

Rishabh Choudhary

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Github: <https://github.com/rishchou>

Education

- **University of Maryland, College Park, M.Eng (Robotics), GPA - 3.9/4.0** Aug 2018 - May 2020
- **Birla Institute of Technology and Science, Pilani, B.E. (Hons), Electrical and Electronics Engineering** 2012 - 2016

Relevant Coursework: Visual learning and recognition, Natural Language Processing, Computer Vision, Path Planning algorithms, Data structures and Algorithms, Operating Systems, Software development for Robotics, Machine learning.

Experience

Professional Experience

- **Computer Vision/Deep learning Intern, Sturfee, Milpitas, CA** Jun - August 2019
 - Synthetic data generation of street and aerial view by navigating the camera in simulated environment in Blender/AirSim for augmented reality applications. The data was also trained and tested over a neural network for alignment of Street view and Aerial Point cloud.
 - This project helped Sturfee generate realistic datasets in house without manually collecting street view pictures and reduced the dataset generation cost.

Software Developer, Cisco systems, Bangalore

Aug 2016 - Aug 2018

- Designed and Implemented Adaptive Authentication model using Machine learning for RADIUS Protocol as part of the Cisco Hackathon. Awarded runner-up position for the idea/implementation. [Python]
- Designed and Implemented boot up memory optimization of AAA (Authentication, Authorization and Accounting) module for Routers and Switches to reduce memory usage at startup by about 30%. [C++]
- Led automation framework for unit testing and integration tests to enhance code quality assurance and boost code coverage of AAA component from 20% to 70%. [SWIFT/C]
- Resolved numerous bugs and deployed new features for the AAA framework.

Research Experience

Graduate Research Assistant, Perception and Robotics Group, University of Maryland

Oct 2018 - May 2019

- Rendered a 3D scene using Blender to simulate data for visual odometry using event-based cameras.

Project Experience

- Traffic sign detection and classification using computer vision and machine learning [Python] May 2019
- Implementation of A* and Dijkstra algorithm for point/rigid robot in a 2D space [Python] March 2019
- Turtlebot Roomba walker using ROS and C++ Oct 2018
- Object detection using Convolutional Neural Networks [Python] April 2019
- Traffic lane detection and tracking using C++ and OpenCV Sept 2018

Computer Skills

- **Languages:** C, C++, Python
- **Tools and Libraries:** Github, Linux, GDB debugging, MATLAB, Eclipse, Blender, Unity, Wireshark, Arduino, Valgrind, OpenCV, PCL, scikit-learn, pandas, numpy, scipy, tensorflow, keras, pytorch, plotly
- **Game Engines/Simulators** - Unity, Blender, Unreal, Microsoft Airsim.
- **Deep learning architectures:** CNNs, RNNs, Neural Style Transfer, YOLO
- **Software development:** Agile development, Automated/Manual Unit testing, Google Mock/Test framework

Positions of Responsibility

- **Project lead, Hackaholic (Cisco's annual hackathon)** June 2018
- **Project coordinator, IEEE, BITS PILANI.** Aug 2014- May 2015
- **Teaching Assistant, Microprocessor and Interfacing course, BITS Pilani** Jan -May 2015