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Batch: T5

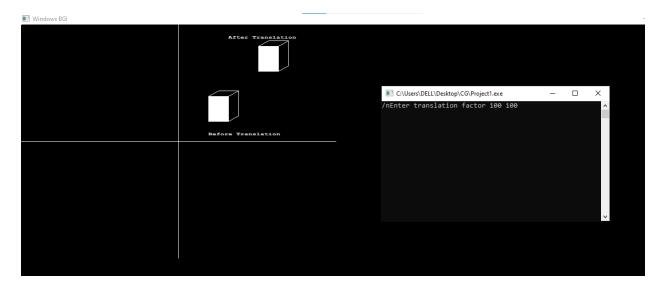
Experiment 6: Implementation of 3D transformation

3D Translation:

```
#include<stdio.h>
#include<stdlib.h>
#include<math.h>
#include<graphics.h>
using namespace std;
int maxx,maxy,midx,midy;
void axis()
       getch();
      line(midx,0,midx,maxy);
       line(0,midy,maxx,midy);
}
int main()
{
      int gd = DETECT, gm;
       detectgraph(&gd, &gm);
       initgraph(&gd, &gm, "c:\\turboc3\\bgi");
      int x, y,z,o, x1, y1, x2, y2;
       maxx=getmaxx();
       maxy=getmaxy();
```

```
midx=maxx/2;
    midy=maxy/2;
    outtextxy(midx+60,midy-20, "Before Translation");
    line(midx,0,midx,maxy);
    line(0,midy,maxx,midy);
bar3d(midx+100,midy-40, midx+60, midy-90, 20,5);
axis();
outtextxy(midx+100,20,"After Translation");
printf("/nEnter translation factor");
scanf("%d%d",&x,&y);
bar3d(midx+100,midy-40, midx+60, midy-90, 20,5);
bar3d(midx+(x+100), midy-(y+40), midx+(x+60), midy-(y+90), 20, 5);
axis();
closegraph();
return 0;
```

OUTPUT:



```
3D Scaling:
#include<stdio.h>
#include<stdlib.h>
#include<math.h>
#include<graphics.h>
using namespace std;
```

int maxx,maxy,midx,midy;

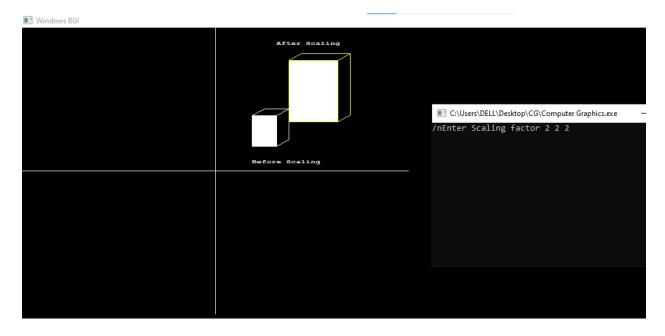
```
void axis()
      getch();
      line(midx,0,midx,maxy);
      line(0,midy,maxx,midy);
}
int main()
      int gd = DETECT, gm;
      detectgraph(&gd, &gm);
      initgraph(&gd, &gm, "c:\\turboc3\\bgi");
      int x, y,z,o, x1, y1, x2, y2;
      maxx=getmaxx();
      maxy=getmaxy();
      midx=maxx/2;
      midy=maxy/2;
```

outtextxy(midx+60,midy-20, "Before Scaling");

```
line(midx,0,midx,maxy);
line(0,midy,maxx,midy);
bar3d(midx+100,midy-40, midx+60, midy-90, 20,5);
axis();
outtextxy(midx+100,20,"After Scaling");
printf("/nEnter Scaling factor");
scanf("%d%d%d",&x,&y, &z);

setcolor(YELLOW);
bar3d(midx+(x*100), midy-(y*40), midx+(x*60), midy-(y*90), 20, 5);
axis();
closegraph();
return 0;
```

OUTPUT:



3D Rotation:

```
#include<stdio.h>
#include<stdlib.h>
#include<math.h>
#include<graphics.h>
using namespace std;
int maxx,maxy,midx,midy;
void axis()
      getch();
      line(midx,0,midx,maxy);
      line(0,midy,maxx,midy);
}
int main()
      int gd = DETECT, gm;
      detectgraph(&gd, &gm);
      initgraph(&gd, &gm, "c:\\turboc3\\bgi");
      int x, y,z,ang, x1, y1, x2, y2;
      maxx=getmaxx();
      maxy=getmaxy();
       midx=maxx/2;
      midy=maxy/2;
      outtextxy(midx+60,midy-20, "Before Rotation");
      line(midx,0,midx,maxy);
      line(0,midy,maxx,midy);
```

```
bar3d(midx+100,midy-40, midx+60, midy-90, 20,5);
printf("Enter the Rotation Angle: ");
scanf("%d",&ang);
x1=100*\cos(ang*3.14/180)-40*\sin(ang*3.14/180);
y1=100*sin(ang*3.14/180)+40*sin(ang*3.14/180);
x2=60*\cos(ang*3.14/180)-90*\sin(ang*3.14/180);
y2=60*\sin(ang*3.14/180)+90*\sin(ang*3.14/180);
axis();
 setcolor(YELLOW);
printf("\n After rotating about x-axis\n");
bar3d(midx+100,midy-40,midx+60,midy-90,20,5);
bar3d(midx+100,midy-x1,midx+60,midy-x2,20,5);
axis();
printf("\n After rotating about z-axis\n");
bar3d(midx+100,midy-40,midx+60,midy-90,20,5);
bar3d(midx+x1,midy-y1,midx+x2,midy-y2,20,5);
axis();
printf("\n After rotating about y-axis\n");
bar3d(midx+100,midy-40,midx+60,midy-90,20,5);
bar3d(midx+x1,midy-40,midx+x2,midy-90,20,5);
axis();
closegraph();
```

OUTPUT:

