Theorem

Let $y_p(x)$ be any particular solution to

$$ay'' + by' + cy = r(x)$$
, a, b, c constants

Also, let $c_1y_1(x) + c_2y_2(x)$ denote the general solution to the complementary equation. Then the general solution to the DE is

$$y(x) = c_1 y_1(x) + c_2 y_2(x) + y_n(x).$$

Proof

First, we will show y(x) satisfies the DE <u>and</u> second, that any solution to the DE can be written in the form of y(x).

1.
$$ay'' + by' + cy = a(c_1y_1 + c_2y_2 + y_p)'' + b(c_1y_1 + c_2y_2 + y_p)' + c(c_1y_1 + c_2y_2 + y_p)$$

$$= [a(c_1y_1 + c_2y_2)'' + b(c_1y_1 + c_2y_2)' + c(c_1y_1 + c_2y_2)]$$

$$+ ay_p'' + by_p' + cy_p$$

$$= 0 + r(x) = r(x).$$

2. Now let z(x) be <u>any</u> solution to the given DE. Now, consider $z(x) - y_p$;

So,
$$a(z(x) - y_p)'' + b(z(x) - y_p)' + c(z(x) - y_p) = az'' + bz' + cz$$

$$-(ay_p'' + by_p' + cy_p)$$

$$= r(x) - r(x)$$

$$= 0$$

Therefore, $z(x) - y_p$ is a solution to the *complementary equation*. But, $c_1y_1(x) + c_2y_2(x)$ is the general solution to the complementary equation, so there are constants c_1 and c_2 such that

$$z(x) - y_p = c_1 y_1(x) + c_2 y_2(x)$$
$$z(x) = c_1 y_1(x) + c_2 y_2(x) + y_n(x).$$

and

Examples

1.
$$y'' + 4y' + 3y = 3x$$

2.
$$y'' - y' - 2y = 2e^{3x}$$

3.
$$y'' - 4y' + 4y = 7\sin(t) - \cos(t)$$

4.
$$y'' + 5y' + 6y = 3e^{-2x}$$

r(x)	Initial guess for $y_p(x)$
k (a constant)	A (a constant)
ax + b	$\mathit{Ax} + \mathit{B}$ (<i>Note</i> : The guess must include both terms even if $b = 0$.)
ax^2+bx+c	Ax^2+Bx+C (Note: The guess must include all three terms even if b or c are zero.)
Higher-order polynomials	Polynomial of the same order as $r(x)$
$ae^{\lambda x}$	$Ae^{\lambda x}$
$a\cos\beta x + b\sin\beta x$	$A\cos eta x + B\sin eta x$ (<i>Note</i> : The guess must include both terms even if either $a=0$ or $b=0$.)
$ae^{lpha x}\coseta x+be^{lpha x}\sineta x$	$Ae^{lpha x}\cos\!eta x+Be^{lpha x}\sin\!eta x$
$(ax^2+bx+c)e^{\lambda x}$	$(Ax^2+Bx+C)e^{\lambda x}$
$(a_2 x^2 + a_1 x + a0) \cos\!eta x \ + (b_2 x^2 + b_1 x + b_0) \sin\!eta x$	$(A_2 x^2 + A_1 x + A_0) \cos\!eta x \ + (B_2 x^2 + B_1 x + B_0) \sin\!eta x$
$(a_2x^2+a_1x+a_0)e^{lpha x}\coseta x \ +(b_2x^2+b_1x+b_0)e^{lpha x}\sineta x$	$(A_2 x^2 + A_1 x + A_0) e^{lpha x} \coseta x \ + (B_2 x^2 + B_1 x + B_0) e^{lpha x} \sineta x$

Examples

1.
$$y'' - 9y = -6\cos 3x$$

2.
$$x'' + 2x' + x = 4e^{-t}$$

3.
$$y'' - 2y' + 5y = 10x^2 - 3x - 3$$

4.
$$y'' - 3y' = -12t$$

Variation of Parameters

Given y'' + py' + qy = r(x) where r(x) is a combination of polynomials, exponentials and/or trig functions. p, q constants

Let $c_1y_1(x) + c_2y_2(x)$ be the general solution to the complementary equation.

Consider a potential particular solution of the form $y_p(x) = u(x)y_1(x) + v(x)y_2(x)$ where u(x), v(x) may not be constants.

$$y_p = uy_1 + vy_2$$

$$y'_p = u'y_1 + uy'_1 + v'y_2 + vy'_2$$

$$y''_p = (u'y_1 + v'y_2)' + u'y'_1 + uy''_1 + v'y'_2 + vy''_2$$

Substituting these into the DE,

$$y'' + py' + qy = [(u'y_1 + v'y_2)' + u'y_1' + uy_1'' + v'y_2' + vy_2'']$$

$$+p[u'y_1 + uy_1' + v'y_2 + vy_2'] + q[uy_1 + vy_2]$$

$$= u[y_1'' + py_1' + qy_1] + v[y_2'' + py_2' + qy_2] + (u'y_1 + v'y_2)' + p(u'y_1 + v'y_2) + (u'y_1' + v'y_2').$$

Now y_1 and y_2 are solutions to the complementary equation, so the first 2 terms are zero. Thus, we have

$$(u'y_1 + v'y_2)' + p(u'y_1 + v'y_2) + (u'y_1' + v'y_2') = r(x)$$

If we impose the additional condition that $u'y_1 + v'y_2 = 0$, the first 2 terms are zero, and we are left with $u'y_1' + v'y_2'$ needing to equal r(x).

We now have a system of two equations with two unknowns, u' and v' that are needed to satisfy the DE. (We get u(x) and v(x) with basic integration.)

$$y_1u' + y_2v' = 0$$

$$y_1'u' + y_2'v' = r(x)$$

And our final solution is $y_p(x) = u(x)y_1(x) + v(x)y_2(x)$.

(Note- We do not need the "+c" when anti-differentiating to get u(x), v(x).)

Cramer's Rule

$$a_1 z_1 + b_1 z_2 = r_1$$

$$a_2z_1 + b_2z_2 = r_2$$

$$z_{1} = \frac{\begin{vmatrix} r_{1} & b_{1} \\ r_{2} & b_{2} \end{vmatrix}}{\begin{vmatrix} a_{1} & b_{1} \\ a_{2} & b_{2} \end{vmatrix}} = \frac{r_{1}b_{2} - b_{1}r_{2}}{a_{1}b_{2} - b_{1}a_{2}} \qquad z_{2} = \frac{\begin{vmatrix} a_{1} & r_{1} \\ a_{2} & r_{2} \end{vmatrix}}{\begin{vmatrix} a_{1} & b_{1} \\ a_{2} & b_{2} \end{vmatrix}} = \frac{a_{1}r_{2} - r_{1}a_{2}}{a_{1}b_{2} - b_{1}a_{2}}$$

1. Use Cramer's Rule to solve the following system of equations:

$$x^2 z_1 + 2x z_2 = 0$$

$$z_1 - 3x^2 z_2 = 2x$$

2. $y'' - 2y' + y = \frac{e^x}{x^2}$. Solutions to the complimentary equation are e^x , xe^x .