

REAL TIME IMPLEMENTATION OF OPTIMAL PATH PLANNING FOR AUTONOMOUS ROBOT

PROJECT REPORT

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requirements for the award of the degree
of
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In
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by

Harshdeep Singh

Lavish Garg

Rishi

Divya Singh

Supervised by

Dr. Afzal Sikander



**Department of Instrumentation and Control Engineering
Dr. B. R. Ambedkar National Institute of Technology
Jalandhar- 144 011 Punjab (INDIA)**

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