

Module - 1
Vector Calculus

Vector Function -

If to each value of a scalar variable t , there corresponds a value of vector \vec{r} , then \vec{r} is called a vector function of the scalar variable t and we write $\vec{r} = \vec{r}(t)$ or $\vec{r} = \vec{f}(t)$

$$\text{Eg} - \vec{r} = t\hat{i} - 2t\hat{j} + t^2\hat{k} = \vec{r}(t)$$

$$\text{if } t=1, \vec{r}(1) = \hat{i} - 2\hat{j} + \hat{k}$$

$$\text{if } t=4, \vec{r}(4) = 4\hat{i} - 8\hat{j} + 16\hat{k}$$

Derivative of vector function w.r.t. a scalar -

Let, $\vec{r} = \vec{f}(t)$ be a vector function of scalar t . Let δt be the small increment in t and $\delta \vec{r}$ be the corresponding increment in \vec{r} .

$$\therefore \vec{r} + \delta \vec{r} = \vec{f}(t + \delta t)$$

$$\Rightarrow \delta \vec{r} = \vec{f}(t + \delta t) - \vec{f}(t)$$

$$\Rightarrow \frac{\delta \vec{r}}{\delta t} = \frac{\vec{f}(t + \delta t) - \vec{f}(t)}{\delta t}$$

$$\Rightarrow \lim_{\delta t \rightarrow 0} \frac{\delta \vec{r}}{\delta t} = \lim_{\delta t \rightarrow 0} \frac{\vec{f}(t + \delta t) - \vec{f}(t)}{\delta t}$$

Corresponding increment in \vec{r}

$$\Rightarrow \frac{d\vec{r}}{dt} = \lim_{\delta t \rightarrow 0} \frac{\vec{f}(t + \delta t) - \vec{f}(t)}{\delta t}$$

Some rules of vector differentiation -

If \vec{a}, \vec{b} and \vec{c} are vector function of a scalar t and ϕ be a scalar function of (t) , then

$$1) \frac{d}{dt}(\vec{a} \pm \vec{b}) = \frac{d\vec{a}}{dt} \pm \frac{d\vec{b}}{dt}$$

$$2) \frac{d}{dt}(\vec{a} \cdot \vec{b}) = \vec{a} \cdot \frac{d}{dt} \vec{b} + \frac{d}{dt} \vec{a} \cdot \vec{b} \quad [\text{write as written}]$$

$$3) \frac{d}{dt}(\vec{a} \times \vec{b}) = \vec{a} \times \frac{d\vec{b}}{dt} + \frac{d\vec{a}}{dt} \times \vec{b}$$

$$4) \frac{d}{dt}(\phi \vec{a}) = \phi \frac{d\vec{a}}{dt} + \frac{d\phi}{dt} \vec{a}$$

$$5) \frac{d}{dt} [\vec{a} \cdot \vec{b} \cdot \vec{c}] = \left[\frac{d\vec{a}}{dt} \cdot \vec{b} \cdot \vec{c} \right] + \left[\vec{a} \cdot \frac{d\vec{b}}{dt} \cdot \vec{c} \right] + \left[\vec{a} \cdot \vec{b} \cdot \frac{d\vec{c}}{dt} \right]$$

$$6) \frac{d}{dt} [\vec{a} \times (\vec{b} \times \vec{c})] = \frac{d\vec{a}}{dt} \times (\vec{b} \times \vec{c}) + \vec{a} \times \left(\frac{d\vec{b}}{dt} \times \vec{c} \right) + \vec{a} \times \left(\vec{b} \times \frac{d\vec{c}}{dt} \right)$$

Proves -

$$\begin{aligned} 2) LHS &= \frac{d}{dt} (\vec{a} \cdot \vec{b}) \\ &= \lim_{\delta t \rightarrow 0} \frac{(\vec{a} + \delta \vec{a})(\vec{b} + \delta \vec{b}) - \vec{a} \cdot \vec{b}}{\delta t} \\ &= \lim_{\delta t \rightarrow 0} \frac{\vec{a} \cdot \vec{b} + \vec{a} \cdot \delta \vec{b} + \delta \vec{a} \cdot \vec{b} + \delta \vec{a} \cdot \delta \vec{b} - \vec{a} \cdot \vec{b}}{\delta t} \\ &= \lim_{\delta t \rightarrow 0} \frac{\vec{a} \cdot \delta \vec{b} + \delta \vec{a} \cdot \vec{b} + \delta \vec{a} \cdot \delta \vec{b}}{\delta t} \\ &= \lim_{\delta t \rightarrow 0} \vec{a} \cdot \frac{\delta \vec{b}}{\delta t} + \lim_{\delta t \rightarrow 0} \frac{\delta \vec{a}}{\delta t} \cdot \vec{b} + \lim_{\delta t \rightarrow 0} \frac{\delta \vec{a}}{\delta t} \cdot \delta \vec{b} \xrightarrow{\delta \vec{b} \rightarrow 0} \\ &= \vec{a} \cdot \frac{d\vec{b}}{dt} + \frac{d\vec{a}}{dt} \cdot \vec{b} \\ &= RHS \end{aligned}$$

$$\begin{aligned} 5) LHS &= \frac{d}{dt} [\vec{a} \cdot \vec{b} \cdot \vec{c}] \\ &= \frac{d}{dt} \{ \vec{a} \cdot (\vec{b} \times \vec{c}) \} \\ &= \vec{a} \cdot \frac{d}{dt} (\vec{b} \times \vec{c}) + \frac{d\vec{a}}{dt} \cdot (\vec{b} \times \vec{c}) \\ &= \vec{a} \left(\vec{b} \times \frac{d\vec{c}}{dt} + \frac{d\vec{b}}{dt} \times \vec{c} \right) + \frac{d\vec{a}}{dt} (\vec{b} \times \vec{c}) \\ &= \vec{a} \cdot \left(\vec{b} \times \frac{d\vec{c}}{dt} \right) + \vec{a} \cdot \left(\frac{d\vec{b}}{dt} \times \vec{c} \right) + \frac{d\vec{a}}{dt} \cdot (\vec{b} \times \vec{c}) \\ &= \left[\vec{a} \cdot \vec{b} \cdot \frac{d\vec{c}}{dt} \right] + \left[\vec{a} \cdot \frac{d\vec{b}}{dt} \cdot \vec{c} \right] + \left[\frac{d\vec{a}}{dt} \cdot \vec{b} \cdot \vec{c} \right] \\ &= RHS \end{aligned}$$

Theorem -

Differentiation of a constant vector is zero vector.

Proof - Let \vec{r} be a constant vector of scalar t .

$$\therefore \vec{r} = \vec{f}(t)$$

$$\therefore \vec{F} + S\vec{F} = \vec{f}(t+St) = \vec{f}(t)$$

$$\Rightarrow S\vec{F} = \vec{f}(t)$$

$$\begin{aligned}\therefore \frac{d\vec{F}}{dt} &= \lim_{St \rightarrow 0} \frac{\vec{f}(t+St) - \vec{f}(t)}{St} \\ &= \lim_{St \rightarrow 0} \frac{\vec{f}(t) - \vec{f}(t)}{St} \\ &= \vec{0}\end{aligned}$$

Theorem -

If $\vec{F}(t)$ has a constant magnitude, then \vec{F} and $\frac{d\vec{F}}{dt}$ are perpendicular.

Solⁿ \vec{F} has constant magnitude

$$|\vec{F}(t)| = \text{const.}$$

$$\text{Now, } \vec{F}(t) \cdot \vec{F}(t) = |\vec{F}(t)|^2 = \text{const.}$$

$$\Rightarrow \vec{F} \cdot \vec{F} = \text{const.}$$

$$\Rightarrow \frac{d}{dt} (\vec{F} \cdot \vec{F}) = 0$$

$$\Rightarrow \vec{F} \cdot \frac{d}{dt} \vec{F} + \frac{d\vec{F}}{dt} \cdot \vec{F} = 0$$

$$\Rightarrow \vec{F} \cdot \frac{d\vec{F}}{dt} = 0$$

$$\therefore \vec{F} \perp \frac{d\vec{F}}{dt}$$

Eg - If \vec{F} has a const. direction then $\vec{F} \times \frac{d\vec{F}}{dt} = 0$

Solⁿ Let $\hat{G}(t)$ be the unit vector in the direction of \vec{F} and

$$\text{so } \vec{F}(t) = |\vec{F}(t)| \cdot \hat{G}(t)$$

$$\Rightarrow \vec{F}(t) = f(t) \hat{G}(t)$$

whence, let $|\vec{F}(t)| = f(t)$

$$\therefore \frac{d}{dt} \vec{F}(t) = \frac{d}{dt} [f(t) \cdot \hat{G}(t)]$$

$$= f(t) \frac{d}{dt} \hat{G}(t) + \frac{d}{dt} f(t) \cdot \hat{G}(t)$$

$$\Rightarrow \frac{d}{dt} \vec{F}(t) = \frac{d}{dt} f(t) \cdot \hat{G}(t) \quad \left[\because \frac{d}{dt} \hat{G}(t) = 0 \right]$$

$$\Rightarrow \vec{F} \times \frac{d}{dt} \vec{F}(t) = \vec{F} \times \frac{d}{dt} f(t) \cdot \hat{G}(t)$$

$$= f(t) \cdot \hat{G} \times \left(\frac{d}{dt} f(t) \cdot \hat{G}(t) \right)$$

$$= f(t) \cdot \frac{d f(t)}{dt} \cdot \cancel{\hat{G} \times \hat{G}}^0$$

$$\therefore \vec{F} \times \frac{d}{dt} \vec{F}(t) = 0$$

Eg - If $\vec{r} = \vec{a} \sin \omega t + \vec{b} \cos \omega t$, where \vec{a} & \vec{b} are constant vector and ω is a constant, then prove that

$$\frac{d^2 \vec{r}}{dt^2} = -\omega^2 \vec{r} \quad \text{and} \quad \vec{r} \times \frac{d \vec{r}}{dt} = -\omega \vec{a} \times \vec{b}$$

Soln Given $\vec{r} = \vec{a} \sin \omega t + \vec{b} \cos \omega t$

$$\frac{d \vec{r}}{dt} = \vec{a} \cos \omega t \cdot \omega + \vec{b} (-\sin \omega t) \cdot \omega$$

$$\begin{aligned} \frac{d^2 \vec{r}}{dt^2} &= -\vec{a} \omega^2 \sin \omega t - \omega^2 \vec{b} \cos \omega t \\ &= -\omega^2 \vec{r} \end{aligned}$$

$$\text{And, } \vec{r} \times \frac{d \vec{r}}{dt} = (\vec{a} \sin \omega t + \vec{b} \cos \omega t) \times (\vec{a} \omega \cos \omega t - \vec{b} \omega \sin \omega t)$$

$$= \omega [(\vec{a} \sin \omega t + \vec{b} \cos \omega t) \times (\vec{a} \cos \omega t) - (\vec{a} \sin \omega t + \vec{b} \cos \omega t) \times (\vec{b} \sin \omega t)]$$

$$= \omega [(\vec{b} \times \vec{a}) \cos^2 \omega t - (\vec{a} \times \vec{b}) \sin^2 \omega t]$$

$$= \omega [-(\vec{a} \times \vec{b}) \cos^2 \omega t - (\vec{a} \times \vec{b}) \sin^2 \omega t]$$

$$= -\omega (\vec{a} \times \vec{b}) (\cos^2 \omega t - \sin^2 \omega t)$$

$$= -\omega (\vec{a} \times \vec{b})$$

Eg - If $\frac{d \vec{u}}{dt} = \vec{\omega} \times \vec{u}$ and $\frac{d \vec{v}}{dt} = \vec{\omega} \times \vec{v}$, prove that

$$\frac{d}{dt} (\vec{u} \times \vec{v}) = \vec{\omega} \times (\vec{u} \times \vec{v})$$

$$\begin{aligned} \frac{d}{dt} (\vec{u} \times \vec{v}) &= \vec{u} \times \frac{d \vec{v}}{dt} + \frac{d \vec{u}}{dt} \times \vec{v} \\ &= \vec{u} \times [\vec{\omega} \times \vec{v}] + [\vec{\omega} \times \vec{u}] \times \vec{v} \\ &= \vec{u} [\vec{\omega} \times \vec{v}] - \vec{v} [\vec{\omega} \times \vec{u}] \end{aligned}$$

$$\begin{aligned}
 &= (\vec{u} \cdot \vec{v}) \vec{\omega} - (\vec{u} \cdot \vec{\omega}) \cdot \vec{v} - [(\vec{v} \cdot \vec{u}) \vec{\omega} - (\vec{v} \cdot \vec{\omega}) \cdot \vec{u}] \\
 &= (\vec{v} \cdot \vec{\omega}) \vec{u} - (\vec{u} \cdot \vec{\omega}) \vec{v} \\
 &= \vec{\omega} \times (\vec{u} \times \vec{v})
 \end{aligned}$$

gradient of a scalar -

Let $\phi(x, y, z)$ be a scalar function, then the vector $\hat{i} \frac{\partial \phi}{\partial x} + \hat{j} \frac{\partial \phi}{\partial y} + \hat{k} \frac{\partial \phi}{\partial z}$ is called gradient of the scalar ϕ and is denoted as $\text{grad } \phi$ or $\nabla \phi$.

The operator $\nabla \equiv \text{grad} = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z}$

Eg - Evaluate $\text{grad } \phi$ or $\nabla \phi$ where $\phi = \log(x^2 + y^2 + z^2)$

$$= \phi(x, y, z)$$

$$\underline{\text{Soln}} \quad \therefore \text{grad } \phi = \nabla \phi = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot \log(x^2 + y^2 + z^2)$$

$$\Rightarrow \nabla \phi = \hat{i} \frac{\partial}{\partial x} \log(x^2 + y^2 + z^2) + \hat{j} \frac{\partial}{\partial y} \log(x^2 + y^2 + z^2) + \hat{k} \frac{\partial}{\partial z} \log(x^2 + y^2 + z^2)$$

$$\Rightarrow \nabla \phi = \hat{i} \frac{1}{x^2 + y^2 + z^2} \cdot 2x + \hat{j} \frac{1}{x^2 + y^2 + z^2} \cdot 2y + \hat{k} \frac{1}{x^2 + y^2 + z^2} \cdot 2z$$

$\text{grad } \phi$ is normal to the surface $\phi(x, y, z) = c$

Properties of gradient -

1) If ϕ is a constant, then $\nabla \phi = \vec{0}$

2) $\nabla(\phi_1 \pm \phi_2) = \nabla \phi_1 \pm \nabla \phi_2$

3) $\nabla(c_1 \phi_1 \pm c_2 \phi_2) = c_1 \nabla \phi_1 \pm c_2 \nabla \phi_2$ (c_1 & c_2 are constants)

4) $\nabla(\phi_1 \cdot \phi_2) = \phi_1 \cdot \nabla \phi_2 + \phi_2 \cdot \nabla \phi_1$

5) $\nabla\left(\frac{\phi_1}{\phi_2}\right) = \frac{\phi_2 \nabla \phi_1 - \phi_1 \nabla \phi_2}{\phi_2^2}, \phi_2 \neq \phi$

Qn Prove -

$$\text{LHS} = \nabla\left(\frac{\phi_1}{\phi_2}\right)$$

$$= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \left(\frac{\phi_1}{\phi_2} \right)$$

$$\begin{aligned}
&= \hat{i} \frac{\partial}{\partial x} \left(\frac{\phi_1}{\phi_2} \right) + \hat{j} \frac{\partial}{\partial y} \left(\frac{\phi_1}{\phi_2} \right) + \hat{k} \frac{\partial}{\partial z} \left(\frac{\phi_1}{\phi_2} \right) \\
&= \hat{i} \frac{\phi_2 \frac{\partial \phi_1}{\partial x} - \phi_1 \frac{\partial \phi_2}{\partial x}}{\phi_2^2} + \hat{j} \frac{\phi_2 \frac{\partial \phi_1}{\partial y} - \phi_1 \frac{\partial \phi_2}{\partial y}}{\phi_2^2} + \hat{k} \frac{\phi_2 \frac{\partial \phi_1}{\partial z} - \phi_1 \frac{\partial \phi_2}{\partial z}}{\phi_2^2} \\
&= \frac{1}{\phi_2^2} \left[\phi_2 \left(\hat{i} \frac{\partial \phi_1}{\partial x} + \hat{j} \frac{\partial \phi_1}{\partial y} + \hat{k} \frac{\partial \phi_1}{\partial z} \right) - \phi_1 \left(\hat{i} \frac{\partial \phi_2}{\partial x} + \hat{j} \frac{\partial \phi_2}{\partial y} + \hat{k} \frac{\partial \phi_2}{\partial z} \right) \right] \\
&= \frac{1}{\phi_2^2} \left[\phi_2 \nabla \phi_1 - \phi_1 \nabla \phi_2 \right]
\end{aligned}$$

#Eg - Find grad ϕ at $(1, -2, -1)$ if $\phi = 3x^2y - y^3z^2$

Solⁿ $\nabla \phi = \hat{i} 6xy + \hat{j} (3x^2 - 3y^2z) - \hat{k} 2yz^3$

at $(1, -2, -1)$

$$\nabla \phi = -12\hat{i} + 15\hat{j} - 16\hat{k}$$

Eg - Find a unit normal to the surface $x^3 + y^3 + 3xyz = 3$ at

Point $(1, 2, -1)$

Solⁿ Let $\phi(x, y, z) = x^3 + y^3 + 3xyz - 3 = 0$

$$\therefore \nabla \phi = (3x^2 + 3yz)\hat{i} + (3y^2 + 3xz)\hat{j} + 3xy\hat{k}$$

at $(1, 2, -1)$

$$\nabla \phi = \{3 + (-6)\}\hat{i} + (12 - 3)\hat{j} + 6\hat{k}$$

$$= -3\hat{i} + 9\hat{j} + 6\hat{k}$$

which is ~~the~~ normal to the given surface

\therefore The unit normal to the given surface is

$$\text{magnitude} = -\frac{3}{3\sqrt{14}}\hat{i} + \frac{9}{3\sqrt{14}}\hat{j} + \frac{6}{3\sqrt{14}}\hat{k}$$

#Eg - Calculate the angle between the ~~no~~ normals to the surface

$xy = z^2$ at the points $(4, 1, 2)$ and $(3, 3, -3)$

Solⁿ Let $\phi(x, y, z) = xy - z^2 = 0$

$$\nabla \phi = y\hat{i} + x\hat{j} - 2z\hat{k}$$

$$\nabla \phi]_{(4,1,2)} = \hat{i} + 4\hat{j} - 4\hat{k}$$

$$\nabla \phi]_{(3,3,-3)} = 3\hat{i} + 3\hat{j} + 6\hat{k}$$

Now, angle between $\nabla \phi]_{(4,1,2)}$ and $\nabla \phi]_{(3,3,-3)}$ is gradient

$$\cos \theta = \left| \frac{(\hat{i} + 4\hat{j} - 4\hat{k}) \cdot (3\hat{i} + 3\hat{j} + 6\hat{k})}{\sqrt{33} \cdot 3\sqrt{6}} \right|$$

$$= \left| \frac{3 + 12 - 24}{3\sqrt{11} \times 3\sqrt{2}} \right|$$

$$= \frac{9}{9\sqrt{22}}$$

$$\cos \theta = \frac{1}{\sqrt{22}}$$

$$\Rightarrow \theta = \cos^{-1} \frac{1}{\sqrt{22}}$$

$$= 77.69^\circ$$

Eg - If $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$ then prove that

$$i) \text{ grad } r = \frac{\vec{r}}{r}$$

Proof - Given, $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

$$\therefore r = |\vec{r}| = \sqrt{x^2 + y^2 + z^2}$$

$$\Rightarrow r^2 = x^2 + y^2 + z^2 \quad \text{--- (1)}$$

Differentiating (1) partially, wrt x . we get

$$2r \frac{\partial r}{\partial x} = 2x$$

$$\Rightarrow \frac{\partial r}{\partial x} = \frac{x}{r}$$

$$\text{Parallelly, } \frac{\partial r}{\partial y} = \frac{y}{r} \quad \text{and} \quad \frac{\partial r}{\partial z} = \frac{z}{r} \quad \left. \right\} \text{ --- (1)}$$

$$\text{grad } r = \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) r$$

$$= \hat{i} \frac{\partial r}{\partial x} + \hat{j} \frac{\partial r}{\partial y} + \hat{k} \frac{\partial r}{\partial z}$$

$$= \hat{i} \frac{x}{r} + \hat{j} \frac{y}{r} + \hat{k} \frac{z}{r} \quad [\text{From (1)}]$$

$$= \frac{1}{\kappa} (\hat{x}\hat{i} + \hat{y}\hat{j} + \hat{z}\hat{k})$$

$$= \frac{\vec{\kappa}}{\kappa}$$

$$\begin{aligned} \text{ii)} \quad \nabla \kappa^n &= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \kappa^n \\ &= \hat{i} \frac{\partial \kappa^n}{\partial x} + \hat{j} \frac{\partial \kappa^n}{\partial y} + \hat{k} \frac{\partial \kappa^n}{\partial z} \\ &= \hat{i} \left(n \kappa^{n-1} \frac{\partial \kappa}{\partial x} \right) + \hat{j} \left(n \kappa^{n-1} \frac{\partial \kappa}{\partial y} \right) + \hat{k} \left(n \kappa^{n-1} \frac{\partial \kappa}{\partial z} \right) \\ &= \hat{i} \left(n \kappa^{n-1} \frac{x}{\kappa} \right) + \hat{j} \left(n \kappa^{n-1} \frac{y}{\kappa} \right) + \hat{k} \left(n \kappa^{n-1} \frac{z}{\kappa} \right) \\ &= n \kappa^{n-2} (\hat{x}\hat{i} + \hat{y}\hat{j} + \hat{z}\hat{k}) \\ &= n \kappa^{n-2} \frac{\vec{\kappa}}{\kappa} \end{aligned}$$

$$\begin{aligned} \text{iii)} \quad \nabla (e^{\kappa^2}) &= \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) e^{\kappa^2} \\ &= \hat{i} \frac{\partial}{\partial x} e^{\kappa^2} + \hat{j} \frac{\partial}{\partial y} e^{\kappa^2} + \hat{k} \frac{\partial}{\partial z} e^{\kappa^2} \\ &= \hat{i} e^{\kappa^2} \cdot 2\kappa \frac{\partial \kappa}{\partial x} + \hat{j} e^{\kappa^2} \cdot 2\kappa \frac{\partial \kappa}{\partial y} + \hat{k} e^{\kappa^2} \cdot 2\kappa \frac{\partial \kappa}{\partial z} \\ &= \hat{i} e^{\kappa^2} \cdot 2\kappa \cdot \frac{x}{\kappa} + \hat{j} e^{\kappa^2} \cdot 2\kappa \cdot \frac{y}{\kappa} + \hat{k} e^{\kappa^2} \cdot 2\kappa \cdot \frac{z}{\kappa} \\ &= 2e^{\kappa^2} (\hat{x}\hat{i} + \hat{y}\hat{j} + \hat{z}\hat{k}) \\ &= 2e^{\kappa^2} \frac{\vec{\kappa}}{\kappa} \end{aligned}$$

$$\text{iv)} \quad \nabla \left(\frac{1}{\kappa} \right) = - \frac{\vec{\kappa}}{\kappa^3}$$

$$\begin{aligned} \text{LHS} &= \nabla \left(\frac{1}{\kappa} \right) \\ &= \hat{i} \frac{\partial}{\partial x} \left(\frac{1}{\kappa} \right) + \hat{j} \frac{\partial}{\partial y} \left(\frac{1}{\kappa} \right) + \hat{k} \frac{\partial}{\partial z} \left(\frac{1}{\kappa} \right) \\ &= -\frac{1}{\kappa^2} \left(\frac{\partial \kappa}{\partial x} \hat{i} + \frac{\partial \kappa}{\partial y} \hat{j} + \frac{\partial \kappa}{\partial z} \hat{k} \right) \\ &= -\frac{1}{\kappa^2} \left(\frac{x}{\kappa} \hat{i} + \frac{y}{\kappa} \hat{j} + \frac{z}{\kappa} \hat{k} \right) \\ &= -\frac{1}{\kappa^3} (\hat{x}\hat{i} + \hat{y}\hat{j} + \hat{z}\hat{k}) \\ &= - \frac{\vec{\kappa}}{\kappa^3} \\ &= RHS \end{aligned}$$

v) $\nabla(\vec{a} \cdot \vec{r}) \vec{a}$, where a is a const. vector

Let $\vec{a} = a_1 \hat{i} + a_2 \hat{j} + a_3 \hat{k}$ (a_1, a_2, a_3 are constants)

$$\text{Now, } \vec{a} \cdot \vec{r} = a_1 x + a_2 y + a_3 z$$

$$\nabla(\vec{a} \cdot \vec{r}) = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) (a_1 x + a_2 y + a_3 z)$$

$$= a_1 \hat{i} + a_2 \hat{j} + a_3 \hat{k}$$

$$= \vec{a}$$

vi) $\nabla \log r = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \log \sqrt{x^2 + y^2 + z^2}$

$$= \frac{1}{\sqrt{x^2 + y^2 + z^2}} \frac{\partial}{\partial x} (\sqrt{x^2 + y^2 + z^2}) \hat{i} + \frac{1}{\sqrt{x^2 + y^2 + z^2}} \frac{\partial}{\partial y} (\sqrt{x^2 + y^2 + z^2}) \hat{j} +$$

$$\frac{1}{\sqrt{x^2 + y^2 + z^2}} \frac{\partial}{\partial z} (\sqrt{x^2 + y^2 + z^2}) \hat{k}.$$

$$= \frac{2x}{2(\sqrt{x^2 + y^2 + z^2})^2} \hat{i} + \frac{2y}{2(\sqrt{x^2 + y^2 + z^2})^2} \hat{j} + \frac{2z}{2(\sqrt{x^2 + y^2 + z^2})^2} \hat{k}$$

$$= \frac{1}{(\sqrt{x^2 + y^2 + z^2})} (x \hat{i} + y \hat{j} + z \hat{k})$$

$$= \frac{\vec{r}}{r^2} \quad \text{RHS}$$

vii) $\nabla |\vec{r}|^2 = 2\vec{r}$

$$\text{LHS} = \nabla |\vec{r}|^2$$

$$= \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) (x^2 + y^2 + z^2)$$

$$= 2x \hat{i} + 2y \hat{j} + 2z \hat{k}$$

$$= 2(\vec{x} \hat{i} + \vec{y} \hat{j} + \vec{z} \hat{k})$$

$$= 2\vec{r} = \text{RHS}$$

viii) $\nabla f(r) = f'(r) \nabla r$

Divergence of a vector function -

The divergence of a vector function \vec{v} is denoted by $\operatorname{div} \vec{v}$

and is defined as,

$$\operatorname{div} \vec{v} = \nabla \cdot \vec{v} \quad (\text{vector } \vec{v}, \nabla \phi \rightarrow \text{scalar})$$

$$\text{If } \vec{v} = v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k}$$

$$\text{then divergence of } \vec{v} = \nabla \cdot \vec{v}$$

$$\Rightarrow \operatorname{div} \vec{v} = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) (v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k})$$

$$\Rightarrow \operatorname{div} \vec{v} = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z}$$

Curl of a vector function -

The curl of a vector function \vec{v} is denoted by $\operatorname{curl} \vec{v}$

and defined as $\operatorname{curl} \vec{v} = \nabla \times \vec{v}$

$$\text{If } \vec{v} = v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k}$$

$$\nabla \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_1 & v_2 & v_3 \end{vmatrix}$$

* If $\operatorname{div} \vec{v} = 0$, then \vec{v} is called solenoidal vector.

* If $\operatorname{curl} \vec{v} = \vec{0}$, then \vec{v} is said to be irrotational vector otherwise it is said to be rotational.

Eg - If $\vec{v} = x \hat{i} + y \hat{j} + z \hat{k}$ show that

$$\text{i)} \operatorname{div} \vec{v} = 3 \qquad \text{ii)} \operatorname{curl} \vec{v} = \vec{0}.$$

$$\text{Soln i)} \operatorname{div} \vec{v} = \nabla \cdot \vec{v}$$

$$= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot (x \hat{i} + y \hat{j} + z \hat{k})$$

$$= 1 + 1 + 1$$

$$= 3$$

$$\text{ii)} \operatorname{curl} \vec{v} = \nabla \times \vec{v}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix}$$

$$= \hat{i} \left(\frac{\partial z}{\partial y} - \frac{\partial e}{\partial z} \right) + \hat{j} \left(\frac{\partial e}{\partial z} - \frac{\partial z}{\partial x} \right) + \hat{k} \left(\frac{\partial e}{\partial x} - \frac{\partial e}{\partial x} \right)$$

$$= 0\hat{i} + 0\hat{j} + 0\hat{k}$$

$$= \vec{0}$$

Eg-i) If $\vec{v} = \frac{x\hat{i} + y\hat{j} + z\hat{k}}{\sqrt{x^2 + y^2 + z^2}}$, show that $\nabla \cdot \vec{v} = \frac{2}{\sqrt{x^2 + y^2 + z^2}}$ and $\nabla \times \vec{v} = \vec{0}$

Proof - Given $\vec{v} = \frac{x\hat{i} + y\hat{j} + z\hat{k}}{\sqrt{x^2 + y^2 + z^2}}$

$$\begin{aligned}\nabla \cdot \vec{v} &= \frac{\partial}{\partial x} \left(\frac{x}{\sqrt{x^2 + y^2 + z^2}} \right) + \frac{\partial}{\partial y} \left(\frac{y}{\sqrt{x^2 + y^2 + z^2}} \right) + \frac{\partial}{\partial z} \left(\frac{z}{\sqrt{x^2 + y^2 + z^2}} \right) \\ &= \frac{3(x^2 + y^2 + z^2) - (x^2 + y^2 + z^2)}{(x^2 + y^2 + z^2)\sqrt{x^2 + y^2 + z^2}} \\ &= \frac{2}{\sqrt{x^2 + y^2 + z^2}}\end{aligned}$$

Eg-ii) If $\vec{A} = (3xz^2)\hat{i} - (yz)\hat{j} + (x+2z)\hat{k}$ find $\text{curl } \vec{A}$

Soln $\nabla \times \vec{A} =$

$$\begin{aligned}\text{2nd part} - \nabla \times \vec{v} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{x}{\sqrt{x^2 + y^2 + z^2}} & \frac{y}{\sqrt{x^2 + y^2 + z^2}} & \frac{z}{\sqrt{x^2 + y^2 + z^2}} \end{vmatrix} \\ &= \hat{i} \left[\frac{\partial}{\partial y} \left(\frac{z}{\sqrt{x^2 + y^2 + z^2}} \right) - \frac{\partial}{\partial z} \left(\frac{y}{\sqrt{x^2 + y^2 + z^2}} \right) \right] \dots \dots \\ &= \hat{i} \left(\frac{-yz}{(x^2 + y^2 + z^2)^{3/2}} + \frac{yz}{(x^2 + y^2 + z^2)^{3/2}} \right) \dots \dots \\ &= 0\hat{i} + 0\hat{j} + 0\hat{k}\end{aligned}$$

$$= \vec{0}$$

Eg-iii) If $\vec{A} = (3xz^2)\hat{i} - (yz)\hat{j} + (x+2z)\hat{k}$ find $\text{curl}(\text{curl } \vec{A})$

Soln $\text{curl } \vec{A} = \nabla \times \vec{A}$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3xz^2 & yz & x+2z \end{vmatrix}$$

$$= y\hat{i} + (6zx - 1)\hat{j}$$

$$\therefore \text{curl}(\text{curl } \vec{A}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & 6xz-1 & 0 \end{vmatrix}$$

$$= -6x \hat{i} + (6z-1) \hat{k}$$

Eg-iii If $u = x^2 + y^2 + z^2$, $\vec{v} = x \hat{i} + y \hat{j} + z \hat{k}$, show that $\text{div}(u \cdot \vec{v}) = 5u$

$$\text{soln} \quad \text{div}(u \cdot \vec{v}) = \text{div}[(x^3 + y^3 + z^3) \hat{i} + (x^2 + y^3 + z^2) \hat{j} + (x^2 + y^2 + z^3) \hat{k}]$$

$$= 3x^2 + 3y^2 + 3z^2$$

$$\text{div}(u \cdot \vec{v}) = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \left\{ (x^3 + xy + xz^2) \hat{i} + (xy^2 + y^3 + yz^2) \hat{j} + (x^2z + y^2z + z^3) \hat{k} \right\}$$

$$= 3x^2 + y^2 + z^2 + x^2 + 3y^2 + z^2 + x^2 + y^2 + 3z^2$$

$$= 5(x^2 + y^2 + z^2)$$

$$= 5u$$

Properties of divergence and curl -

i) For a constant vector \vec{a} , $\text{div } \vec{a} = 0$, $\text{curl } \vec{a} = \vec{0}$

ii) If \vec{A} is a vector function and ϕ is a scalar function, then,

$$\begin{aligned} \text{div}(\phi \vec{A}) &= \phi (\nabla \vec{A}) + (\nabla \phi) \vec{A} \\ &= \phi (\text{div } \vec{A}) + (\text{grad } \phi) \vec{A} \end{aligned}$$

Proof - $\text{div}(\phi \vec{A}) = \nabla(\phi \vec{A})$

$$= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) (\phi \vec{A})$$

$$= \hat{i} \frac{\partial}{\partial x} (\phi \vec{A}) + \hat{j} \frac{\partial}{\partial y} (\phi \vec{A}) + \hat{k} \frac{\partial}{\partial z} (\phi \vec{A})$$

$$= \hat{i} \left(\phi \frac{\partial \vec{A}}{\partial x} + \frac{\partial \phi}{\partial x} \vec{A} \right) + \hat{j} \left(\phi \frac{\partial \vec{A}}{\partial y} + \frac{\partial \phi}{\partial y} \vec{A} \right) + \hat{k} \left(\phi \frac{\partial \vec{A}}{\partial z} + \frac{\partial \phi}{\partial z} \vec{A} \right)$$

$$= \phi \left(\frac{\partial \vec{A}}{\partial x} \hat{i} + \frac{\partial \vec{A}}{\partial y} \hat{j} + \frac{\partial \vec{A}}{\partial z} \hat{k} \right) + \vec{A} \left(\frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k} \right)$$

$$= \phi (\nabla \vec{A}) + (\text{grad } \phi) \vec{A}$$

$$3) \operatorname{curl}(\phi \vec{A}) = (\operatorname{grad} \phi) \times \vec{A} + \phi (\operatorname{curl} \vec{A})$$

$$4) \nabla(\vec{A} \cdot \vec{B}) = (\vec{A} \cdot \nabla) \cdot \vec{B} + (\vec{B} \cdot \nabla) \cdot \vec{A} + \vec{A} \times (\nabla \times \vec{B}) + \vec{B} \times (\nabla \times \vec{A})$$

Proof $\nabla(\vec{A} \cdot \vec{B}) = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) (\vec{A} \cdot \vec{B})$

$$= \sum \hat{i} \frac{\partial}{\partial x} (\vec{A} \cdot \vec{B}) \quad \left[\text{This means } \hat{i} \frac{\partial}{\partial x} (\vec{A} \cdot \vec{B}) + \hat{j} \frac{\partial}{\partial y} (\vec{A} \cdot \vec{B}) + \hat{k} \frac{\partial}{\partial z} (\vec{A} \cdot \vec{B}) \right]$$

$$= \sum \hat{i} \left(\vec{A} \cdot \frac{\partial \vec{B}}{\partial x} + \frac{\partial \vec{A}}{\partial x} \cdot \vec{B} \right)$$

$$= \sum \left(\vec{A} \cdot \frac{\partial \vec{B}}{\partial x} \right) \hat{i} + \sum \left(\frac{\partial \vec{A}}{\partial x} \cdot \vec{B} \right) \hat{i} \quad \text{--- (I)}$$

$$\left(\vec{A} \cdot \frac{\partial \vec{B}}{\partial x} \right) \hat{i} = \left(\vec{A} \cdot \hat{i} \right) \cdot \frac{\partial \vec{B}}{\partial x} - \vec{A} \times \left(\frac{\partial \vec{B}}{\partial x} \times \hat{i} \right)$$

$$= \left(\vec{A} \cdot \hat{i} \right) \frac{\partial \vec{B}}{\partial x} + \vec{A} \times \left(\hat{i} \times \frac{\partial \vec{B}}{\partial x} \right)$$

$$\sum \left(\vec{A} \cdot \frac{\partial \vec{B}}{\partial x} \right) \hat{i} = \sum \left(\vec{A} \cdot \hat{i} \right) \frac{\partial \vec{B}}{\partial x} + \vec{A} \times \sum \left(\hat{i} \times \frac{\partial \vec{B}}{\partial x} \right) \quad \text{--- (II)}$$

$$\sum \left(\frac{\partial \vec{A}}{\partial x} \cdot \vec{B} \right) \hat{i} = \sum \left(\vec{B} \cdot \frac{\partial \vec{A}}{\partial x} \right) \hat{i}$$

$$= \left(\vec{B} \cdot \sum \hat{i} \frac{\partial \vec{A}}{\partial x} \right) \vec{A} + \vec{B} \times \sum \left(\hat{i} \times \frac{\partial \vec{A}}{\partial x} \right) \quad \text{--- (III)}$$

$$\sum \left(\vec{A} \cdot \frac{\partial \vec{B}}{\partial x} \right) \hat{i} = \left(\vec{A} \cdot \sum \hat{i} \frac{\partial}{\partial x} \right) \vec{B} + \vec{A} \times \sum \left(\hat{i} \times \frac{\partial \vec{B}}{\partial x} \right) \quad \text{--- (II)}$$

$$\sum \left(\frac{\partial \vec{A}}{\partial x} \cdot \vec{B} \right) \hat{i} = \sum \left(\vec{B} \cdot \frac{\partial \vec{A}}{\partial x} \right) \hat{i}$$

$$= \left(\vec{B} \cdot \sum \hat{i} \frac{\partial \vec{A}}{\partial x} \right) \vec{A} + \vec{B} \times \sum \left(\hat{i} \times \frac{\partial \vec{A}}{\partial x} \right) \quad \text{--- (III)}$$

Putting (II) & (III) in (I), we get

$$\nabla(\vec{A} \cdot \vec{B}) = \left(\vec{A} \cdot \sum \hat{i} \frac{\partial}{\partial x} \right) \vec{B} + \vec{A} \times \sum \left(\hat{i} \times \frac{\partial \vec{B}}{\partial x} \right) + \left(\vec{B} \cdot \sum \hat{i} \frac{\partial}{\partial x} \right) \vec{A} + \vec{B} \times \sum \left(\hat{i} \times \frac{\partial \vec{A}}{\partial x} \right)$$

Eg - $\operatorname{curl}(\operatorname{grad} \phi) = \vec{0}$

Proof - $\operatorname{curl}(\operatorname{grad} \phi) = \nabla \times \nabla \phi$

$$= \nabla \times \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \phi$$

$$= \nabla \times \left(\hat{i} \frac{\partial \phi}{\partial x} + \hat{j} \frac{\partial \phi}{\partial y} + \hat{k} \frac{\partial \phi}{\partial z} \right)$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{vmatrix}$$

$$= \hat{i} \left(\frac{\partial^2 \phi}{\partial x^2} - \frac{\partial^2 \phi}{\partial y^2} \right) + \hat{j} \left(\frac{\partial^2 \phi}{\partial x^2} - \frac{\partial^2 \phi}{\partial z^2} \right) + \hat{k} \left(\frac{\partial^2 \phi}{\partial y^2} - \frac{\partial^2 \phi}{\partial z^2} \right)$$

$$= \vec{0}$$

Eg - $\operatorname{div}(\operatorname{curl} \vec{v}) = 0$

Sol $\nabla(\nabla \times \vec{v})$

$$= \nabla \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix}$$

$$= \nabla(0\hat{i} + 0\hat{j} + 0\hat{k})$$

$$= (\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z})(0\hat{i} + 0\hat{j} + 0\hat{k})$$

$$= 0$$

* If $\nabla \times \vec{A} = \vec{0}$, then the vector \vec{A} is irrotational, then there will be a consecutive scalar field ϕ with potential $d\phi$ and $\vec{A} = \operatorname{grad} \phi$

Eg - A vector field given by $\vec{A} = (x^2 + xy^2)\hat{i} + (y^2 + x^2y)\hat{j}$. Show that the field vector is irrotational or field is conservative and find the scalar of potential.

Sol Given, $\vec{A} = (x^2 + xy^2)\hat{i} + (y^2 + x^2y)\hat{j}$

$$\nabla \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 + xy^2 & y^2 + x^2y & 0 \end{vmatrix}$$

$$= \vec{0}$$

\therefore The field is conservative or we can say that vector is irrotational.

Let ϕ be the scalar of potential.

$$\vec{A} = \operatorname{grad} \phi$$

$$\Rightarrow (x^2 + xy^2)\hat{i} + (y^2 + x^2y)\hat{j} = \frac{\partial \phi}{\partial x}\hat{i} + \frac{\partial \phi}{\partial y}\hat{j} + \frac{\partial \phi}{\partial z}\hat{k}$$

Comparing both sides, we get

$$\frac{\partial \phi}{\partial x} = x^2 + xy^2$$

$$\frac{\partial \phi}{\partial y} = y^2 + x^2y$$

$$\frac{\partial \phi}{\partial z} = 0$$

Now,

for scalar of potential,

$$d\phi = \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz$$

$$= (x^2 + xy^2)dx + (y^2 + x^2y)dy + 0$$

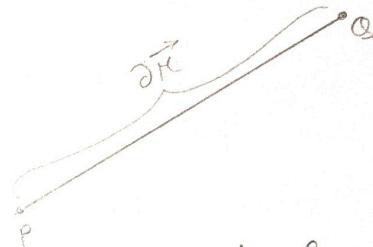
$$d\phi = x^2 dx + \cancel{xy^2 dx} + y^2 dy + xy \left(\underset{d(xy)}{\cancel{y dx + x dy}} \right)$$

Integrating both side, we get

$$\Rightarrow \phi = \frac{x^3}{3} + \frac{y^3}{3} + \frac{x^2 y^2}{2} + C$$

Directional derivative -

If ϕ be a scalar field, then $\frac{d\phi}{dr}$ is called directional derivative of ϕ at point P in the direction PQ.



The directional derivative $\frac{d\phi}{dr}$ is the resolved part of $\nabla \phi$ in the direction of an unit vector along PQ.

$$\begin{aligned}\frac{d\phi}{dr} &= \frac{\partial \phi}{\partial x} \cdot \frac{dx}{dr} + \frac{\partial \phi}{\partial y} \cdot \frac{dy}{dr} + \frac{\partial \phi}{\partial z} \cdot \frac{dz}{dr} \\ \Rightarrow \frac{d\phi}{dr} &= \left(\frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k} \right) \left(\frac{dx}{dr} \hat{i} + \frac{dy}{dr} \hat{j} + \frac{dz}{dr} \hat{k} \right) \\ \Rightarrow \frac{d\phi}{dr} &= \nabla \phi \cdot \vec{b}, \text{ where } \vec{b} = \frac{dx}{dr} \hat{i} + \frac{dy}{dr} \hat{j} + \frac{dz}{dr} \hat{k}\end{aligned}$$

The directional derivative of ϕ in the direction PQ is given by

$$\frac{d\phi}{dr} = \nabla \phi \cdot \frac{\vec{b}}{|\vec{b}|}$$

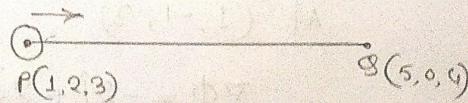
$\nabla \phi$ gives the maximum rate of change of ϕ and maximum magnitude is $|\nabla \phi|$.

Eg - Find directional derivative of the function $\phi = x^2 - y^2 + 2z^2$ at the point P(1, 2, 3) in the direction of PQ, where Q is the point (5, 0, 4)

Sol^m Given,

Scalar field is

$$\phi = x^2 - y^2 + 2z^2$$



$$\text{Now, } \nabla \phi = \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) (x^2 - y^2 + 2z^2)$$

$$= 2x \hat{i} - 2y \hat{j} + 4z \hat{k}$$

\therefore At point $P(1, 2, 3)$

$$\text{grad } \phi = 2\hat{i} - 4\hat{j} + 12\hat{k}$$

Now, \hat{b} is unit vector along \overrightarrow{PQ}

$$\text{Now, } \overrightarrow{PQ} = 4\hat{i} - 2\hat{j} + 1\hat{k}$$

\therefore unit vector along \overrightarrow{PQ} is \hat{b}

$$\hat{b} = \frac{4\hat{i} - 2\hat{j} + \hat{k}}{\sqrt{21}}$$

\therefore The directional derivative of ϕ at $P(1, 2, 3)$ in the direction \overrightarrow{PQ} is

$$\begin{aligned} \frac{d\phi}{dr} &= \nabla \phi \cdot \hat{b} \\ &= (2\hat{i} - 4\hat{j} + 12\hat{k}) \cdot \frac{1}{\sqrt{21}} (4\hat{i} - 2\hat{j} + \hat{k}) \\ &= \frac{1}{\sqrt{21}} (8 + 8 + 12) \\ &= \frac{28}{\sqrt{21}}, \text{ which is scalar.} \end{aligned}$$

And maximum value of directional derivative is

$$\begin{aligned} |\nabla \phi| &= \sqrt{4 + 16 + 144} \\ &= \sqrt{164} \end{aligned}$$

Eg- Find directional derivative for $f(x, y, z) = 2xy + z^2$ at $(1, -1, 3)$ in the direction of the vector $\hat{i} + 2\hat{j} + 2\hat{k}$.

Solⁿ scalar field is

$$\phi = 2xy + z^2$$

$$\begin{aligned} \text{Now, } \nabla \phi &= \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) (2xy + z^2) \\ &= 2y\hat{i} + 2x\hat{j} + 2z\hat{k} \end{aligned}$$

At $(1, -1, 3)$

$$\nabla \phi = -2\hat{i} + 2\hat{j} + 6\hat{k}$$

Now,

unit vector along $\hat{i} + 2\hat{j} + 2\hat{k}$ is

$$\hat{b} = \frac{\hat{i} + 2\hat{j} + 2\hat{k}}{\sqrt{9}} \\ = \frac{\hat{i} + 2\hat{j} + 2\hat{k}}{3}$$

The directional derivative of ϕ at $(1, -1, 3)$ in the direction $(\hat{i} + 2\hat{j} + 2\hat{k})$ is ,

$$\begin{aligned}\frac{d\phi}{dr} &= \nabla\phi \cdot \hat{b} \\ &= \frac{1}{3}(-2\hat{i} + 2\hat{j} + 6\hat{k}) \cdot (\hat{i} + 2\hat{j} + 2\hat{k}) \\ &= \frac{1}{3}(-2 + 4 + 12) \\ &= 14/3\end{aligned}$$

Eq - If $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$, then prove that

i) $\operatorname{div} \left(\frac{\vec{r}}{r^3} \right) = 0$ ~~by~~ ∇

ii) $\nabla^2 r^n = n(n+1)r^{n-2}$

iii) $\nabla^2 \left(\frac{1}{r} \right) = 0$

iv) $\nabla(r^n \cdot \vec{r}) = (n+3)r^n$

i) Proof $\operatorname{div} \left(\frac{\vec{r}}{r^3} \right) = \nabla \left(r^{-3} \vec{r} \right)$

$$= r^{-3} \nabla \vec{r} + \nabla r^{-3} \cdot \vec{r}$$

$$= \vec{r}^{-3} \cdot \nabla \vec{r} + (-3)r^{-5} \vec{r} \cdot \vec{r} \quad [\because \nabla r^n = n r^{n-2} \vec{r}]$$

$$= r^{-3} \cdot 3 - 3 \cdot r^{-5} \cdot r^2$$

$$= 3r^{-3} - 3r^{-3}$$

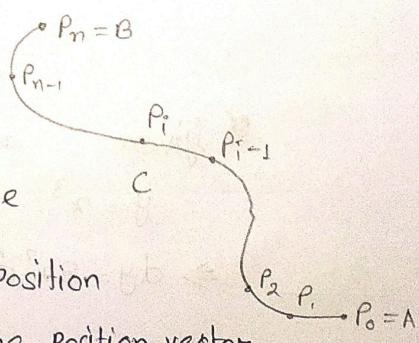
$$= 0$$

Line Integral -

Consider a continuous vector function

$\vec{F}(r)$ which is defined at each point of the curve in space. Divide C into n parts at the

points $P_0 = A, P_1, P_2, \dots, P_{n-1}, P_n = B$. Let their position vectors be $\vec{r}_0, \vec{r}_1, \vec{r}_2, \dots, \vec{r}_n$. Let \vec{r}_i be the position vector



of any point on the arc P_{i-1}, P_i . Now consider the sum.

$$S = \sum_{i=0}^n \vec{F}(r_i) \delta \vec{r}_i, \text{ whence } \delta \vec{r}_i = \vec{r}_i - \vec{r}_{i-1}$$

The limit of the sum at $n \rightarrow \infty$ in such a way that $|\delta \vec{r}_i| \rightarrow 0$
is called the tangential line integral of $\vec{F}(r)$ along c is symbolically

written as $\int_c \vec{F}(r) d\vec{r}$ or $\int_c \vec{F} \frac{d\vec{r}}{dt} dt$

when the path of integration is a closed curve, this fact is denoted by using \oint in place of \int

If $\vec{F}(r) = F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}$ is a vector function and

$$\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}, \text{ then}$$

$$\int_c \vec{F}(r) \cdot d\vec{r} = \int_c (F_1 dx + F_2 dy + F_3 dz), \text{ whence } d\vec{r} = dx \hat{i} + dy \hat{j} + dz \hat{k}$$

The other two types of line integrals are $\int_c \vec{F} \times d\vec{r}$ and $\int_c \phi d\vec{r}$,
if \vec{F} is replaced by a scalar function ϕ . Both are vectors.

Work → If \vec{F} represents the forces acting on a particle moving along an arc AB, then the work done during small displacement $\delta \vec{r}$ is

$$\vec{F} \cdot \delta \vec{r}$$

The total work done by \vec{F} during the displacement from A to B is given by line integral $\int_A^B \vec{F} \cdot d\vec{r}$

Eg- i) If $\vec{F} = (5xy - 6x^2) \hat{i} + (2y - 4x) \hat{j}$ evaluate $\int_c \vec{F} \cdot d\vec{r}$ along the curve c in the xy plane $y = x^3$ from the point $(1,1)$ to $(2,8)$

Solⁿ In the xy-plane let $\vec{r} = x \hat{i} + y \hat{j}$

$$\begin{aligned} \text{Then } \vec{F} \cdot d\vec{r} &= [(5xy - 6x^2) \hat{i} + (2y - 4x) \hat{j}] \cdot (dx \hat{i} + dy \hat{j}) \\ &= (5xy - 6x^2) dx + (2y - 4x) dy \quad \text{--- ①} \end{aligned}$$

Given $y = x^3$ $\Rightarrow \vec{F} \cdot d\vec{r} = (5x^4 - 6x^2) dx + (2x^3 - 4x) dy$ ~~$3x^2 dx$~~

$$\Rightarrow dy = 3x^2 dx \quad \therefore \int_c \vec{F} \cdot d\vec{r} = \int_1^2 [5x^4 - 6x^2 + 6x^5 - 12x^3] dx$$

Eg:2 - A vector field is given by $\vec{F} = \sin y \hat{i} + x(1+\cos y) \hat{j}$. Evaluate

the line integral over a circular path $x^2 + y^2 = a^2, z=0$

Solⁿ We take, $\vec{r} = x\hat{i} + y\hat{j}$

$$\text{So, } \vec{F} \cdot d\vec{r} = \sin y dx + x(1+\cos y) dy$$

$$\begin{aligned}\int_C \vec{F} \cdot d\vec{r} &= \int_C (\sin y dx + x \cos y dy) + \int_C x dy \\ &= \int_C x \sin y dx + \int_C x dy\end{aligned}$$

For circular path

$$\text{let, } x = a \cos t, y = a \sin t, z=0$$

where t varies from 0 to 2π

$$\text{Then, } dx = -a \sin t dt, dy = a \cos t dt$$

$$\text{So, } dx = -a \sin t dt, dy$$

$$\begin{aligned}\text{So, } \int_C \vec{F} \cdot d\vec{r} &= \int_0^{2\pi} d\{a \cos t \sin(a \sin t)\} + \int_0^{2\pi} a \cos t (a \cos t) dt \\ &= [a \cos t \sin(a \sin t)]_0^{2\pi} + a^2 \int_0^{2\pi} \cos^2 t dt \\ &= [a \cos 2\pi \sin(a \sin 2\pi) - 0] + \frac{a^2}{2} \int_0^{2\pi} (1 + \cos 2t) dt \\ &= 0 + \frac{a^2}{2} \left[t + \frac{\sin t}{2} \right]_0^{2\pi} \\ &= 0 + \frac{a^2}{2} (2\pi + 0) = \pi a^2\end{aligned}$$

Eg 3) If $\vec{F} = 2y\hat{i} - z\hat{j} + x\hat{k}$ evaluate $\int_C \vec{F} \times d\vec{r}$ along the curve $x = \text{const.}$

$$y = \sin t, z = 2 \cos t \text{ from } t=0 \text{ to } t=\pi/2$$

$$\text{Sol}^n \quad \vec{F} \times d\vec{r} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2y & -z & x \\ dx & dy & dz \end{vmatrix}$$

$$= \hat{i}(-z dy - x dz) + \hat{j}(x dx - 2y dz) + \hat{k}(2y dy + z dx)$$

Now, replace,

$$x \text{ by const, } dx \text{ by } (-\sin t dt)$$

$$y \text{ by } \sin t, dy \text{ by } (\cos t dt)$$

$$z \text{ by } 2 \cos t, dz \text{ by } (-2 \sin t dt)$$

Then integrate $\int_C \vec{F} \cdot d\vec{r} = \dots$

$$\text{Ans} = (2 - \frac{\pi}{4})\hat{i} + (-\frac{1}{2} + \pi)\hat{j}$$

Eg 4) Find the work done by the force $\vec{F} = x\hat{i} - z\hat{j} + 2y\hat{k}$ in the displacement along the closed path C consisting of the segments C_1, C_2, C_3 , where

$$\text{On } C_1: 0 \leq x \leq 1, y = x, z = 0$$

$$\text{On } C_2: 0 \leq z \leq 1, x = 1, y = 1$$

$$\text{On } C_3: 1 \geq x \geq 0, y = x = z$$

Soln Here $\vec{F} = x\hat{i} - z\hat{j} + 2y\hat{k}$

$$\text{Let } \vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$\text{The work done} = \oint_C \vec{F} \cdot d\vec{r}$$

$$= \oint_C (xdx - zdz + 2ydz)$$

On C_1 : $dy = dx, dz = 0$, and x varies from 0 to 1. (as $z=0$)

On C_2 : $dx = 0, dy = 0$ & z varies from 0 to 1

On C_3 : $dy = dx = dz$ and x varies from 1 to 0

$$\therefore \oint_C \vec{F} \cdot d\vec{r} = \left(\int_{C_1} + \int_{C_2} + \int_{C_3} \right) \vec{F} \cdot d\vec{r}$$

$$= \int_0^1 xdx + \int_0^1 2dz + \int_1^0 (xdx - zdz + 2ydz)$$

$$= \left[\frac{x^2}{2} \right]_0^1 + [2z]_0^1 + \left[\frac{2x^2}{2} \right]_0^1$$

$$= \frac{1}{2} + 2 - 1$$

$$= \frac{3}{2}$$

Eg 5- Find the total work done in moving a particle in a force field given by $\vec{F} = 3xy\hat{i} - 5z\hat{j} + 10x\hat{k}$ along the curve $x = t^2 + 1, y = 2t^2, z = t^3$ from $t = 1$ to 2

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Eg-6 - Find the work done in moving a particle once around a circle in the $x-y$ plane, if the circle has centre at the origin and radius 3 and if the force field is given by $\vec{F} = (2x-y+z)\hat{i} + (x+y-z^2)\hat{j} + (3x-2y+4z)\hat{k}$

Hint - In $x-y$ -plane $\Rightarrow z=0$

For the circle $x = 3\cos\theta$, $y = 3\sin\theta$ where $0 \leq \theta \leq 2\pi$

$$\vec{r} = x\hat{i} + y\hat{j}, \vec{F} = (2x-y)\hat{i} + (x+y)\hat{j} + (3x-2y)\hat{k}$$

Ans is 18π.

Eg-7 - If $\vec{A} = (3x^2+6y)\hat{i} - 14yz\hat{j} + 12xz^2\hat{k}$ evaluate $\int \vec{A} \cdot d\vec{r}$, from $(0,0,0)$ to $(1,1,1)$ along the following path c .

i) $x=t, y=t^2, z=t^3$

ii) The straight line from $(0,0,0)$ to $(1,0,0)$ then to $(1,1,0)$ and then to $(1,1,1)$

iii) The straight line joining $(0,0,0)$ and $(1,1,1)$

Solⁿ Here, $\int_c \vec{A} \cdot d\vec{r} = \int [(3x^2+6y)dx - (14yz)dy + (12xz^2)dz]$

where $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

i) Put $x=t, y=t^2, z=t^3$

$$dx = dt, dy = 2t dt, dz = 3t^2 dt$$

The points $(0,0,0)$ and $(1,1,1)$ corresponds to $t=0$ to $t=1$

$$\therefore \int_c \vec{A} \cdot d\vec{r} = \int_0^1 [(3t^2+6t^2)dt - (-14t^5) \cdot 2t dt + (20t^7) 3t^2 dt]$$

$$= \int_0^1 (3t^2 - 28t^6 + 60t^9) dt$$

$$= 5$$

ii) Along the straight line from $(0,0,0)$ to $(1,0,0)$, $y=0, z=0$, $dy=0, dz=0$ and x varies from 0 to 1.

Then the integral over this part of the path is

$$\int_{x=0}^1 3x^2 dx = 1$$

Along the st line from $(1,0,0)$ to $(1,1,0)$, $x=1$, $z=0$,

$dx=0$, $dz=0$ and y varies from 0 to 1.

Then the integral over this part of the path is 0.

Along the straight line from $(1,1,0)$ to $(1,1,1)$, $x=1$, $y=1$ and $dx=0$, $dy=0$, z varies from 0 to 1. Then the integral over this part of the path is $\int_0^1 20z^2 dz = 20 \left(\frac{z^3}{3}\right)_0^1 = \frac{20}{3}$

\therefore By adding we get

$$\int_C \vec{A} \cdot d\vec{r} = 1 + 0 + \frac{20}{3} = \frac{23}{3}$$

ii) The straight line joining $(0,0,0)$ and $(1,1,1)$ is given in parametric form by $x=t$, $y=t$ and $z=t$, where t varies from 0 to 1

\therefore limits are same, so $x=t$, $y=t$ & $z=t$

$$\begin{aligned} \therefore \int_C \vec{A} \cdot d\vec{r} &= \int_{t=0}^1 \{(3t^2 + 6t) dt - 14t^2 dt + 20t^3 dt\} \\ &= 13/3 \end{aligned}$$

1/2 - 1) If $\vec{F} = xy\hat{i} + (x^2+y^2)\hat{j}$ obtain $\int_C \vec{F} \cdot d\vec{r}$ where c is the arc of the parabola $y=x^2-4$ from $(2,0)$ to $(4,12)$

2) If $\phi = 2xyz^2$, and c is the curve, $x=t^2$, $y=2t$, $z=t^3$

from $t=0$ to $t=1$, evaluate the line integral $\int_C \phi d\vec{r}$ ($\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$)

Scalar fields and vector fields -

If to each point $P(x,y,z)$ of a region R in space, there correspond a unique function $f(P)$, then $f(P)$ is called a scalar point function and we say that a scalar field f has been defined in R .

For eg -