

# Eigen Values and Eigen Vector

Module - III

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1. Solve the Eigen values

$$A = \begin{bmatrix} -1 & 3 \\ -2 & 4 \end{bmatrix}$$

So we have  $|A - \lambda I| = 0$

$$\begin{vmatrix} -1-\lambda & 3 \\ -2 & 4-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (-1-\lambda)(4-\lambda) + 6 = 0$$

$$\Rightarrow \lambda^2 - 3\lambda + 2 = 0$$

$$\Rightarrow \lambda^2 - 2\lambda - \lambda + 2 = 0$$

$$\Rightarrow \lambda(\lambda - 2) - 1(\lambda - 2) = 0$$

$$\Rightarrow (\lambda - 1)(\lambda - 2) = 0$$

$$\Rightarrow \lambda - 2 = 0 \quad | \lambda = 2 \quad \lambda - 1 = 0$$

$$\boxed{\lambda = 2} \quad \boxed{\lambda = 1}$$

The Eigen values  $\boxed{\lambda = 1, 2}$

$$\text{Now } [A - \lambda I]x = 0$$

$$(-1-\lambda)x + 3y = 0$$

$$-2x + (4-\lambda)y = 0 \quad \boxed{\text{or}}$$

Case (i)  $\Rightarrow$  If  $\lambda = 1$  in (i)

$$-2x + 3y = 0 \rightarrow (i)$$

$$-2x + 3y = 0 \rightarrow (ii)$$

$$\text{from (i)} \quad -2x + 3y = 0$$

$$2x = 3y$$

$$\Rightarrow \frac{x}{3} = \frac{y}{2} = k \text{ (say)}$$

$$x_1 = [3k, 2k]^T \quad \text{or}$$

$$x_1 = [3, 2]^T \text{ if } \lambda = 1$$

and Eigen vector for the matrix

Case (ii) If  $\lambda = 2$  in (i)

$$-3x + 3y = 0 \rightarrow (3)$$

$$-2x + 2y = 0 \rightarrow (4)$$

$$\text{from (3)} \quad -3x + 3y = 0$$

$$\Rightarrow 3x = 3y \Rightarrow \frac{x}{1} = \frac{y}{1}$$

$$\Rightarrow \frac{x}{1} = \frac{y}{1} = k \text{ (say)}$$

$$\therefore x_2 = [k, k]^T \text{ if } \lambda = 2$$

or

$$x_2 = [1, 1]^T \text{ if } \lambda = 2$$

$$\therefore \lambda_1 = 1 \quad \& \quad x_1 = [3, 2]^T$$

$$\lambda_2 = 2 \quad \& \quad x_2 = [1, 1]^T$$

2. Find all the Eigen values & and Eigen vector for the matrix  $A = \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix}$

So we have  $|A - \lambda I| = 0$

$$\begin{vmatrix} 8-\lambda & -6 & 2 \\ -6 & 7-\lambda & -4 \\ 2 & -4 & 3-\lambda \end{vmatrix} = 0$$

$$\text{Now } \lambda^3 - (\Sigma d)\lambda^2 + (\Sigma m_d)\lambda - |A| = 0$$

$$\Sigma d = 18, \Sigma m_d = 45, |A| = 0 \quad \text{---(1)}$$

where

$\Sigma d$  = Sum of the diagonal elements of  $A$ .

$\Sigma m_d$  = Sum of the minors of the diagonal elements of  $A$

$|A|$  = Determinant of  $A$

$$\text{Eqn (1)} \Rightarrow \lambda^3 - 18\lambda^2 + 45\lambda = 0$$

$$\Rightarrow \lambda(\lambda^2 - 18\lambda + 45) = 0$$

$$\Rightarrow \lambda = 0 \quad \& \quad \lambda^2 - 18\lambda + 45 = 0$$

$$\lambda^2 - 15\lambda - 3\lambda + 45 = 0$$

$$\Rightarrow \lambda(\lambda - 15) - 3(\lambda - 15) = 0$$

$$(\lambda - 3)(\lambda - 15) = 0$$

$$\lambda - 3 = 0 \quad \& \quad \lambda - 15 = 0$$

$$\boxed{\lambda = 3}$$

$$\boxed{\lambda = 15}$$

The Eigen values  $\boxed{\lambda = 0, 3, 15}$

we have  $[A - \lambda I]x = 0$

$$(8-\lambda)x - 6y + 2z = 0$$

$$-6x + (7-\lambda)y - 4z = 0 \quad \text{---(2)}$$

$$8x - 4y + (3-\lambda)z = 0$$

Case (i) If  $\lambda = 0$  in (1)

$$8x - 6y + 2z = 0 \quad \text{---(3)}$$

$$-6x + 7y - 4z = 0 \quad \text{---(4)}$$

$$8x - 4y + 3z = 0 \quad \text{---(5)}$$

from (3) & (4) by applying rule of cross multiplication, we have

$$\begin{vmatrix} x \\ -6 & 2 \\ 7 & -4 \end{vmatrix} = \begin{vmatrix} -y \\ 8 & 2 \\ -6 & -4 \end{vmatrix} = \begin{vmatrix} z \\ 8 & -6 \\ -6 & 7 \end{vmatrix}$$

$$\frac{x}{24-14} = \frac{-y}{-32+12} = \frac{z}{56-36}$$

$$\Rightarrow \frac{x}{10} = \frac{-y}{-20} = \frac{z}{20} \quad [x \neq 0, y \neq 0]$$

$$\Rightarrow \frac{x}{1} = \frac{y}{2} = \frac{z}{2} = k \quad (\text{say})$$

$$x_1 = [1k \ 2k \ 2k]$$

or

$$x_1 = [1 \ 2 \ 2]$$

if  $\lambda = 0$

Case (ii) If  $\lambda = 3$  in (1)

$$5x - 6y + 2z = 0 \quad \text{---(6)}$$

$$-6x + 4y - 4z = 0 \quad \text{---(7)}$$

$$8x - 4y + 0z = 0 \quad \text{---(8)}$$

from (6) & (7) by applying rule of cross multiplication, we have

$$\begin{vmatrix} x \\ -6 & 2 \\ -8 & -4 \end{vmatrix} = \begin{vmatrix} -y \\ 5 & 2 \\ -6 & -4 \end{vmatrix} = \begin{vmatrix} z \\ 5 & -6 \\ -6 & 4 \end{vmatrix}$$

$$\frac{x}{24-8} = \frac{-y}{-20+12} = \frac{z}{20-36}$$

$$\frac{x}{16} = \frac{-y}{-8} = \frac{z}{-16}$$

$\times 8$  by 8

$$\frac{x}{2} = \frac{y}{-1} = \frac{z}{-2} = k \text{ (say)}$$

$$x_2 = [2k \ 1k \ -2k]^T$$

(or) if  $\lambda = 3$

$$x_2 = [2 \ 1 \ -2]^T$$

Case (ii) If  $\lambda = 15$  in (I)

$$-7x - 6y + 2z = 0 \rightarrow ⑦$$

$$-6x - 8y - 4z = 0 \rightarrow ⑧$$

$$2x - 4y - 12z = 0 \rightarrow ⑨$$

from ⑦ & ⑧ by applying rule  
of cross multiplication on both  
sides.

$$\begin{vmatrix} x \\ -6 & 2 \\ -8 & -4 \end{vmatrix} = \begin{vmatrix} -y \\ -7 & 2 \\ -6 & -4 \end{vmatrix} = \begin{vmatrix} z \\ -7 & -6 \\ -6 & -8 \end{vmatrix}$$

$$\frac{x}{24+16} = \frac{-y}{28+12} = \frac{z}{56-36}$$

$$\frac{x}{40} = \frac{-y}{40} = \frac{z}{20}$$

$\times 20$  by 20

$$\frac{x}{2} = \frac{y}{-2} = \frac{z}{1} = k \text{ (say)} \quad ②$$

$$x_3 = [2k \ -2k \ 1k]^T$$

(or)

$$x_3 = [2 \ -2 \ 1]^T \text{ if } \lambda = 15$$

Convert an  $n^{\text{th}}$  order differential equation to a system of equations:

An  $n^{\text{th}}$  order differential equation

$$y^{(n)} = F(t, y, y', y'', \dots, y^{(n-1)}) \rightarrow \textcircled{1}$$

can be reduced to a system of ' $n$ ' first order differential equation as

$$\begin{aligned} x_1 &= y \xrightarrow{\text{Differentiation}} x'_1 = y' \xrightarrow{\text{Name as}} x_2 \\ x_2 &= y' \xrightarrow{} x'_2 = y'' \xrightarrow{} x_3 \\ x_3 &= y'' \xrightarrow{} x'_3 = y''' \xrightarrow{} x_4 \\ x_4 &= y''' \xrightarrow{} x'_4 = y^{IV} \xrightarrow{} x_5 \\ x_5 &= y^{IV} \xrightarrow{} x'_5 = y^V \xrightarrow{} x_6 \\ x_6 &= y^V \xrightarrow{} x'_6 = y^{VI} \xrightarrow{} x_7 \\ &\vdots && \vdots && \vdots \\ x_n &= y^{(n+1)} \xrightarrow{} x'_n = y^n \xrightarrow{} x_{n+1} \end{aligned}$$

Sub. in  $\textcircled{1}$  we get

$$x'_1 = x_2$$

$$x'_2 = x_3$$

$$x'_3 = x_4$$

$$x'_4 = x_5$$

$$\vdots \quad \vdots$$

$$x'_n = x_{n+1}$$

1. Convert the following second order differential equation as a system of first order linear differential equation and represent in the form matrix notation

$$y'' + 3ay' - 4a^2y = 0$$

Given that  $y'' + 3ay' - 4a^2y = 0 \rightarrow \textcircled{1}$

Here  $* y \rightarrow \text{dependent variable}$  and  $t \rightarrow \text{independent variable}$

The Given D.E is second order D.E

∴ choose two variables  $x_1$  and  $x_2$

Now  $x_1 = y \xrightarrow{\text{Diff.}} x_1' = y'$   $\xrightarrow{\text{name as}} x_2$   
 $x_2 = y' \xrightarrow{} x_2' = y''$

Eg ① becomes

$$y'' + 3ay' - 4a^2y = 0$$

$$\Rightarrow y'' = 4a^2y - 3ay'$$

$$\Rightarrow x_2' = 4a^2x_1 - 3ax_2$$

Hence System of first order D.E is

$$x_1' = x_2$$

[OR]

$$x_1' = 0 \cdot x_1 + 1 \cdot x_2$$

$$x_2' = 4a^2x_1 - 3ax_2$$

$$x_2' = 4a^2x_1 - 3ax_2$$

In matrix form

$$\begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 4a^2 & -3a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Diff.

$$\boxed{x' = Ax} \rightarrow \text{Homogeneous } \uparrow \text{eqn}$$

where  $x' = \begin{bmatrix} x_1' \\ x_2' \end{bmatrix}$ ;  $A = \begin{bmatrix} 0 & 1 \\ 4a^2 & -3a \end{bmatrix}$  and  $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

2. Write the following 4th order differential equation as a system of first order differential equations

$$y'''' + 3y'' - \sin t y' + 8y = t^2$$

Sos Given that  $y'''' + 3y'' - \sin t y' + 8y = t^2 \rightarrow ①$

Here  $y \rightarrow$  dependent variable and  $t \rightarrow$  independent variable  
The given differential equation is 4th order D.E

∴ choose 4 variables  $x_1, x_2, x_3$  and  $x_4$

(25)

Put  $x_1 = y \xrightarrow{\text{Diff.}} x_1' = y'$   $\xrightarrow{\text{Name as}} x_2$   
 $x_2 = y' \longrightarrow x_2' = y'' \longrightarrow x_3$   
 $x_3 = y'' \longrightarrow x_3' = y''' \longrightarrow x_4$   
 $x_4 = y''' \longrightarrow x_4' = y^{IV}$

Eqn (1) becomes  $y^{IV} + 3y'' - \sin t y' + 8y = t^2$   
 $\Rightarrow y^{IV} = -8y + \sin t y' - 3y'' + t^2$   
 $\therefore x_4' = -8x_1 + \sin t x_2 - 3x_3 + t^2$

Hence System of first order D.E i.e

$$x_1' = x_2$$

$$x_2' = x_3$$

$$x_3' = x_4$$

$$x_4' = -8x_1 + \sin t x_2 - 3x_3 + t^2$$

(012)

$$x_1' = 0 \cdot x_1 + 1 \cdot x_2 + 0 \cdot x_3 + 0 \cdot x_4 + 0 \cdot t^2$$

$$x_2' = 0 \cdot x_1 + 0 \cdot x_2 + 1 \cdot x_3 + 0 \cdot x_4 + 0 \cdot t^2$$

$$x_3' = 0 \cdot x_1 + 0 \cdot x_2 + 0 \cdot x_3 + 1 \cdot x_4 + 0 \cdot t^2$$

$$x_4' = -8x_1 + \sin t x_2 - 3x_3 + 0 \cdot x_4 + t^2$$

In matrix form

$$\begin{bmatrix} x_1' \\ x_2' \\ x_3' \\ x_4' \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -8 & \sin t & -3 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \\ t^2 \end{bmatrix}$$

$$x' = Ax + F \rightarrow \text{Non-homogeneous } \xrightarrow{\text{diff.}} \text{Equation}$$

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where  $x' = \begin{bmatrix} x_1' \\ x_2' \\ x_3' \\ x_4' \end{bmatrix}$ ,  $A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -8 & \sin t & -3 & 0 \end{bmatrix}$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}; F = \begin{bmatrix} 0 \\ 0 \\ 0 \\ t \end{bmatrix}$$

Home work

- Convert the differential equation  $y''' + 5y' + 6y = 0$  into System of linear differential equation.
- Convert the differential equation  $y''' + 2y'' + y' + 2y = 0$  into System of linear differential equation.

Solution system of linear differential equation  
by diagonalization method :-

Homogeneous :-

$$\text{Let } \dot{x} = Ax \rightarrow \textcircled{1}$$

Assume solution be as

$$x = py$$

Diff

$$\dot{x} = py'$$

Eqn \textcircled{1} becomes

$$py' = Apy$$

$$y' = (\bar{p}^T A p)y$$

$$y' = Dy$$

where  $D = \bar{p}^T A p$

$$\therefore y' = Dy$$

In  $2 \times 2$  matrix

$$\begin{bmatrix} y'_1 \\ y'_2 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

Solve D.E by variable separable method [VSM]

$$y'_1 = \lambda_1 y_1 \rightarrow y_1 = c_1 e^{\lambda_1 t}$$

$$y'_2 = \lambda_2 y_2 \rightarrow y_2 = c_2 e^{\lambda_2 t}$$

Now Solution of System i.e., given by

$$x = py$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$x_1 = a_1 y_1 + b_1 y_2$$

$$x_2 = a_2 y_1 + b_2 y_2$$

$$x = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} y_1 + \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} y_2$$

$$x = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} c_1 e^{\lambda_1 t} + \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} c_2 e^{\lambda_2 t}$$

In general  $[n \times n]$

$$\begin{bmatrix} y'_1 \\ y'_2 \\ \vdots \\ y'_n \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 & 0 & \dots \\ 0 & \lambda_2 & 0 & \dots \\ 0 & 0 & \ddots & \dots \\ \dots & \dots & \dots & \lambda_n \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

Solve D.E by variable separable method [VSM]

$$y'_1 = \lambda_1 y_1 \xrightarrow{VSM} y_1 = C_1 e^{\lambda_1 t}$$

$$y'_2 = \lambda_2 y_2 \longrightarrow y_2 = C_2 e^{\lambda_2 t}$$

$$\vdots \quad \vdots \quad \vdots$$

$$y'_n = \lambda_n y_n \longrightarrow y_n = C_n e^{\lambda_n t}$$

Now Solution of System i.e., given by

$$x = py$$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} a_1 & a_2 & \dots & a_n \\ b_1 & b_2 & \dots & b_n \\ \vdots & \vdots & \ddots & \vdots \\ z_1 & z_2 & \dots & z_n \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$$x_1 = a_1 y_1 + a_2 y_2 + \dots + a_n y_n$$

$$x_2 = b_1 y_1 + b_2 y_2 + \dots + b_n y_n$$

$$\vdots \quad \vdots \quad \vdots \quad \vdots$$

$$x_n = z_1 y_1 + z_2 y_2 + \dots + z_n y_n$$

$$X = \begin{bmatrix} a_1 \\ b_1 \\ \vdots \\ z_1 \end{bmatrix} y_1 + \begin{bmatrix} a_2 \\ b_2 \\ \vdots \\ z_2 \end{bmatrix} y_2 + \dots + \begin{bmatrix} a_n \\ b_n \\ \vdots \\ z_n \end{bmatrix} y_n$$

where  $y_1 = c_1 e^{x_1 t}$ ,  $y_2 = c_2 e^{x_2 t}$  ...  $y_n = c_n e^{x_n t}$

Eigen value and Stability of the System :  $\Rightarrow$

The table below given ~~are~~ a complete overview of the stability corresponding to each type of eigen value

Eigen values	Stability
All real and positive	Unstable
All real and negative	Stable
Mixed positive & negative real	Unstable
$a+ib$	Unstable
$-a+ib$	Stable
$0+bi$	Unstable
Repeated values	Depends upon orthogonality of eigen vectors

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1. Solve the system  $\dot{x} = \begin{bmatrix} -5 & 1 \\ 4 & -2 \end{bmatrix}x$  by diagonalization and hence discuss the stability of the system

So Given that  $\dot{x} = \begin{bmatrix} -5 & 1 \\ 4 & -2 \end{bmatrix}x$

$$\Rightarrow \dot{x} = Ax \rightarrow (i) \text{ where } A = \begin{bmatrix} -5 & 1 \\ 4 & -2 \end{bmatrix}$$

we have  $|A - \lambda I| = 0 \Rightarrow \begin{vmatrix} -5-\lambda & 1 \\ 4 & -2-\lambda \end{vmatrix} = 0$

$$\Rightarrow (-5-\lambda)(-2-\lambda) - 4 = 0 \Rightarrow 10 + 5\lambda + 2\lambda + \lambda^2 - 4 = 0$$

$$\Rightarrow \lambda^2 + 7\lambda + 6 = 0$$

Solving  $\boxed{\lambda = -1, -6}$  → Eigen values

Now consider  $[A - \lambda I]x = 0$

$$\begin{aligned} \Rightarrow (-5-\lambda)x + y &= 0 \\ 4x + (-2-\lambda)y &= 0 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \rightarrow (I)$$

Case(i) If  $\lambda = -1$  in (I)

$$-4x + y = 0 \rightarrow (1)$$

$$4x - y = 0 \rightarrow (2)$$

from (1)  $-4x + y = 0$

$$x + y = 0$$

$$\frac{x}{1} = \frac{y}{4} = k \text{ (say)}$$

$$x_1 = [1k, 4k]^T$$

(or)

$$\boxed{x_1 = [1, 4]^T \text{ if } \lambda = -1}$$

Case(ii) If  $\lambda = -6$  in (I)

$$x + y = 0 \rightarrow (3)$$

$$4x + 4y = 0 \rightarrow (4)$$

from (3)  $x + y = 0$

$$x = -y$$

$$\Rightarrow \frac{x}{1} = \frac{y}{1} = k \text{ (say)}$$

$$x_2 = [-1k, 1k]^T$$

(or)

$$\boxed{x_2 = [-1, 1]^T \text{ if } \lambda = -6}$$

The modal matrix or Spectral matrix  $P = [x_1, x_2]$

$$P = \begin{bmatrix} 1 & -1 \\ 4 & 1 \end{bmatrix}$$

To find  $\bar{P}^1 = ?$

we have  $\bar{P}^1 = \frac{\text{adj } P}{|P|}$ ;  $|P| = 1+4$

$$\text{adj } P = \begin{bmatrix} 1 & 1 \\ -4 & 1 \end{bmatrix} \quad |P| = \boxed{s}$$

$$\therefore \bar{P}^1 = \frac{1}{s} \begin{bmatrix} 1 & 1 \\ -4 & 1 \end{bmatrix}$$

$$\bar{P}^1 = \begin{bmatrix} 1/s & 1/s \\ -4/s & 1/s \end{bmatrix} \quad \text{or} \quad P = \begin{bmatrix} 0.2 & 0.2 \\ -0.8 & 0.2 \end{bmatrix}$$

Now to find  $D$

$$D = \begin{bmatrix} 1/s & 1/s \\ -4/s & 1/s \end{bmatrix} \begin{bmatrix} -5 & 1 \\ 4 & -2 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 4 & 1 \end{bmatrix}$$

$$D = \begin{bmatrix} -1 & 0 \\ 0 & -6 \end{bmatrix}$$

we have  $x' = Ax$  from given data

put  $x = Py \rightarrow$  (Assume soln)  
Diff.

$$x' = Py'$$
  
Exn (1) becomes

$$x' = Py' = Apy$$

$$y' = (\bar{P}^1 A P) y$$

$$y' = Dy$$

$$\Rightarrow \begin{bmatrix} y'_1 \\ y'_2 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -6 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$y'_1 = -y_1 + 0y_2$$

$$y'_2 = 0y_1 - 6y_2$$

$$y_1' = -y_1$$

$$y_2' = -6y_2$$

$$\frac{dy_1}{dt} = -y_1 \quad [SVM]$$

$$\frac{dy_2}{dt} = -6y_2$$

$$\frac{dy_1}{y_1} = -dt$$

$$\frac{dy_2}{y_2} = -6dt$$

on Integrating on both sides we get

$$\int \frac{dy_1}{y_1} = - \int dt$$

$$\int \frac{dy_2}{y_2} = -6 \int dt$$

$$\log y_1 = -t + c_1$$

$$\log y_2 = -6t + c_2$$

$$y_1 = e^{-t+c_1}$$

$$y_2 = e^{-6t+c_2}$$

$$= e^{-t} \cdot e^{c_1}$$

$$y_2 = e^{-6t} \cdot e^{c_2}$$

$$\boxed{y_1 = C_1 e^{-t}}$$

$$\boxed{y_2 = C_2 e^{-6t}}$$

$$\text{where } e^{c_1} = C_1$$

where

$$e^{c_2} = C_2$$

$$\text{Let } x = py$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} C_1 e^{-t} \\ C_2 e^{-6t} \end{bmatrix}$$

$$x_1 = C_1 e^{-t} - C_2 e^{-6t}$$

$$x_2 = 4C_1 e^{-t} + C_2 e^{-6t}$$

$$x = C_1 \begin{bmatrix} 1 \\ 4 \end{bmatrix} e^{-t} + C_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^{-6t}$$

The Eigen values are real and distinct and negative  
[Real and negative]

$\therefore$  The System is stable

2. Solve  $x' = \begin{bmatrix} -2 & -1 & 8 \\ 0 & -3 & 8 \\ 0 & -4 & 9 \end{bmatrix} x$  by diagonalization

So Given that  $x' = \begin{bmatrix} -2 & -1 & 8 \\ 0 & -3 & 8 \\ 0 & -4 & 9 \end{bmatrix} x$

$$\Rightarrow x' = Ax \rightarrow \textcircled{1}$$

where  $A = \begin{bmatrix} -2 & -1 & 8 \\ 0 & -3 & 8 \\ 0 & -4 & 9 \end{bmatrix}$

The characteristic equation of  $A$  is  $|A - \lambda I| = 0$

$$\begin{vmatrix} -2-\lambda & -1 & 8 \\ 0 & -3-\lambda & 8 \\ 0 & -4 & 9-\lambda \end{vmatrix} = 0$$

Now  $\lambda^3 - (\Sigma d)\lambda^2 + (\Sigma m_d)\lambda - |A| = 0$

where  $\frac{\Sigma d = +4}{\lambda^3}$   $\frac{\Sigma m_d = -7}{\lambda^2}$   $\frac{|A| = -10}{\lambda^0}$   
 $\therefore \lambda^3 - 4\lambda^2 - 7\lambda + 10 = 0$

Solving  $\lambda = -2, 1, 5$  → Eigen values

Consider  $[A - \lambda I][x] = 0$

$$\begin{cases} (-2-\lambda)x - y + 8z = 0 \\ 0x + (-3-\lambda)y + 8z = 0 \\ 0x - 4y + (9-\lambda)z = 0 \end{cases} \rightarrow \textcircled{2}$$

case (i) If  $\lambda = -2$  in  $\textcircled{2}$

$$0x - y + 8z = 0 \rightarrow \textcircled{1}$$

$$0x - y + 8z = 0 \rightarrow \textcircled{2}$$

$$0x - 4y + 11z = 0 \rightarrow \textcircled{3}$$

from ② & ③ by applying

rule of cross multiplication,  
we have

$$\Rightarrow \frac{x}{-11+32} = -\frac{y}{0-0} = \frac{z}{0-0}$$

$$\Rightarrow \frac{x}{21} = \frac{y}{0} = \frac{z}{0}$$

$\times 21$  by 21,

$$\frac{x}{1} = \frac{y}{0} = \frac{z}{0} = k \text{ (say)}$$

$$x_1 = [k, 0, 0]^T$$

(or)  $x_1 = [1, 0, 0]^T \text{ if } \lambda = -2$

case 1

case (ii) :- If  $\lambda = 1$  in ①

$$-7x - y + 8z = 0 \rightarrow ⑦$$

$$0x - 8y + 8z = 0 \rightarrow ⑧$$

$$0x - 4y + 4z = 0 \rightarrow ⑨$$

From ⑦ & ⑧ by applying  
RCM, we have

$$\Rightarrow \frac{x}{56} = -\frac{y}{56-0} = \frac{z}{56-0}$$

$$\Rightarrow \frac{x}{56} = -\frac{y}{56} = \frac{z}{56}$$

$\times 56$  by 56

$$\Rightarrow \frac{x}{1} = \frac{y}{1} = \frac{z}{1} = k \text{ (say)}$$

$$x_3 = [1k, 1k, 1k]^T \text{ if }$$

(or)  $x_3 = [1, 1, 1]^T \text{ if } \lambda = 1$

case (ii) :- If  $\lambda = 1$  in ①

$$-3x - y + 8z = 0 \rightarrow ④$$

$$0x - 4y + 8z = 0 \rightarrow ⑤$$

$$0x - 4y + 8z = 0 \rightarrow ⑥$$

from ④ & ⑤ by applying  
RCM, we have

$$\Rightarrow \frac{x}{24} = -\frac{y}{24-0} = \frac{z}{12-0}$$

$$\Rightarrow \frac{x}{24} = \frac{y}{24} = \frac{z}{12}$$

$\times 12$  by 12

$$\Rightarrow \frac{x}{2} = \frac{y}{2} = \frac{z}{1} = k \text{ (say)}$$

$$\Rightarrow x_2 = [2k, 2k, 1k]$$

(or)  $x_2 = [2, 2, 1]^T \text{ if } \lambda = 1$

there

The modal matrix  $P = [x_1 \ x_2 \ x_3]$

$$P = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

To find  $\bar{P}^{-1} = ?$ ;  $\bar{P}^{-1} = \frac{\text{adj } P}{|P|}$  ;  $|P| = 1$

$$\bar{P}^{-1} = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

Also to find :- Diag =  $\bar{P}^{-1} A P$

$$\text{①} = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} -2 & -1 & 8 \\ 0 & -3 & 8 \\ 0 & -4 & 9 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$\text{②} = \begin{bmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

Eq ① becomes  $x' = Ax$  [Given data]

put  $x = Py \rightarrow \text{②}$  [Assume soln]

Diff

$$x' = \bar{P}y'$$

Eq ② becomes  $\bar{P}y' = A\bar{P}y$

$$\Rightarrow y' = (\bar{P}^{-1} A \bar{P})y$$

$$y' = \text{②}y$$

$$\begin{bmatrix} y'_1 \\ y'_2 \\ y'_3 \end{bmatrix} = \begin{bmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 5 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

$$y_1' = -2y_1 + 0y_2 + 0y_3$$

$$y_2' = 0y_1 + 1y_2 + 0y_3$$

$$y_3' = 0y_1 + 0y_2 + 5y_3$$

$$y_1' = -2y_1$$

$$\frac{dy_1}{dt} = -2y_1$$

$$\frac{dy_1}{y_1} = -2dt \quad \boxed{\text{SVM}}$$

$$\int \frac{dy_1}{y_1} = -2 \int dt$$

$$\log y_1 = -2t + c_1$$

$$y_1 = e^{-2t + c_1}$$

$$y_1 = e^{-2t} \cdot e^{c_1}$$

$$\boxed{y_1 = c_1 e^{-2t}}$$

where

$$c_1 = e^{c_1}$$

$$y_2' = 1y_2$$

$$\frac{dy_2}{dt} = 1y_2$$

$$\frac{dy_2}{y_2} = dt \quad \boxed{\text{SVM}}$$

$$\int \frac{dy_2}{y_2} = \int dt$$

$$\log y_2 = t + c_2$$

$$y_2 = e^{t + c_2}$$

$$y_2 = e^t \cdot e^{c_2}$$

$$\boxed{y_2 = c_2 e^t}$$

$$\text{where } c_2 = e^{c_2}$$

$$y_3' = 5y_3$$

$$\frac{dy_3}{dt} = 5y_3$$

$$\frac{dy_3}{y_3} = 5dt$$

$$\int \frac{dy_3}{y_3} = 5 \int dt$$

$$\log y_3 = 5t + c_3$$

$$y_3 = e^{5t + c_3}$$

$$y_3 = e^{5t} \cdot e^{c_3}$$

$$\boxed{y_3 = c_3 e^{5t}}$$

$$\text{where } c_3 = e^{c_3}$$

Now we have  $x = py$  [from ②]

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

$$x_1 = 1y_1 + 2y_2 + 1y_3$$

$$x_2 = 0y_1 + 2y_2 + 1y_3$$

$$x_3 = 0y_1 + 1y_2 + 1y_3$$

$$x_1 = 1y_1 + 2y_2 + 1y_3$$

$$x_2 = 0y_1 + 2y_2 + 1y_3$$

$$x_3 = 0y_1 + 1y_2 + 1y_3$$

$$X = c_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} y_1 + \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} y_2 + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} y_3$$

$$X = c_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} e^{-2t} + c_2 \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} e^t + c_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} e^{5t}$$

(or)

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 e^{-2t} \\ c_2 e^t \\ c_3 e^{5t} \end{bmatrix}$$

$$x_1 = c_1 e^{-2t} + 2c_2 e^t + c_3 e^{5t}$$

$$x_2 = 0c_1 e^{-2t} + 2c_2 e^t + c_3 e^{5t}$$

$$x_3 = 0c_1 e^{-2t} + c_2 e^t + c_3 e^{5t}$$

$$X = c_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} e^{-2t} + c_2 \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} e^t + c_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} e^{5t}$$

Solve the system of linear differential equation  
by diagonalization method

Q. Non-Homogeneous  $\rightarrow$

$$\text{Let } \dot{x} = Ax + F \rightarrow \textcircled{1}$$

Assume solution be as

$$x = Py$$

Diff. wrt 't'

$$\dot{x} = P\dot{y}$$

Eq  $\textcircled{1}$  becomes

$$\cancel{\dot{x}} = P\dot{y} = APy + F$$

$$\Rightarrow \dot{y} = \bar{P}^{-1}[APy + F]$$

$$\Rightarrow \dot{y} = (\bar{P}^{-1}AP)y + \bar{P}^{-1}F$$

$$\Rightarrow \dot{y} = Dy + \bar{P}^{-1}F$$

$$\text{where } D = \bar{P}^{-1}AP$$

In  $2 \times 2$  matrix  $\rightarrow$

$$y' = Dy + \bar{P}^{-1}F$$

$$P = \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \end{bmatrix}$$

$$\begin{bmatrix} y'_1 \\ y'_2 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} + \begin{bmatrix} a'_1 & b'_1 \\ a'_2 & b'_2 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \end{bmatrix}$$

$$y'_1 = \lambda_1 y_1 + a'_1 f_1 + b'_1 f_2$$

$$y'_2 = \lambda_2 y_2 + a'_2 f_1 + b'_2 f_2$$

Solving using linear D.E method

$$\frac{dy}{dt} + Py = Q ; I.F = e^{\int P dt} ; y_1 \text{ and } y_2$$

$$\text{Solve if } y(I.F) = \int Q(I.F) dt + c$$

Now Solution of System is given by

$$x = py$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$x_1 = a_1 y_1 + b_1 y_2$$

$$y_2 = a_2 y_1 + b_2 y_2$$

$$X = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} y_1 + \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} y_2$$

In general [ $n \times n$  matrix]

$$y' = \mathcal{D}y + \hat{p}' F$$

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ \vdots & \vdots & \vdots \\ 0 & 0 & \lambda_n \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} + \begin{bmatrix} a_1 & a_2 & \dots & a_n \\ b_1 & b_2 & \dots & b_n \\ \vdots & \vdots & \ddots & \vdots \\ z_1 & z_2 & \dots & z_n \end{bmatrix} \begin{bmatrix} p_{t_1} \\ p_{t_2} \\ \vdots \\ p_{t_n} \end{bmatrix}$$

$$y'_1 = \lambda_1 y_1 + A_1 f_{t_1} + \dots$$

$$y_2' = \alpha_2 y_2 + \beta_1 f_{t_1} + \dots$$

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$$\tilde{y}_n = x_n y_n + z_1 f_{t_1} + \dots$$

Solve by using Ligear D.E method

$$\frac{dy}{dt} + py = q ; \quad I.F = e^{\int p dt}$$

$$\therefore y(I.F) = \int q(I.F) dt + c$$

$$y_1 = \underline{\hspace{2cm}}$$

$$y_2 = -$$

1

$$y_n = \underline{\hspace{2cm}}$$

Ques.

Now Solution of System is given by

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} a_1 & a_2 & \dots & a_n \\ b_1 & b_2 & \dots & b_n \\ \vdots & \vdots & \ddots & \vdots \\ z_1 & z_2 & \dots & z_n \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$$x_1 = a_1 y_1 + a_2 y_2 + \dots + a_n y_n$$

$$x_2 = b_1 y_1 + b_2 y_2 + \dots + b_n y_n$$

$\vdots$

$$x_n = z_1 y_1 + z_2 y_2 + \dots + z_n y_n$$

$$x = \begin{bmatrix} a_1 \\ b_1 \\ \vdots \\ z_1 \end{bmatrix} y_1 + \begin{bmatrix} a_2 \\ b_2 \\ \vdots \\ z_2 \end{bmatrix} y_2 + \dots + \begin{bmatrix} a_n \\ b_n \\ \vdots \\ z_n \end{bmatrix} y_n$$

1. Solve  $x' = \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} x + \begin{bmatrix} 3e^t \\ e^t \end{bmatrix}$  by diagonalization

and hence discuss the stability of the system.

Sol<sup>n</sup> Given that  $x' = \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} x + \begin{bmatrix} 3e^t \\ e^t \end{bmatrix}$

$$\Rightarrow x' = Ax + F \rightarrow \textcircled{1}$$

where  $A = \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix}$ ;  $x' = \begin{bmatrix} x'_1 \\ x'_2 \end{bmatrix}$ ;  $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

$$F = \begin{bmatrix} 3e^t \\ e^t \end{bmatrix}$$

The characteristic equation of A is  $|A - \lambda I| = 0$

$$\Rightarrow \begin{vmatrix} 4-\lambda & 2 \\ 2 & 1-\lambda \end{vmatrix} = 0 \Rightarrow (4-\lambda)(1-\lambda) - 4 = 0$$

$$\Rightarrow \lambda^2 - 5\lambda = 0 \Rightarrow \lambda(\lambda - 5) = 0$$

$$\Rightarrow \lambda(\lambda - 5) \Rightarrow \boxed{\lambda = 0} \text{ or } \lambda - 5 = 0 \Rightarrow \boxed{\lambda = 5}$$

$\boxed{\lambda = 0, 5} \rightarrow \text{Eigen values}$

Now consider  $[A - \lambda I]x = 0$

$$\begin{aligned} (4-\lambda)x + 2y &= 0 \\ 2x + (1-\lambda)y &= 0 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \rightarrow \textcircled{1}$$

Case (i) : If  $\lambda = 0$  in  $\textcircled{1}$

$$4x + 2y = 0 \rightarrow \textcircled{1}$$

$$2x + y = 0 \rightarrow \textcircled{2}$$

$$\text{from } \textcircled{1} \quad 4x + 2y = 0$$

$$\Rightarrow 4x = -2y$$

$$\Rightarrow 2x = -y$$

$$\Rightarrow \frac{x}{1} = \frac{-y}{2} = k \text{ (say)}$$

$$\Rightarrow x_1 = [k, -2k]^T$$

$$\text{Or } \boxed{x_1 = [1, -2]^T \text{ if } \lambda = 0}$$

Case (ii) : If  $\lambda = 5$  in  $\textcircled{1}$

$$-x + 2y = 0 \rightarrow \textcircled{3}$$

$$2x - 4y = 0 \rightarrow \textcircled{4}$$

$$\text{from } \textcircled{3} \quad -x + 2y = 0$$

$$\Rightarrow x = 2y$$

$$\Rightarrow \frac{x}{2} = \frac{y}{1} = k \text{ (say)}$$

$$\therefore x_2 = [2k, k]^T$$

$$\boxed{x_2 = [2, 1]^T \text{ if } \lambda = 5}$$

The modal matrix  $P = [x_1 \ x_2]$

$$P = \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix} ; |P| = 1+4$$

$$\boxed{|P| = 5}$$

To find :  $\bar{P}^{-1} = \frac{\text{adj } P}{|P|}$

$$\therefore \bar{P}^{-1} = \frac{1}{5} \begin{bmatrix} 1 & -2 \\ 2 & 1 \end{bmatrix} \quad \boxed{D^{-1}} \quad \bar{P}^{-1} = \begin{bmatrix} 0.2 & -0.4 \\ 0.4 & 0.2 \end{bmatrix}$$

Also to find :  $D = \bar{P}^{-1} P$

$$D = \frac{1}{5} \begin{bmatrix} 1 & -2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix}$$

$$D = \begin{bmatrix} 0 & 0 \\ 0 & 5 \end{bmatrix}$$

Now Non-Homogeneous

$$x' = Ax + F \rightarrow \textcircled{1} \quad [\text{Given data}]$$

(4L)

$$\therefore \text{put } \rightarrow x = Py \quad [\text{Assume soln}]$$

↓  
Dwrt 't'

$$x' = Py'$$

Eq \textcircled{1} becomes

$$Py' = Apy + F$$

$$y' = \tilde{p}'[Ap y + F]$$

$$y' = (\tilde{p}' A p)y + \tilde{p}' F$$

$$y' = Dy + \tilde{p}' F \quad \text{where } D = \tilde{p}' A p$$

$$\begin{bmatrix} y_1' \\ y_2' \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} + \begin{bmatrix} \frac{1}{5} & -\frac{2}{5} \\ \frac{2}{5} & \frac{1}{5} \end{bmatrix} \begin{bmatrix} 3e^t \\ e^t \end{bmatrix}$$

$$y_1' = 0y_1 + 0y_2 + \frac{3}{5}e^t - \frac{2}{5}e^t$$

$$y_2' = 5y_2 + \frac{6}{5}e^t + \frac{1}{5}e^t$$

$$y_1' = \frac{3}{5}e^t - \frac{2}{5}e^t$$

$\uparrow$        $\uparrow$   
Same

$$y_1' = \frac{1}{5}e^t$$

$$\frac{dy_1}{dt} = \frac{1}{5}e^t$$

VSM

$$\frac{dy_1}{1} = \frac{1}{5}e^t dt$$

⇒ I.O.B.S

$$\int dy_1 = \frac{1}{5} \int dt e^t dt$$

$$y_1 = \frac{1}{5}e^t + c_1$$

$$y_2' = 5y_2 + \frac{6}{5}e^t + \frac{1}{5}e^t$$

$\uparrow$        $\uparrow$   
Same

$$y_2' = 5y_2 + \frac{7}{5}e^t$$

$$\frac{dy_2}{dt} - 5y_2 = \frac{7}{5}e^t \rightarrow \text{Linear}$$

$$\frac{dy_2}{dt} + P y_2 = Q \rightarrow \text{linear in } y_2$$

$$\begin{aligned} I.F &= e^{\int P dt} & P &= -5; \\ &= e^{\int (-5) dt} & Q &= \frac{7}{5}e^t \end{aligned}$$

$$I.F = \frac{-5t}{e}$$

$$\therefore y_2(I.F) = \int Q(I.F) dt + c_2$$

$$\Rightarrow y_2 e^{-st} = \int \frac{7}{5} e^t \cdot (e^{-st}) dt + c_2$$

$$\Rightarrow y_2 e^{-st} = \frac{7}{5} \int e^{-ht} dt + c_2$$

$$\Rightarrow y_2 e^{-st} = \frac{7}{5} \left( \frac{e^{-ht}}{-h} \right) + c_2$$

$$\Rightarrow y_2 e^{-st} = -\frac{7}{20} e^{-4t} + c_2$$

$$\boxed{y_2 = -\frac{7}{20} e^t + c_2 e^{st}}$$

Now we have  $x = Py$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{5} e^t + c_1 \\ -\frac{7}{20} e^t + c_2 e^{st} \end{bmatrix}$$

$$x_1 = \frac{1}{5} e^t + c_1 - \frac{14}{20} e^t + 2c_2 e^{st}$$

$$x_2 = -\frac{2}{5} e^t - 2c_1 - \frac{7}{20} e^t + c_2 e^{st}$$

$$x_1 = -\frac{1}{2} e^t + c_1 + 2c_2 e^{st}$$

$$x_2 = -\frac{15}{20} e^t + 2c_1 + c_2 e^{st}$$

$$x = \begin{bmatrix} 1 \\ 2 \end{bmatrix} c_1 + \begin{bmatrix} 2 \\ 1 \end{bmatrix} c_2 e^{st} - \begin{bmatrix} x_2 \\ \frac{x_1}{2} \end{bmatrix} e^t$$

$$\therefore \frac{\frac{1}{5} - \frac{14}{20}}{\frac{4 - 14}{20}} = \frac{-10}{20} = -\frac{1}{2}$$

$$\therefore \frac{-2}{5} - \frac{7}{20} = \frac{-8 - 7}{20} = \frac{-15}{20}$$

$$\therefore \lambda = 0, 5$$

$\Rightarrow$  All eigen values are real, distinct and positive  
 $\Rightarrow$  Hence System is unstable

Q. Convert the differential Equation  $x'' + 5x' + 6x = 0$ , into System of linear differential equation and hence solve them by diagonalization method. Also discuss the Stability of the System

Sol Given that  $x'' + 5x' + 6x = 0 \rightarrow ①$

The given diff. Eq is second order D.E

$\therefore$  choose two variables  $x_1$  and  $x_2$

$$\text{Let } x_1 = x \xrightarrow{\text{diff}} x_1' = x' \xrightarrow{\text{name}} x_2$$

$$x_2 = x' \rightarrow x_2' = x''$$

Eg ① becomes

$$x'' + 5x' + 6x = 0$$

$$\Rightarrow x'' = -6x - 5x'$$

$$\Rightarrow x_2' = -6x_1 - 5x_2$$

Hence System of first order D.E is

$$x_1' = x_2$$

or

$$x_2' = -6x_1 - 5x_2$$

$$x_1' = 0.x_1 + 1.x_2$$

$$x_2' = -6x_1 - 5x_2$$

In matrix form

$$\begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -6 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$x' = Ax \rightarrow ②$$

$$\text{where } x' = \begin{bmatrix} x_1' \\ x_2' \end{bmatrix}; A = \begin{bmatrix} 0 & 1 \\ -6 & -5 \end{bmatrix} \text{ and } x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & 1 \\ -6 & -5 \end{bmatrix}$$

The characteristic equation of  $A$  is  $|A - \lambda I| = 0$

$$\Rightarrow \begin{vmatrix} 0-\lambda & 1 \\ -6 & -5-\lambda \end{vmatrix} = 0 \Rightarrow -\lambda(-5-\lambda) + 6 = 0$$

$$\Rightarrow 5\lambda + \lambda^2 + 6 = 0 \Rightarrow \lambda^2 + 5\lambda + 6 = 0$$

$$\Rightarrow \lambda^2 + 3\lambda + 2\lambda + 6 = 0 \Rightarrow \lambda(\lambda + 3) + 2(\lambda + 3) = 0$$

$$\Rightarrow (\lambda + 2)(\lambda + 3) = 0$$

$$\Rightarrow \lambda + 2 = 0 \quad \text{or} \quad \lambda + 3 = 0$$

$$\Rightarrow \boxed{\lambda = -2} \quad \text{or} \quad \boxed{\lambda = -3}$$

$\therefore \boxed{\lambda = -2, -3} \rightarrow \text{Eigen values}$

Now consider  $[A - \lambda I][X] = 0$

$$\begin{aligned} -\lambda x + y &= 0 \\ -6x + (-5-\lambda)y &= 0 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \rightarrow \textcircled{1}$$

Case i If  $\lambda = -2$  in  $\textcircled{1}$

$$+2x + y = 0 \rightarrow \textcircled{3}$$

$$-6x - 3y = 0 \rightarrow \textcircled{4}$$

$$\text{from } \textcircled{3} \quad +2x + y = 0$$

$$2x = -y$$

$$\Rightarrow \frac{x}{1} = \frac{-y}{2} = k \text{ (say)}$$

$$\Rightarrow x_1 = [1, k]^T$$

or  $\boxed{x_1 = [1, -2]^T \text{ if } \lambda = -2}$

Case ii If  $\lambda = -3$  in  $\textcircled{1}$

$$3x + y = 0 \rightarrow \textcircled{5}$$

$$-6x - 2y = 0 \rightarrow \textcircled{6}$$

$$\text{from } \textcircled{5} \quad 3x + y = 0$$

$$\Rightarrow 3x = -y$$

$$\Rightarrow \frac{x}{1} = \frac{-y}{3} = k \text{ (say)}$$

$$\Rightarrow x_2 = [1, -3k]^T$$

or  $\boxed{x_2 = [1, -3]^T \text{ if } \lambda = -3}$

The model matrix  $P = [x_1, x_2]$

$$P = \begin{bmatrix} 1 & 1 \\ -2 & -3 \end{bmatrix} ; |P| = -3 + 2$$

$$\boxed{|P| = -1}$$

$$\text{To find } \bar{P} = \frac{\text{adj} P}{|P|} \quad \therefore \bar{P} = \begin{bmatrix} 3 & 1 \\ -2 & -1 \end{bmatrix}$$

$$\text{Also to find } D = \bar{P}' A P$$

$$= \begin{bmatrix} 3 & 1 \\ -2 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -6 & -5 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -2 & -3 \end{bmatrix}$$

$$D = \begin{bmatrix} -2 & 0 \\ 0 & -3 \end{bmatrix}$$

$$\text{Eqn (2) becomes } x' = Ax$$

Put  $x = Py$ ,  $\boxed{\text{Assume soln}}$   
~~Wrt t~~  $\quad \quad \quad$

$$\therefore x' = Py'$$

$$\therefore Py' = Ap y$$

$$y' = (\bar{P}' A P) y \quad \text{where } \boxed{D = \bar{P}' A P}$$

$$y' = Dy$$

$$\begin{bmatrix} y'_1 \\ y'_2 \end{bmatrix} = \begin{bmatrix} -2 & 0 \\ 0 & -3 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$y'_1 = -2y_1 + 0y_2$$

$$y'_2 = 0y_1 - 5y_2$$

$$y'_1 = -2y_1$$

$$\frac{dy_1}{dt} = -2y_1$$

$$\frac{dy_1}{y_1} = -2dt$$

$$\int \frac{dy_1}{y_1} = -\int 2dt$$

VSM

$$y'_2 = -5y_2$$

$$\frac{dy_2}{dt} = -5y_2$$

$$\frac{dy_2}{y_2} = -5dt$$

$$\int \frac{dy_2}{y_2} = -5 \int dt$$

I.O.B.S

$$\Rightarrow \log y_1 = -2t + c_1$$

$$\Rightarrow y_1 = e^{-2t+c_1}$$

$$\Rightarrow y_1 = e^{-2t} \cdot e^{c_1}$$

$$\Rightarrow \boxed{y_1 = C_1 e^{-2t}}$$

where  $C_1 = e^{c_1}$

$$\Rightarrow \log y_2 = -5t + c_2$$

$$\Rightarrow y_2 = e^{-5t+c_2}$$

$$\Rightarrow y_2 = e^{-5t} \cdot e^{c_2}$$

$$\Rightarrow \boxed{y_2 = C_2 e^{-5t}}$$

where  $C_2 = e^{c_2}$

Now we have

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} C_1 e^{-2t} \\ C_2 e^{-5t} \end{bmatrix} \quad [from \text{ } ⑦]$$

$$x_1 = C_1 e^{-2t} + C_2 e^{-5t}$$

$$x_2 = -2C_1 e^{-2t} - 3C_2 e^{-5t}$$

$$x = C_1 \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-2t} + C_2 \begin{bmatrix} 1 \\ -3 \end{bmatrix} e^{-5t}$$

Here  $\lambda = -2, -3$

$\Rightarrow$  All eigen values are real, distinct & negative

$\Rightarrow$  Hence System is Stable

Assignment - 6

1. Solve  $x' = \begin{bmatrix} -3 & 1 \\ 2 & -4 \end{bmatrix} x + \begin{bmatrix} 3t \\ e^{-t} \end{bmatrix}$  by diagonalization and hence discuss the Stability of the system.

2. Solve  $x' = \begin{bmatrix} 2 & -2 & 3 \\ 1 & 1 & 1 \\ 1 & 3 & -1 \end{bmatrix}$  by diagonalization and hence discuss the Stability of the system.