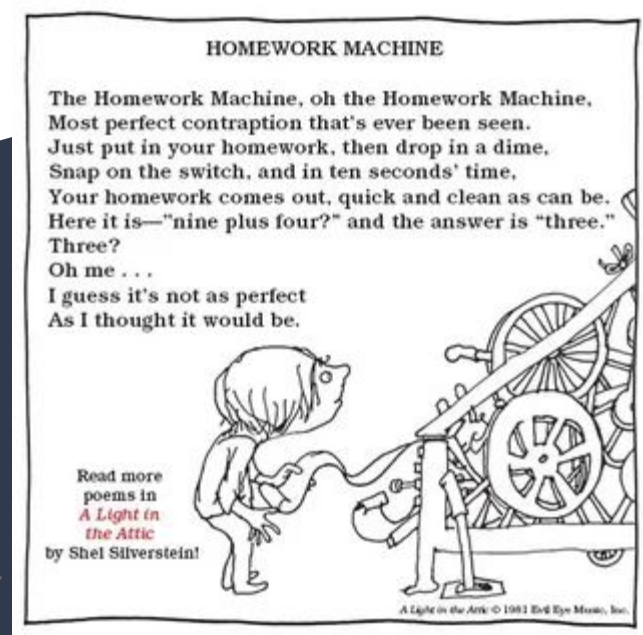


# CS 2340 – Computer Architecture

02 Introduction to Assembly Language  
Programming  
Dr. Alice Wang

Shel Silverstein predicted  
ChatGPT



# Housekeeping

- To be counted for the Attendance policy you don't need to get the answer correct for the Attendance Quiz.
- Don't be concerned if you got the wrong answer
- I won't check any of the grades, I will only check that the quiz is submitted

# Review

## Last time

- Computing is pervasive
- All computers are made up of CPU, memory and I/O

## Today

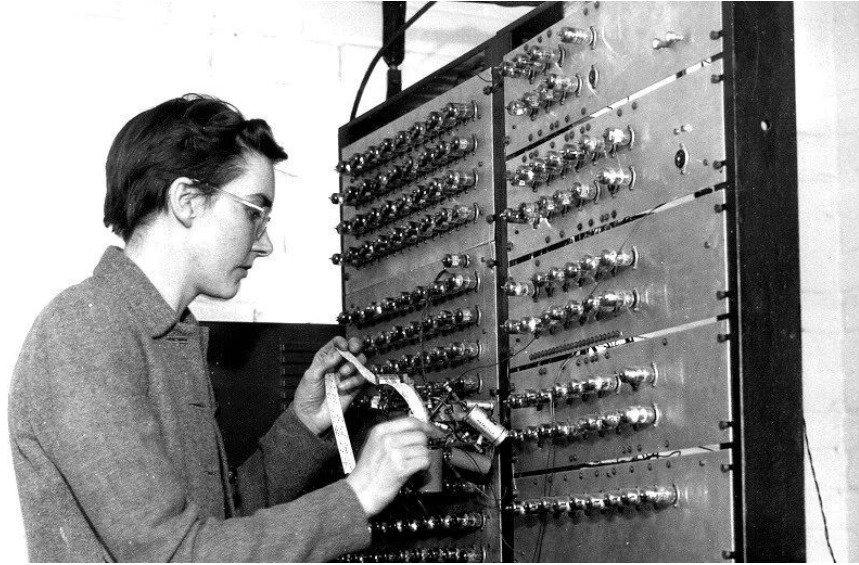
- Introduction to MIPS assembly language
- Not comprehensive, but will be enough to write simple programs
- Tutorial/Demo of MARS

*Download the MARS RISC ASSEMBLER/SIMULATOR on eLearning or in MS Teams*

# History

## Kathleen Booth

<b>Born</b>	Kathleen Hylda Valerie Britten 9 July 1922 <a href="#">Stourbridge, Worcestershire,</a> England
<b>Died</b>	29 September 2022 (aged 100)
<b>Alma mater</b>	University of London
<b>Known for</b>	Invented the first <a href="#">assembly language</a> for her University's computer
<b>Spouse</b>	<a href="#">Andrew Booth</a> ( <a href="#">m.</a> , 1950; died 2009)
	<b>Scientific career</b>
<b>Fields</b>	<a href="#">Computer science</a>
<b>Institutions</b>	<a href="#">Birkbeck College</a>



- At London's Birkbeck College joined a team of scientists who were performing calculations using X-ray images to determine crystal structures. She was the sole programmer.
- She was credited with the first "assembly language," and assembler to create the machine language

# Review: Microprocessor Software

Software is a set of instructions, data or programs used to operate computers and execute specific tasks

	Level	Readability	Code-type	Examples
<b>High-level code</b>	High-level	Human-readable	Machine-Independent	C, Java, Python
<b>Assembly code</b>	Low-level	Human-readable	Machine-dependent	ARM, MIPS, x86
<b>Machine code</b>	Lowest-level	Machine-readable	Machine-dependent	0's and 1's

# Review: Coding Example

## High-level

```
int f, g, y; // global

int main(void)
{
    f = 2;
    g = 3;

    y = sum(f, g);
    return y;
}

int sum(int a, int b) {
    return (a + b);
}
```

## Assembly code

```
.data
f:
g:
y:
.text
main:
    addi $sp, $sp, -4    # stack frame
    sw   $ra, 0($sp)    # store $ra
    addi $a0, $0, 2      # $a0 = 2
    sw   $a0, f          # f = 2
    addi $a1, $0, 3      # $a1 = 3
    sw   $a1, g          # g = 3
    jal  sum             # call sum
    sw   $v0, y          # y = sum()
    lw   $ra, 0($sp)    # restore $ra
    addi $sp, $sp, 4     # restore $sp
    jr   $ra            # return to
    OS
sum:
    add  $v0, $a0, $a1   # $v0 = a + b
    jr   $ra            # return
```

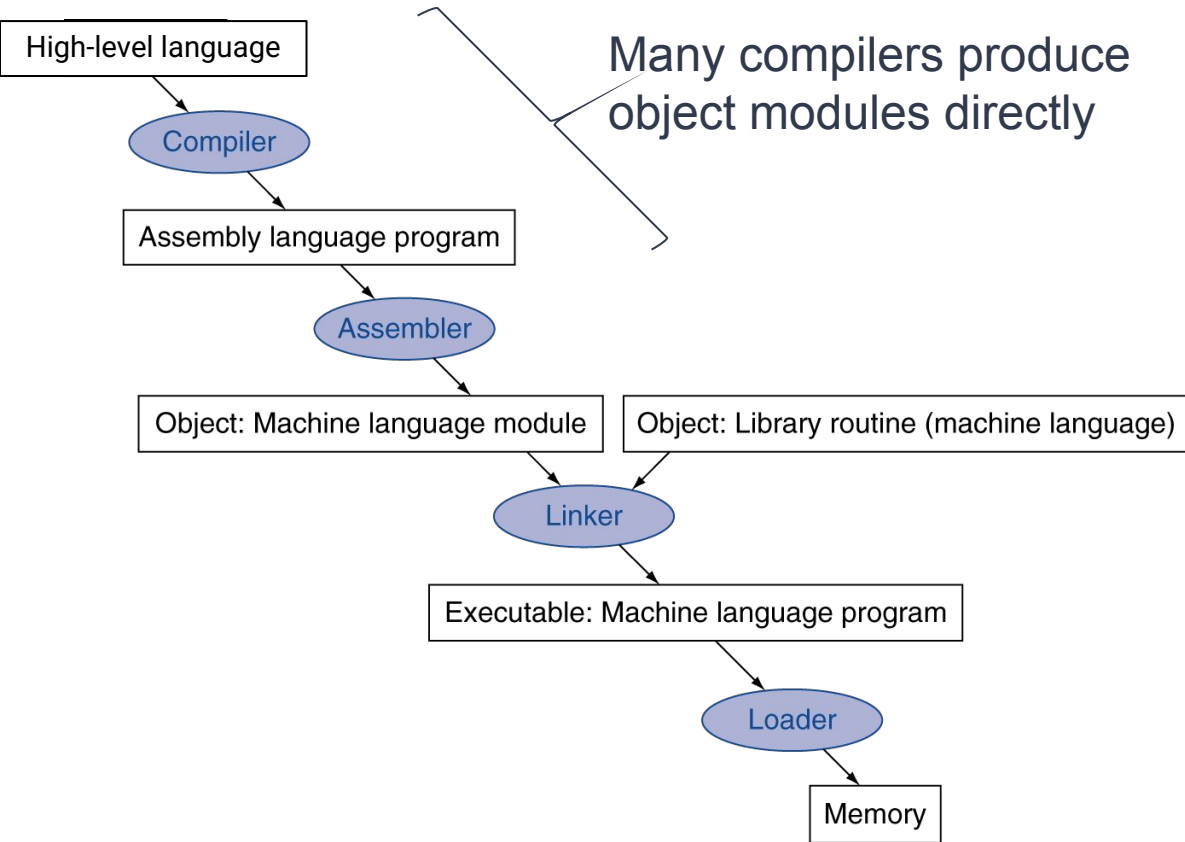
## Machine coding

Executable file header	Text Size	Data Size
	0x34 (52 bytes)	0xC (12 bytes)
Text segment	Address	Instruction
addi \$sp, \$sp, -4	0x00400000	0x23BDFFFC
sw \$ra, 0(\$sp)	0x00400004	0xAFBF0000
addi \$a0, \$0, 2	0x00400008	0x20040002
sw \$a0, 0x8000(\$gp)	0x0040000C	0xAF848000
addi \$a1, \$0, 3	0x00400010	0x20050003
sw \$a1, 0x8004(\$gp)	0x00400014	0xAF858004
jal 0x0040002C	0x00400018	0x0C10000B
sw \$v0, 0x8008(\$gp)	0x0040001C	0xAF828008
lw \$ra, 0(\$sp)	0x00400020	0x8FBF0000
addi \$sp, \$sp, -4	0x00400024	0x23BD0004
jr \$ra	0x00400028	0x03E00008
add \$v0, \$a0, \$a1	0x0040002C	0x00851020
jr \$ra	0x00400030	0x03E00008
Data segment	Address	Data
	0x10000000	f
	0x10000004	g
	0x10000008	y

# Do I need to know Assembly?

- Yes!
- Access the bare metal HW
- Used to address low-level performance issues
- Commonly used on device drivers and embedded systems
- Tricky part: Assembly code is specific to the machine
  - You can't use x86 Assembly Code on ARM CPU

# Translation Hierarchy





# What is a Compiler?



com·pil·er

/kəm'pīlər/

*noun*

1. a person who produces a list or book by assembling information or written material collected from other sources.  
"this passage was revised in different ways by later compilers"
  2. **COMPUTING**  
a program that converts instructions into a machine-code or lower-level form so that they can be read and executed by a computer.  
"conversion would require more than just running it through a different compiler"
- Lower-level aka Assembly code

# What is an Assembler?



**as·sem·bler**

/ə'semblər/

A software tool for converting instructions written in assembly code into machine code (zeros and ones). The output is often an output file (.o or .obj) which includes instructions, data, and information to place the program into memory.

# MARS

- MARS is a MIPS emulator, assembler, debugger (using breakpoints) and runtime simulator written in Java
- It also has an editing function for writing MIPS assembly language programs
- We will be using MARS extensively in our projects and in our lecture



# What is an Instruction Set Architecture (ISA)?

- ISA and Computer Architecture are interchangeable
  - Defines instructions, data types, registers, memory management and features, addressing modes, and the input/output model
- Most common ISA's
  - Reduced Instruction Set Computer (RISC)
    - ARM, MIPS, RISC-V
  - Complex Instruction Set Computer (CISC)
    - X86
- Custom ISA's - Application specific
  - GPU (CUDA, NVIDIA), TPU (Google)
- Not the implementation of the processor (microarchitecture)

# MIPS instruction set

- Used as the example throughout this class
- Invented at Stanford University
  - Later commercialized by MIPS Technologies
- Where you can find MIPS CPU's in the wild
  - Classic game consoles: Nintendo 64 (1996), Sony Playstation (1994)
  - Cars: Tesla Model S

# Assembly code – Template

Header is required  
for all code (Best  
Practice)

Comments  
preceded by  
# - won't be  
compiled

```
1  # Assembly program template
2  # Author: your name
3  # Date: current date
4  # Description: high-level description of your program
6
6  .data
7
8  # Data segment:
9  # constant and variable definitions go here
10
11 .text
12
13 # Text segment: assembly instructions go here
14 # your code
```

.data is the start of the  
section where you  
store all of your data  
(constants & variables)

.text is the start of the  
section where your  
assembly code goes

# Data storage

Use local labels to easily access the data's location

`.data`

```
val1: .word 1 # the first value
val2: .word 2 # the second value
A:    .word 1,2,3,4,5,6,7
      # An Array of data called A

name: .asciiz "Daniel" # my name
prompt: .asciiz "Enter a number"
        # Prompt to user
newline: .asciiz "\n"
```

## Memory Labels (similar to variables)

- It is often necessary to refer to a memory location by name, whether the location contains an instruction or data
- Labels in MIPS assembler must start with a letter and can contain letters, digits, dollar signs, and underscores
- The label name is followed by a colon

# Data storage

Use local labels to easily access the data's location

`.data`

```
val1: .word 1 # the first value
val2: .word 2 # the second value
A:    .word 1,2,3,4,5,6,7
      # An Array of data called A
```

`.word` is 32-bit value or 4 Bytes  
(A Byte is 8-bits)

```
name: .ascii "Daniel" # my name
prompt: .ascii "Enter a number"
        # Prompt to user
newline: .ascii "\n"
```

`.ascii` stores the string in the NULL-terminated format - puts NULL at the end of the string signifying where the string ends



# Assembler Directives

- **.text**, **.data** and **.ascii** are Assembler Directives.
- Look like statements but do not compile to machine instructions
- Directive names always begin with a period

.align	.data	.eqv	.half	.set
.ascii	.double	.extern	.include	.space
.asciiz	.end_macro	.float	.kdata	.text
.byte	.macro	.globl	.ktext	.word

More about the Assembler Directives in reference

# .space

- Reserves a specific number of **bytes** for data
- Use this directive for defining fixed-size buffers, arrays
- Example: Set aside 256 bytes for an array called B

```
B:    .space 256
```

# .eqv

- Substitutes second operand for first
- First operand is symbol, second operand is expression (like #define)
- Can be used for strings and entire instructions

```
.eqv LIMIT      20
```

```
.eqv CTR        $t2
```

```
.eqv CLEAR_CTR  add CTR, $zero, 0
```

# Learning MIPS assembly coding

Four key things to know:

- Registers
- Instructions
- Memory
- Syscall interface

# MIPS Register Set

Name	Register Number	Usage
\$0, \$zero	0	the constant value 0
\$at	1	assembler temporary
\$v0 - \$v1	2-3	Function return values
\$a0 - \$a3	4-7	Function arguments
\$t0 - \$t7	8-15	temporaries
\$s0 - \$s7	16-23	saved variables
\$t8 - \$t9	24-25	more temporaries
\$k0 - \$k1	26-27	OS temporaries
\$gp	28	global pointer
\$sp	29	stack pointer
\$fp	30	frame pointer
\$ra	31	Function return address

Registers - where we store data that the CPU uses in instructions

- \$ before name
- Example: \$t0 is the 0th temporary register
- In total there are 32 registers in MIPS, each is 32-bit

Review:

1 Word = \_\_\_\_ bits

1 Byte = \_\_\_\_ bits

# MIPS Register Set

Name	Register Number	Usage
\$0, \$zero	0	the constant value 0
\$at	1	assembler temporary
\$v0 - \$v1	2-3	Function return values
\$a0 - \$a3	4-7	Function arguments
\$t0 - \$t7	8-15	temporaries
\$s0 - \$s7	16-23	saved variables
\$t8 - \$t9	24-25	more temporaries
\$k0 - \$k1	26-27	OS temporaries
\$gp	28	global pointer
\$sp	29	stack pointer
\$fp	30	frame pointer
\$ra	31	Function return address

Register names indicate their specific purposes:

- \$0 always holds the constant value 0. Very useful!
- \$s0 - \$s7, the *saved variables*, are used to hold variables
- \$t0 - \$t9, the *temporary registers*, are used to hold intermediate values during a larger computation
- \$v0 - \$v1 (return values) and \$a0 - \$a3 (arguments) have specific uses in procedures and system calls
- We will discuss others at a later date

# Instructions: Getting started

## Python Code

```
a = 5;  
b = 7;
```

## MIPS assembly code

```
li $a0, 5  
li $v0, 7
```

```
li $dst, immediate    # Load immEDIATE (constant) into  
                        # a register ($dst)
```

# Instructions: Arithmetic operations

## Python Code

```
a = b + c;  
a = b - c;
```

## MIPS assembly code

```
add $t0, $t1, $t2  
sub $s0, $s1, $s2
```

```
add $dst, $src0, $src1 # add $t1 to $t2 and store in $t0  
sub $dst, $src0, $src1 # sub $s2 from $s1 and store in $s0
```

The first register is the destination register,  
the second two are source or inputs



# Instructions: Adding constants

## Python Code

```
a = b + 5;  
a = b - 7;
```

## MIPS assembly code

```
addi $t0, $s0, 5
```

**`addi $dst, $src0, immediate`**

# add the immEDIATE (constant) to the value in \$src0  
and store in register \$dst

Question: Do we need a subi instruction?

# Example: Simple MIPS assembly

Register	Register Value
\$t0	0
\$t1	0
\$t2	0
\$t3	0

## Instructions

`.text`

```
li $t1, 5      # load immEDIATE 5 to reg $t1
li $t2, 7      # load immEDIATE 7 to reg $t2
add $t3, $t1, $t2
```

# Example: Simple MIPS assembly

Register	Register Value
\$t0	0
\$t1	5
\$t2	0
\$t3	0

## Instructions

`.text`

```
li $t1, 5      # load immEDIATE 5 to reg $t1
li $t2, 7      # load immEDIATE 7 to reg $t2
add $t3, $t1, $t2
```

# Example: Simple MIPS assembly

Register	Register Value
\$t0	0
\$t1	5
\$t2	7
\$t3	0

## Instructions

`.text`

`li $t1, 5      # load immEDIATE 5 to reg $t1`

`li $t2, 7      # load immEDIATE 7 to reg $t2`

`add $t3, $t1, $t2`

# Example: Simple MIPS assembly

Register	Register Value
\$t0	0
\$t1	5
\$t2	7
\$t3	12

## Instructions

`.text`

`li $t1, 5       # load immEDIATE 5 to reg $t1`

`li $t2, 7       # load immEDIATE 7 to reg $t2`

`add $t3, $t1, $t2`

# Mars demo

## Part 1



# Mars demo

- How to startup MARS
  - Look at syllabus if you have a MAC
- How to edit your code
- How to save your code
- The Register Table
- How to Assemble your code
- How to Run your code one-line at a time

# Register vs Memory

Register	Register Value
\$t0	0
\$t1	5
\$t2	7
\$t3	12

Registers store data (Variables)

Registers are few (e.g. <100)  
→ Only a subset of data

Data is stored by name  
(e.g. \$t1 = 5)

Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

Memories store data (Arrays and Variables)

Memories are big (1GB~10TB)  
→ Stores all of your data

Data is stored by address  
(Mem[1] = 90, Address = 1)



# Register vs Memory

Register	Register Value
\$t0	0
\$t1	5
\$t2	7
\$t3	12

MIPS CPU **can** perform calculations directly on register data

Therefore, if we want to perform calculation on memory data we have to copy the data from the memory to registers first

Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

MIPS CPU **cannot** perform calculations directly on memory data

# Example: MIPS lw

Register	Register Value
\$t0	23
\$t1	53
\$t2	564
\$t3	100

	Address	Memory Array
x	0	783
y	1	90
A[0] →	2	34
A[1]	3	453
A[2]	4	44
...	...	

## Python Code

```
x = 783
y = 90
A = np.array[34,453,44]
```

## MIPS assembly code

```
.data
x: .word 783
y: .word 90
A: .word 34,453,44
```

How do we execute `A[0] + A[2]`?

# Example: MIPS lw

Register	Register Value
\$t0	23
\$t1	53
\$t2	564
\$t3	100

A[0] →

A[1]

A[2]

...

Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

How do we execute  $A[0] + A[2]$  ?

First, move A[0] from memory to register. 2 step process

(1) Put Address into a register. Use Load Address (1a)

(2) Put Mem[Address] into a register

# Example: MIPS lw

Register	Register Value
\$t0	23
\$t1	53
\$t2	564
\$t3	100

A[0] →

A[1]

A[2]

...

Mem Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

## Instructions

**.text**

**la \$dst, \$symbol**

# Load Address (label) into a  
# register (\$dst)

(1) Put Address into a register. Use Load Address (la)

# Example: MIPS lw

Register	Register Value
\$t0	23
\$t1	53
\$t2	564
\$t3	100

Mem Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

A[0] →

A[1]

A[2]

...

## Instructions

```
.text
```

```
la $t1, A           # load base address of Array A to $t1
```

(1) Put Address into a register. Use Load Address (la)

# Example: MIPS lw

Register	Register Value
\$t0	23
\$t1	2
\$t2	564
\$t3	100

A[0] →

A[1]

A[2]

...

Mem Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

## Instructions

**.text**

**lw \$dst, offset(\$src)**    # Load a Word from the memory at  
# address = \$src + offset into reg \$dst

(2) Put Mem[Address] into a register. Use Load Word (**lw**)

# Example: MIPS lw

Register	Register Value
\$t0	23
\$t1	2
\$t2	564
\$t3	100

Mem Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

A[0] →

A[1]

A[2]

...



## Instructions

**.text**

```
la $t1, A          # load base address of Array A to $t1
lw $t3, 0($t1)      # Calculate address = $t1 + 0 = 2
                    # $t3 = A[0] = Mem[2]
```

(2) Put Mem[Address] into a register. Use Load Word (**lw**)

# Example: MIPS lw – Your Turn

Register	Register Value
\$t0	23
\$t1	2
\$t2	564
\$t3	34

A[0] →

A[1]

A[2]

...

Mem Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

What is the code to  
load A[2] to \$t2

**.text**

**la \$t1, A**

**# load base address of Array A to \$t1**

**lw \_\_\_\_, \_\_\_\_(\$t1)**

**# load word from address \$t1+2 to \$t2**



# Example: MIPS add

Register	Register Value
\$t0	23
\$t1	2
\$t2	44
\$t3	34

## Python Code

```
A = np.array[34, 453, 44]
```

```
a = A[0]      # a=34
b = A[2]      # b=44
c = a+b
```

A[0] →

A[1]

A[2]

...

Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

## MIPS Code

```
.text
la $t1, A
lw $t3, 0($t1)
lw $t2, 2($t1)
add $t0, $t2, $t3
```

# Example: MIPS sw

Register	Register Value
\$t0	23
\$t1	2
\$t2	44
\$t3	34

A[0] →  
A[1]  
A[2]  
...

Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

## Instructions

**sw \$src, offset(\$dst)**      # Store a Word from register \$src  
                                  # to the memory at address \$dst+offset

(3) Put register data into a Mem[Address]. Use Store Word (**sw**)

# Example: MIPS sw

Register	Register Value
\$t0	78
\$t1	2
\$t2	44
\$t3	34

Address	Memory Array
0	783
1	90
2	34
3	453
4	44
...	

A[0] →

A[1]

A[2]

...

Instructions

```
add $t0, $t2, $t3
```

```
sw $t0, 1($t1)    # store word from $t0 to address $t1+1 = 3  
                  # A[1] = Mem[3] = 78
```

(3) Put register data into a Mem[Address]. Use Store Word (**sw**)

# Example: MIPS sw – Your Turn

Register	Register Value
\$t0	78
\$t1	2
\$t2	44
\$t3	34

A[0] →  
A[1]  
A[2]  
...

Address	Memory Array
0	783
1	90
2	34
3	78
4	44
...	

Instructions

sw \$t0, -2(\$t1) # store word from reg \_\_\_\_\_ to address \_\_\_\_\_

What does this instruction do?

# Instructions (so far)

```
li $dst, immediate  
la $dst, $symbol  
lw $dst, offset($src)  
sw $src, offset($dst)  
add $dst, $src0, $src1  
sub $dst, $src0, $src1  
addi $dst, $src0, immediate
```

**Now you have enough assembly instructions  
(li, la, lw, sw, add, sub, addi) to do  
your first programming assignment!**

# What is a Pseudo-operation (Pseudo-code)?

- A Pseudo-operations are instructions that has no direct machine operation but makes it easier to code in Assembly language.
- The Hardware doesn't need to implement pseudo-operations because the Assembler knows how to read and translate pseudo-code.

Task	Pseudo-Instruction	Programmer Writes	Assembler Translates To
Move the contents of one register to another.	<code>move &lt;dest&gt; &lt;source&gt;</code>	<code>move \$t0, \$s0</code>	<code>addu \$t0, \$zero, \$s0</code>
Load a constant into a register. (Negative values are handled slightly differently.) "li" stands for <b>load immediate</b> .	<code>li &lt;dest&gt; &lt;immed&gt;</code>	<code>li \$s0, 10</code>	<code>ori \$s0, \$zero, 10</code>
Load the <i>address</i> of a named memory location into a register. <b>Value</b> is a label that the programmer has attached to a memory location. 16 is the offset of that memory location from the beginning of the data segment. It is calculated by the assembler for you.	<code>la &lt;dest&gt; &lt;label&gt;</code>	<code>la \$s0, variable</code>	<code>lui \$at, 0x1001</code> <code>ori \$s0, \$at, 16</code>

# SYSCALL Functions and Interface

Instructions to interact with the outside world (System Calls)

Examples of SYSCALL functions:

- Print to screen : integers, fractions, strings
- Read from Keyboard: integers, fractions, strings
- Allocate to dynamic memory (heap)
- Reading from files (File I/O)
- Generate random numbers

# SYSCALL

Registers with specific SYSCALL functions

**\$v0** - what action do we take, service number

**\$a0-\$a2, \$f12** - arguments of that action

**\$v0-\$v1, \$f1** - results from the action

Step 1. Load the service number in register \$v0.

Step 2. Load argument values, if any, in \$a0, \$a1, \$a2, or \$f12

Step 3. Issue the SYSCALL instruction.

Step 4. Retrieve return values, if any, from result registers as specified.

On eLearning there is a PDF with all SYSCALL functions



# SYSCALL functions available in MARS

\$v0 -  
Service number

\$a0~\$a2, \$f12  
Arguments to syscall

\$v0~\$v1, \$f0  
Results from syscall

Let's use these  
system calls

Service	Code in \$v0	Arguments	Result
print integer	1	\$a0 = integer to print	
print float	2	\$f12 = float to print	
print double	3	\$f12 = double to print	
print string	4	\$a0 = address of null-terminated string to print	
read integer	5		\$v0 contains integer read
read float	6		\$f0 contains float read
read double	7		\$f0 contains double read
read string	8	\$a0 = address of input buffer \$a1 = maximum number of characters to read	See note below table
sbrk (allocate heap memory)	9	\$a0 = number of bytes to allocate	\$v0 contains address of allocated memory
exit (terminate execution)	10		
print character	11	\$a0 = character to print	See note below table
read character	12		\$v0 contains character read

1: Print integer

4: Print string

5: Read integer

# A very important file – SysCalls.asm

```
# Definitions of various useful system calls for MIPS assembly.  
# This file must be included using .include "SysCalls.asm" rather  
# than being assembled as a separate module.  
# Written by John Cole starting January 2, 2022
```

```
.eqv SysPrintInt      1  
.eqv SysPrintFloat    2  
.eqv SysPrintDouble   3  
.eqv SysPrintString   4  
.eqv SysReadInt       5  
.eqv SysReadFloat     6  
.eqv SysReadDouble    7  
.eqv SysReadString    8  
.eqv SysAlloc         9  
.eqv SysExit         10  
.eqv SysPrintChar     11  
.eqv SysReadChar      12  
.eqv SysOpenFile      13  
.eqv SysReadFile      14  
.eqv SysWriteFile     15  
.eqv SysCloseFile     16  
.eqv SysExitValue     17
```

```
.include "SysCalls.asm"  
.text  
    li $v0, SysPrintInt    # Code for print integer  
    add $a0, $t0, $zero    # load value into $a0  
    syscall
```

This file is on eLearning.  
You will get points deducted on your assignment if you don't include SysCalls.asm on your projects and if you don't use these names in your syscalls.

# SYSCALL – Example code & demo

```
1  # CS2340 Lecture 1. Mars demo of syscall
2  #
3  # Author: Alice Wang
4  # Date: 05-03-2024
5  # Location: UTD
6  #
7
8  .include "SysCalls.asm"           # include this file in all programs
9  .data
10     msg: .ascii "Hello World!"
11     ArrayA: .word 1,2,3,4,5,6,7
12
13
14 .text
15     li $v0, SysReadInt           # service call: read integer from keyboard to $v0
16     syscall                     # run system call
17     move $s0, $v0               # $s0 = $v0
18
19     li $v0, _____           # service call: print integer (SysCalls.asm)
20     move $a0, $s0                # $a0 = $s0
21     syscall                     # run system call
22
23     li $v0, _____           # service call: print string (SysCalls.asm)
24     la $a0, msg                  # load address of string to $a0
25     syscall                     # run system call
26
27     li $v0, _____           # service call: exit
28     syscall
29
```

} Header (required for full credit)

} Include SysCalls.asm (required to include this file in your HW Submission and use it)

Comments on almost every line (required for full credit)

# SYSCALL – Example code & demo

What do you think we will see printed on the screen?

```
1  # CS2340 Lecture 1. Mars demo of syscall
2  #
3  # Author: Alice Wang
4  # Date: 05-03-2024
5  # Location: UTD
6  #
7
8  .include "SysCalls.asm"           # include this file in all programs
9  .data
10     msg:    .ascii "Hello World!"
11     ArrayA: .word 1,2,3,4,5,6,7
12
13
14 .text
15     li $v0, SysReadInt           # service call: read integer from keyboard to $v0
16     syscall                     # run system call
17     move $s0, $v0               # $s0 = $v0
18
19     li $v0, _____           # service call: print integer (SysCalls.asm)
20     move $a0, $s0               # $a0 = $s0
21     syscall                     # run system call
22
23     li $v0, _____           # service call: print string (SysCalls.asm)
24     la $a0, msg                 # load address of string to $a0
25     syscall                     # run system call
26
27     li $v0, _____           # service call: exit
28     syscall
29
```

} Data storage

} Read an integer from the keyboard

} Print the same integer on the screen

} Print the string to the screen

} Exit gracefully (req'd)

# Mars demo

## Part 2

The partial code is on eLearning  
“lecture2-mars demo.asm”  
so that you can try it too.



# Mars demo

- How to startup MARS
    - Look at syllabus if you have a MAC
  - How to edit your code
  - How to save your code
  - The Register Table
  - The Data memory
- Step-by-step demo in the reference section
- How to Assemble your code
  - How to Run your code
  - Run I/O vs Mars Messages windows
  - How to Debug your code using breakpoints
  - How to view data in decimal, ASCII & hex

# HW #1 – MARS setup and Assembly code practice

## .data Section Requirements

Declare the following variables

- a, b, c to hold the numbers 45, 32 and 90 respectively (use .word)
- username to hold the user's name (use .space)
- animal to hold the name of an animal (use .space)

Declare string messages using .ascii:

- A prompt for username
- A prompt for favorite animal
- Messages to display the results

# HW #1 – MARS setup and Assembly code practice

## .text Section Requirements

Write MIPS instructions to:

1. Prompt the user for their name and save it to memory (username)
2. Prompt the user for a name of their favorite animal and save it to memory (animal)
3. Prompt user for an integer between 1-50 (store word in variable c)
4. Calculate  $\text{sum} = 2*a + b - c + 21$  (load word a, b and c to registers)
5. Display should look like

Run I/O  
screen will  
look like

```
Enter your name: Alice
Enter the name of an animal: cheetah
Enter one integer from 1-50: 23
Aloha Alice
Your favorite animal is the cheetah
Our crystal ball says your favorite number is 120
-- program is finished running --
```



Next lecture

# CPU Performance



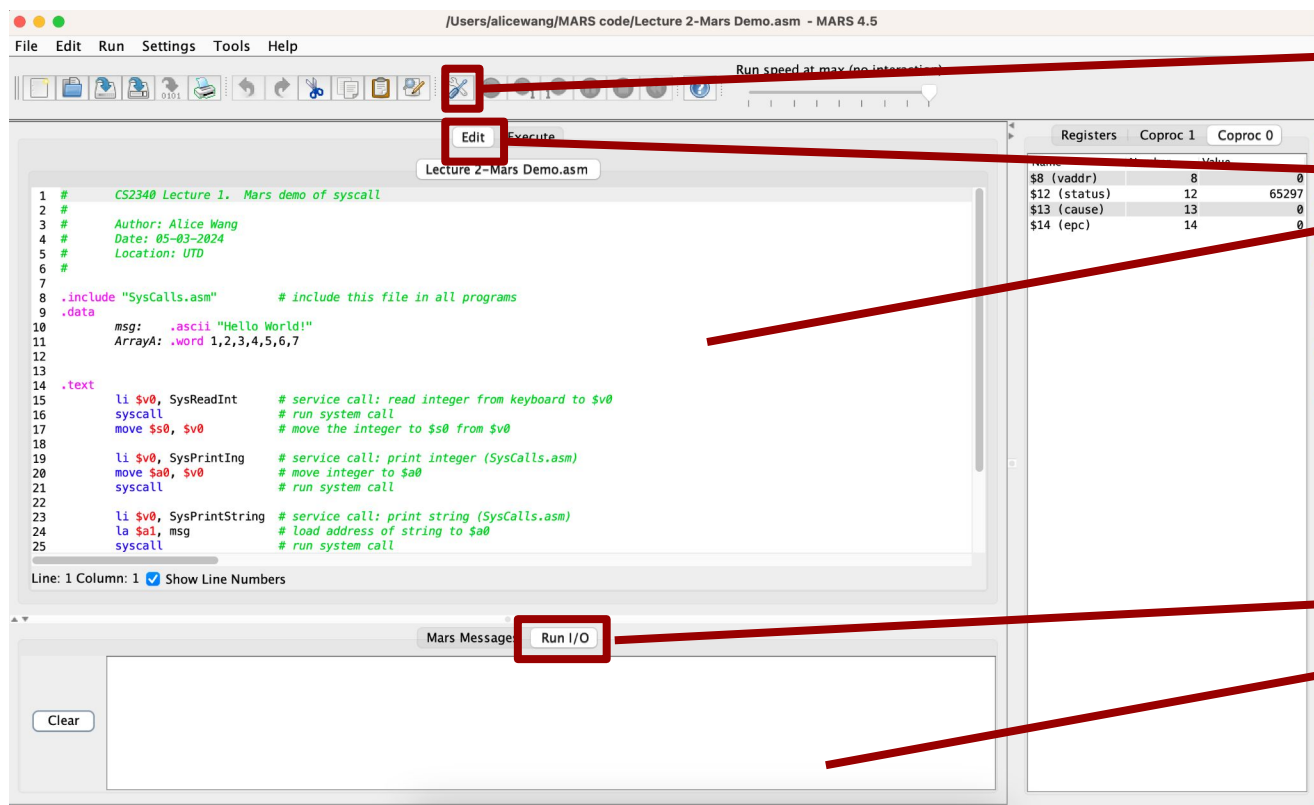
# Reference: Directives

- .align** Align next data item on specified byte boundary (0=byte, 1=half, 2=word, 3=double)
- .ascii** Store the string in the Data segment but do not add null terminator
- .asciiz** Store the string in the Data segment and add null terminator
- .byte** Store the listed value(s) as 8 bit bytes
- .data** Subsequent items stored in Data segment at next available address
- .double** Store the listed value(s) as double precision floating point
- .end\_macro** End macro definition. See .macro
- .macro** Begin macro definition. See .end\_macro
- .eqv** Substitute second operand for first. First operand is symbol, second operand is expression (like #define)
- .extern** Declare the listed label and byte length to be a global data field
- .float** Store the listed value(s) as single precision floating point

# Reference: Directives

- .global** Declare the listed label(s) as global to enable referencing from other files
- .half** Store the listed value(s) as 16 bit halfwords on halfword boundary
- .include** Insert the contents of the specified file. Put filename in quotes.
- .kdata** Subsequent items stored in Kernel Data segment at next available address
- .ktext** Subsequent items (instructions) stored in Kernel Text segment at next available address
- .set** Set assembler variables. Currently ignored but included for SPIM compatibility
- .space** Reserve the next specified number of bytes in Data segment
- .text** Subsequent items (instructions) stored in Text segment at next available address
- .word** Store the listed value(s) as 32 bit words on word boundary

# Reference: MARS Demo



Saves and  
Assembles code

Click to see  
Assembly Code  
Editor: Here you  
can edit your  
code.

Click to see Run  
I/O Display: Print  
screen and Read  
from Keyboard

# Reference: MARS Demo

File Edit Run Settings Tools Help

Run speed at max (no interaction)

Edit Execute

Lecture 2-Mars Demo.asm

```
1 # CS2340 Lecture 1. Mars demo of syscall
2 #
3 # Author: Alice Wang
4 # Date: 05-03-2024
5 # Location: UTD
6 #
7
8 .include "SysCalls.asm" # include this file in all programs
9 .data
10 msg: .ascii "Hello World!"
11 Array: .word 1,2,3,4,5,6,7
12
13
14 .text
15 li $v0, SysReadInt # service call: read integer from keyboard to $v0
16 syscall # run system call
17 move $s0, $v0 # move the integer to $s0 from $v0
18
19 li $v0, SysPrintInt # service call: print integer (SysCalls.asm)
20 move $a0, $v0 # move integer to $a0
21 syscall # run system call
22
23 li $v0, SysPrintString # service call: print string (SysCalls.asm)
24 la $a1, msg # load address of string to $a0
25 syscall # run system call
```

Line: 19 Column: 68 ✓ Show Line Numbers

Mars Messages Run I/O

Go: execution completed successfully.

Clear

Assemble: assembling /Users/alicewang/MARS code/Lecture 2-Mars Demo.asm

Error in /Users/alicewang/MARS code/Lecture 2-Mars Demo.asm line 19 column 10: "SysPrintInt": operand is of incorrect type

Assemble: operation completed with errors.

Registers		
Coproc 1		
Coproc 0		
Name	Number	Value
\$8 (vaddr)	8	0
\$12 (status)	12	65297
\$13 (cause)	13	0
\$14 (epc)	14	0

Error highlighted

Click to view  
Mars Message  
window: Console

# Reference: MARS Demo

The screenshot shows the MARS 4.5 IDE interface. The main window displays the assembly code for 'Lecture 2-Mars Demo.asm'. The 'Text Segment' window shows the assembly code with addresses and instructions. The 'Data Segment' window shows the data memory layout. The 'Labels' window shows the labels and their addresses. The 'Registers' window shows the state of the registers. The 'Mars Messages' window shows the output of the assembly process.

**Text Segment**

Bkpt	Address	Code	Basic	Source
	0x00400000	0x24020005	addiu \$2,\$0,5	15: li \$v0, 5 # service call: read ...
	0x00400004	0x0000000c	syscall	16: syscall # run system ...
	0x00400008	0x00028021	addiu \$16,\$0,\$2	17: move \$s0, \$v0 # move the in...
	0x0040000c	0x24020001	addiu \$2,\$0,1	19: li \$v0, 1 # service call: print...
	0x00400010	0x00022021	addiu \$4,\$0,\$2	20: move \$a0, \$v0 # move intege...
	0x00400014	0x0000000c	syscall	21: syscall # run system ...
	0x00400018	0x24020004	addiu \$2,\$0,4	23: li \$v0, 4 # service call: print...
	0x0040001c	0x3c011001	lui \$1,4097	24: la \$a1, msg # load address...
	0x00400020	0x34250000	ori \$5,\$1,0	
	0x00400024	0x0000000c	syscall	25: syscall # run system ...

**Data Segment**

Address	Value (+0)	Value (+4)	Value (+8)	Value (+c)	Value (+10)	Value (+14)	Value (+18)	Value (+1c)
0x10010000	1819043144	1867980911	560229490	1	2	3	4	
0x10010020	6	7	0	0	0	0	0	0
0x10010040	0	0	0	0	0	0	0	0
0x10010060	0	0	0	0	0	0	0	0
0x10010080	0	0	0	0	0	0	0	0
0x100100a0	0	0	0	0	0	0	0	0
0x100100c0	0	0	0	0	0	0	0	0

**Labels**

Label	Address
Lecture 2-Mars Demo.asm	
msg	0x10010000
ArrayA	0x1001000c

**Registers**

Name	Number	Value
\$zero	0	0
\$at	1	0
\$v0	2	0
\$v1	3	0
\$a0	4	0
\$a1	5	0
\$a2	6	0
\$a3	7	0
\$t0	8	0
\$t1	9	0
\$t2	10	0
\$t3	11	0
\$t4	12	0
\$t5	13	0
\$t6	14	0
\$t7	15	0
\$s0	16	0
\$s1	17	0
\$s2	18	0
\$s3	19	0
\$s4	20	0
\$s5	21	0
\$s6	22	0
\$s7	23	0
\$s8	24	0
\$s9	25	0
\$k0	26	0
\$k1	27	0
\$gp	28	26846822
\$sp	29	2147479548
\$fp	30	0
\$ra	31	0
pc		4194304
hi		0
lo		0

**Mars Messages**

Error in /Users/alicewang/MARS code/Lecture 2-Mars Demo.asm line 19 column 10: "SysPrinting": operand is of incorrect type  
Assemble: operation completed with errors.

Assemble: assembling /Users/alicewang/MARS code/Lecture 2-Mars Demo.asm  
Assemble: operation completed successfully.

Click to view  
Execute windows

.text  
Instruction Memory:  
Your code after  
assembled

.data  
Data Memory:  
Where your Array,  
strings and  
variables are  
stored

# Reference: MARS Demo

The screenshot shows the MARS 4.5 IDE interface. The top menu bar includes File, Edit, Run, Settings, Tools, and Help. Below the menu is a toolbar with various icons. A red box highlights the 'Run' button (a green play icon) in the toolbar. The main window is divided into several panes: 'Text Segment' (showing assembly code), 'Labels' (showing labels for the code), 'Data Segment' (showing memory values), and 'Registers' (showing the state of CPU registers). The 'Text Segment' pane shows assembly code for 'Lecture 2-Mars Demo.asm'. The 'Registers' pane shows a table of registers and their values. The 'Data Segment' pane shows a table of memory addresses and their values. The 'Mars Messages' pane at the bottom shows error messages and assembly status.

Run speed at max (no interaction)

Run all

Run 1 step

Reset to start

Register Table: View data stored in registers

Click here to see your strings in ASCII

Click here to see your strings in ASCII

# Reference: MARS Demo

The screenshot shows the MARS 4.5 IDE interface. The top menu bar includes File, Edit, Run, Settings, Tools, and Help. Below the menu is a toolbar with various icons. The main window is divided into several panes:

- Text Segment:** Displays assembly code with columns for Bkpt, Address, Code, Basic, and Source. The code includes instructions like `addiu $2,$0,5`, `syscall`, `move $s0,$v0`, `li $v0,1`, `addiu $2,$0,1`, `move $a0,$s0`, `syscall`, `li $v0,4`, `la $a0,msg`, and `ori $4,$1,0`.
- Data Segment:** A table showing memory addresses and their values at different offsets from the base address `0x10010000`. The values are in hexadecimal.
- Labels:** A list of labels and their addresses, including `msg` at `0x10010000` and `ArrayA` at `0x1001000c`.
- Registers:** A table on the right showing the state of registers. The `$s0` register is highlighted with a red arrow pointing to it from the text "Register \$s0 is updated".
- Mars Messages:** A text area at the bottom left showing the output of the program: `5Hello World!` and `--- program is finished running ---`.

Red arrows point from the text annotations to specific elements in the interface:

- One arrow points to the `Run` button in the top menu bar.
- Another arrow points to the `Execute` button in the `Text Segment` pane.
- A third arrow points to the `Drop down to view stack, heap, etc.` text.
- A fourth arrow points to the `Hexadecimal Addresses` checkbox.
- A fifth arrow points to the `Hexadecimal Values` checkbox.
- A sixth arrow points to the `ASCII` checkbox.

Set  
breakpoints  
here

Register \$s0 is  
updated

Drop down to view stack,  
heap, etc.

Click these to view data or  
addresses in Hex vs Dec



# References: Keyboard Shortcuts

- F3 – Assemble and run
- F5 – Run the program to the next breakpoint, if any
- F7 – Single-step one instruction
- F8 – Back up one instruction
- F12 – Reset program and start over

# Extra: MARS Plug-ins

- Tools are plug-ins to extend MARS functionality
- Many useful tools are already included including one developed by a UTD student
  - VisualStack tool displays the state of the stack during a program execution (UTD)
  - Floating-point representation tool displays floating point number representations and converts between them
  - Instruction counter tool shows the number of instructions executed per type (R-type, I-type and J-type)

