, y) + \mu(x, y)N(x, y)y' = 0$$

By Theorem 2.6.1, this equation is exact if and only if

$$(\mu M)_y = (\mu N)_x$$

By the product rule, we get another differential equation

$$M\mu_y - N\mu_x + (M_y - N_x)\mu = 0$$

Solving this gets you $\mu(x, y)$, which will make the original equation exact, so you could solve that too.

If $\mu(x, y) = \mu(x)$ is only a function of x , we can set $\mu_x = \frac{d\mu}{dx}$ and $\mu_y = 0$. So we get

$$\frac{d\mu}{dx} = \frac{M_y - N_x}{N}\mu$$

which is both linear and separable.