

ELECTROMAGNETIC

WAVES

Date:- 03/02/2023

CLASSMATE

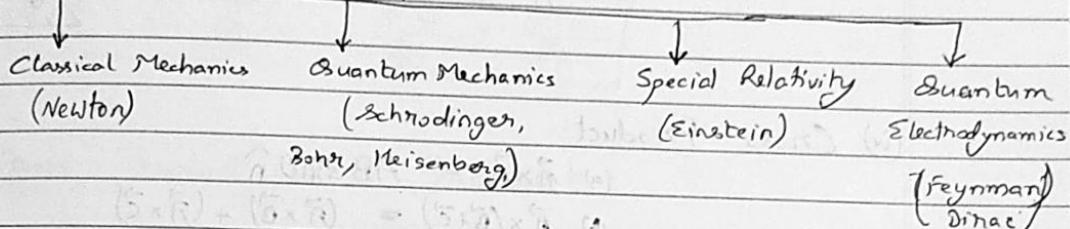
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Books:-

1. John D. Krauss
2. R. K. Shengarankar

Physical World



Mechanics: Study of a system under different forces

Forces

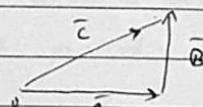
- (1) → Strong force (proton-proton, proton-neutron)
- (2) → Weak force (Radiation)
- (3) → Gravitational force
- (4) → Electromagnetic force

→ EM Waves (Electromagnetic force theory) was mostly developed by Faraday & Maxwell

Date:- 04/02/2023

Vector Analysis/Calculus:

Any quantity which has magnitude & dirn.



Properties of vectors:

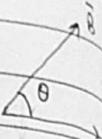
- (i) Addition of two vectors . (a) $\vec{A} + \vec{B} = \vec{B} + \vec{A}$
- (b) $(\vec{A} + \vec{B}) + \vec{C} = \vec{A} + (\vec{B} + \vec{C})$
- (c) $(\vec{A} - \vec{B}) = \vec{A} + (-\vec{B})$

(ii) Multiplication of vectors by scalar.

$$(a) \alpha(\vec{A} + \vec{B}) = \alpha\vec{A} + \alpha\vec{B}$$

(iii) Dot Product.

$$\vec{A} \cdot \vec{B} = AB \cos\theta$$



(iv) Cross Product.

$$(a) \vec{A} \times \vec{B} = AB \sin\theta \hat{n}$$

$$(b) \vec{A} \times (\vec{B} + \vec{C}) = (\vec{A} \times \vec{B}) + (\vec{A} \times \vec{C})$$

Scalar Triple Product:

$$\vec{A} \cdot (\vec{B} \times \vec{C}) = \vec{B} \cdot (\vec{C} \times \vec{A}) = \vec{C} \cdot (\vec{A} \times \vec{B})$$

Vector Triple Product:

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B} \cdot (\vec{C} \times \vec{A}) - \vec{C} \cdot (\vec{B} \times \vec{A})$$

Gradient of a Vector :-

T is a function of (x, y, z) ; $T(x, y, z)$

$$dT = \frac{\partial T}{\partial x} dx + \frac{\partial T}{\partial y} dy + \frac{\partial T}{\partial z} dz$$

$$= \left(\frac{\partial T}{\partial x} \hat{x} + \frac{\partial T}{\partial y} \hat{y} + \frac{\partial T}{\partial z} \hat{z} \right) \cdot (\hat{x} dx + \hat{y} dy + \hat{z} dz)$$

$$= (\vec{V} T \cdot d\vec{I}) \text{, where }$$

$\vec{V} T \rightarrow$ Gradient of T

$$\vec{\nabla} T = \frac{\partial T}{\partial x} \hat{x} + \frac{\partial T}{\partial y} \hat{y} + \frac{\partial T}{\partial z} \hat{z}$$

Dot Product of Gradient:

$$\vec{\nabla} \cdot \vec{T} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot \vec{T}$$

$$\Rightarrow \vec{\nabla} \cdot \vec{T} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (T_x \hat{x} + T_y \hat{y} + T_z \hat{z})$$

$$\Rightarrow \boxed{\vec{\nabla} \cdot \vec{T} = \frac{\partial T_x}{\partial x} + \frac{\partial T_y}{\partial y} + \frac{\partial T_z}{\partial z}}$$

Cross Product of a Gradient:

$$\vec{\nabla} \times \vec{T} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ T_x & T_y & T_z \end{vmatrix}$$

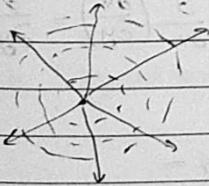
$$= \hat{x} \left(\frac{\partial T_z}{\partial y} - \frac{\partial T_y}{\partial z} \right) - \hat{y} \left(\frac{\partial T_z}{\partial x} - \frac{\partial T_x}{\partial z} \right)$$

$$TV = (T_x) + \hat{z} \left(\frac{\partial T_y}{\partial x} - \frac{\partial T_x}{\partial y} \right)$$

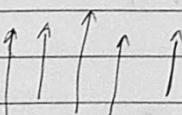
Physical Significance:

Dot Product \rightarrow Dot product signifies divergence
i.e. how much two vectors diverge
from each other.

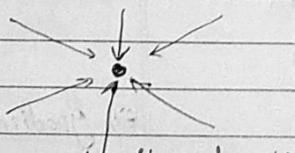
Eg \rightarrow (i) Waves generated are circular and diverge, when a stone is thrown at a pond.



circular waves
Very high value

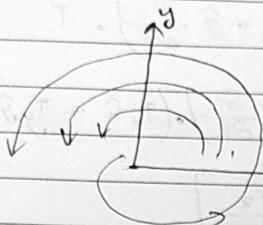


parallel flow
0-magnitude

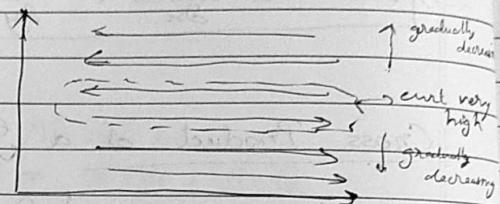


water flowing down sink
→ (high Value)

Cross Product → Cross product of two vectors give curl of a vector



very high



Second Derivative of Gradient

(i) Divergence of a gradient =

$$(I) \quad \nabla \cdot (\nabla T) = \nabla^2 T \quad (\text{divergence of a scalar})$$

$$= \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right), \text{ where}$$

$T \rightarrow$ scalar variable

$\nabla \rightarrow$ vector quantity

$\nabla^2 \rightarrow$ Laplacian Operator

$$(II) \quad (\nabla \cdot \nabla) v = \nabla^2 v \quad (\text{divergence of a vector})$$

(ii) Curl of a Gradient =

$$\nabla \times (\nabla T) = 0$$

$$\left\{ \frac{\partial}{\partial x} \left(\frac{\partial v}{\partial y} \right) = \frac{\partial}{\partial y} \left[\frac{\partial v}{\partial x} \right] \right.$$

(iii) Gradient of a Divergence of a vector =

$$\nabla(\nabla \cdot v) \neq (\nabla \cdot \nabla)v$$

(iv) Divergence of a curl =

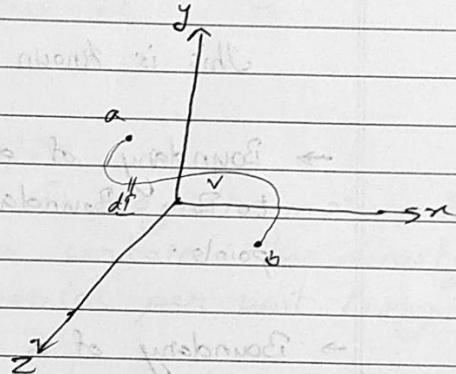
$$\nabla \cdot (\nabla \times \vec{v}) = 0$$

(v) Curl of a curl =

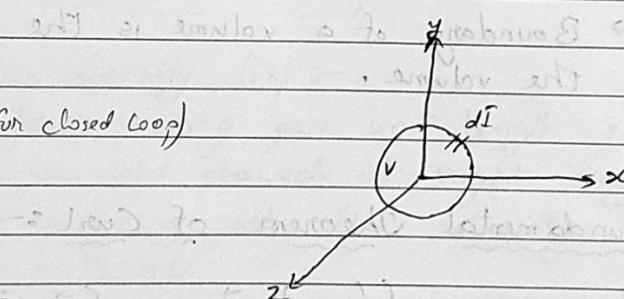
$$\begin{aligned} \nabla \times (\nabla \times \vec{v}) &= \nabla(\nabla \cdot \vec{v}) - \vec{v}(\nabla \cdot \nabla) \\ &= \nabla(\nabla \cdot \vec{v}) - \nabla^2 \vec{v} \end{aligned}$$

Integral Calculus :-

(a) Line Integral :- $\int v dI$

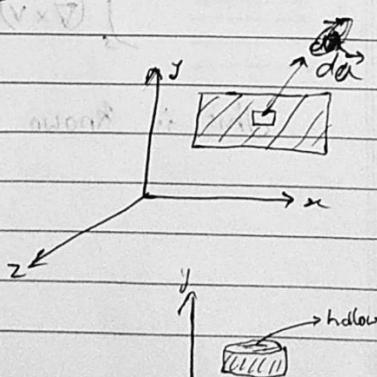


$\oint v \cdot dI$ (for closed loop)



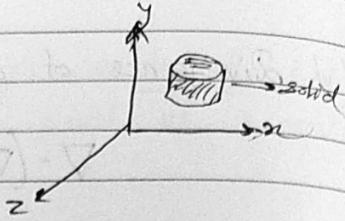
(b) Surface Integral :- $\int v \cdot d\vec{a}$

$\oint v \cdot d\vec{a}$



$$(c) \text{Volume Integral} = \int_V \mathbf{T} \cdot d\mathcal{V}$$

$$d\mathcal{V} = dx dy dz$$



$$\int_V v d\mathcal{V} = \int_V (v_x \hat{i} + v_y \hat{j} + v_z \hat{k}) d\mathcal{V}$$

$$= \int v_x dx + \int v_y dy + \int v_z dz$$

Fundamental Theorem of Divergence :-

$$\int_V (\nabla \cdot \mathbf{v}) d\mathcal{V} = \oint_S \mathbf{v} \cdot d\mathbf{a}$$

This is known as Green's Theorem / Gauss' Theorem

- Boundary of a line of a string starting from A to B. Boundary of a line is just the two end points.
- Boundary of a surface is its perimeter.
- Boundary of a volume is the surface enclosing the volume.

Fundamental Theorem of Curl :-

$$\int_S (\nabla \times \mathbf{v}) \cdot d\mathbf{a} = \oint_C \mathbf{v} \cdot d\mathbf{l} = \oint_C \mathbf{v} \cdot d\vec{l}$$

This is known as Stokes' Theorem

Basic Quantities of Electromagnetic-Waves :-

(1) Electric Field Intensity, (E) :-

It is the force experienced by a unit positive charge placed at that point. i.e.

$$\boxed{E = F/q}$$

(2) Electric Flux Density, (D) :-

It is the electric flux passing through a unit area perpendicular to the direction of the flux. i.e.

$$\boxed{D = \epsilon E}$$



(3) Magnetic Field Intensity, (H) :-

It is the ratio of magnetic motive force (MMF) needed to create a certain flux density within a particular material per unit length. i.e.

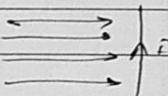
$$\boxed{H = B/\mu - M} \rightarrow \text{Magnetisation (mostly 0).}$$

(4) Magnetic Flux Density, (B) :-

The force acting per unit length per unit current on a wire placed at right angle to the magnetic field is the magnetic flux density. i.e.

$$F = qvB \sin \theta$$

$$\Rightarrow \boxed{B = F/v \sin \theta}$$



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$$\# C = 3 \times 10^8 \text{ m/s}$$

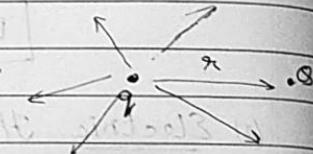
$$\epsilon_0 = 8.854 \times 10^{-12} \text{ F/m}$$

$$\mu_0 = 4\pi \times 10^{-7} \text{ H/m}$$

Basic Laws of Electro Magnetism

Coulomb's law:

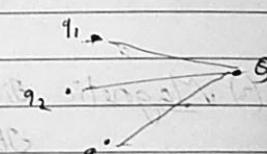
$$F = \frac{q_1 q_2}{4\pi\epsilon_0 r^2} \hat{r}$$



where θ is a test charge in elec. field of q

For n charges in electric field of q ,

$$\text{Force, } F = \frac{q_1 q_2}{4\pi\epsilon_0 r_1^2} + \frac{q_1 q_3}{4\pi\epsilon_0 r_2^2} + \dots$$



Electric Field, $E = F/q$

$$\Rightarrow E = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

→ Electric Flux: For a sphere:

Electric flux through the sphere is given by,



$$\Phi_E = \oint \vec{E} \cdot d\vec{A}$$

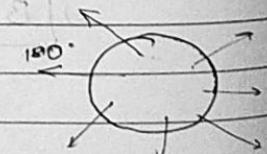
$$\Rightarrow \Phi_E = \oint E da \cos \theta$$

$$= E \oint da$$

$$= E \times 4\pi r^2$$

$$= \frac{4\pi r^2}{4\pi\epsilon_0} \frac{q}{r^2}$$

$$\Rightarrow \Phi_E = \frac{q}{\epsilon_0}, \text{ for } r = r_1 \quad (\text{Gauss's law})$$



For n charges around a sphere,

$$\text{Flux, } \Phi_E = \sum \frac{q_i}{\epsilon_0}$$

$$\Rightarrow \boxed{\Phi_E = \frac{Q_{\text{enclosed}}}{\epsilon_0}}, \text{ where } Q_{\text{enclosed}} = \sum q_i$$

For multiple point sources,

From the principle of superposition,

$$\text{Elc. field, } \vec{E} = \sum_{i=1}^n E_i$$

\therefore Flux through a ^{sphere} $\oint \vec{E} \cdot d\vec{A}/\epsilon_0 = \sum_{i=1}^n \oint \vec{E}_i \cdot d\vec{A}$

Gauss's law in differential form:

We know,

$$\oint \vec{E} \cdot d\vec{A} = \int (\nabla \cdot \vec{E}) dV \quad [\text{From divergence theorem}]$$

Rewriting the charge enclosed (Q_{enc}),

$$Q_{\text{enc}} = \int_V \rho dV, \text{ where}$$

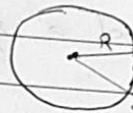
$$\therefore \oint \vec{E} \cdot d\vec{A} = \frac{Q_{\text{enc}}}{\epsilon_0}$$

$$\Rightarrow \int (\nabla \cdot \vec{E}) dV = \frac{1}{\epsilon_0} \int_V \rho dV$$

$$\Rightarrow \nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}, \text{ this is the Gauss's law in differential form}$$

Applications of Gauss's law:

Ex(i) Find the electric field outside a uniformly charged solid sphere of radius R and total charge, Q .



\rightarrow Gaussian machine

From Gauss's law,

$$\oint \vec{E} \cdot d\vec{a} = \frac{Q_{\text{enc}}}{\epsilon_0}$$

$$\Rightarrow \phi_E = \frac{q}{\epsilon_0} \rightarrow (1)$$

Further,

$$\oint \vec{E} \cdot d\vec{a} = \oint E da \cos 90^\circ$$

$$= \oint E da \cos 0^\circ$$

$$= \oint E da$$

$$= E \oint da \quad (\because E \text{ is uniformly distributed})$$

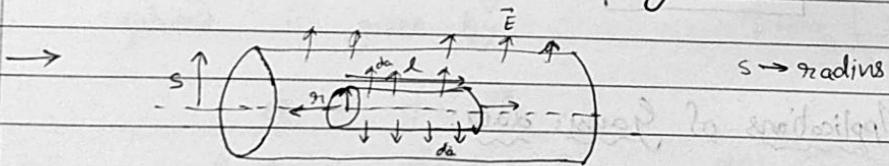
$$= E \cdot 2\pi r l^2$$

Putting this in eqn (1),

$$E \cdot 2\pi r l^2 = \frac{q}{\epsilon_0}$$

$$\Rightarrow E = \frac{q}{2\pi r l^2 \epsilon_0} \rightarrow (2) \{ \text{Coulomb's Law} \}$$

Ex :- (2) A long cylinder carries a charge density that is proportional to the distance from the axis $\rho = ks$, for some constant k. Find the electric field inside the cylinder.



Applying Gauss's Law, $\oint \vec{E} \cdot d\vec{a} = \frac{Q_{\text{enc}}}{\epsilon_0} \rightarrow (1)$

Now,

$$\begin{aligned}\Phi_{\text{enc}} &= \int_V \mathbf{P} \cdot d\mathbf{r} \quad , \text{ where } \mathbf{P} = k\mathbf{s} \\ &= \int_V (ks) (dx dy dz) \quad \left\{ dx dy dz \text{ in cartesian co-ordinate system} \right\} \\ &= \int_V (ks) (s ds d\phi dl) \quad \left\{ s ds d\phi dl \text{ in cylindrical co-ordinate system} \right\}\end{aligned}$$

$$dxdydz = r dr d\phi dl$$

$r \rightarrow \text{radius}$

$$\begin{aligned}\Rightarrow \Phi_{\text{enc}} &= k \int_0^h \int_0^\pi \int_0^{2\pi} s^2 ds d\phi dl \quad h \rightarrow \text{height} \\ &= k \int_0^h s^2 ds \int_0^\pi d\phi \int_0^{2\pi} dl \quad \phi \rightarrow \text{circular angle} \\ &= 2\pi l k \int s^2 ds \\ &= \frac{2\pi l k s^3}{3}\end{aligned}$$

$$(1) \Rightarrow \oint \mathbf{E} \cdot d\mathbf{a} = \oint E da$$

$$\begin{aligned}&= E da \quad (\text{for curved surface}), (1) \\ &= E \times 2\pi s l \quad s \rightarrow \text{radius}\end{aligned}$$

$$\Rightarrow E \times 2\pi s l = \frac{\Phi_{\text{enc}}}{\epsilon_0}$$

$$\Rightarrow E \times 2\pi s l = \frac{2\pi l k s^3}{3}$$

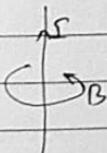
$$\Rightarrow \boxed{E = \frac{ks^2}{3\epsilon_0}} \rightarrow (2) \text{ is the reqd. elec. field inside the cylinder}$$

Ampere's Law

$$\rightarrow \nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t} + \mathbf{J} ; \text{ where } \mathbf{H} \rightarrow \text{Magnetic field intensity}$$

$\mathbf{D} \rightarrow \text{electric flux density}$

$\mathbf{J} \rightarrow \text{Flowing electric current}$



Ampere's law in differential form

Amperes Law in Integral form:

$$\oint \mathbf{H} \cdot d\mathbf{l} = I_{\text{enclosed}}$$

$$\Rightarrow \oint \mu_0 \mathbf{H} \cdot d\mathbf{l} = \mu_0 I_{\text{enclosed}}$$

$$\Rightarrow \oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I_{\text{enc}} ; \quad \mathbf{B} \rightarrow \text{Magnetic field.}$$

Defn: The magnetic field enclosed by an electric current is proportional to the size of that electric current with a constant of proportionality, which is permeability (i.e. μ_0).

Application :-

(1) Given a wire carrying current \vec{I} , the magnetic field around the wire is given by :-

→ By Ampere's law,

$$\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I_{\text{enc}} \rightarrow (1)$$

$$\Rightarrow \oint \mathbf{B} \cdot d\mathbf{l} = \oint B dl \cos \theta$$

$$= \oint B dl \cos 0^\circ \quad [\because \theta = 0^\circ]$$

$$= \oint B dl$$

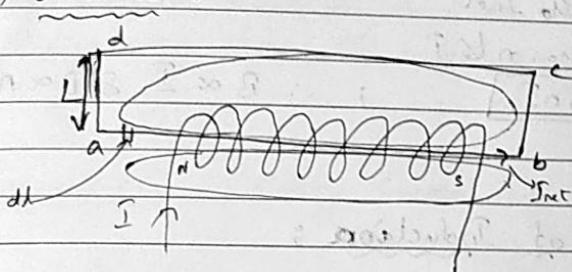
$$= B \oint dl$$

$d\mathbf{l}$ = area

$$\therefore (1) \Rightarrow B \times 2\pi r = \mu_0 I_{\text{enc}}$$

$$\Rightarrow B = \frac{\mu_0 I_{\text{enc}}}{2\pi r} = \frac{\mu_0 \times 2 I_{\text{enc}}}{4\pi r}$$

(ii) Solenoid :-



For ab, when b will start moving upwards.

$$\text{according to } \oint \vec{B} \cdot d\vec{l} = \mu_0 I \text{, we have}$$

$$\Rightarrow \int_{a}^{b} \vec{B} \cdot d\vec{l} \cos \theta = \mu_0 I \quad [\because \text{upward direction}]$$

$$\Rightarrow \int_a^b \vec{B} \cdot d\vec{l} = \mu_0 I \quad [\because \cos \theta = \cos 0^\circ = 1]$$

$$\Rightarrow \vec{B} \int_a^b d\vec{l} = \mu_0 I \Leftrightarrow$$

$$\Rightarrow BL = \mu_0 I \Rightarrow B = \frac{\mu_0 I}{L}$$

$$\oint_{\text{whole area}} \vec{B} \cdot d\vec{l} = \int_a^b \vec{B} \cdot d\vec{l} + \int_b^c \vec{B} \cdot d\vec{l} + \int_c^d \vec{B} \cdot d\vec{l} + \int_d^a \vec{B} \cdot d\vec{l}$$

$$\Rightarrow \oint_{\text{whole area}} \vec{B} \cdot d\vec{l} = \int_a^b \vec{B} \cdot d\vec{l} + \int_d^a \vec{B} \cdot d\vec{l} \quad [\because \text{for cd side, } B \approx 0]$$

$$\Rightarrow \oint_{\text{whole area}} \vec{B} \cdot d\vec{l} = BL$$

∴ from Ampere's Law, $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{net}}$, but \rightarrow induced current

$$\Rightarrow BL = \mu_0 I_{\text{net}} \rightarrow (1)$$

$$\times I_{\text{net}} = nL I, \quad L \rightarrow \text{inductance length}$$

$n \rightarrow$ no. of turns/coils/length

$I \rightarrow$ current

$$\therefore (1) \Rightarrow BL = \mu_0 I_{\text{net}}$$

$$\Rightarrow BK = \mu_0 n K I$$

$$\Rightarrow [B = \mu_0 n I] \quad ; \quad \therefore B \propto I \quad \& \quad B \propto n$$

Faraday's Law of Induction:

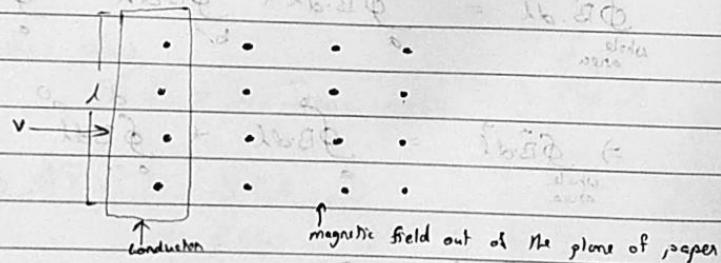
A change in magnetic flux can induce an emf and this theorem is called Faraday's law of induction.

for single loop, $[e = - \frac{\Delta \Phi_B}{\Delta t} = - \frac{\partial \Phi_B}{\partial t}]$; $\Phi_B \rightarrow \text{magnetic flux}$
 $t \rightarrow \text{time}$

For N number of loops, emf, $[e = -N \frac{\Delta \Phi_B}{\Delta t}]$; $\Phi_B = BA \cos \theta$

$$\therefore - \frac{\partial \Phi_B}{\partial t} = - N \frac{\partial (BA \cos \theta)}{\partial t}$$

Example-1



Emf generated due to movement of conductor,

$$e = - \frac{\Delta \Phi_B}{\Delta t}$$

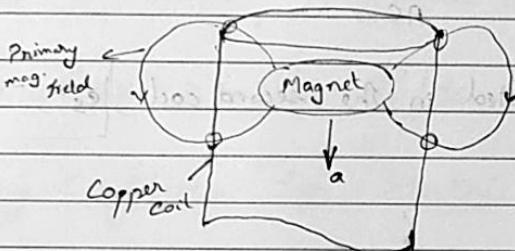
$$\Delta A \rightarrow \text{change in area} \quad e = - \frac{B \Delta A}{\Delta t}$$

$$= L B v \frac{\Delta t}{\Delta t}$$

$$\Rightarrow [e = - B v l]$$

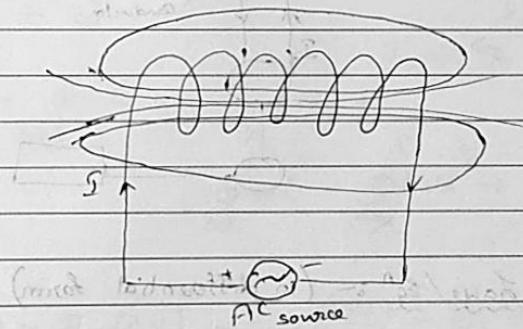
The induced current is in a dir'n that tends to slow the moving bar. It takes an ext. force to keep it moving.

Example :- 2 Eddy Current



The current induced in a bulk piece of conductor as shown in the expt. is the eddy current.

Self Induction :-



The effect of changing current in a circuit induces an emf in the same circuit and this is called self induction.

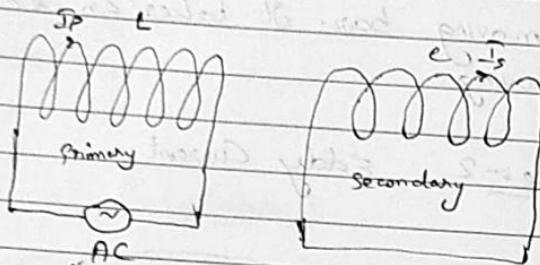
$$e = -L \frac{\Delta I}{\Delta t}$$

$L \rightarrow$ self induction

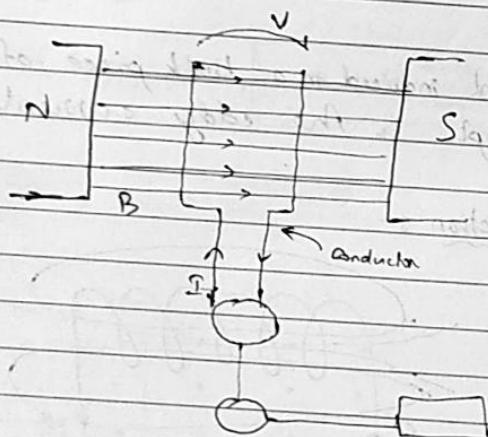
$$(with constant) \quad (B_0 + B) = H \times J \quad (W)$$

Mutual Induction :-

$I_p \rightarrow$ current in primary
 $I_s \rightarrow$ current gen. in secondary



EMF generated in the second coil, $e_s = - \frac{M A \frac{dI_p}{dt}}{dt}$

Generator :-Maxwell's Laws/Eqn :- (in differential form)

$$(i) \nabla \cdot D = \rho \quad \text{(Gauss's Law)}$$

(ii) $\nabla \cdot B = 0$ {Gauss's Law for magnetic field}
 (\rightarrow This implies magnetic field never diverges)
 Hence, there is no magnetic monopole

$$(iii) \nabla \times E = - \frac{\partial B}{\partial t} \quad (\text{Faraday's law})$$

$$(iv) \nabla \times H = \left(J + \frac{\partial D}{\partial t} \right) \quad (\text{Ampere's law})$$

Maxwell's Laws (in Integral form) :-

$$(i) \oint \vec{D} \cdot d\vec{s} = \iiint \rho dv$$

$$(ii) \oint \vec{B} \cdot d\vec{s} = 0$$

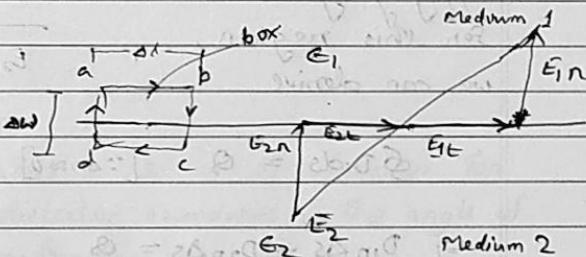
$$(iii) \oint \vec{E} \cdot d\vec{l} = \iint \frac{\partial \vec{B}}{\partial t} \cdot d\vec{s}$$

$$(iv) \oint \vec{H} \cdot d\vec{l} = \iint \left(J + \frac{\partial \vec{D}}{\partial t} \right) ds$$

Boundary Conditions for Electric Field :-

1) Dielectric - dielectric medium —

We have,



$$\oint \vec{E} \cdot d\vec{l} = 0$$

$$\Rightarrow \oint_{abcd} \vec{E} \cdot d\vec{l} = 0$$

$$\Rightarrow \oint_{ab} \vec{E} \cdot d\vec{l} + \oint_{bc} \vec{E} \cdot d\vec{l} + \oint_{cd} \vec{E} \cdot d\vec{l} + \oint_{da} \vec{E} \cdot d\vec{l} = 0$$

$$\oint_{ab} \vec{E} \cdot d\vec{l} + \oint_{bc} \vec{E} \cdot d\vec{l} + \oint_{cd} \vec{E} \cdot d\vec{l} + \oint_{da} \vec{E} \cdot d\vec{l} = 0$$

$$\Rightarrow E_{1t} \Delta l - E_{1n} \left(\frac{\Delta l}{2} \right) - E_{2n} \left(\frac{\Delta l}{2} \right) - E_{2t} \Delta l + E_{2n} \left(\frac{\Delta l}{2} \right) + E_{1n} \left(\frac{\Delta l}{2} \right) = 0$$

$$\Rightarrow E_{1t} \Delta l - E_{2t} \Delta l = 0$$

$E_n \rightarrow$ Normal component of \vec{E}

$$\Rightarrow E_{1t} = E_{2t}$$

$E_t \rightarrow$ Tangential component of \vec{E}

\Rightarrow Tangential Components of \vec{E} are equal at the boundary.
i.e. E_t is continuous and undergoes no change at dielectric boundaries.

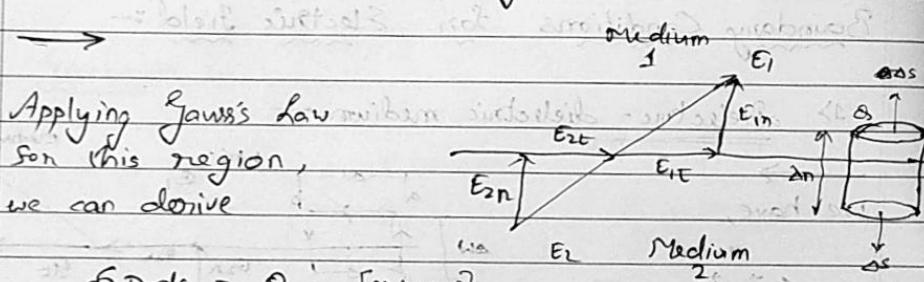
$$\therefore E_{1t} = (E_{2t} \text{ horizontal at } ii) \text{ and, it is zero}$$

$$\Rightarrow \frac{\cancel{E_1}}{E_1} \parallel \frac{D_{1t}}{E_1} \neq \frac{D_{2t}}{E_2} \quad (i)$$

$$\Rightarrow \frac{D_{1t}}{E_1} = \frac{D_{2t}}{E_2} \quad (ii)$$

$$\Rightarrow E_2 D_{1t} = E_1 D_{2t} \quad (iii)$$

Hence, D_t (tangential component of D) is discontinuous across dielectric boundary.



Applying Gauss's Law for this region, we can derive

$$\oint D \cdot dS = Q : [\because dS \approx 0]$$

$$\Rightarrow D_{1n} dS - D_{2n} dS = Q$$

$$\Rightarrow D_{1n} dS - D_{2n} dS = \rho_s dS ; \quad \rho_s \rightarrow \text{Surface Charge Density}$$

$$\Rightarrow D_{1n} - D_{2n} = \rho_s$$

If there are no free charge present in the region, then

$$D_{1n} - D_{2n} = 0$$

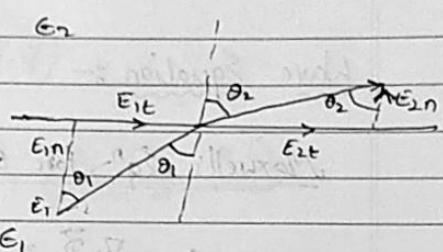
$$\Rightarrow D_{1n} = D_{2n} , \text{ for regions where there are no free charge}$$

$$\Rightarrow E_1 E_{1n} = E_2 E_{2n}$$

Normal component of D are equal at the boundary for no free charge. E is discontinuous for normal component and is given by the above eqn.

→ We have,

$$\Rightarrow E_1 \sin \theta_1 = E_2 \sin \theta_2 \rightarrow (1)$$



$$D_{1n} = D_{2n}$$

$$\Rightarrow \epsilon_1 E_{1n} = \epsilon_2 E_{2n}$$

$$\Rightarrow \epsilon_1 E_1 \cos \theta_1 = \epsilon_2 E_2 \cos \theta_2 \rightarrow (2)$$

$$(1) \div (2) \Rightarrow \frac{E_1 \sin \theta_1}{\epsilon_1 E_1 \cos \theta_1} = \frac{\epsilon_2 \sin \theta_2}{\epsilon_2 E_2 \cos \theta_2}$$

$$\Rightarrow \frac{1}{\epsilon_1} \tan \theta_1 = \frac{1}{\epsilon_2} \tan \theta_2$$

$$\Rightarrow \left[\frac{\tan \theta_1}{\tan \theta_2} = \frac{\epsilon_1}{\epsilon_2} \right]$$

This is the Law of refraction for dielectric boundaries & the angle of refraction can be found.

ASSIGNMENT - I

Date:- 17/02/23

- 1) Find the magnetic field of a toroid & mention the differences between a toroid & a solenoid.
- 2) Evaluate the boundary condition for conductor-dielectric boundary & finally show the special condition of conductor free space boundary.

Due:- 23/02/23

$$(J.A)S - (S.A)F = (3 \times \mu + \mu)$$

Date - 17/02/03

Wave Equation :-Maxwell's Eqn for lossless or non-conducting medium :-

$$\cdot \quad \nabla \cdot \vec{D} = 0 \quad [\because \rho = 0] \rightarrow (b)$$

$$\cdot \quad \nabla \cdot \vec{B} = 0 \rightarrow (d)$$

$$\cdot \quad \nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \rightarrow (c)$$

$$\cdot \quad \nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} \quad [\text{for } \vec{J} = 0] \rightarrow (d)$$

Wave Eqn for lossless or non-conducting medium :-

$$\text{From (d)} \Rightarrow \nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t}$$

$$\Rightarrow \frac{\partial}{\partial t} (\nabla \times \vec{H}) = \frac{\partial}{\partial t} \left(\frac{\partial \vec{D}}{\partial t} \right)$$

$$\Rightarrow \left(\nabla \times \frac{\partial \vec{H}}{\partial t} \right) = \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} \quad [\text{from property}] \rightarrow (1)$$

Now,

$$(c) \Rightarrow \nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$\Rightarrow \nabla \times (\nabla \times \vec{E}) = - \nabla \times \frac{\partial \vec{B}}{\partial t}$$

$$\Rightarrow \nabla \times (\nabla \times \vec{E}) = - \mu \epsilon \left(\nabla \times \frac{\partial \vec{H}}{\partial t} \right) \quad [\because B = \mu H]$$

From (1), we get

$$\nabla \times (\nabla \times \vec{E}) = - \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} \rightarrow (2)$$

We know,

$$(\vec{A} \times \vec{B} \times \vec{C}) = \vec{B} (\vec{A} \cdot \vec{C}) - \vec{C} (\vec{A} \cdot \vec{B})$$

$$\therefore \nabla \times (\nabla \times E) = \nabla(\nabla \cdot \vec{E}) - \vec{E}(\vec{\nabla} \cdot \vec{\nabla})$$

$$\Rightarrow \nabla \times (\nabla \times E) = \nabla(\nabla \cdot \vec{E}) - \vec{\nabla}^2 E \quad \xrightarrow{\text{definition of } E} \quad (3)$$

Again,

$$\nabla \cdot \vec{D} = 0 \quad [D = \epsilon E]$$

$$\text{or, } \nabla \cdot \vec{E} = 0 \quad [\because D = \epsilon E] \quad \leftrightarrow (3)$$

$$\therefore (3) \Rightarrow \nabla \times (\nabla \times E) = -\vec{\nabla}^2 E \quad (4) \quad [\because \nabla \cdot \vec{E} = 0]$$

$$\therefore (2) \Rightarrow -\vec{\nabla}^2 E = -\mu \epsilon \frac{\partial^2 E}{\partial t^2} \quad [\text{from eqn (4)}]$$

$$\Rightarrow \boxed{\nabla^2 E = \mu \epsilon \frac{\partial^2 E}{\partial t^2}}$$

This eqn is called the Wave Eqn in free space & in terms of \vec{E}

We have,

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad [\text{eqn (6)}]$$

$$\nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} \quad [\text{eqn (7)}]$$

$$(6) \Rightarrow \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\Rightarrow \frac{\partial}{\partial t} (\nabla \times \vec{E}) = -\frac{\partial^2 \vec{B}}{\partial t^2}$$

$$\Rightarrow \left(\nabla \times \frac{\partial \vec{E}}{\partial t} \right) = -\mu \epsilon \frac{\partial^2 \vec{B}}{\partial t^2} \quad \xrightarrow{\text{from (4)}} \quad (1)$$

$$(d) \Rightarrow \nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t}$$

$$\Rightarrow \nabla \times \nabla \times \vec{H} = \nabla \times \frac{\partial \vec{D}}{\partial t} = \epsilon \left(\nabla \times \frac{\partial \vec{B}}{\partial t} \right)$$

$$\Rightarrow \nabla \times \nabla \times \vec{H} = -\mu \epsilon \frac{\partial^2 \vec{H}}{\partial t^2} \quad \xrightarrow{\text{from (1)}} \quad (2)$$

$$\Rightarrow \nabla \times \nabla \times H = \nabla (\nabla \cdot H) - H (\nabla \cdot \nabla)$$

$$= \nabla (\nabla \cdot H) - \nabla^2 H$$

Again,

$$\nabla \cdot B = 0 \quad [\text{from Maxwell eqn}]$$

$$\Rightarrow \nabla \cdot H = 0$$

$$\therefore \nabla \times \nabla \times H = -\nabla^2 H \rightarrow (3)$$

$$\therefore (2) \Rightarrow -\nabla^2 H = -\mu e \frac{\partial^2 H}{\partial t^2}$$

$$\Rightarrow \boxed{\nabla^2 H = \mu e \frac{\partial^2 H}{\partial t^2}} \rightarrow \text{This is wave eqn in terms of } H$$

In rectangular co-ordinate system, we can write as follows :-

$$\nabla^2 E_x = \mu e \frac{\partial^2 E_x}{\partial t^2}$$

$$\nabla^2 E_y = \mu e \frac{\partial^2 E_y}{\partial t^2}$$

$$\nabla^2 E_z = \mu e \frac{\partial^2 E_z}{\partial t^2} \quad \text{similarly for } D, M \& B$$

If the electric field intensity is varying harmonically with time, then

$$\vec{E} = E_s e^{j\omega t}$$

$$\Rightarrow \frac{\partial \vec{E}}{\partial t} = E_s \frac{\partial}{\partial t} e^{j\omega t}$$

$$= E_s (j\omega) e^{j\omega t}$$

$$= j\omega E_s e^{j\omega t}$$

$$= j\omega \vec{E} ; \vec{E} = E_s e^{j\omega t}$$

$$\Rightarrow \frac{\partial^2 \vec{E}}{\partial t^2} = j\omega \left(\frac{\partial \vec{E}}{\partial t} \right)$$

$$= (j\omega) \cdot \left(\frac{\partial}{\partial t} E_s e^{j\omega t} \right)$$

$$= j\omega E_s (j\omega e^{j\omega t})$$

$$\Rightarrow \frac{\partial^2 \vec{E}}{\partial t^2} = j^2 \omega^2 \vec{E}$$

$$\Rightarrow \boxed{\frac{\partial^2 \vec{E}}{\partial t^2} = -\omega^2 \vec{E}}$$

We have,

wave eqn for electric field,

$$\nabla^2 \vec{E} = \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\therefore \boxed{\nabla^2 \vec{E} = -\mu \epsilon \omega^2 \vec{E}} \rightarrow \text{This is wave eqn when it is time harmonic}$$

$$\text{Similarly, } \nabla^2 \vec{H} = -\mu \epsilon \omega^2 \vec{H}$$

$$\nabla^2 \vec{B} = -\mu \epsilon \omega^2 \vec{B}$$

$$\nabla^2 \vec{D} = -\mu \epsilon \omega^2 \vec{D}$$

This eqn's are known as Homogeneous Vector Wave eqn in complex time harmonic form for free space.

Date: 24/02

$$\Rightarrow \nabla^2 \vec{E} = \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$$

Also, $v = \frac{1}{\sqrt{\mu \epsilon}}$

$$\Rightarrow v^2 = \frac{1}{\mu \epsilon}$$

$$\therefore \boxed{\nabla^2 \vec{G} = \frac{1}{v^2} \frac{\partial^2 \vec{E}}{\partial t^2}}$$

Wave Eqⁿ in Conducting / lossy medium:

$$\rightarrow \nabla \times H = J + \frac{\partial D}{\partial t}$$

$$= \sigma \vec{E} + \epsilon \frac{\partial \vec{E}}{\partial t} \quad [\because J = \sigma \vec{E},]$$

σ = Conductivity

$$= \sigma \vec{E} + \epsilon \frac{\partial \vec{E}}{\partial t}$$

$$\Rightarrow \frac{\partial}{\partial t} (\nabla \times H) = \sigma \frac{\partial \vec{E}}{\partial t} + \epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\Rightarrow \left(\nabla \times \frac{\partial H}{\partial t} \right) = \sigma \frac{\partial \vec{E}}{\partial t} + \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} \rightarrow (1)$$

From Faraday's law,

$$\nabla \times \vec{E} = - \frac{\partial B}{\partial t}$$

$$\Rightarrow \nabla \times (\nabla \times \vec{E}) = \nabla \times \left(- \frac{\partial B}{\partial t} \right)$$

$$\Rightarrow \nabla \times \nabla \times \vec{E} = - \mu \left(\nabla \times \frac{\partial H}{\partial t} \right) \quad [\because B = \mu H]$$

$$\Rightarrow \nabla \times \nabla \times \vec{E} = - \mu \left(\sigma \frac{\partial \vec{E}}{\partial t} + \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} \right) \rightarrow (2) \quad [\text{From eqn (1)}]$$

Now,

$$\nabla \times \nabla \times \vec{E} = \nabla (\nabla \cdot \vec{E}) - \vec{E} (\nabla \cdot \nabla)$$

$$= \nabla (\nabla \cdot \vec{E}) - \nabla^2 \vec{E} \rightarrow (3) (2)$$

$$\therefore (2) \Rightarrow \nabla (\nabla \cdot \vec{E}) - \nabla^2 \vec{E} = - \mu \sigma \frac{\partial \vec{E}}{\partial t} - \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} \rightarrow (4)$$

For a conductor, there is no charge within it- Hence,
we can write:- $\nabla D = 0 \quad [\because \varphi = 0]$

$$\Rightarrow \nabla E = 0$$

$$\therefore (4) \Rightarrow -\nabla^2 E = -\mu_0 \frac{\partial E}{\partial t} - \mu_0 \epsilon \frac{\partial^2 E}{\partial t^2}$$

$$\Rightarrow \boxed{\nabla^2 E = \mu_0 \frac{\partial E}{\partial t} + \mu_0 \epsilon \frac{\partial^2 E}{\partial t^2}}$$

→ This is the wave eqⁿ for conducting medium in terms of ele. field, E .

Wave Eqⁿ for conducting medium in terms of H :

We have,

$$\nabla \times H = J + \frac{\partial D}{\partial t}$$

$$= \sigma B + \epsilon \frac{\partial E}{\partial t}$$

$$\Rightarrow \nabla \times \nabla \times H = \sigma (\nabla \times E) + \epsilon \left(\nabla \times \frac{\partial E}{\partial t} \right) \rightarrow (1)$$

$$\text{From Maxwell's eqⁿ, } \nabla \times E = - \frac{\partial B}{\partial t}$$

$$\Rightarrow \nabla \times E = -\mu \frac{\partial H}{\partial t}$$

$$\Rightarrow \frac{\partial}{\partial t} (\nabla \times E) = -\mu \frac{\partial^2 H}{\partial t^2}$$

$$\Rightarrow \nabla \times \frac{\partial E}{\partial t} = -\mu \frac{\partial^3 H}{\partial t^2} \rightarrow (2)$$

$$\therefore (1) \Rightarrow \nabla \times \nabla \times H = \sigma (\nabla \times E) + \epsilon (-\mu \frac{\partial^2 H}{\partial t^2})$$

$$= \sigma \left(-\frac{\partial B}{\partial t} \right) + -\mu \epsilon \frac{\partial^2 H}{\partial t^2}$$

$$= -\mu_0 \frac{\partial H}{\partial t} - \mu \epsilon \frac{\partial^2 H}{\partial t^2} \quad [\because B = \mu H] \rightarrow (3)$$

$$\Rightarrow \nabla \times \nabla \times H = \nabla (\nabla \cdot H) - H (\nabla \cdot \nabla)$$

$$= \nabla (\nabla \cdot H) - \nabla^2 H$$

$$\therefore (3) \Rightarrow \nabla(\nabla \cdot \vec{H}) - \nabla^2 \vec{H} = -\mu_0 \frac{\partial \vec{H}}{\partial t} - \mu_0 c \frac{\partial^2 \vec{H}}{\partial t^2}$$

$$\therefore \nabla \times \vec{B} = 0 \text{ by}$$

Maxwell's Eqn

$$\Rightarrow -\nabla^2 \vec{H} = -\mu_0 \frac{\partial \vec{H}}{\partial t} - \mu_0 c \frac{\partial^2 \vec{H}}{\partial t^2}$$

$\Rightarrow \boxed{\nabla^2 \vec{H} = \mu_0 \frac{\partial \vec{H}}{\partial t} + \mu_0 c \frac{\partial^2 \vec{H}}{\partial t^2}}$ → This is the wave eqn for conducting medium in terms of \vec{H} .

$E = E_s e^{(j\omega + jk)t}$
 $H = H_s e^{(j\omega + jk)t}$

Putting this in the wave eqn, we get

$$\nabla^2 \vec{E} = j\omega \mu_0 \vec{E} - \omega^2 \mu_0 \vec{E}$$

$$\text{let } \gamma^2 = j\omega \mu_0 - \omega^2 \mu_0$$

∴ The wave eqn:- $\boxed{\nabla^2 \vec{E} = \gamma^2 \vec{E}}$ → This is the wave eqn for time harmonic signal.

Characteristics of Uniform Plane Wave :-

(i) EM Waves generated from a point source and spreads out uniformly, which is called spherical waveform.

(ii) An observer at a large distance observes the EM Wave as a plane wave.

- (iii) ~~EM~~ E & H are perpendicular to each other & to the direction of propagation. Hence, they are called transverse EM Wave.
- (iv) A uniform plane wave is one in which E & H lie in a plane and ~~the~~ have the same value everywhere in that plane.
- (v) For a uniform plane wave travelling in z -direction, the space variations of E & H are zero over $z = \Theta K$ (constant) plane.