

Arduino Programming

- Arduino board is a microcontroller having some inbuilt program put in to ~~communicate~~ communicate with computer.

- General purpose I/O pins -

These allow user to avail

- 1) SWITCH → Manual switch

The pin which is made high or low by the user or by some automatic circuitry & will be read by the arduino to sense the external activity is an input (I/O) pin.

- 2) READ

- 3) INPUT

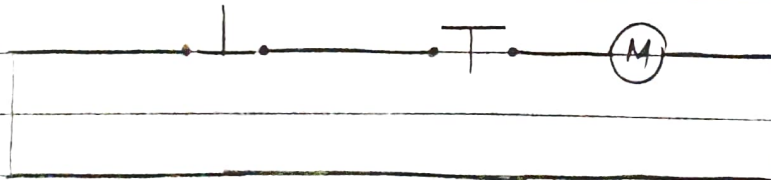
- Output pins -

They will be made logic 1 or Logic 0 based on the input of microcontroller.

Logic 1 ⇒ SET / WRITE

Logic 0 ⇒ RESET / OUTPUT

- STARTER in motors -



• Programming of Arduino:

sensory \leftrightarrow input pin of a switch is a manual switch.
 (H) or (L)

output is based on instruction.

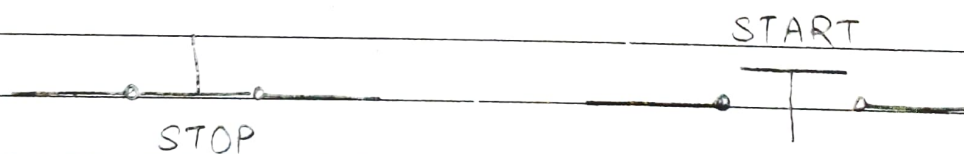


LOGIC 1 or LOGIC 0 by microcontroller of arduino.

e.g. SET P12 Possible through many ways.
 RESET P21 to make output pins.
 WRITE (P13, FLAG) 1 or 0 (High or Low) using
 OUTPUT (P32.0) specific instruction in program

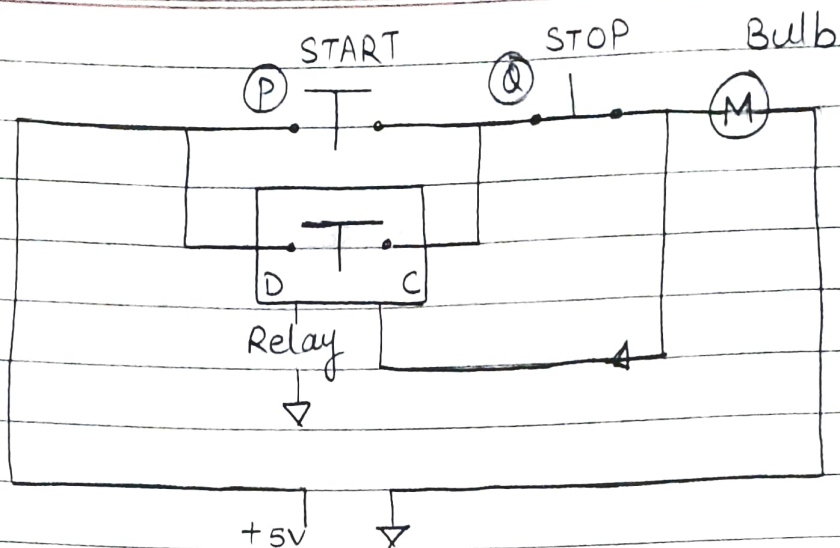
• Digital Circuit :- Deciding status of output pins depending upon input state of microcontroller.

e.g. Starters in Motors :



(NO) pressed START (ON) then motor is started.
 Even START (switch) released then motor still start.

IF STOP pressed then motor stops & even released START, motor stops.

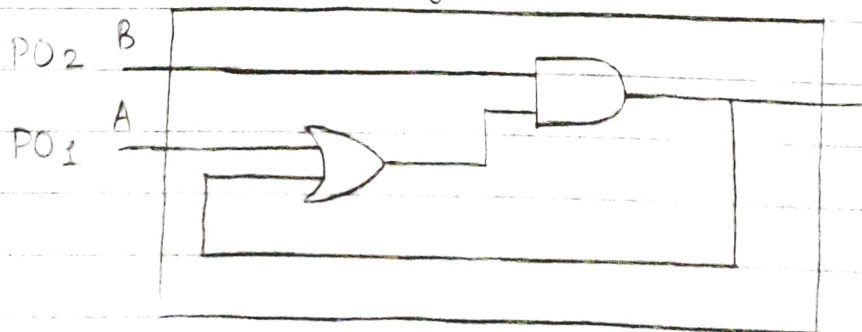


$$M = (P+M)\bar{Q} \quad \text{JUMP table.}$$

START	STOP	M
1	0	1
1	1	0
X	1	0
0	1	1
0	0	(0,1)

★ For the bulb to ON, keep relay ON.

• Digital input



$$Y = C \cdot B$$

$$Y = (A+Y) \cdot B$$

$$B^0$$

$$\downarrow$$

$$A$$

$$B^1$$

$$\downarrow$$

$$B$$

$$B^2$$

$$\downarrow$$

$$Y$$

← Internal register

RESET B2

BO = RFAD PO1

MOV = BO · PO1.

MOV, B1, PO2 or B2, B0

and B2, B1, MOV PO, PO2

- * Microcontroller instructions are arithmetic logic instructions.

Below is a simple microcontroller program of a given circuit in which $Y = (A + r)B$ obtained.
In a program there is always JUMP begin.

* Analog I/P (PWM O/P)

↓

these are inbuilt analog to digital converters

e.g.

5V convert to FF (max)

e.g.

8 BIT \Rightarrow 00 0 \leftarrow 0V analog
| |
FF 255 \leftarrow 5V : 1V

Analog to digital conversion cannot be accurate.
It is always approximate.

e.g.

P.2.0 P2.1 \rightarrow A I/p

MOV(R1, P.2.0)

1 bit P2.0 is register in 1 bit of R1 of 8 bit

- * User sets SETP. \rightarrow Read by Arduino.

System changes process (P.V) \rightarrow Read by Arduino
switch o/p pin or relay \leftarrow controlled by Arduino