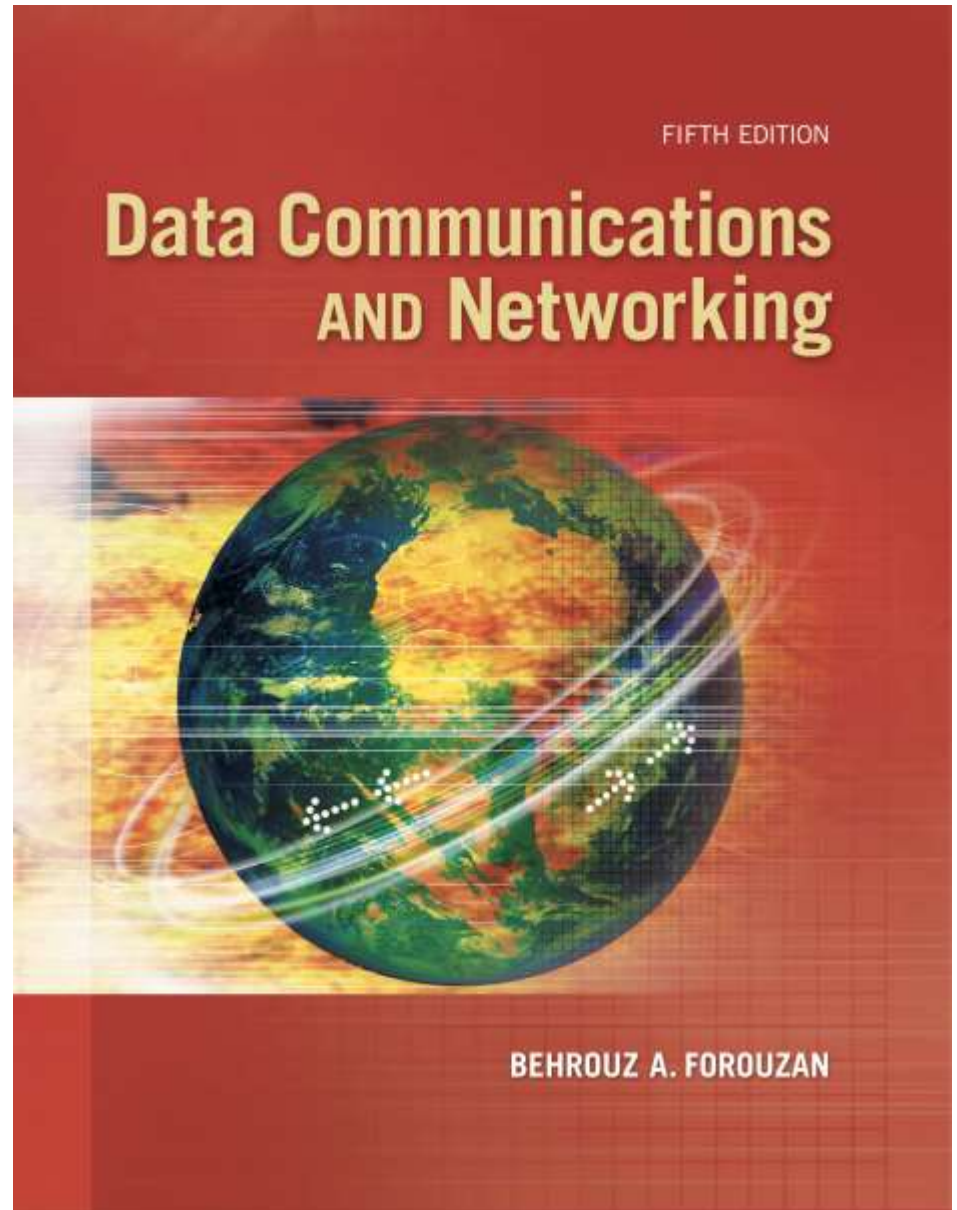



Chapter 6

Bandwidth Utilization





Chapter 6: Outline

6.1 MULTIPLEXING

6.2 SPREAD SPECTRUM



Chapter 6: Objective

- *The first section discusses multiplexing. The first method is called frequency-division multiplexing (FDM). The second method is called wavelength division multiplexing (WDM). The third method is called time-division multiplexing (TDM).*
- *The second section discusses spectrum spreading, in which we first spread the bandwidth of a signal to add redundancy for the purpose of more secure transmission before combining different channels. The first method is called frequency hopping spread spectrum (FHSS). The second method is called direct sequence spread spectrum (DSSS).*

6-1 MULTIPLEXING

Multiplexing is the set of techniques that allows the simultaneous transmission of multiple signals across a single data link. As data and telecommunications use increases, so does traffic. We can accommodate this increase by continuing to add individual links each time a new channel is needed, or we can install higher-bandwidth links and use each to carry multiple signals.

Figure 6.1: *Dividing a link into channels*

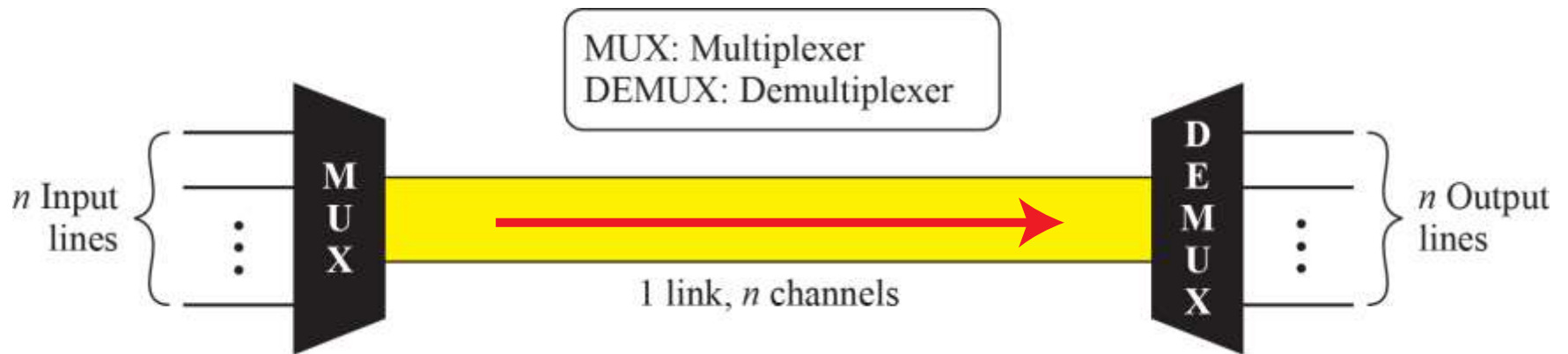
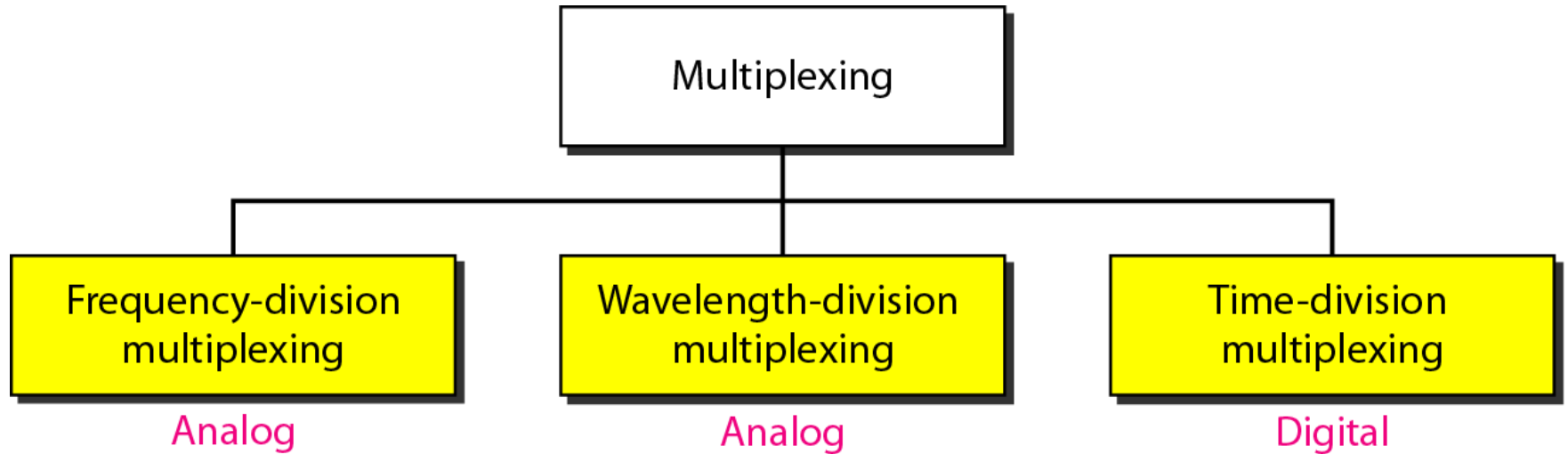


Figure 6.2: *Categories of multiplexing*





6.6.1 Frequency-Division Multiplexing

Frequency-division multiplexing (FDM) is an analog technique that can be applied when the bandwidth of a link (in hertz) is greater than the combined bandwidths of the signals to be transmitted. In FDM, signals generated by each sending device modulate different carrier frequencies. These modulated signals are then combined into a single composite signal that can be transported by the link.

Figure 6.3: *Frequency-division multiplexing*

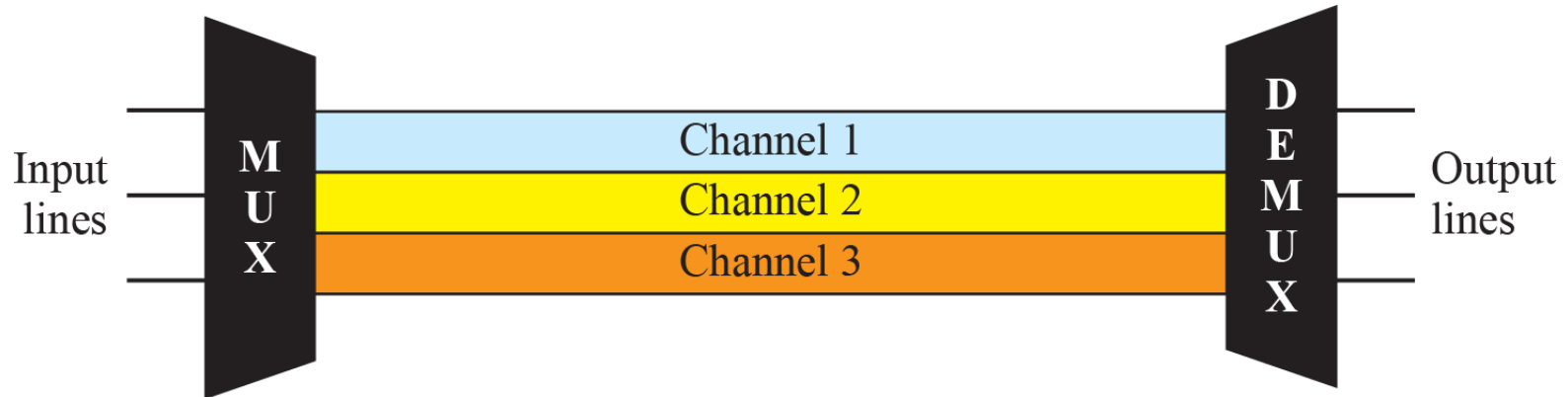


Figure 6.4: FDM Process

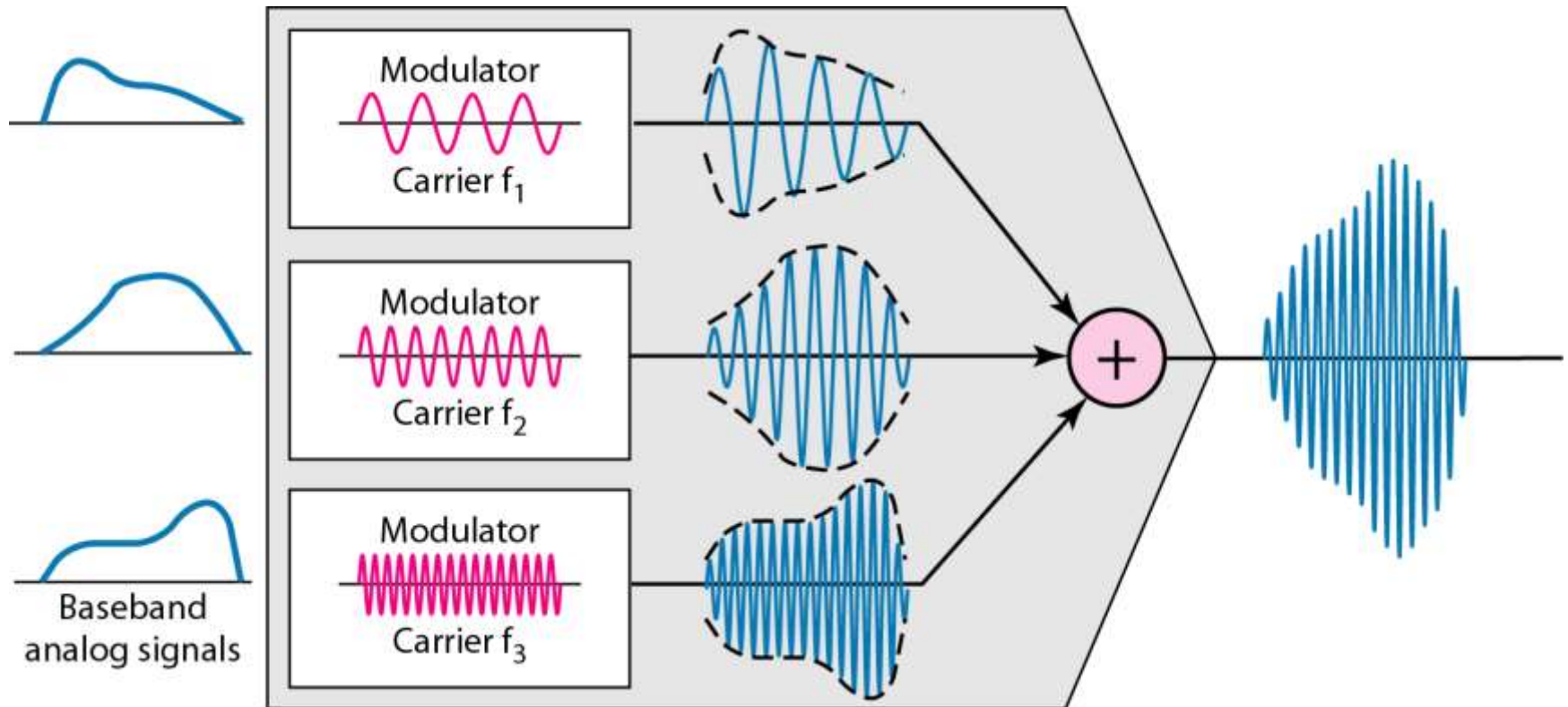
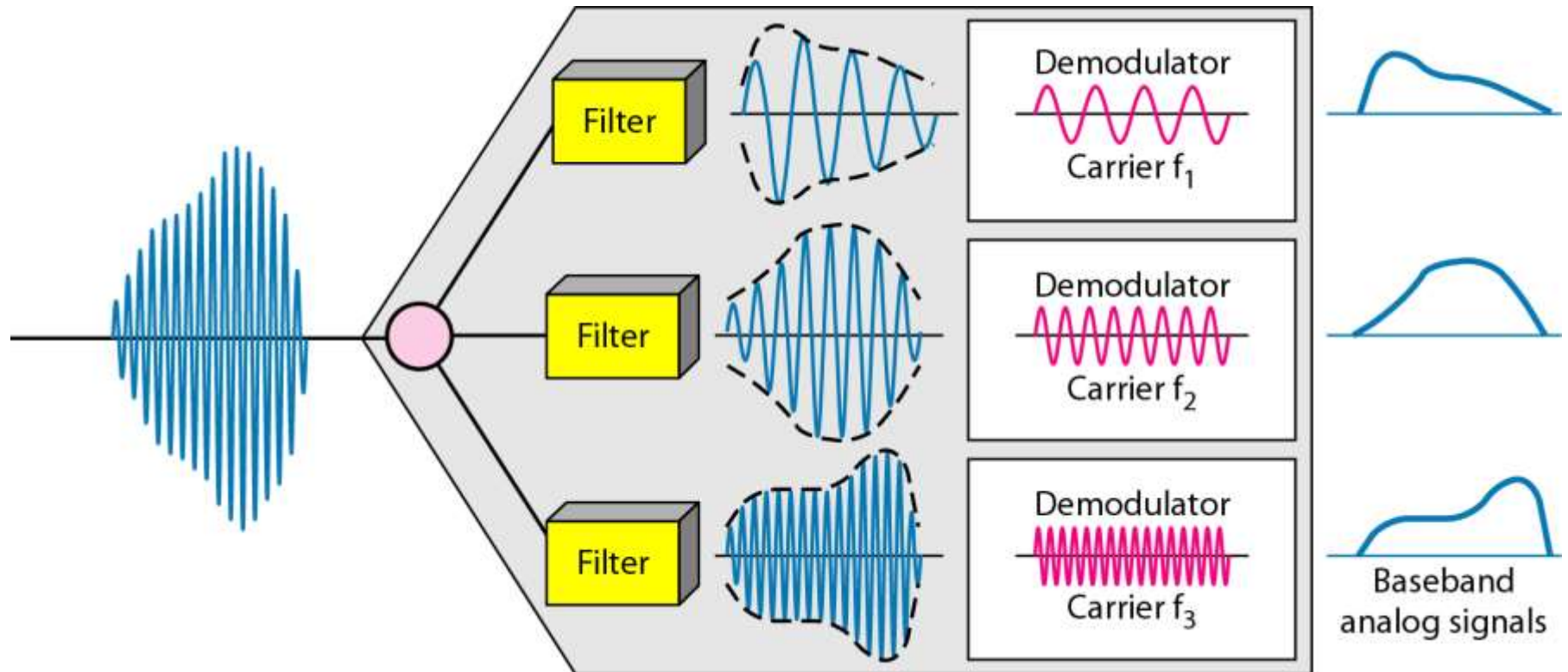


Figure 6.5: *FDM demultiplexing example*



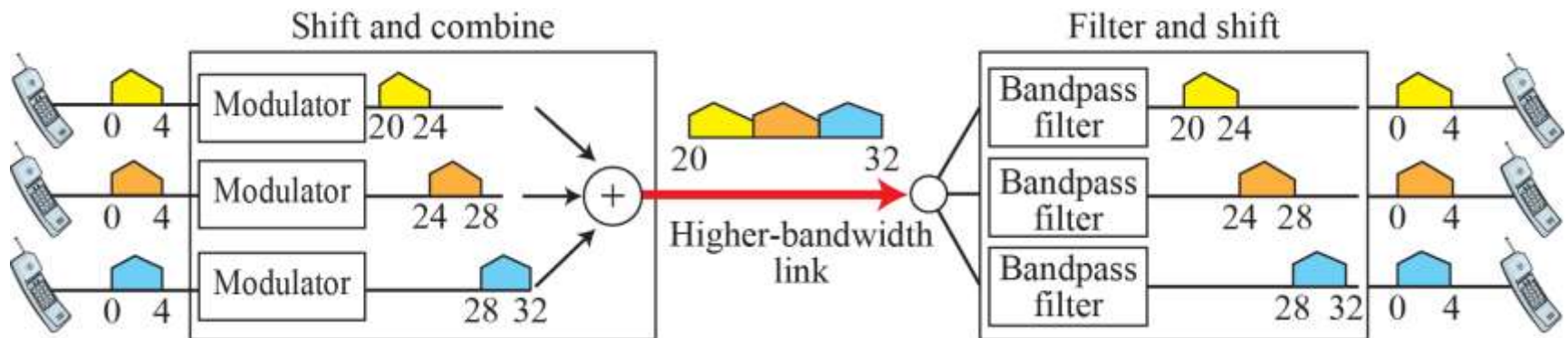
Example 6.1

Assume that a voice channel occupies a bandwidth of 4 kHz. We need to combine three voice channels into a link with a bandwidth of 12 kHz, from 20 to 32 kHz. Show the configuration, using the frequency domain. Assume there are no guard bands.

Solution

We shift (modulate) each of the three voice channels to a different bandwidth, as shown in Figure 6.6.

Figure 6.6: Example 6.1



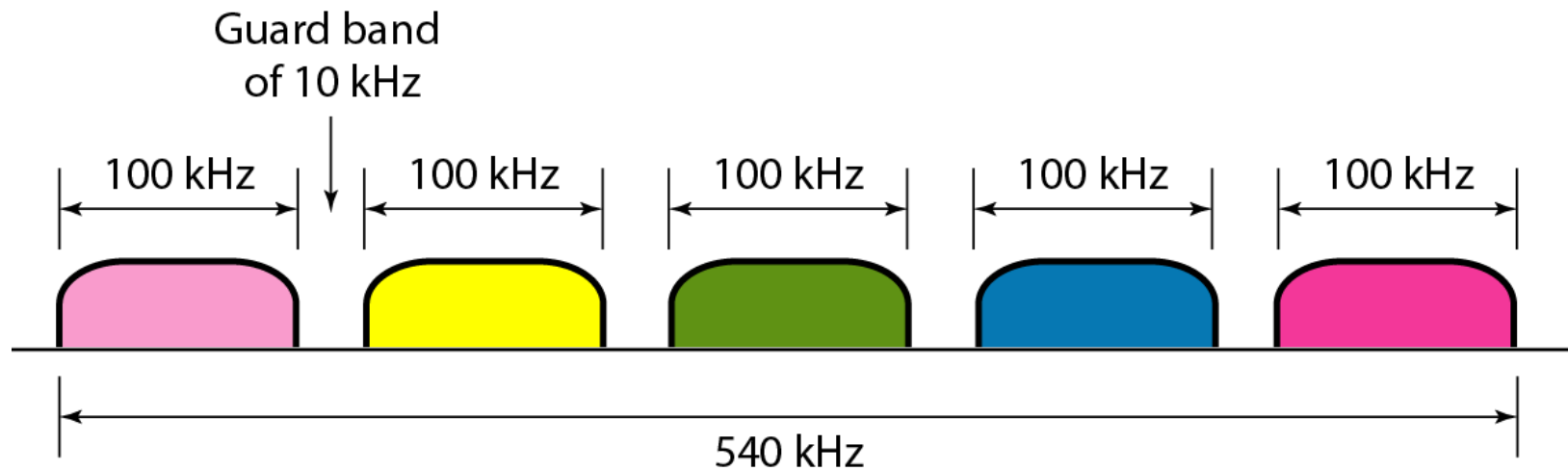
Example 6.2

Five channels, each with a 100-kHz bandwidth, are to be multiplexed together. What is the minimum bandwidth of the link if there is a need for a guard band of 10 kHz between the channels to prevent interference?

Solution

For five channels, we need at least four guard bands. This means that the required bandwidth is at least $5 \times 100 + 4 \times 10 = 540$ kHz, as shown in Figure 6.7.

Figure 6.7: Example 6.2



Example 6.3

Four data channels (digital), each transmitting at 1 Mbps, use a satellite channel of 1 MHz. Design an appropriate configuration, using FDM.

Solution

The satellite channel is analog. We divide it into four channels, each channel having a 250-kHz bandwidth. Each digital channel of 1 Mbps is modulated so that each 4 bits is modulated to 1 Hz. One solution is 16-QAM modulation. Figure 6.8 shows one possible configuration.

Figure 6.8: Example 6.3

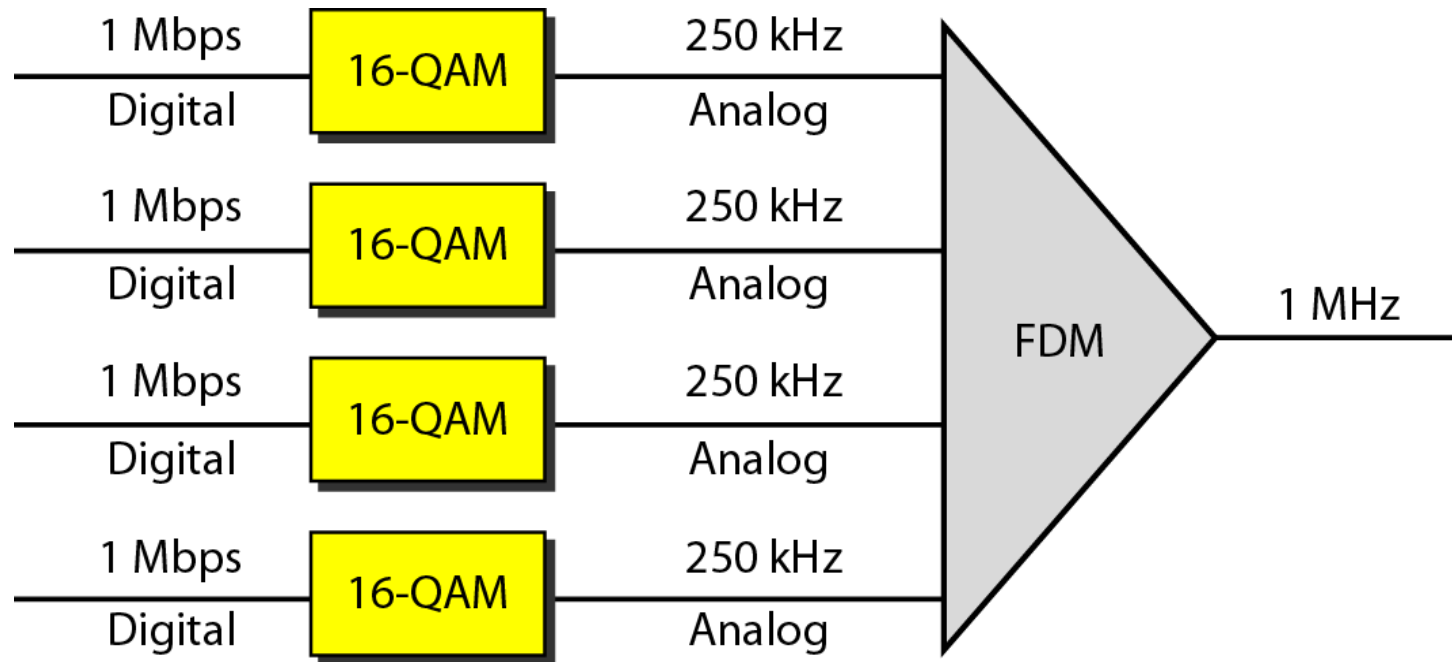
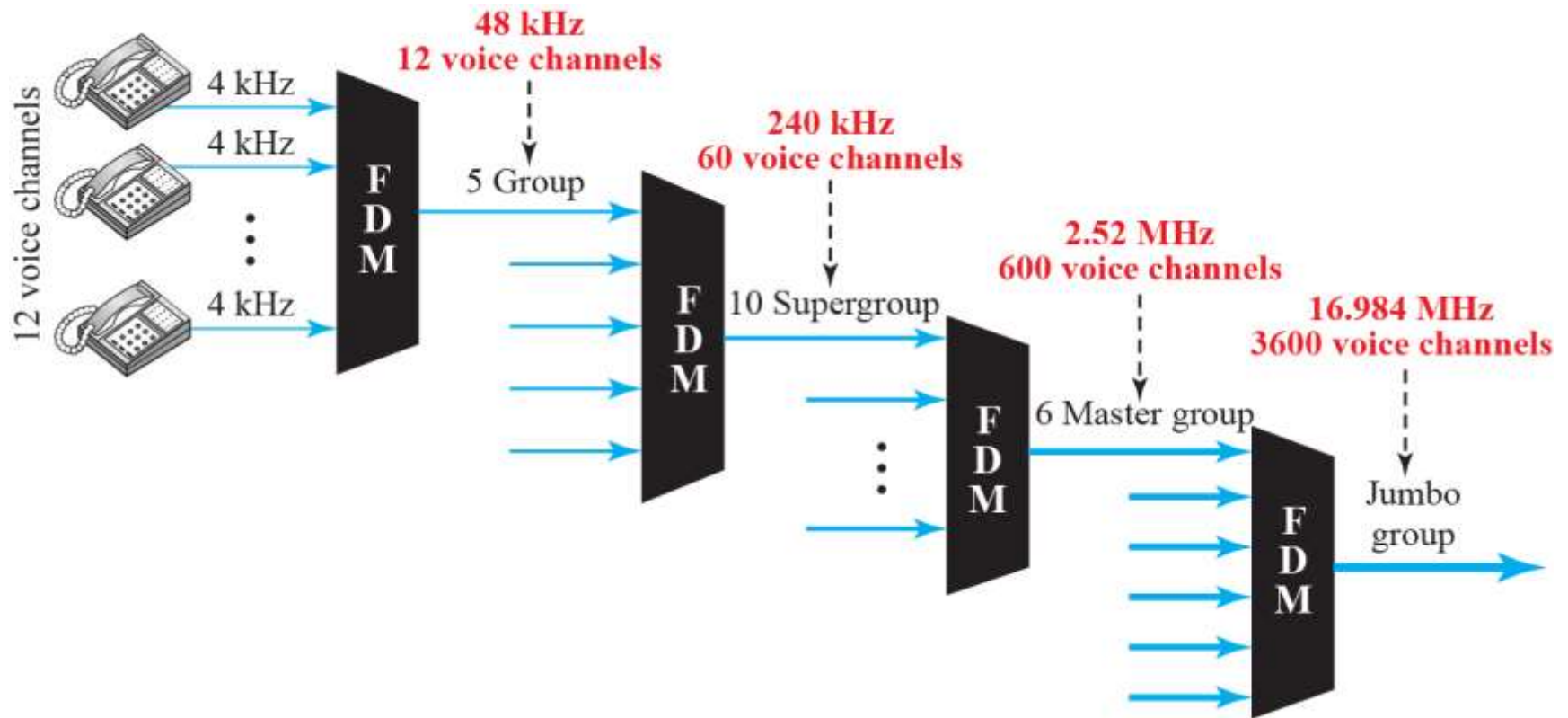


Figure 6.9: *Analog hierarchy*



Example 6.4

The Advanced Mobile Phone System (AMPS) uses two bands. The first band of 824 to 849 MHz is used for sending, and 869 to 894 MHz is used for receiving. Each user has a bandwidth of 30 kHz in each direction. The 3-kHz voice is modulated using FM, creating 30 kHz of modulated signal. How many people can use their cellular phones simultaneously?.

Solution

Each band is 25 MHz. If we divide 25 MHz by 30 kHz, we get 833.33. In reality, the band is divided into 832 channels. Of these, 42 channels are used for control, which means only 790 channels are available for cellular phone users.



6.6.2 Wavelength-Division Multiplexing

Wavelength-division multiplexing (WDM) is designed to use the high-data-rate capability of fiber-optic cable. The optical fiber data rate is higher than the data rate of metallic transmission cable, but using a fiber-optic cable for a single line wastes the available bandwidth. Multiplexing allows us to combine several lines into one.

Figure 6.10: Wavelength-division multiplexing

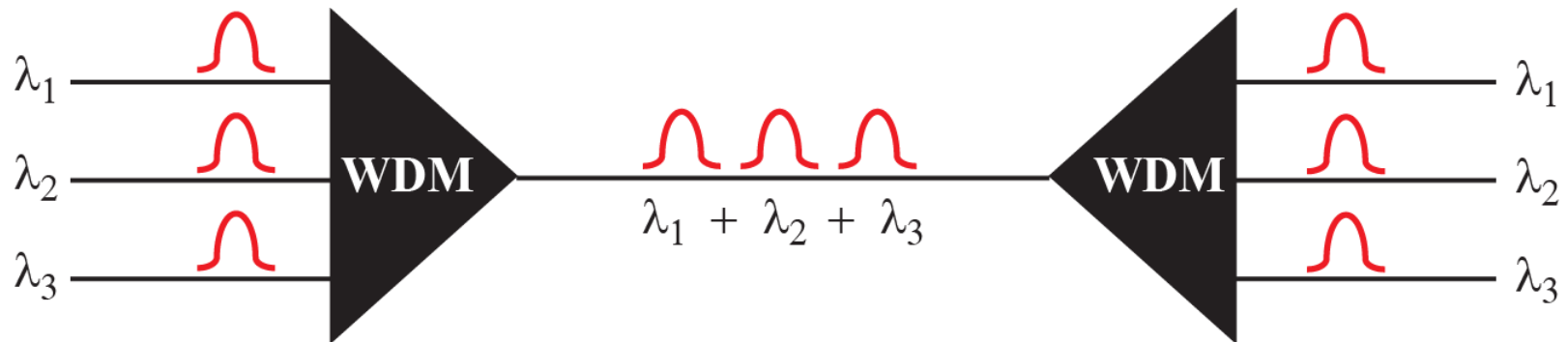
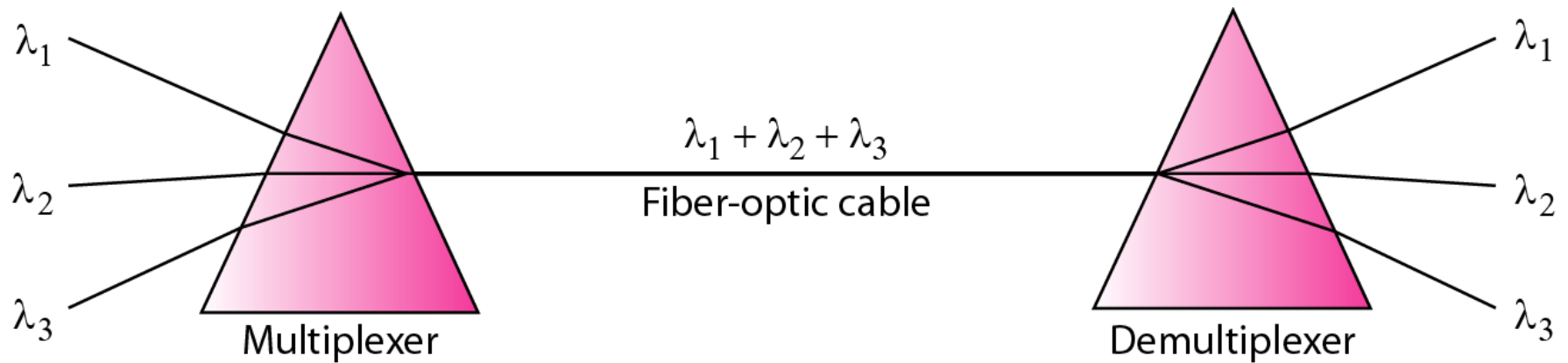


Figure 6.11: *Prisms in wave-length division multiplexing*





6.6.3 Time-Division Multiplexing

Time-division multiplexing (TDM) is a digital process that allows several connections to share the high bandwidth of a link. Instead of sharing a portion of the bandwidth as in FDM, time is shared. Each connection occupies a portion of time in the link. Figure 6.12 gives a conceptual view of TDM. Note that the same link is used as in FDM; here, however, the link is shown sectioned by time rather than by frequency. In the figure, portions of signals 1, 2, 3, and 4 occupy the link sequentially.

Figure 6.12: TDM

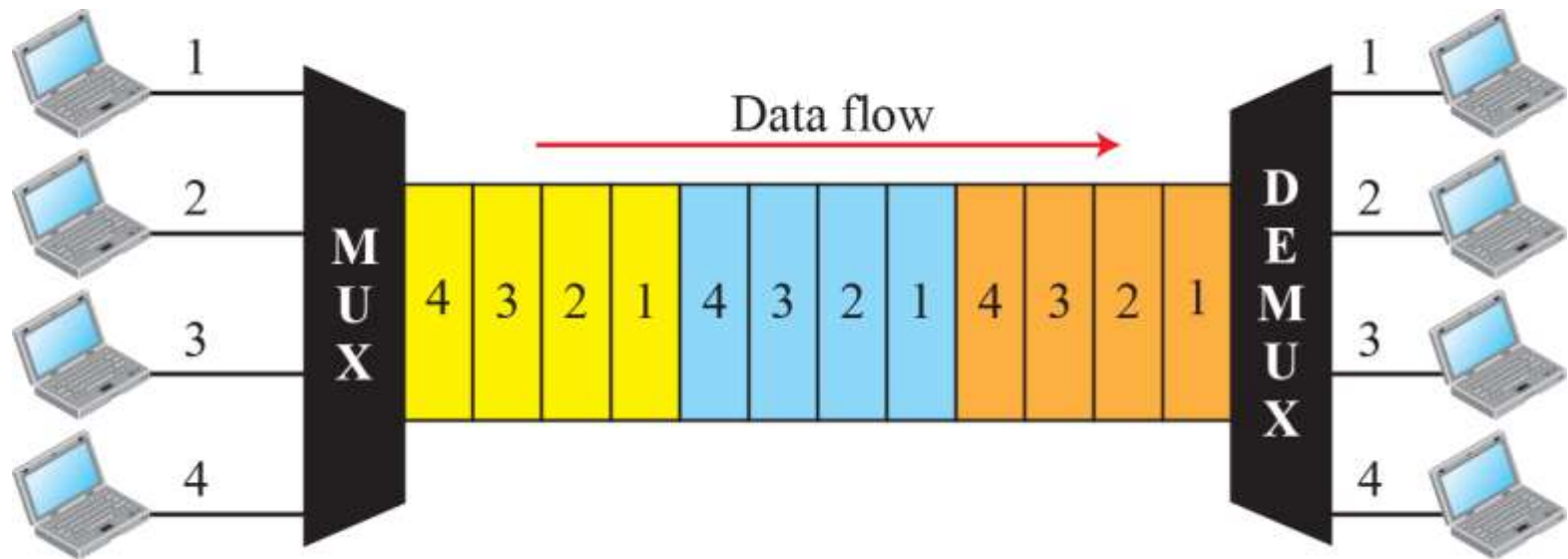
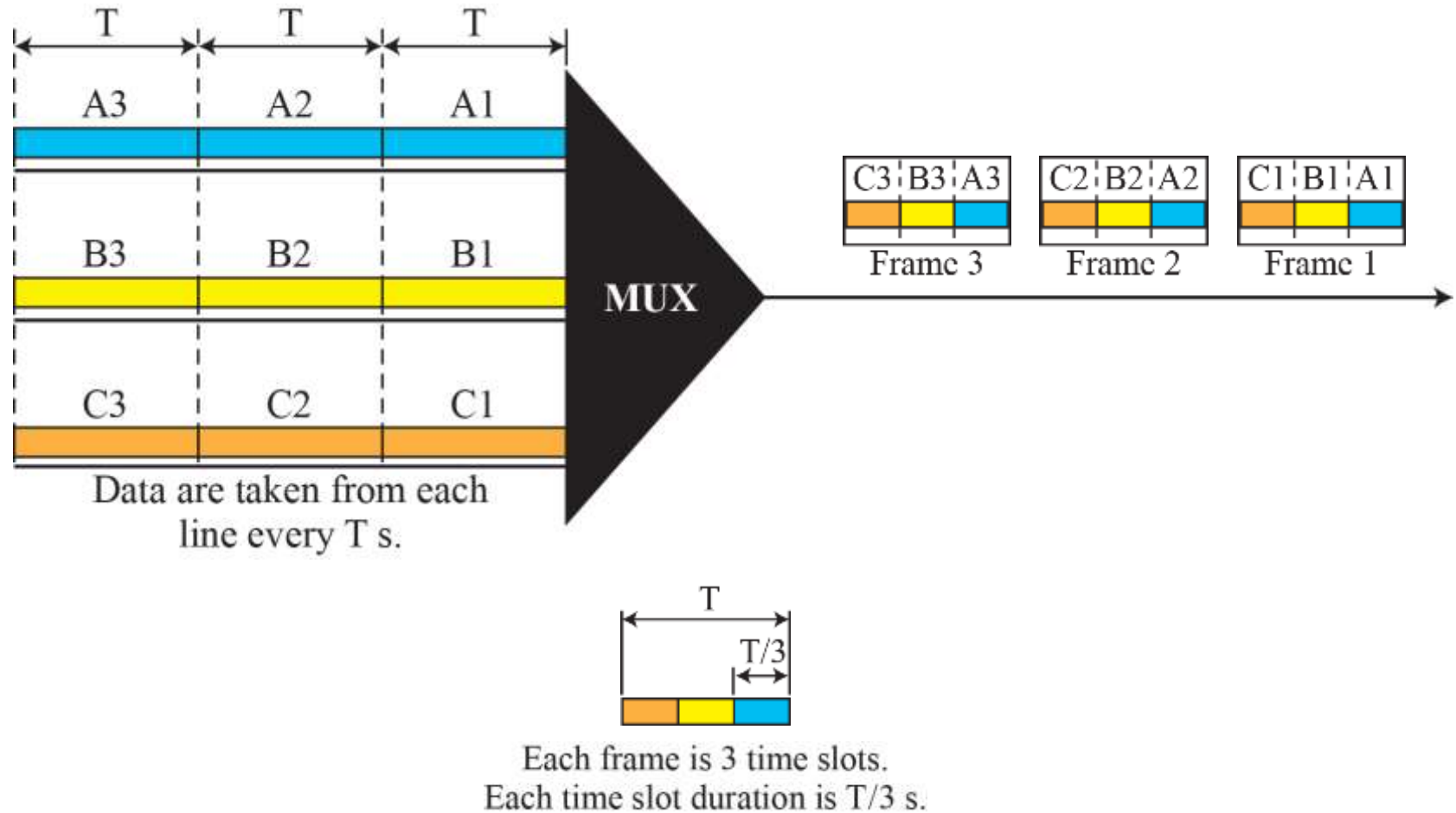


Figure 6.13: Synchronous time-division multiplexing



Example 6.5

In Figure 6.13, the data rate for each input connection is 1 kbps. If 1 bit at a time is multiplexed (a unit is 1 bit), what is the duration of

6. each input slot,
2. each output slot, and
3. each frame?

Example 6.5 (continued)

Solution

We can answer the questions as follows:

6. The data rate of each input connection is 1 kbps. This means that the bit duration is $1/1000$ s or 1 ms. The duration of the input time slot is 1 ms (same as bit duration).
2. The duration of each output time slot is one-third of the input time slot. This means that the duration of the output time slot is $1/3$ ms.
3. Each frame carries three output time slots. So the duration of a frame is $3 \times (1/3)$ ms, or 1 ms. The duration of a frame is the same as the duration of an input unit.

Example 6.6

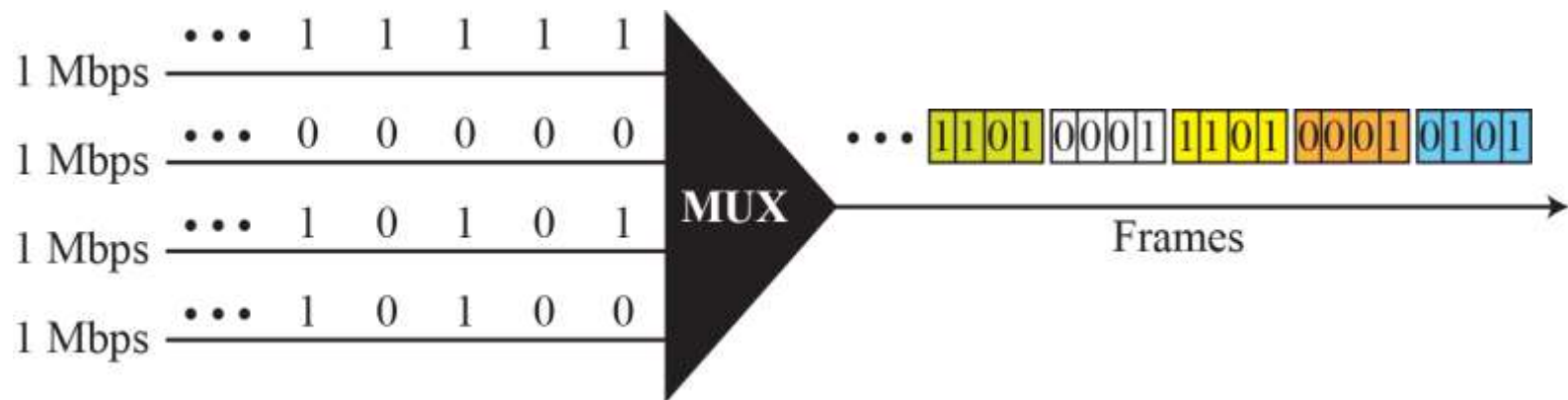
Figure 6.14 shows synchronous TDM with a data stream for each input and one data stream for the output. The unit of data is 1 bit. Find (a) the input bit duration, (b) the output bit duration, (c) the output bit rate, and (d) the output frame rate.

Solution

We can answer the questions as follows:

1. The input bit duration is the inverse of the bit rate: $1/1 \text{ Mbps} = 1 \mu\text{s}$.
2. The output bit duration is one-fourth of the input bit duration, or $1/4 \mu\text{s}$.
3. The output bit rate is the inverse of the output bit duration, or $1/(1/4) \mu\text{s}$ or 4 Mbps. This can also be deduced from the fact that the output rate is 4 times as fast as any input rate; so the output rate $= 4 \times 1 \text{ Mbps} = 4 \text{ Mbps}$.
4. The frame rate is always the same as any input rate. So the frame rate is 1,000,000 frames per second. Because we are sending 4 bits in each frame, we can verify the result of the previous question by multiplying the frame rate by the number of bits per frame.

Figure 6.14: Example 6.6



Example 6.7

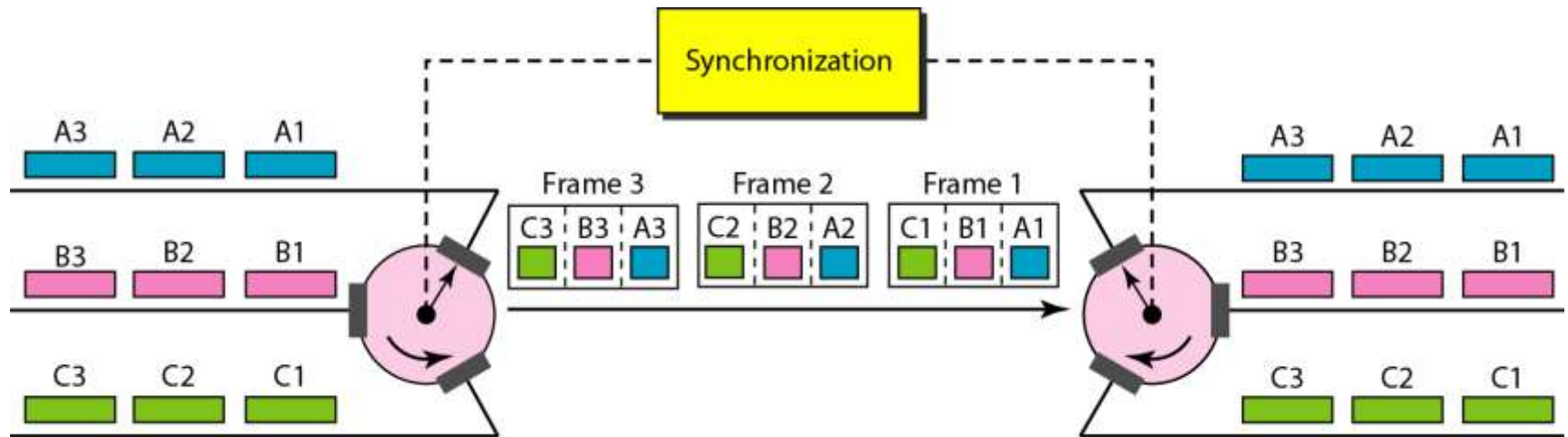
Four 1-kbps connections are multiplexed together. A unit is 1 bit. Find (1) the duration of 1 bit before multiplexing, (2) the transmission rate of the link, (3) the duration of a time slot, and (4) the duration of a frame.

Solution

We can answer the questions as follows:

1. The duration of 1 bit before multiplexing is $1/1$ kbps, or 0.001 s (1 ms).
2. The rate of the link is 4 times the rate of a connection, or 4 kbps.
3. The duration of each time slot is one-fourth of the duration of each bit before multiplexing, or $1/4$ ms or 250 μ s. Note that we can also calculate this from the data rate of the link, 4 kbps. The bit duration is the inverse of the data rate, or $1/4$ kbps or 250 μ s.
4. The duration of a frame is always the same as the duration of a unit before multiplexing, or 1 ms. We can also calculate this in another way. Each frame in this case has four time slots. So the duration of a frame is 4 times 250 μ s, or 1 ms.

Figure 6.15: Interleaving



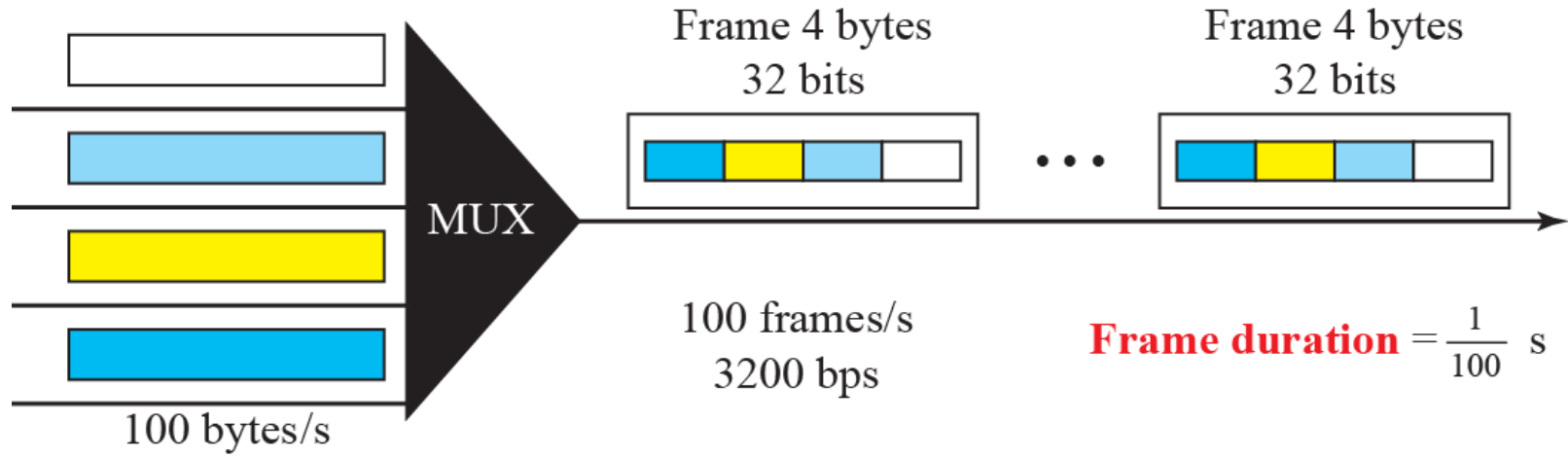
Example 6.8

Four channels are multiplexed using TDM. If each channel sends 100 bytes/s and we multiplex 1 byte per channel, show the frame traveling on the link, the size of the frame, the duration of a frame, the frame rate, and the bit rate for the link.

Solution

The multiplexer is shown in Figure 6.16. Each frame carries 1 byte from each channel; the size of each frame, therefore, is 4 bytes, or 32 bits. The frame rate is 100 frames per second. The duration of a frame is therefore $1/100$ s. The link is carrying 100 frames per second, and since each frame contains 32 bits, the bit rate is 100×32 , or 3200 bps.

Figure 6.16: Example 6.8



Example 6.9

A multiplexer combines four 100-kbps channels using a time slot of 2 bits. Show the output with four arbitrary inputs. What is the frame rate? What is the frame duration? What is the bit rate? What is the bit duration?

Solution

Figure 6.17 shows the output for four arbitrary inputs. The link carries 50,000 frames per second since each frame contains 2 bits per channel. The frame duration is therefore $1/50,000$ s or $20\text{ }\mu\text{s}$. The frame rate is 50,000 frames per second, and each frame carries 8 bits; the bit rate is $50,000 \times 8 = 400,000$ bits or 400 kbps. The bit duration is $1/400,000$ s, or $2.5\text{ }\mu\text{s}$.

Figure 6.17: Example 6.9

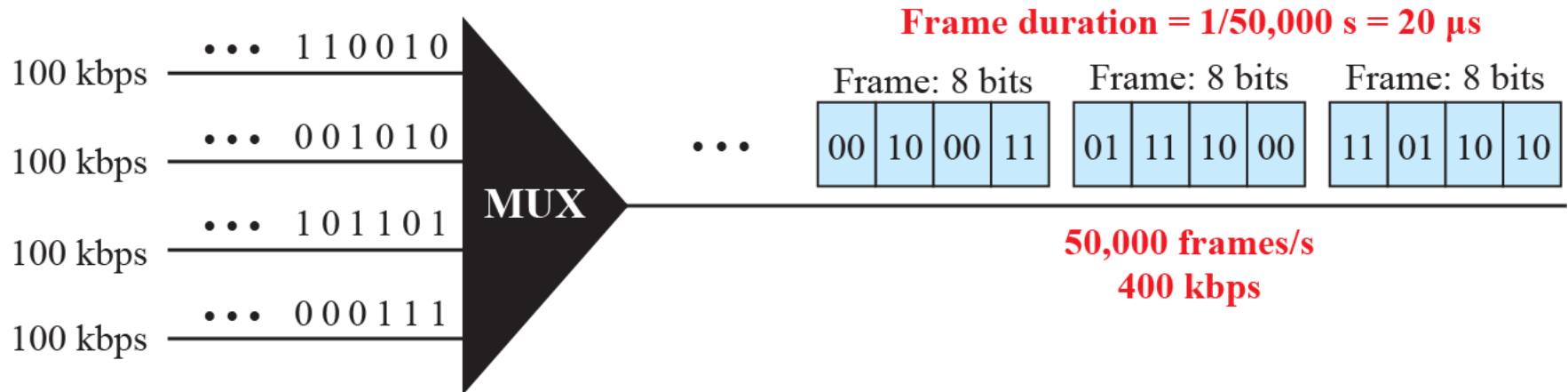


Figure 6.18: *Empty slots*

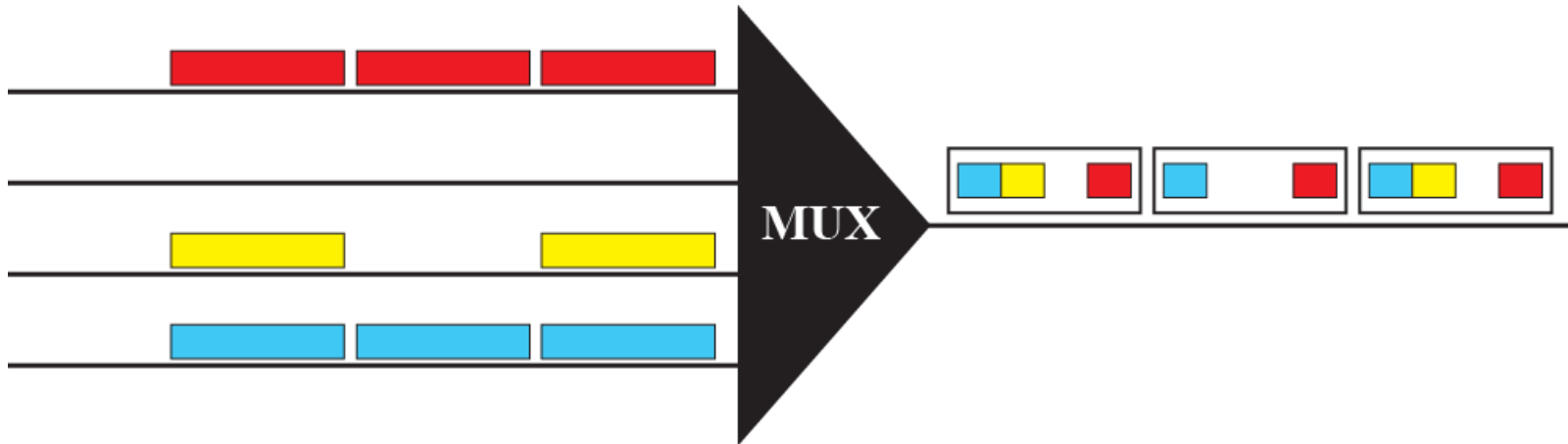


Figure 6.19: *Multilevel multiplexing*

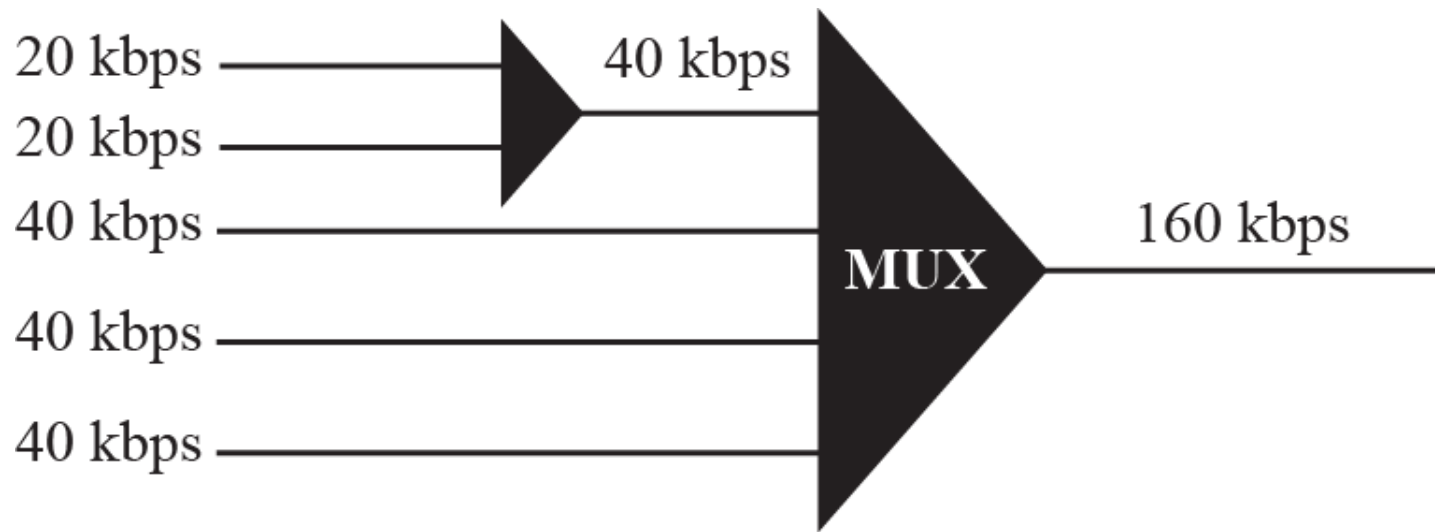


Figure 6.20: Multiple-slot multiplexing

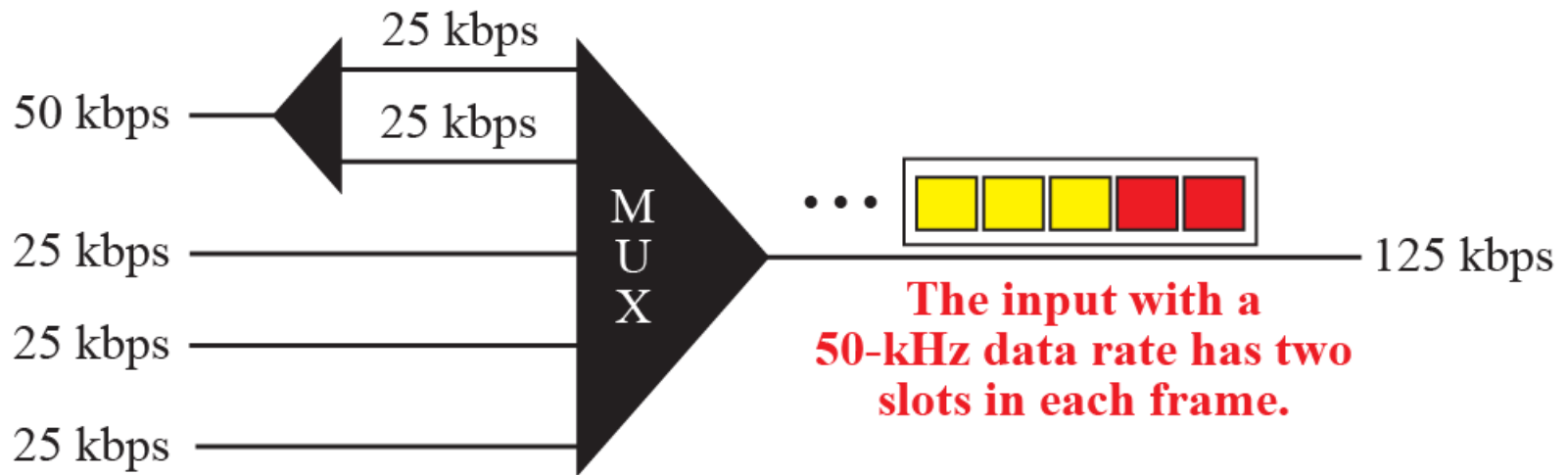


Figure 6.21: Pulse stuffing

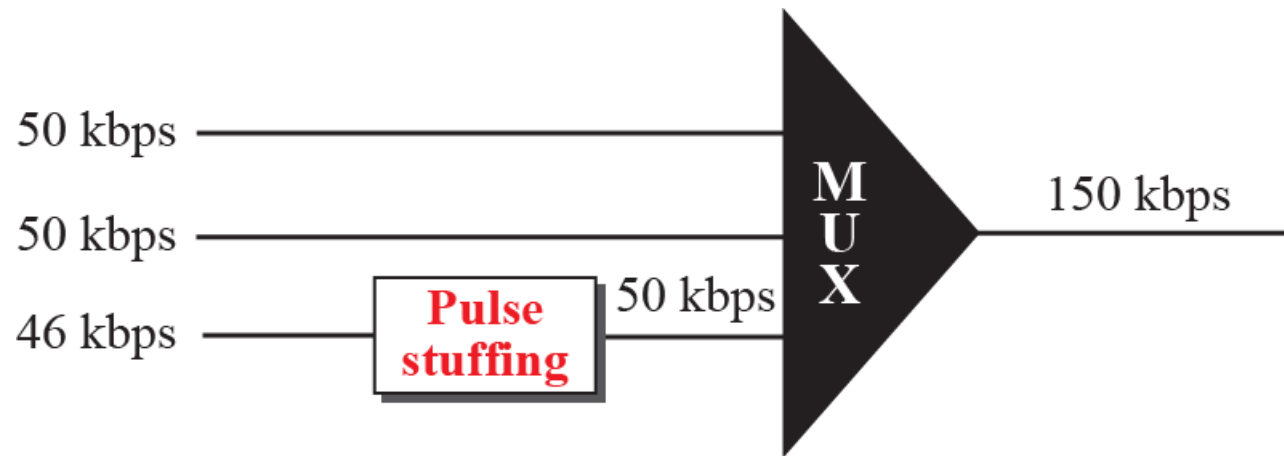
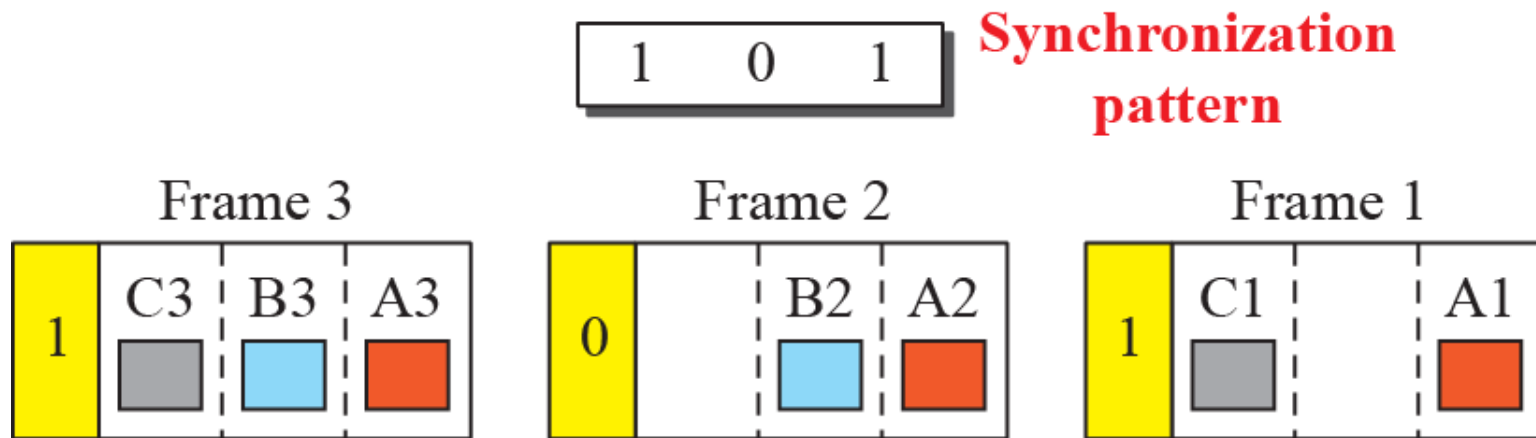


Figure 6.22: Framing bits



Example 6.10

We have four sources, each creating 250 characters per second. If the interleaved unit is a character and 1 synchronizing bit is added to each frame, find (1) the data rate of each source, (2) the duration of each character in each source, (3) the frame rate, (4) the duration of each frame, (5) the number of bits in each frame, and (6) the data rate of the link.

Solution

6. The data rate of each source is $250 \times 8 = 2000 \text{ bps} = 2 \text{ kbps}$.
2. Each source sends 250 characters per second; therefore, the duration of a character is $1/250 \text{ s}$, or 4 ms.

Example 6.10 (Continued)

3. Each frame has one character from each source, which means the link needs to send 250 frames per second.
4. The duration of each frame is $1/250$ s, or 4 ms.
5. Each frame carries 4 characters and 1 extra synchronizing bit. This means that each frame is $4 \times 8 + 1 = 33$ bits.
6. The link sends 250 frames per second, and each frame contains 33 bits. This means that the data rate of the link is 250×33 , or 8250 bps.

Example 6.11

Two channels, one with a bit rate of 100 kbps and another with a bit rate of 200 kbps, are to be multiplexed. How this can be achieved? What is the frame rate? What is the frame duration? What is the bit rate of the link?.

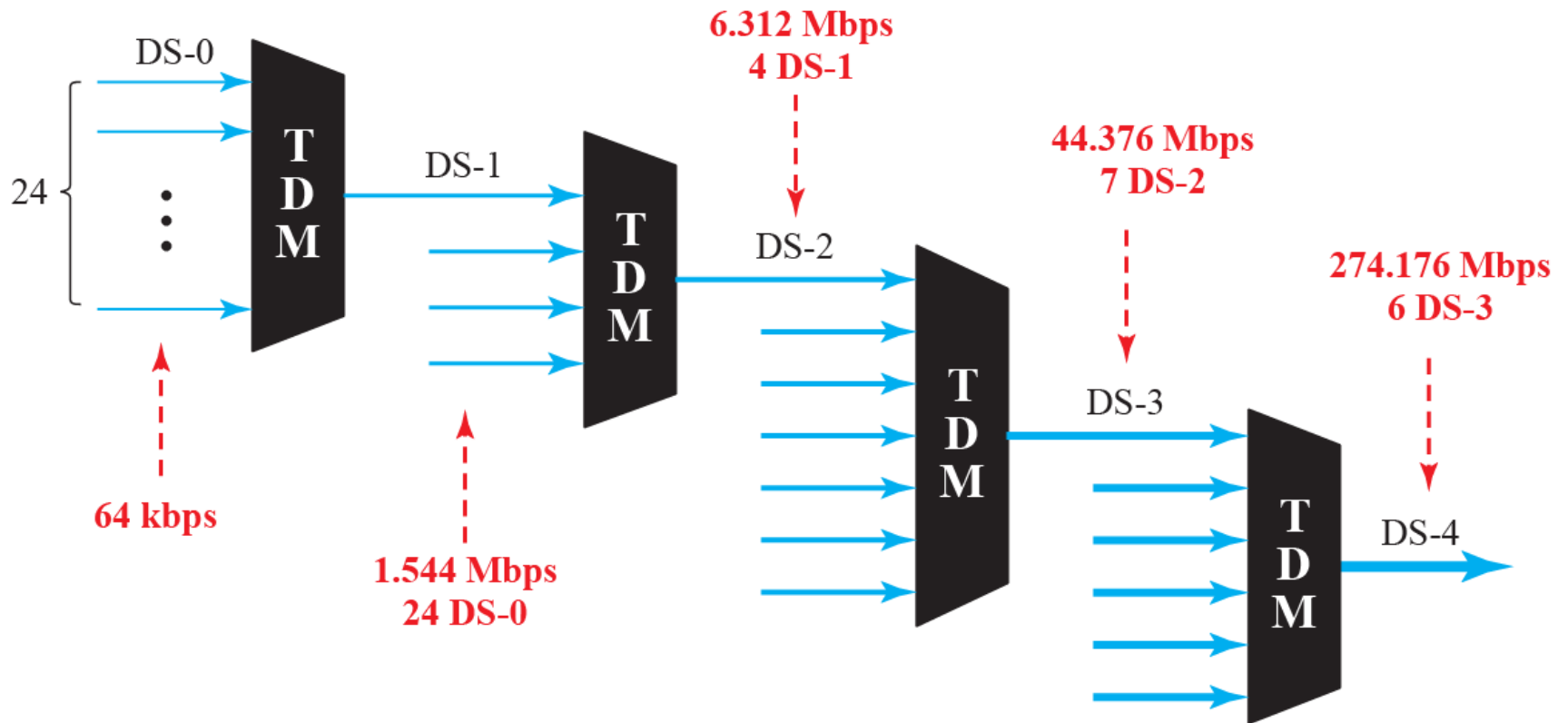
Solution

We can allocate one slot to the first channel and two slots to the second channel. Each frame carries 3 bits. The frame rate is 100,000 frames per second because it carries 1 bit from the first channel. The frame duration is $1/100,000$ s, or 10 ms. The bit rate is $100,000 \text{ frames/s} \times 3 \text{ bits per frame}$, or 300 kbps.

Example 6.11 (Continued)

3. Each frame has one character from each source, which means the link needs to send 250 frames per second.
4. The duration of each frame is $1/250$ s, or 4 ms.
5. Each frame carries 4 characters and 1 extra synchronizing bit. This means that each frame is $4 \times 8 + 1 = 33$ bits.
6. The link sends 250 frames per second, and each frame contains 33 bits. This means that the data rate of the link is 250×33 , or 8250 bps.

Figure 6.23: Digital hierarchy



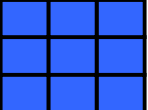


Table 6.1: DS and T line rates

<i>Service</i>	<i>Line</i>	<i>Rate (Mbps)</i>	<i>Voice Channels</i>
DS-1	T-1	1.544	24
DS-2	T-2	6.312	96
DS-3	T-3	44.736	672
DS-4	T-4	274.176	4032

Figure 6.24: T-1 line

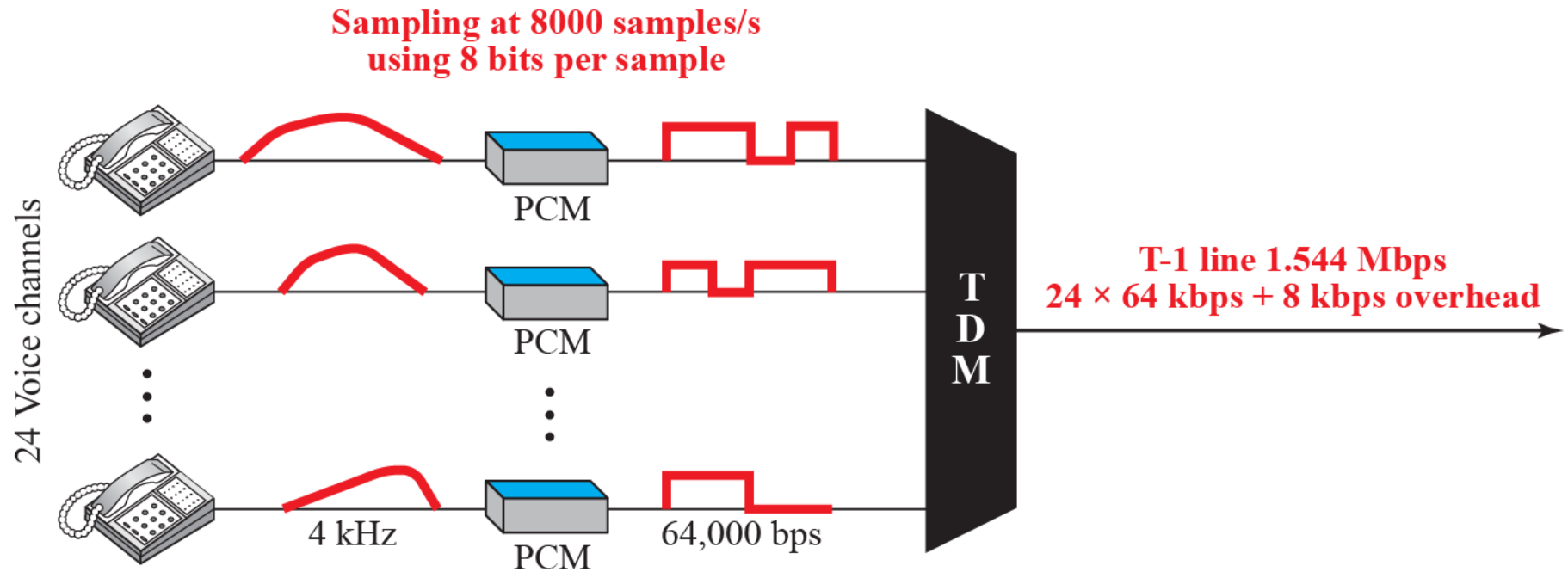
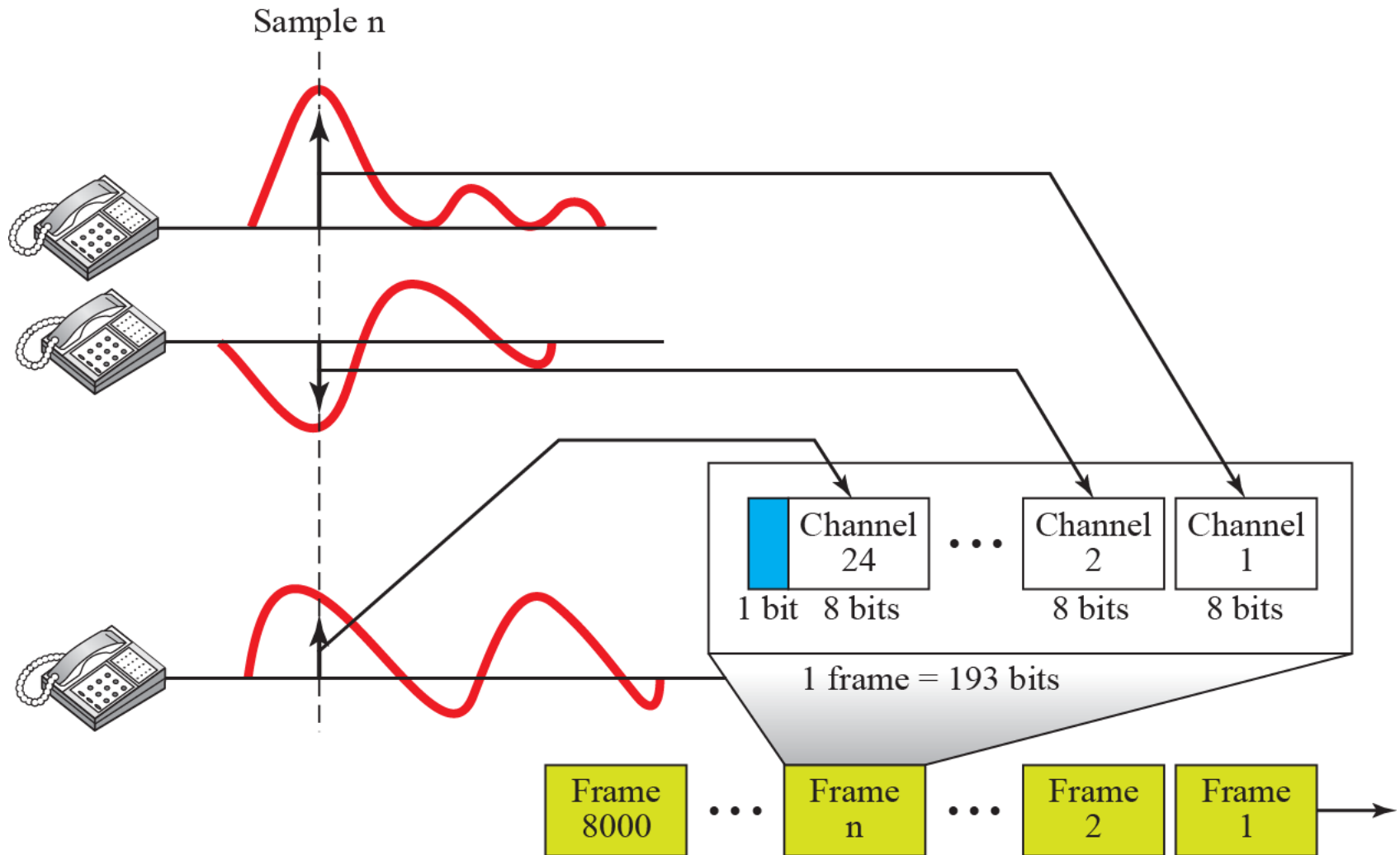


Figure 6.25: T-1 line frame structure



T-1: 8000 frames/s = 8000×193 bps = 1.544 Mbps

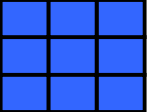
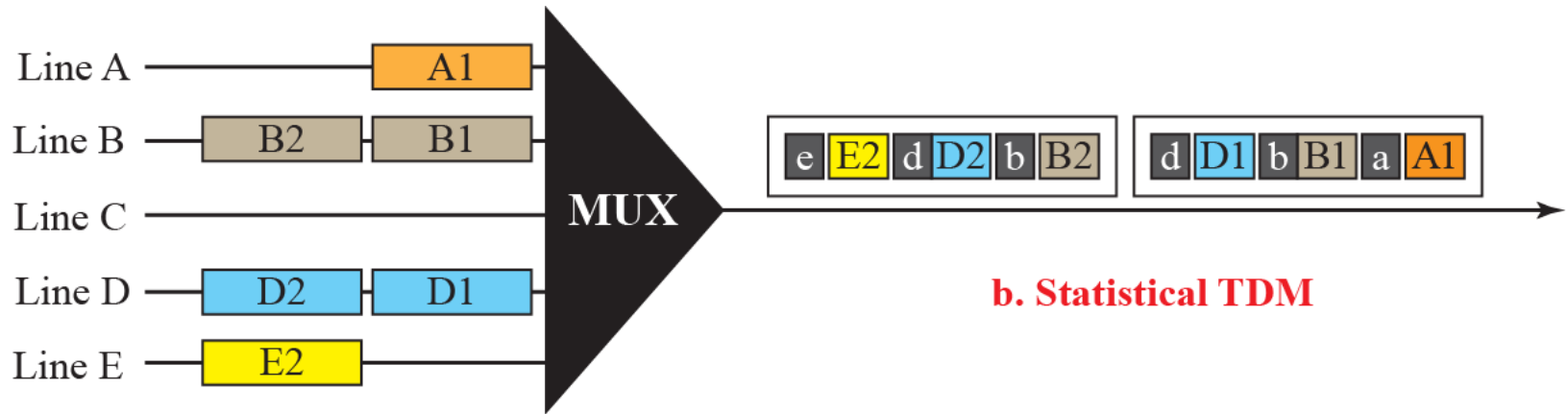
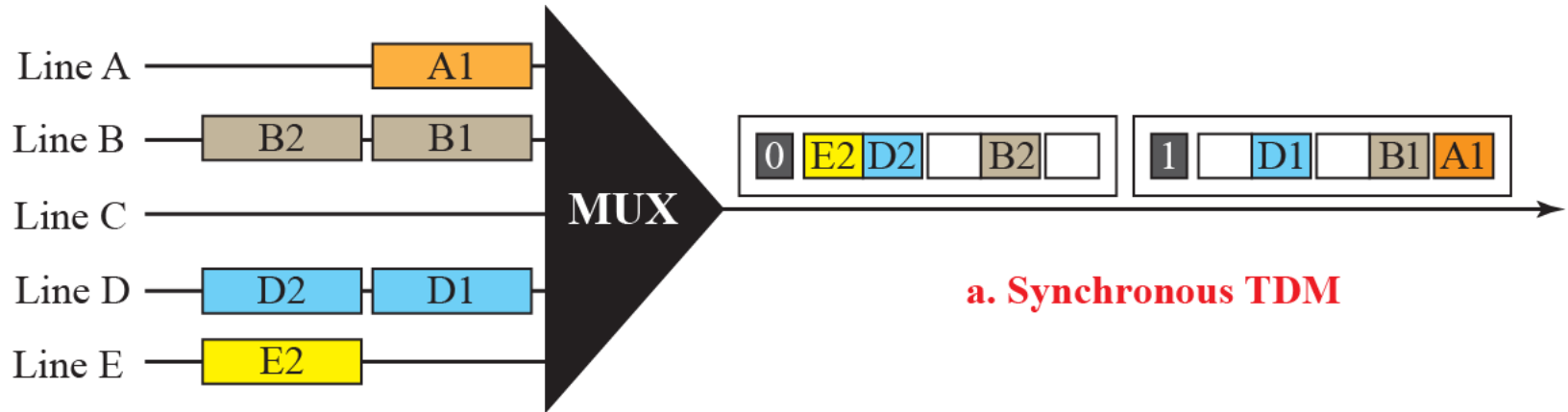


Table 6.2: E line rates

<i>Line</i>	<i>Rate (Mbps)</i>	<i>Voice Channels</i>
E-1	2.048	30
E-2	8.448	120
E-3	34.368	480
E-4	139.264	1920

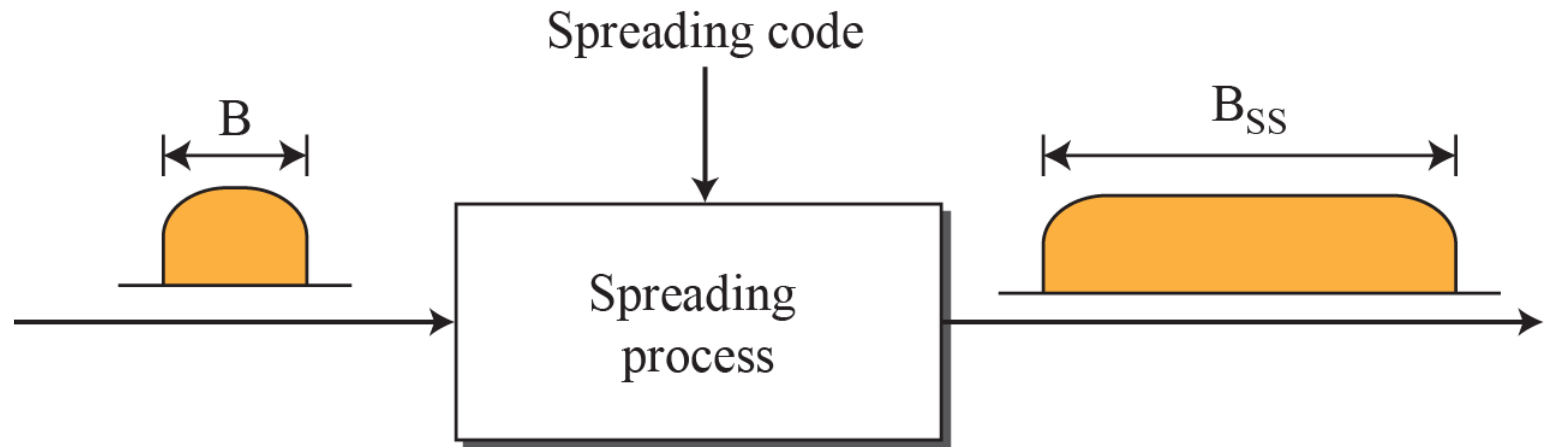
Figure 6.26: TDM slot comparison



6-2 SPREAD SPECTRUM

In some applications, we have some concerns that outweigh bandwidth efficiency. In wireless applications, stations must be able to share this medium without interception by an eavesdropper and without being subject to jamming from a malicious intruder To achieve these goals, spread spectrum techniques add redundancy;

Figure 6.27: Spread spectrum





6.2.1 FHHS

In PM transmission, the phase of the carrier signal is modulated to follow the changing voltage level (amplitude) of the modulating signal. The peak amplitude and frequency of the carrier signal remain constant, but as the amplitude of the information signal changes, the phase of the carrier changes correspondingly.

Figure 6.28: *Frequency hopping spread spectrum (FHSS)*

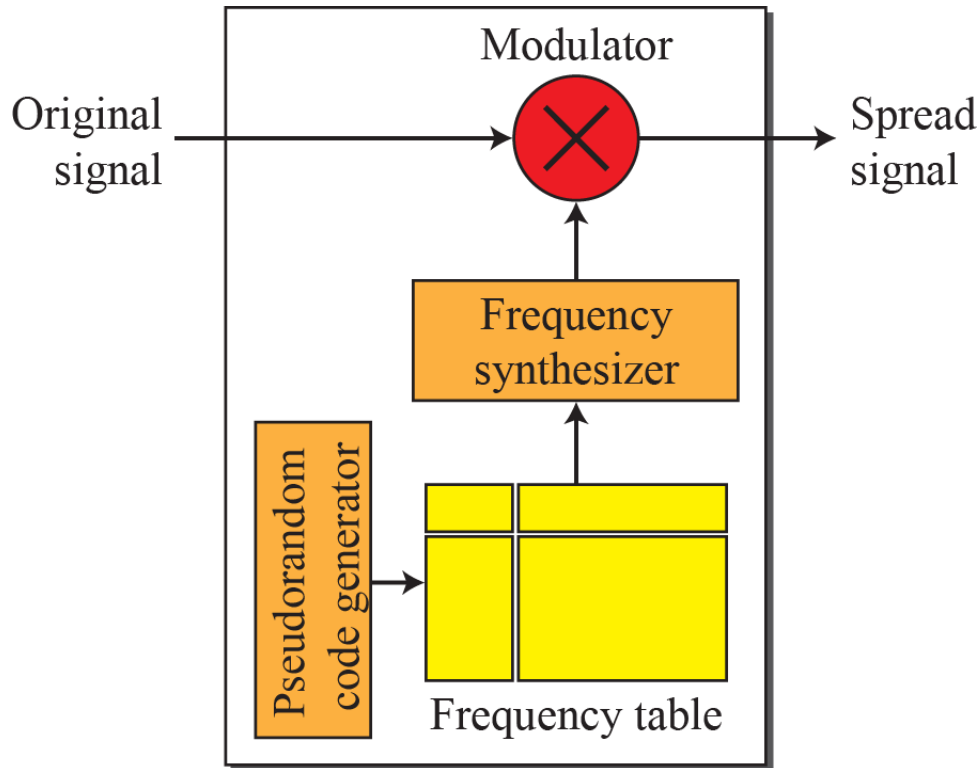


Figure 6.29: *Frequency selection in FHSS*

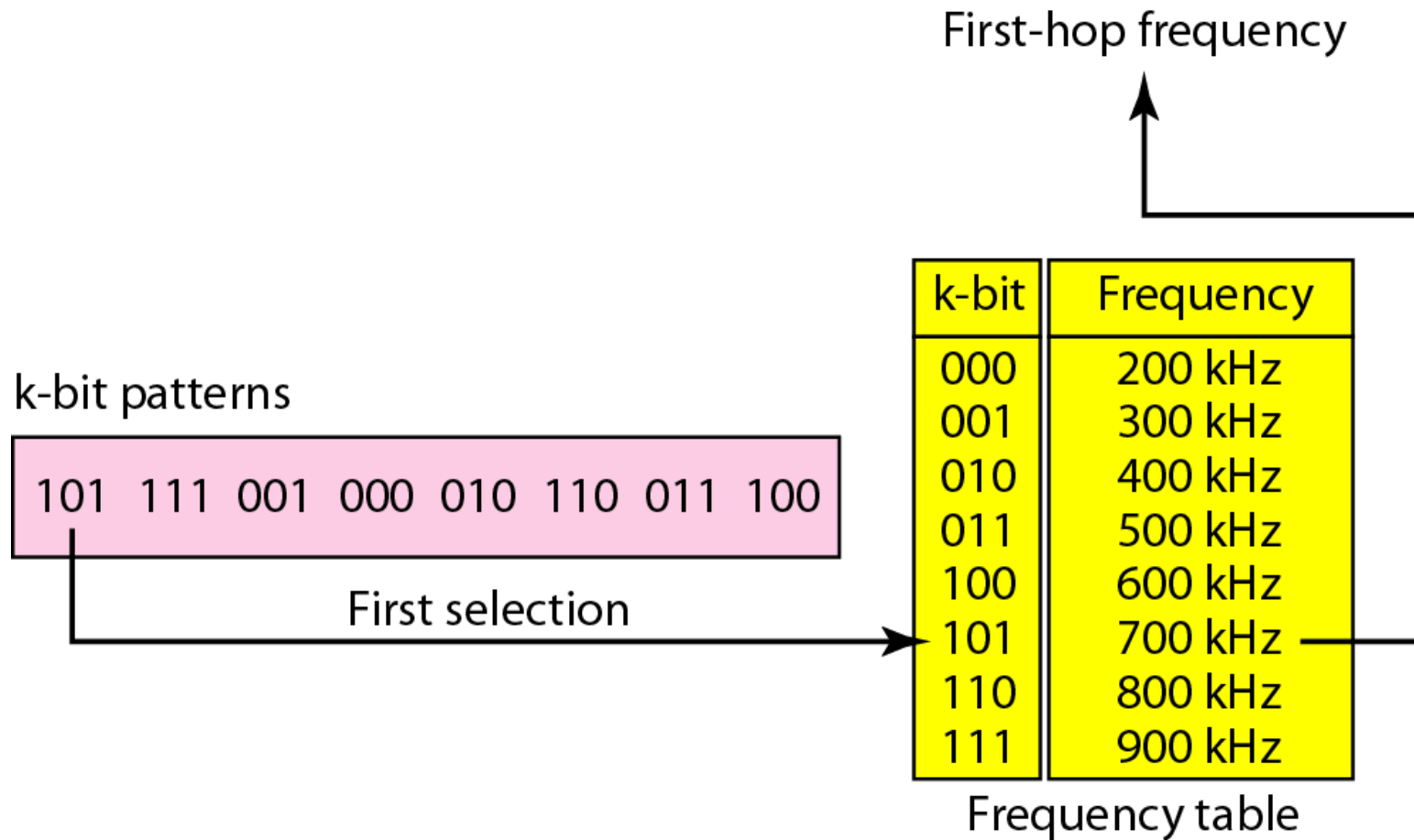


Figure 6.30: FHSS cycles

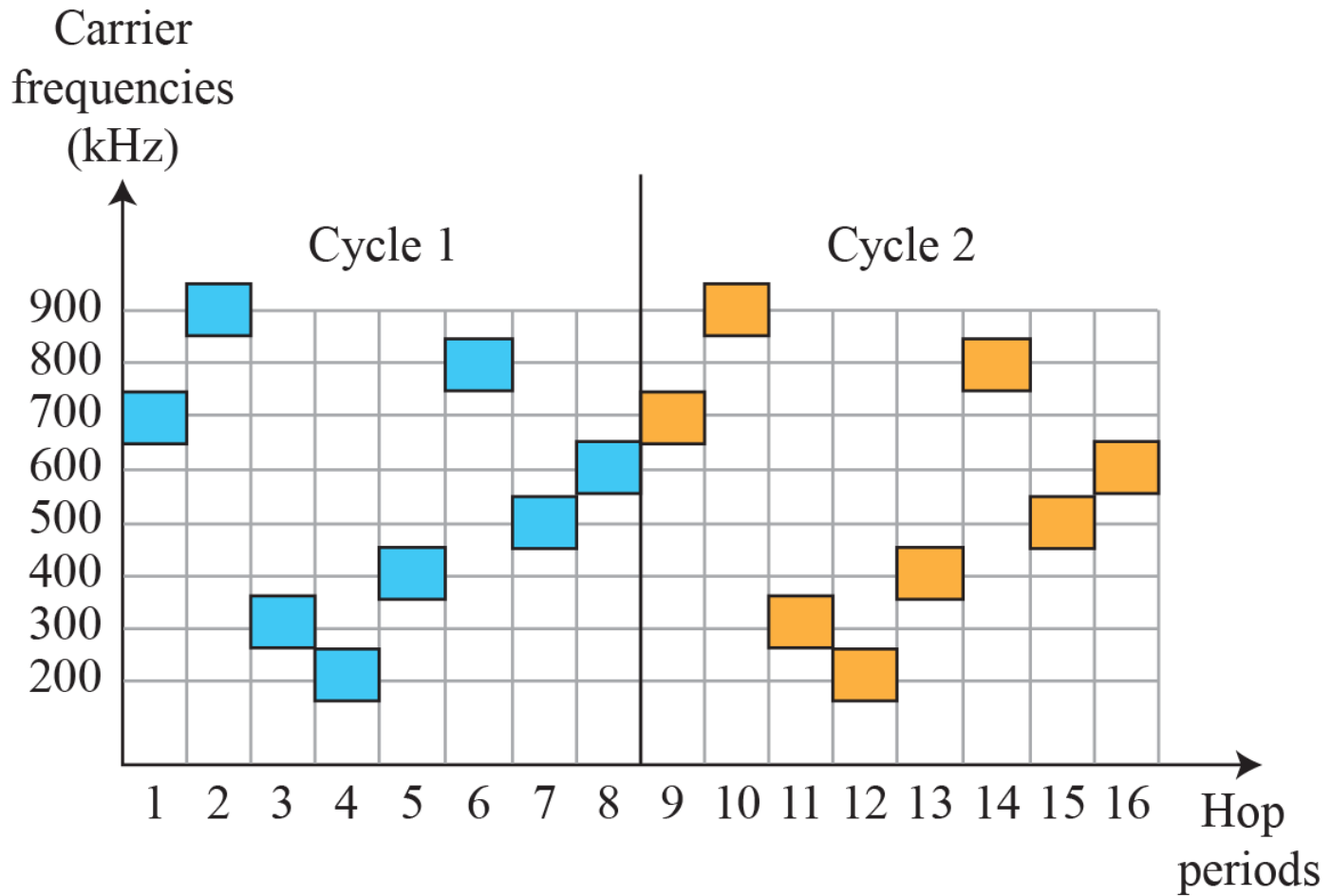
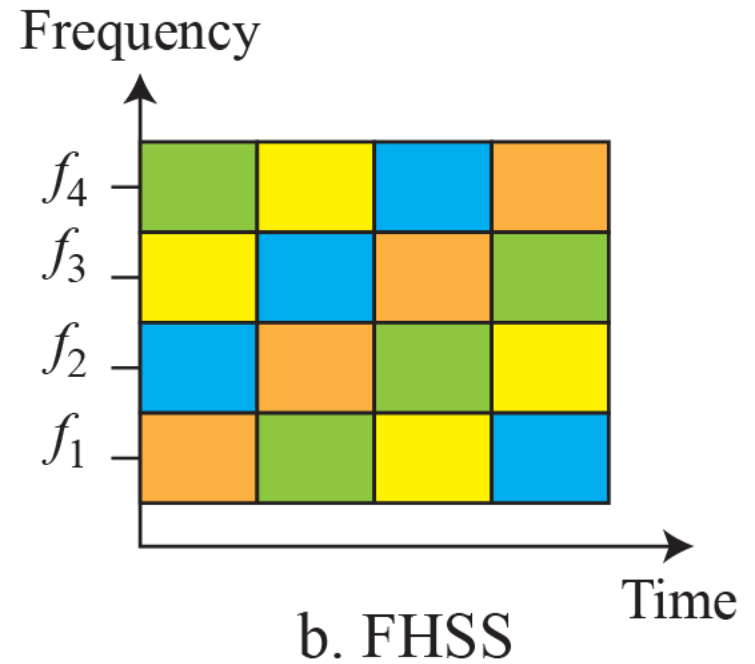
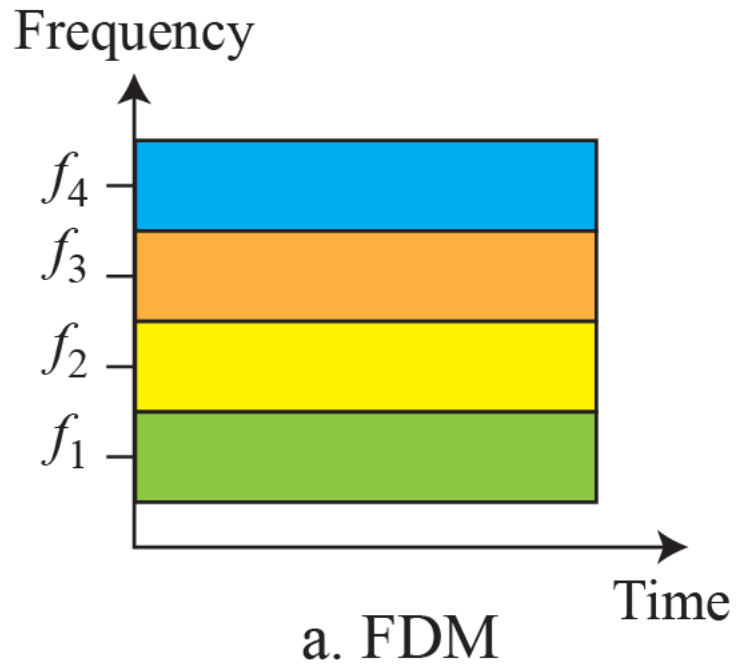


Figure 6.31: Bandwidth sharing





6.2.2 DSSS

The direct sequence spread spectrum (DSSS) technique also expands the bandwidth of the original signal, but the process is different. In DSSS, we replace each data bit with n bits using a spreading code. In other words, each bit is assigned a code of n bits, called chips, where the chip rate is n times that of the data bit. Figure 6.32 shows the concept of DSSS.

Figure 6.32: DSSS

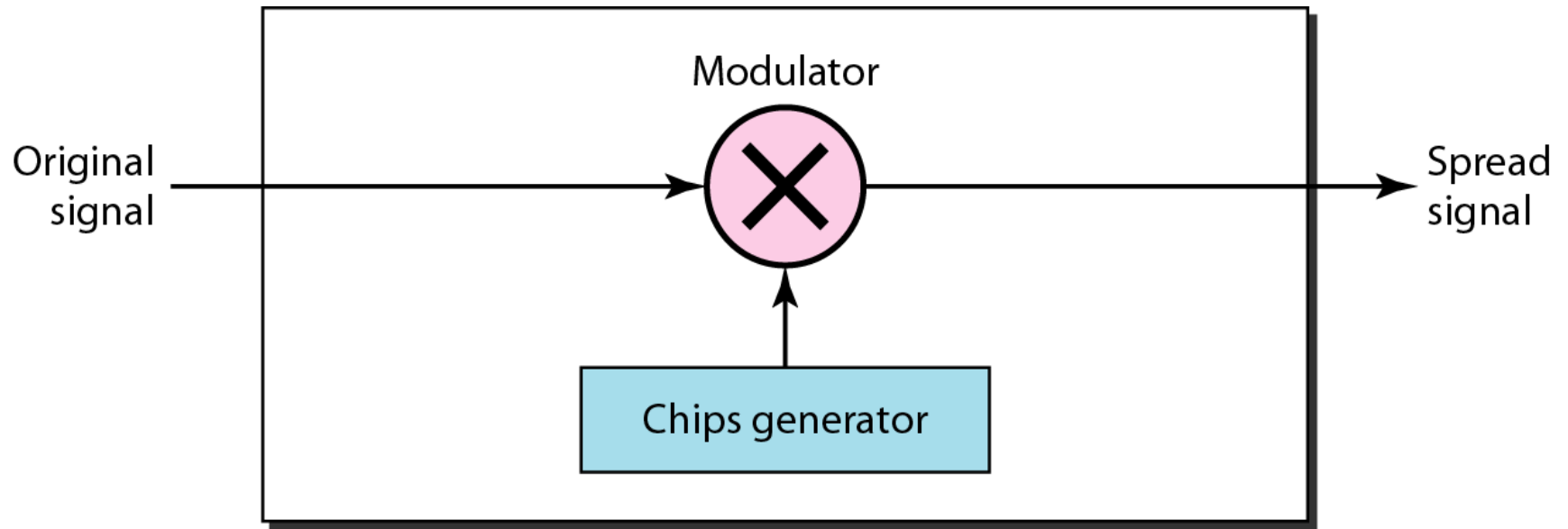


Figure 6.32: *DSSS example*

