A Project Report

On

Target Detection & Tracking

Submitted for the partial fulfillment of the requirement

for the award of the Degree of

BACHELOR OF TECHNOLOGY

In

COMPUTER SCIENCE & ENGINEERING

by

Ritam Ghosh (160111046)

Dhiraj Kumar Saini (160110084)

Rachit Goyal (160112002)

Under the Guidance of

Rohit Kamboj
IBM Trainer

DIT UNIVERSITY, DEHRADUN
Uttarakhand 248009, India.

April 2019

DECLARATION

This is to certify that the Project entitled **"Target Detection & Tracking"** in partial fulfillment of the requirement for the award of the **Degree of BACHELOR OF TECHNOLOGY** in **COMPUTER SCIENCE & ENGINEERING** submitted to **DIT University, Dehradun, Uttarakhand, India,** is an authentic record of bonafide work carried out by me, under the guidance of Rohit Kamboj (IBM Trainer).

The matter embodied in this Project/Thesis/Dissertation has not been submitted for the award of any other degree or diploma to any University/Institution.

Students Name & Signature:

Dhiraj Kumar Saini

Ritam Ghosh

Rachit Goyal

Supervisor Name, Designation & Signature:

Mr. Rohit Kamboj
IBM Trainer

Dr. Vishal Bharti
Head of Department CSE
Signature

Mr. Gagandeep Singh
Controller of Examination
Signature

Date:

Place: Dehradun

CERTIFICATE

This is to certify that the Project entitled **"Target Detection & Tracking"** in partial fulfillment of the requirement for the award of the **Degree of BACHELOR OF TECHNOLOGY** in **COMPUTER SCIENCE & ENGINEERING** submitted to **DIT University, Dehradun, Uttarakhand, India,** is an authentic record of bonafide research work carried out by

Mr. Ritam Ghosh Roll No 160111046
Mr. Dhiraj Kumar Saini Roll No 160110084
Mr. Rachit Goyal Roll No 160112002

under my supervision/ guidance.

Rohit Kamboj

IBM Trainer
Supervisor/Guide

ACKNOWLEDGEMENT

The success and final outcome of this project required a lot of guidance and assistance from many people and we are extremely privileged to have got this all along the completion of our project. All that we have done is only due to such supervision and assistance and we would not forget to thank them.

We respect and thank **Dr Vishal Bharti, HOD CSE Department**, DIT University, Dehradun, for providing us an opportunity to do the project work and giving us all support and guidance, which made us complete the project duly. We are extremely thankful to him for providing support and guidance.

We owe our deep gratitude to our project guide & mentor **Rohit Kamboj, IBM Trainer**, who took keen interest on our project work and guided us all along, till the completion of our project work by providing all the necessary information for developing a good system.

We heartily thank our internal project guide **Mr. Soumen Kanrar, Assistant Professor**, DIT University for his ideology, guidance and suggestions during this project work by providing resources & teaching to work with real time data & information.

We are also grateful to **Rochak Sharma, IBM Trainer**, who took interest on our work and help use solving real time errors and guide us how to proceed further step by step.

We are thankful to and fortunate enough to get constant encouragement, support and guidance from all Teaching staffs of CSE Department which helped us in successfully completing our project work. Also, we would like to extend our sincere esteems to all staff in laboratory for their timely support.

Ritam Ghosh
Dhiraj Kumar Saini
Rachit Goyal

ABSTRACT

This project is to recognize and identify the moving objects for (specific) interest, and to track those moving objects throughout their life spans. This project aims for the existing challenging issue in the area of unsupervised surveillance and security. This project also aims to solve the issue that video feeds can't be processes in real time and we cannot track the object in real time with accuracy. In this project deep neural network have been implemented to provide accuracy and we divided its functionalities into modules to make up for the speed. This project can be implemented to process video feed of the drones or sniffers and help the controller to identify the target and trace it path in real time view. This project was implemented in 3 months & it involves going through research work on object tracking & trying to develop the best out of it. The results are included in this report and we would be working on its future expansion to increase speed and accuracy & make it more effective for ease of use in standard system.

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