



SLP REPORT

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## Report Title

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## List of Symbols

$x$	position
$v$	velocity
$a$	acceleration
$t$	time
$F$	force

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# 1 Abstract

This supervised learning project develops a theory & computation of lagrangian coherent structures using 2 approaches i.e., one is *lagrangian approach* and the other is *eularian approach*. Both these approaches have their own advantages and disadvantages. We will go through their approaches and deep mathematical relationship that exists between two of them and we will define new Eularian diagnostic: Infinitesimal-time LCS (iLCS). iLCS will be shown to be the limit of LCS as  $t \rightarrow 0$  and finally using the iLCS we will demonstrate the effectiveness of iLCS using double gyre and comparing the alteration rate field to F.I.L.E. field.

# 2 Introduction

These diagnostics can help to predict how particles spread in a fluid from over a certain time interval. However, when you look at the lagrangian methods, they rely on the integration of particle trajectories which is time consuming & computationally expensive but the eularian approach, they use the eularian rate of strain tensor which is calculated from the gradients of velocity i.e., here we analyze the system without integration which reduces time & computational power.

Now let us look at both the approaches and compare them.

## 3 Literature Review

This section contains review of papers in bibliography. From these we take the foundation & implement it for one example.

### 3.1 Lagrangian Approach

Consider the Dynamical System,

$$\begin{aligned}\frac{d}{dt}(n(t)) &= V\left(\left(\frac{x}{t}\right), t\right) \\ x_0 &= x(t_0) \\ x &\in \mathbb{R}^n, t \in \mathbb{R}\end{aligned}\tag{3.1}$$

For LCS, it is needed to compute Finite-Time-Lyapunov-Exponent (F.L.L.E), with a F.L.L.E for each grid point the structures can be plotted.

F.L.L.E is a scalar  $\sigma_{t_0}^T(n)$  which represents structures of a fluid at a location. The maximum show the atrocity (or repelling barriers). Let's say a particle at  $\mathcal{X}(t_0)$  goes to a new location after time  $T$ .

Flow map of that point can be written as

$$F_{t_0}^t(n_0) = n_0 + \int_{t_0}^T V(x(t), t) dt\tag{3.2}$$

Let's say there is another point close to  $x(t_0)$  which is  $y = x + dx(t_0)$ . After a time interval  $T$ ,

distance between these 2 points becomes

$$\begin{aligned} 8n(t_0 + T) &= F_{t_0}^{toti}(y) - F_{t_0}^{toti}(x) \\ &= \nabla F_{t_0}^{toti}(x) \end{aligned} \quad (3.3)$$

From above equation we can calculate the neon strain tensor,

$$C = \nabla F_{t_0}^{toti}(x)^T \dot{F}_{t_0}^{toti}(n) \quad (3.4)$$

Eigan values of which are  $\lambda_1, \lambda_2, \dots, \lambda_n$  & associated normalized eigenvectors,  $\epsilon_{\lambda_i}$  ( $i \in \{1, 2, 3, \dots, n\}$ )

$\therefore$  From the maximum eigenvalue of chuchy green tensor F.I.L.E can be calculated as

$$\sigma_{t_0}^T(n_0) = \frac{1}{2|T|} \log(\lambda_n) \quad (3.5)$$

#TODO: what?

$$\begin{aligned} \lambda_n &= \max eig(???) \\ &= \max eig(\nabla F_{t_0}^{toti}(x)^T \dot{F}_{t_0}^{toti}(n)) \end{aligned} \quad (3.6)$$

To complete F.I.L.E, it is necessary to have locations of particles at initial state  $t = t_0$  & at  $t = t_0 + T$ .  $\therefore$  Flow map can be determined.

#TODO: Complete Formula

$$F_{t_0}^{toti^T} = \quad (3.7)$$

#TODO: Insert Diagram.

Now let's see the Eulerian Approach.

## 3.2 Eulerian Approach

The Eulerian role of strain Tensor is defined as

$$S(n, t) = \frac{1}{2} \nabla(x, t) + \nabla V(x, t)^T \quad (3.8)$$

and eigan values of which are  $S_1 < S_2 < \dots < S_n$  and associated normalized eigen vectors,  $\epsilon_{S_i}$   $i \in \{1, 2, \dots, n\}$

From the eigen values of eulerian rate of stain tensor, one can identify regions of flow which are more attracting & repelling.

There  $S_1 \rightarrow$  minimum eigen values provides measure of attraction &  $S_2$  maximum value of repulsion.

### 3.2.1 Relation between Cauchy-Green Strain Tensor & Eulerian Rate of Strain Tensor

Eigen value of  $S$  as F.I.L.E limit as integration of time goes to 0.

For small  $|T|$ , let us expand  $C_{t_0}^t(n)$  as #TODO: Doubt in eq??

$$C_{t_0}^t(n) = 1 + 2T\overline{IS}(x, t_0) + T^2 S(n, t_0) + ll_2 T^3 Q(x, t_0) + O(T^4) \quad (3.9)$$

Where, #TODO: Doubt in eq??

$$\overline{IS} = \frac{1}{2} [\nabla a(x, t_0) + (\nabla a(x, t_0))^T] + \nabla V(x, t_0)^T \dot{\nabla} V(x, t_0) \quad (3.10)$$

Where acceleration field  $a(x, t_0)$  is

$$a(x, t_0) = \frac{d}{dt} V(x, t_0) = \frac{\partial}{\partial t} V(x, t_0) + V(x, t_0) \dot{\nabla} V(x, t_0) \quad (3.11)$$

$$\lambda_n = \lambda^+(C_{t_0}^t(x)) \text{ for small, } T > 0 \quad (3.12)$$

We can neglect  $O(T^2)$  in #TODO: what???

$$\therefore \lambda^+(C_{t_0}^t(x)) = 1 + 2T\lambda^x(S(x, t_0)) + O(T^2) \quad (3.13)$$

$$\begin{aligned} \log(\lambda_n) &= \log(1 + 2T\lambda^+(S(x, t_0))) \\ &= 2T\lambda^+(S(x, t_0)) \\ &= 2TS_n(x, t_j) \end{aligned} \quad (3.14)$$

In the limit of small  $T$ ,  $\log(1 + \epsilon) = \epsilon$



$$\begin{aligned}
\sigma_{t_0}^T &= \frac{1}{2|T|} \log(\lambda_n) \\
&= \frac{1}{2T} S(x, t_0) \\
&= S_n(x, t_0)
\end{aligned} \tag{3.15}$$

For  $T < 0$ , with small  $T$

$$\lambda^+(C_{t_0}^t(x)) = 1 + 2T\lambda^-(S(x, t_0)) \tag{3.16}$$

$$\begin{aligned}
\log(\lambda_n) &= 2T\lambda^-(S(x, t_0)) \\
&= 2TS_1(x, t_0)
\end{aligned} \tag{3.17}$$

$\therefore |T| = -T$  if  $T < 0$

$$\sigma_{t_0}^t = \frac{1}{2|T|} \log(\lambda_n) = -S_1(x, t_0) \tag{3.18}$$

$\therefore$  We can summarize as follows,

$$\sigma_{t_0}^t = \pm S^\pm(x, t_0) \text{ as } t - t_0 \rightarrow 0^\pm \tag{3.19}$$

$$\nabla V = \begin{bmatrix} \frac{\partial U}{\partial x} & \frac{\partial U}{\partial y} \\ \frac{\partial V}{\partial x} & \frac{\partial V}{\partial y} \end{bmatrix} \tag{3.20}$$

#TODO: Doubt??

$$\nabla S = \begin{bmatrix} \frac{\partial U}{\partial x} & ll_2(\frac{\partial U}{\partial y} + \frac{\partial V}{\partial x}) \\ ll_2(\frac{\partial U}{\partial y} + \frac{\partial V}{\partial x}) & \frac{\partial V}{\partial y} \end{bmatrix} \tag{3.21}$$

## 4 Examples

### 4.1 Double Gyre

Let's look at the double gyre flow. This flow comes from hamiltonian stream function.

$$\Psi(x, y, t) = A \sin(\pi f(x, t)) \sin(\pi y) \quad (4.1)$$

Where,

$$f(x, t) = t \sin(wt)x^2 + (1 - 2\epsilon \sin(wt)) \quad (4.2)$$

We can calculate the velocity field  $V = (U, V)$  as

$$\begin{aligned} x' &= U(x, y, t) \\ &= -A\pi \sin(\pi f(x, t)) \cos(\pi y) \end{aligned} \quad (4.3)$$

$$\begin{aligned} y' &= v(x, y, t) \\ &= A\pi \cos(\pi f(x, t)) \sin(\pi y) \frac{\partial F}{\partial x} \end{aligned} \quad (4.4)$$

# TODO: Figure

We use the parameters,  $A = 0.1$ ,  $w = 0.2\pi$  and  $\epsilon = 0.25$

$$\begin{aligned}
\therefore \nabla V &= \begin{bmatrix} \frac{\partial U}{\partial x} & \frac{\partial U}{\partial y} \\ \frac{\partial V}{\partial x} & \frac{\partial V}{\partial y} \end{bmatrix} \\
&= \begin{bmatrix} -\pi^2 A \cos(\pi f) \cos(\pi y) \frac{\partial f}{\partial x} & \pi^2 A \sin(\pi f) \sin(\pi y) \\ -\pi^2 A \sin(\pi f) \sin(\pi y) \frac{\partial f}{\partial x} + \pi f \cos(\pi f) \sin(\pi y) \frac{\partial^2 f}{\partial x^2} & \pi^2 A \cos(\pi f) \cos(\pi y) \frac{\partial f}{\partial x} \end{bmatrix} \quad (4.5)
\end{aligned}$$

Now Eulerian Rate of Strain Tensor,

$$\therefore \nabla V = \begin{bmatrix} \frac{\partial U}{\partial x} & ll_2(\frac{\partial U}{\partial y} + \frac{\partial V}{\partial x}) \\ ll_2(\frac{\partial U}{\partial y} + \frac{\partial V}{\partial x}) & \frac{\partial V}{\partial y} \end{bmatrix} \quad (4.6)$$

Now the below figure shows a comparison of the F.I.L.E field for a short integration Time  $T = -0.5$  first with an approximation to first order in  $T$ .

# TODO: Figure

## 5 Conclusion

These mathematical connections prove that the attraction and repulsion rates are the limits of E.I.L.E. as integration time goes to 0. Additionally this manuscript also shows that for small integration time  $|T| \ll 1$  eigen vectors for cauchy-green strain tensor are equal to eularian rate of strain tensor.

### 5.1 Equality of Eigen Vectors of $S$ & $C$

$$\begin{aligned} S\epsilon_i &= S_i\epsilon_i \\ 2iS\epsilon_i + \epsilon_i &= 2T_{S_i}\epsilon_i + \epsilon_i \\ (2iS + 1)\epsilon_i &= (2iS_i + 1)\epsilon_i \\ C\epsilon_i &= \lambda_i\epsilon_i \end{aligned} \tag{5.1}$$

$\Rightarrow \epsilon_i$  is an eigen vector of  $S$  then  $\epsilon_i$  is an eigen vector of  $C$ .

$\therefore$  We can say as  $T$  goes to 0, eigen vector of  $C$  is same as eigen vector of  $S$ .