

Gitaran Mekanik. Tugas 4

0) Diketahui:

$$m = 4,6 \times 10^{-12} \text{ kg}$$

$$K = 0,380 \text{ N/m}$$

$$C = 4,93 \times 10^{-7} \text{ Ns/m}$$

$$v_0 = 30 \text{ m/s}$$

$$x_0 = 0 \text{ m}$$

a. natural frequency (ω_n) & critical damping (C_c).

$$\omega_n = \sqrt{\frac{K}{m}}$$

$$\omega_n = \sqrt{\frac{0,380 \text{ N/m}}{4,6 \times 10^{-12} \text{ kg}}}$$

$$\omega_n = \sqrt{8,260869565 \times 10^{10}}$$

$$\omega_n = 9,088 \times 10^5 \text{ rad/s.}$$

$$C_c = 2\sqrt{mk}.$$

$$C_c = 2\sqrt{(4,6 \times 10^{-12} \text{ kg})(0,380 \text{ N/m})}$$

$$C_c = 2\sqrt{1,748 \times 10^{-12}}$$

$$C_c = 2,095 \times 10^{-6} \text{ Ns/m}$$

b. Damping ratio (ζ)

$$\zeta = \frac{C}{2\sqrt{mk}}$$

$$\zeta = \frac{4,93 \times 10^{-7} \text{ Ns/m}}{2(9,088 \times 10^5 \text{ rad/s})}$$

$$\zeta = \frac{4,93 \times 10^{-7}}{1,8176 \times 10^6}$$

$$\zeta = 2,71 \times 10^{-13}$$

c. the frequency of damped oscillation:

$$\omega_d = \sqrt{\omega_n^2 - \zeta^2}$$

$$= \sqrt{(9,088 \times 10^5)^2 - (2,71 \times 10^{-13})^2}$$

$$= \sqrt{8,26744 \times 10^{11}}$$

$$= 9,091 \times 10^5 \text{ rad/s}$$

d. the response of the accelerometer.

$$x(t) = e^{-\zeta \omega_n t} (A \cos(\omega_d t) + B \sin(\omega_d t))$$

$$\text{At } t=0, x(0) = 0$$

$$\text{At } t=0, v(0) = 30 \text{ m/s}$$

$$x(0) = e^{-\zeta \omega_n \times 0} (A \cos(\omega_d \times 0) + B \sin(\omega_d \times 0)) = 0$$

$$= A \cos(0) + B \sin(0) = 0$$

$$= A = 0$$

$$v(0) = -\zeta \omega_n A e^{-\zeta \omega_n \times 0} \sin(\omega_d \times 0) + \omega_d B e^{-\zeta \omega_n \times 0} \cos(\omega_d \times 0) = 30$$

$$= 0 + \omega_d B = 30$$

$$= B = \frac{30}{\omega_d}$$

find $B =$

$$B = \frac{30}{9,091 \times 10^5}$$

$$B = 3,301 \times 10^{-5} \text{ m/s.}$$

$$\text{So, } x(t) = e^{-\zeta \omega_n t} (0 \cos(\omega_d t) + (3,301 \times 10^{-5}) \sin(\omega_d t)).$$

e. Value displacement at $t = 1 \mu\text{s}$.

$$x(1 \mu\text{s}) = e^{-\zeta \omega_n (1 \mu\text{s})} (0 \cos(\omega_d (1 \mu\text{s})) + (3,301 \times 10^{-5}) \sin(\omega_d (1 \mu\text{s})))$$