

pidController

- double kp
- double kd
- double ki
- double dt
- double prevError

- + pidController()
- + ~pidController()
- + double getParamkp()
- + double getParamki()
- + double getParamkd()
- + void setParamki(double ki_)
- + void setParamkp(double ki_)
- + void setParamkddouble ki_)
- + void setParamdt(double ki_)
- + void setParamE(double ki_)
- + double compute (double setPoint, double cV)