

Design of Digital filters

→ Discrete time system.

→ Z-transform

Q. why digital filters? why not analog filters?

→ Difference eq.

→ frequency related operations (filtering).

→ Design ~~specific~~ flexibility

Disadvantage

→ Speed limit (cause of ADC / DAC)

(conversion time settling time)

→ Finite word length.

In Signal processing

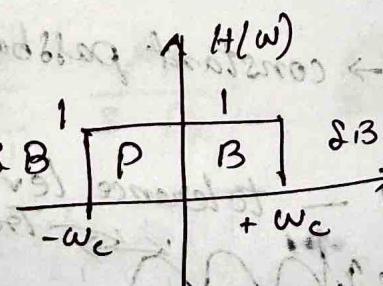
Ideal filter

→ constant gain - passband zero gain - stop band

→ linear phase response.

Magnitude

response.



$$H(\omega) = \begin{cases} 1 & \forall \omega_c < \omega < \omega_c \\ 0, \text{ otherwise} \end{cases}$$

$$h(n) = \text{IFT}(H(\omega))$$

$$h(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H(\omega) e^{j\omega n} d\omega = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} 1 \cdot e^{j\omega n} d\omega$$

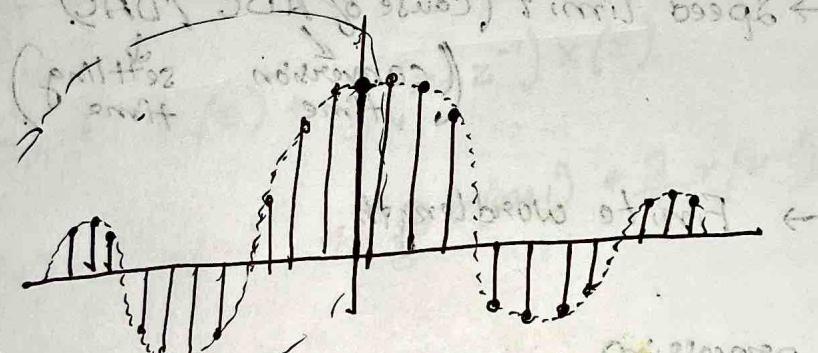
$$n=0 \quad h(n) = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} 1 \cdot d\omega = \frac{1}{2\pi} [2\omega_c] = \frac{\omega_c}{\pi}$$

$$n \neq 0 \quad h(n) = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} e^{j\omega n} d\omega = \frac{1}{2\pi} \left[\frac{e^{j\omega n}}{jn} \right]_{-\omega_c}^{\omega_c}$$

$$= \frac{1}{2\pi} \left[\frac{e^{j\omega_c n} - e^{-j\omega_c n}}{2jn} \right]$$

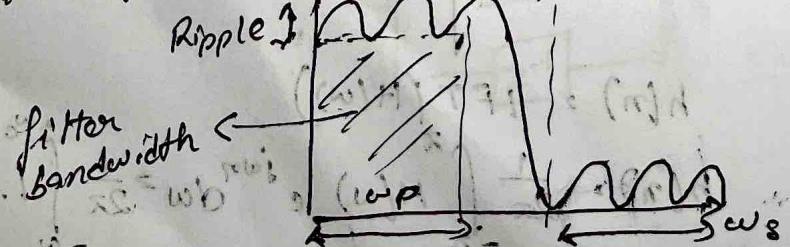
$$\frac{\sin \omega_c n}{\pi n} \rightarrow \text{sin C pulse.}$$

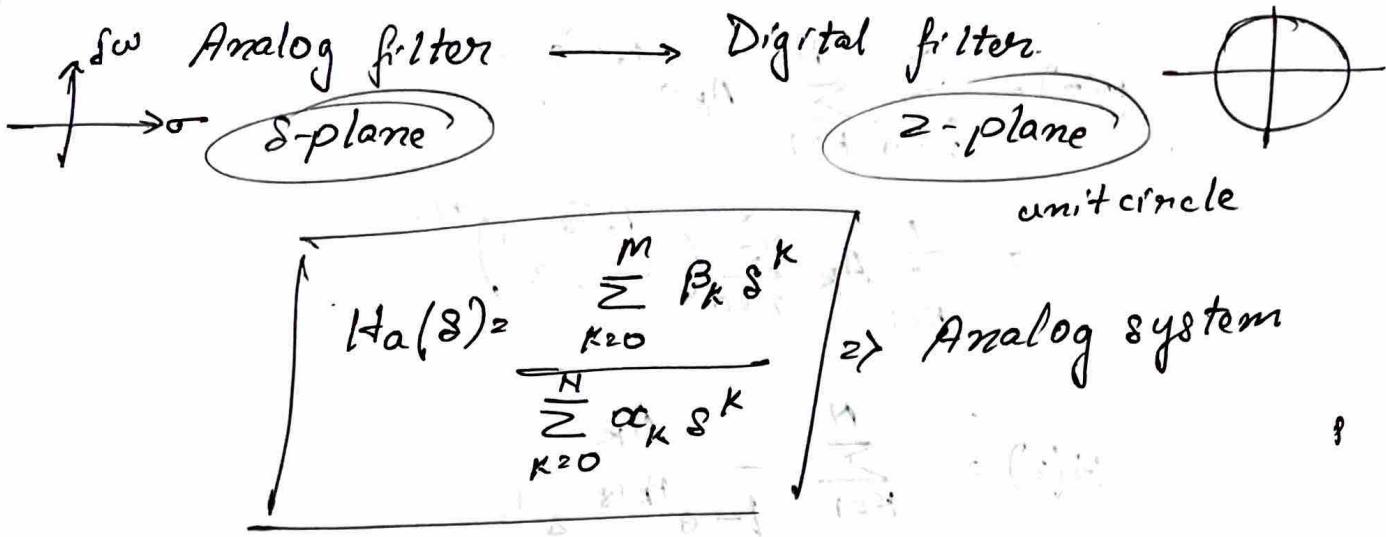
For causal filter $h(n) = 0 \forall n < 0$



Impulse response is not realizable as
 $h(n) \neq 0 \forall n < 0$ for basic ideal filter.

$|H(\omega)| \rightarrow$ constant passband not necessary.
 → Stop band → tolerance level
 Ripple → Transition band



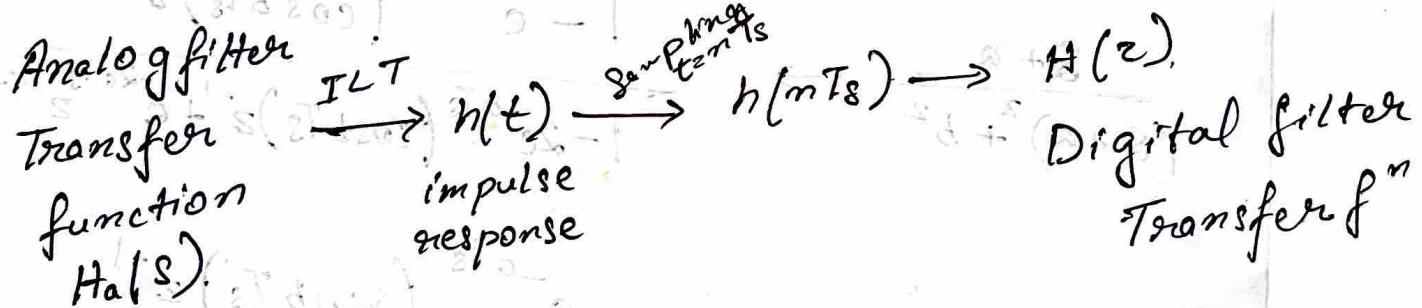


$$H_a(s) = \frac{\sum_{k=0}^M \beta_k s^k}{\sum_{k=0}^N \alpha_k s^k} \quad | \rightarrow \text{Analog system}$$

$$H_a(s) = \int h(t) e^{-st} dt$$

$$\sum_{k=0}^N \alpha_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M \beta_k \frac{d^k x(t)}{dt^k} \quad | \text{stability}$$

Impulse Invariance method.



Analog frequency (ω)

$$\textcircled{1} \quad H_a(s) = \sum_{k=1}^N \frac{A_k}{s - P_k}$$

$$h(t) = \text{ILT}[H_a(s)]$$

$$\textcircled{2} \quad h(t) = \sum_{k=1}^N A_k e^{P_k t}$$

$$\textcircled{3} \quad h(nT_s) = \sum_{k=1}^N A_k e^{P_k nT_s}$$

Z-transform-

$$\textcircled{4} \quad H(z) = \sum_{n=0}^{\infty} h(nT_s) z^{-n}$$

$$H(z) = \sum_{n=0}^{\infty} \sum_{k=1}^N A_k e^{-P_k n T_s} z^{-n}$$

$$= \sum_{k=1}^N A_k \sum_{n=0}^{\infty} \left(e^{-P_k T_s} z^{-1} \right)^n$$

$$H(z) = \sum_{k=1}^N \frac{A_k}{1 - e^{-P_k T_s} z^{-1}}$$

$$\frac{1}{s - P_k} \rightarrow \frac{1}{1 - e^{-P_k T_s} z^{-1}}$$

$$\sum_{n=0}^{\infty} e^{-P_k n T_s} z^{-n} = \frac{1}{1 - e^{-P_k T_s} z^{-1}}$$

$$\frac{1}{s - P_k} \rightarrow \frac{1}{1 - e^{-P_k T_s} z^{-1}}$$

$$\frac{(s+a)}{(s+a)^2 + b^2} \rightarrow \frac{1 - e^{-a T_s} (\cos b T_s) z^{-1}}{1 - 2e^{-a T_s} (\cos b T_s) z^{-1} + e^{-2a T_s} z^{-2}}$$

$$\frac{b}{(s+a)^2 + b^2} \rightarrow \frac{e^{-a T_s} (s \tan b T_s) z^{-1}}{1 - 2e^{-a T_s} (\cos b T_s) z^{-1} + e^{-2a T_s} z^{-2}}$$

$$Q. H_a(s) = \frac{2}{(s+1)(s+2)}$$

$$\rightarrow s_{12} - \text{PdF} \left(\frac{s_0}{s_1} \right)$$

Bilinear Transformation Method.

Problems in impulse invariance method.

- Aliasing effect present
- Many to one mapping
- Not suitable for high pass and band reject filter.
- Only poles of the system can be mapped.

$$f_s^2 = \frac{1}{T_s}$$

$$(n-1)T_s$$

$$nT_s$$

$T_s \rightarrow$ Sampling period
very small

Trapezoidal rule

↓
Area of integral
can be approx
by mean height
of $x(t)$ b/w
2 limits &
later multiplying
by width.

$$\begin{aligned} x(t) &\xrightarrow{\text{S}} y(t) \\ \frac{y(s)}{x(s)} &= \frac{1}{s} \quad H(s) = \frac{1}{s} \end{aligned}$$

$$y(t) = \int x(t) dt$$

$$\int_{(n-1)T_s}^{nT_s} y(t) dt = \int_{(n-1)T_s}^{nT_s} x(t) dt$$

$$\Rightarrow y(t) \Big|_{(n-1)T_s}^{nT_s} = \int_{(n-1)T_s}^{nT_s} x(t) dt$$

$$\Rightarrow y(nT_s) - y((n-1)T_s) = \int_{(n-1)T_s}^{nT_s} x(t) dt$$

$$= T_s \left[\frac{x(nT_s) + x((n-1)T_s)}{2} \right]$$

$y(nT_s) \approx y(n) \quad [\because T_s \text{ is very small}]$

$$y((n-1)T_s) \approx y(n-1)$$

$$\Rightarrow y(n) - y(n-1) = \frac{T_s}{2} [x(n) + x(n-1)]$$

Taking z-transform -

$$y(z) - z^{-1}y(z) = \frac{T_s}{2} [x(z) + z^{-1}x(z)]$$

$$\Rightarrow y(z)[1 - z^{-1}] = \frac{T_s}{2} x(z)[1 + z^{-1}]$$

$$x'(z) = \frac{2}{T_s} \left[\frac{1 - z^{-1}}{1 + z^{-1}} \right] y(z)$$

Digital.

$$x(s) = s y(s)$$

Analog

$$s \rightarrow \frac{2}{T_s} \left[\frac{1 - z^{-1}}{1 + z^{-1}} \right]$$

$s \rightarrow$ Analog fⁿ
 $\omega \rightarrow$ Digital

$$s = \sigma + j\omega \approx \frac{2}{T_s} \left[\frac{2 - 1}{z + 1} \right]$$

$$\Rightarrow \sigma + j\omega \approx \frac{2}{T_s} \left[\frac{2e^{j\omega} - 1}{2e^{j\omega} + 1} \right]$$

to solve

$$\frac{2e^{-j\omega} + 1}{2e^{-j\omega} - 1}$$

$$② e^{j\omega} = \cos \omega + j \sin \omega$$

$$① \sigma = \frac{2}{T_s} \left[\frac{2e^{-j\omega} + 1}{2e^{-j\omega} - 1} \right]$$

$$② \sigma = \frac{2}{T_s} \left[\frac{2 \cos \omega + j \sin \omega}{2 \cos \omega - j \sin \omega} \right]$$

when

$2 \cos \omega$ = pre dot

$$\begin{aligned}\omega_2 &= \frac{2}{T_s} \left[\frac{2 \sin \omega}{1 + 2 \cos \omega + 1} \right] \\ &= \frac{2}{T_s} \left[\frac{\sin \omega}{1 + \cos \omega} \right].\end{aligned}$$

$$= \frac{2}{T_s} \left[\frac{2 \sin \omega / 2 \cos \omega / 2}{1 + 2 \cos^2 \omega / 2 - 1} \right]$$

$$\begin{aligned}&\boxed{\omega_2 = \frac{2}{T_s} \tan(\frac{\omega}{2})} \\ &\boxed{\omega_2 = \frac{2}{T_s} \tan\left(\frac{\omega T_s}{2}\right)}\end{aligned}$$

$$\frac{\omega_2 T_s}{2} = \tan \frac{\omega}{2}.$$

$$\boxed{\omega = 2 \tan^{-1}\left(\frac{\omega_2 T_s}{2}\right)}$$

Q. An. analog filter has following transfer fⁿ

$$H(s) = \frac{1}{s+1}$$

Defⁿ the transfer function of digital filter
H(z) using BLT. Also write the eqⁿ of digital filter.

$$\rightarrow \boxed{\frac{\sin \omega}{s} s^2 \frac{2}{T_s} \left[\frac{z-1}{z+1} \right]}.$$

$$= 2 \left(\frac{z-1}{z+1} \right)$$

$$T_s = 18^\circ C$$

$$H(z) = \frac{1}{2\left(\frac{z-1}{z+1}\right) + 1}$$

$$= \frac{z+1}{3z-1}$$

$$\frac{Y(z)}{X(z)} = \frac{z+1}{3z-1} = \frac{1+z^{-1}}{3z^{-1}-1}$$

$$3y(z) - y(z)z^{-1} = x(z) + z^{-1}(\cancel{x}(z))$$

~~$$3y(n) - y(n-1) = x(n) + x(n-1)$$~~

$$y(n) = \frac{1}{3}y(n-1) + \frac{1}{3}x(n-1) + \frac{1}{3}x(n)$$

Q. $H(s) = \frac{3}{(s+2)(s+3)}$ $T_s = 0.1806$

Find $H(z)$ using BLT.

- Q. Design a single pole low pass filter with a 3-dB bandwidth of 0.2π . The transfer function of analog filter is of the form $H(s) = \frac{\omega_c}{s + \omega_c}$ where ω_c is 3dB bandwidth of analog filter.

$$\omega_c = 0.2\pi$$

$$\omega_c = \frac{2}{T_s} \tan\left(\frac{\omega_c}{2}\right)$$

$$\omega_c = \frac{2}{T_s} \tan(0.1\pi)$$

$$s_{2c} = \frac{0.65}{T_s} \left[\frac{1-s}{1+s} \right] \quad (2)$$

$$H(s) = \frac{0.65/T_s}{s + 0.65/T_s}$$

$$s = \frac{2}{T_s} \left[\frac{z-1}{z+1} \right]$$

$$\begin{aligned} H(z)^2 &= \frac{0.65/T_s}{\frac{2}{T_s} \left[\frac{z-1}{z+1} \right] + 0.65/T_s} \\ &= \frac{0.65}{\frac{2z-2}{z+1} + 0.65} \\ &= \frac{0.245(z^2+1)}{z^2 - 0.509} \end{aligned}$$

$$H(z) = \frac{s+0.1}{(s+0.1)^2 + 16}$$

Q. The transfer function of analog filter is $H(s) = \frac{s+0.1}{(s+0.1)^2 + 16}$
 Obtain the transfer function of digital filter using BLT
 which is resonant at $\omega_r = \pi/2$. \leftarrow Digital filter.

$$\rightarrow H(z) = \frac{s+0.1}{(s+0.1)^2 + 4}$$

$$\begin{cases} (s+0.1)^2 + 4 = 0 \\ (s+0.1)^2 = 4 \\ s^2 - 0.1 \pm \sqrt{4} \end{cases}$$

$$s_2 = \frac{2}{T_s} \tan\left(\frac{\omega}{2}\right)$$

$$= \frac{2}{T_s} \tan\left(\frac{\pi}{4}\right) \Rightarrow T_s = \frac{2}{\pi} e^{0.509 \text{ rad/sec}}$$

$$s^2 \frac{2}{Ts} \left[\frac{z-1}{z+1} \right] \Rightarrow H(s)$$

Q. The analog transfer f" of low pass filter is
 $H(s) = \frac{1}{s+2}$ and its bandwidth is 1 rad/sec

Design a digital filter using BLT method whose cut-off freq is 20π and sampling time is 0.0167 sec by considering wrapping effect.



$$H(s) = \frac{1}{s+2}$$

$$\omega^* = \frac{2}{0.0167} \tan\left(\frac{20\pi \times 0.0167}{2}\right)$$

$$= 69.31$$

$$\begin{aligned} \omega_c &= \frac{\pi}{T_s} \\ \omega^* &= \frac{2}{T_s} \tan\left(\frac{\omega_c}{2}\right) \\ H(s) &\rightarrow H(s)^* \\ s^2 &\frac{s}{s^2} \end{aligned}$$

$$H^*(s) = \frac{1}{s^2 + 2} = \frac{1}{\frac{8}{69.31} + 2} = \frac{69.31}{8 + 138.62}$$

$$H(z) = \frac{2}{Ts} \left[\frac{z-1}{z+1} \right]$$

$$H(z) = \frac{69.31}{\frac{2}{0.0167} \left[\frac{z-1}{z+1} \right] + 138.62}$$

$$= \frac{z+1}{3.73z + 0.27}$$

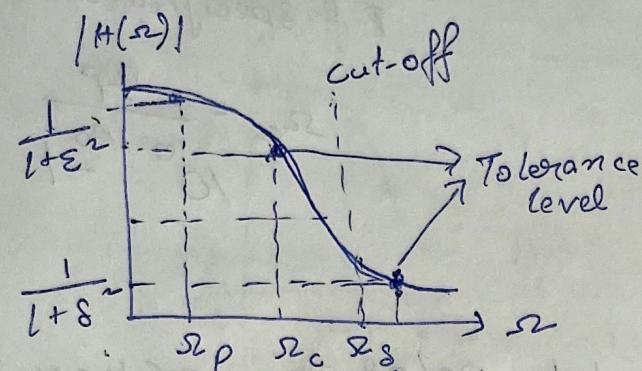
$$\left(\frac{w}{z} \right) \text{ and } \frac{z}{w} = z$$

$$z = \sqrt{3.73^2 - 0.27^2} e^{j\theta} = \sqrt{3.73^2 - 0.27^2} e^{j\theta}$$

Butterworth Filter Approximation

$$|H(s_2)|^2 = \frac{1}{1 + \left(\frac{s_2}{s_{c0}}\right)^{2N}}$$

s_{2p} = pass band edge frequency
 s_{2c} = cut-off freq.
 ϵ = Ripple related parameter in pass band
 δ = ripple related parameter in ~~pass~~ stop band
 $N \rightarrow$ order



Design Steps

Step-1 For given specification of digital; obtain equivalent analog filter

Step-2 Calculate order of filter (N)

$$N = \frac{1}{2} \left\{ \log \left[\left(\frac{1}{A_s^2} - 1 \right) / \left(\frac{1}{A_p^2} - 1 \right) \right] \right\} / \log \left(\frac{s_2s}{s_{2p}} \right)$$

or

$$N = \frac{1}{2} \left\{ \log \left[\left(\frac{1}{A_s^2} - 1 \right) \right] \right\} / \log \left(\frac{s_2s}{s_{2c}} \right)$$

If given in decibels.

$$N = \frac{1}{2} \left\{ \log \left[\frac{10^{0.1} A_s(dB) - 1}{10^{0.1} A_p(dB) - 1} \right] \right\} / \log \left(\frac{s_2s}{s_{2p}} \right)$$

$A_p \rightarrow$ Pass band attenuation.
 $A_s \rightarrow$ Stop band attenuation.
 $s_2s \rightarrow$ attenuation in stop band

Step-3 Now we calculate cut-off frequency ω_c

For Impulse Invariance.

$$\omega_c = \frac{\omega_c}{T_s}$$

If ω_c is not given

$$\omega_c = \frac{s_p}{\left(\frac{1}{A_p^2} - 1\right)^{1/2N}}$$

For BLT

$$\omega_c = \frac{2}{T_s} \tan\left(\frac{\omega_c}{2}\right)$$

If specification is in dB

$$\omega_c = \frac{s_p}{10^{\frac{0.1 A_p}{2}} - 1}$$

Step-4 we now calculate poles as $0 \leq k \leq N-1$

$$(P_k = \pm \omega_c e^{j(N+2k+1)\pi/2N}, \quad k=0, 1, 2, \dots, N-1)$$

We should select poles from left side of plane only.

$$H(s) = \frac{\omega_c^N}{(s-P_1)(s-P_2) \dots}$$

Step 5

A. A design filter has following specifications

Passband freq. = $0.2\pi = \omega_p$

Stopband freq. = $0.3\pi = \omega_s$.

What are the specifications in Analog domain if we use.

a) Impulse Invariance Method

$$\omega_{s,p} = \frac{\omega_{s,p}}{T_s}$$

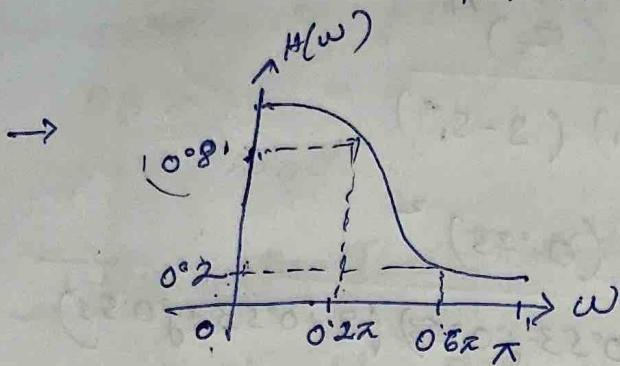
b) BLT

$$\omega_{s,p} = \frac{2}{T_s} \tan\left(\frac{\omega_{s,p}}{2}\right)$$

Q. Using BLT design a Butterworth filter satisfying following cond'n.

$$|0.8 \leq |H(\omega)| \leq 1| \quad \forall 0 \leq \omega \leq 0.2\pi$$

$$|H(\omega)| \leq 0.2 \quad \forall 0.6\pi \leq \omega \leq \pi$$



$$A_p = 0.8, \omega_p = 0.2\pi$$

$$A_s = 0.2, \omega_s = 0.6\pi$$

Step 1

$$\omega_c = \frac{2}{T_s} \tan\left(\frac{\omega_s}{2}\right)$$

$$\omega_{cs} = \frac{2}{T_s} \tan\left(\frac{\omega_s}{2}\right)$$

$$= 2.75$$

$$\omega_{cp} = \frac{2}{T_s} \tan\left(\frac{\omega_p}{2}\right)$$

$$= 0.65$$

Step 2

$$N = \frac{1}{2} \frac{\log \left[\left(\frac{1}{A_s^2} - 1 \right) / \left(\frac{1}{A_p^2} - 1 \right) \right]}{\log \left(\frac{\omega_c}{\omega_{cp}} \right)}$$

$$= 1.3 \approx 2$$

Step 3

$$\omega_c = \sqrt{\frac{A_p}{A_s^2 - 1}}^{1/2N} = 0.75$$

Step 4

$$P_k = \pm \omega_c e^{j(N+2k+1)\pi/2N}$$

$\therefore N=2$

$$P_0 = \pm 0.75 e^{j(3\pi/4)}$$

$$= \pm 0.75 \left\{ \cos\left(\frac{3\pi}{4}\right) + j \sin\left(\frac{3\pi}{4}\right) \right\} =$$

$$= -0.53 + j0.53, \quad \underline{0.53 - j0.53} \times$$

$$P_1 = -0.53 - j0.53, \quad \underline{0.53 + j0.53} \times$$

(Step 5)

$$H(s) = \frac{(s_c)^N}{(s-s_1)(s-s_1^*)}$$

$$= \frac{(0.75)^2}{(s+0.53-j0.53)(s+0.53+j0.53)}$$

$$H(s) = \frac{0.56}{s^2 + 1.063 + 0.56}$$

$$\textcircled{A} \quad s^2 - \frac{2}{Ts} \left[\frac{z-1}{z+1} \right]$$

$$H(z) = \frac{0.56(z+1)^2}{6.68z^2 - 6.88z + 2.44}$$

Chebyshev Filter

- Poles of butterworth filter lie on a circle while the poles of chebyshev filter lie on a ellipse.
- Butterworth filter has a flat response in both PB & SB whereas chebyshev filter has ripples in pass band.

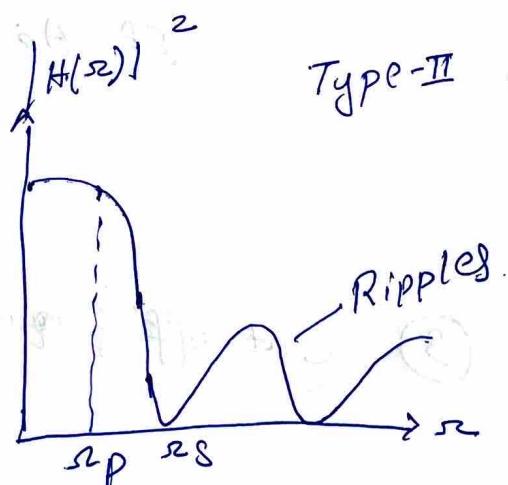
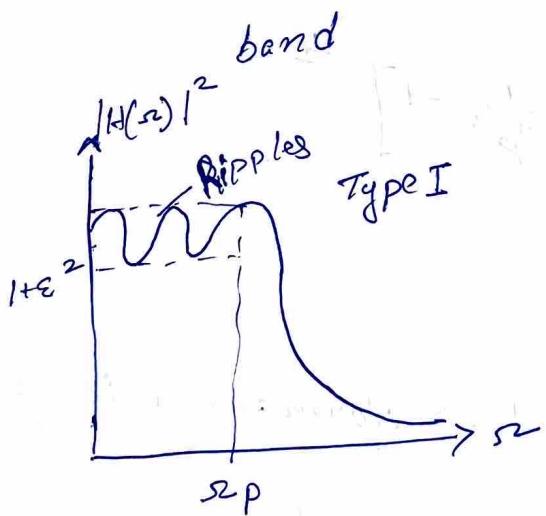
~~why should one select chebyshev over butterworth~~

why should one select chebyshev over butterworth.

- Chebyshev filter has better roll-off rate eg - for same order if butterworth has say - 6dB

chebyshev will have say - 8dB

- For sharp transitions from pass band to stop band



$$\left| H(s^2) \right|^2 = \frac{1}{1 + \epsilon^2 C_N(\omega^2/s^2_p)}$$

$C_N(x)$ = chebyshev polynomial of order N

$C_N(\frac{\omega^2}{s^2_p})$
chebyshev
polynomial
of order
N

$$C_{N+1}(x) = 2x C_N(x) - C_{N-1}(x)$$

$$C_0(x) = 1, \quad C_1(x) = x$$

Design.

① Frequency Response

$$|H(j\omega)|^2 = \frac{1}{1 + \varepsilon^2 C_N^2(\omega/\omega_p)}$$

$C_N(\omega/\omega_p)$ = Chebyshev polynomial of order N

② ε

$$\varepsilon = \left[\frac{0.1 A_p(B)}{10} - 1 \right]^{1/2}$$

If A_p is not in dB

$$\varepsilon = \left[\frac{1}{A_p^2} - 1 \right]^{1/2}$$

③ Cut-off frequency

ω_c

At $\omega_c = 1 \rightarrow$ Normalized filter

$$|H(j\omega)| = \frac{1}{\sqrt{1 + \varepsilon^2}}$$

④ Order of filter

$$|H(j\omega)| = -20 \log_{10} \varepsilon - 6(N-1) - 20 \log_{10} \left(\frac{\omega}{\omega_0} \right).$$

⑤ Poles

First we calculate the regular position of poles of butterworth filter

Pole position.

$$\omega_p = R \cos \theta_k + j R \sin \theta_k \quad \theta_k = \frac{\pi}{2} + \frac{(2k+1)\pi}{2N}, \quad k=0, 1, 2, \dots, N-1$$

Position of poles

i.e. on ellipse ω_p & θ_k

$$\omega_k = R \cos \theta_k$$

$$\theta_k = R \sin \theta_k$$

$$R = \sqrt{\frac{\beta^2 - 1}{\beta^2 + 1}} \quad \beta = \frac{\omega_p}{\omega_n}$$

$$\frac{1}{N}$$

$$\theta_k = \tan^{-1} \frac{\beta^2 - 1}{2\beta} \quad \text{minor axis of ellipse}$$

$$\beta = \frac{\omega_p}{\omega_n} \quad \text{major axis}$$

- Q. Design a low pass 1 rad/sec. bandwidth chebyshov filter with following characteristics

(i) Pass band ripple of 2dB

$$A_p = 2$$

(ii) Cut-off frequency of 1 rad/sec

(iii) Stop band attenuation of 20dB or greater beyond 1.8 rad/sec

⑥ Transfer f^n

$$H(s)^2 = \frac{k}{(s-s_0)(s-s_1)} \cdot$$

$$\Rightarrow H(s)^2 = \frac{k}{s^N + b_{N-1}s^{N-1} + \dots + b_0}$$

$$k^2 \begin{cases} b_0 & \text{if } n = \text{odd} \\ \frac{b_0}{\sqrt{1+\varepsilon^2}} & \text{if } n = \text{even} \end{cases}$$

$$\rightarrow A_p = 20 \text{dB}, \quad S_C = 1 \quad \left. \right| H(j\omega) \rightarrow N$$

$\Theta \quad S_S = 1.3 \text{ rad/se.}$

$$① \quad \varepsilon = \left[10^{0.1 \times 2} - 1 \right]^{1/2} = 0.765$$

$$|H(\omega)| = -20 \text{dB}, \quad S_S = 1.3 \text{ rad}$$

$$② \quad |H(j\omega)| = -20 \log_{10} \varepsilon - G(N-1) - 20 \log_{10} S_S$$

$$\Rightarrow -20 = -20 \log_{10}(0.765) - G(N-1) - 20 \log_{10}(1.3)$$

$$\Rightarrow N = 3.421 \approx 4$$

③ Pole calculation.

$$\beta = \sqrt{\frac{\sqrt{1+\varepsilon^2} + 1}{\varepsilon}}$$

$$= 1.31$$

$$\begin{aligned} g_2 &= s_p \frac{\beta^2 - 1}{2\beta} \\ &= 1 \times \frac{1.31^2 - 1}{2 \times 1.31} \end{aligned}$$

$$R = s_p \frac{\beta^2 + 1}{2\beta}$$

$$= 1.04$$

$$\theta = 0^\circ, 1^\circ, 2^\circ, 3^\circ$$

$$\theta_k = \frac{\pi}{2} + \frac{(2k+1)\pi}{2N}$$

$$\theta_1 = \frac{7\pi}{8}, \theta_2, \theta_3, \theta_0 = \dots$$

$$S_1 = g \cos \theta_1 + j R \cos \theta_1$$

$$\Rightarrow 0.273 \cos\left(\frac{7\pi}{8}\right) + j 1.0481 \sin\left(\frac{7\pi}{8}\right)$$

$$= -0.25 + j 0.4$$

$$H(s) = \frac{k}{(s-s_0)(s-s_1)(s-s_2)(s-s_3)}$$

↓ After solving

$$= \frac{k}{s^4 + 0.7s^3 + 1.25s^2 + 0.518 + 0.207}$$

$$k^2 = \frac{b_0}{\sqrt{1+\epsilon^2}} \mid \text{even} \mid b_0^2 \text{ constant term in denominator.}$$

$$= \frac{0.207}{\sqrt{1+0.765^2}} \approx 0.16$$

$$\therefore H(s) = \frac{0.16}{s^4 + 0.7s^3 + 1.25s^2 + 0.518 + 0.207}$$

Q. Design a chebyshev filter for following specification.

$\frac{1}{2}$ dB rppk in PB $0 \leq \omega \leq 0.24\pi$ min 50dB

attenuation in stop band $0.35\pi \leq \omega \leq \pi$
use ~~Sec~~ BLT for $T=1$ sec

$$\rightarrow A_p = \frac{1}{2} \text{dB}$$

$$|H(s)| \geq 50 \text{dB}$$

$$\omega_p = 0.24\pi$$

$$\omega_s = 0.35\pi$$

$$s_p = \frac{2}{78} \tan\left(\frac{\omega_p}{2}\right)$$

Frequency Transformation

When (cut-off frequency) $\omega_0 = 1 \rightarrow \text{Normalized filter}$

$$\omega = 2\pi f$$

Conversion table

Low pass Normalized
filter

Sampling frequency

$$f_U = \frac{\omega_U}{f_S} \quad f_L = \frac{\omega_L}{f_S}$$

| | |
|-------------|--|
| → low pass | $S \rightarrow \frac{\omega_c}{\omega_{LP}} S$ |
| → High pass | $S \rightarrow \frac{\omega_c}{S} \omega_{HP}$ |
| → Band pass | $S \rightarrow \omega_c \times \frac{S^2 + \omega_e \omega_u}{S(\omega_u - \omega_e)}$ |
| → Band pass | $S \rightarrow \omega_c \times \frac{S(\omega_u - \omega_e)}{S^2 + \omega_u \omega_e}$ |

Q. The T.F of 1st order normalized LPF is

$$H(S) = \frac{1}{S+1}$$

Obtain the system f'n of 2nd order bandpass

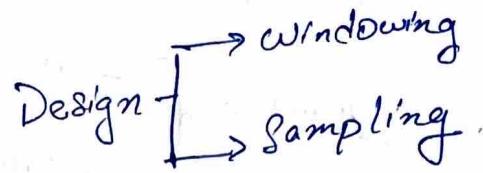
filter having passband from 1KHz - 2KHz.

$$S = \omega_c \frac{S^2 + \omega_e \omega_u}{S(\omega_u - \omega_e)} \quad \omega_c = 1$$

$$f_U = 24\text{Hz} \quad f_L = 1\text{kHz}$$

$$\omega_u = 2\pi f_U \quad \omega_e = 2\pi f_L$$

FIR filter Design.



$$y(n) = - \sum_{k=1}^M a_k y(n-k) + \sum_{k=0}^M b_k x(n-k)$$

* Non-Recursive filter → No feedback.

$$y(n) = \sum_{k=0}^M b_k x(n-k)$$

↓
z transform.

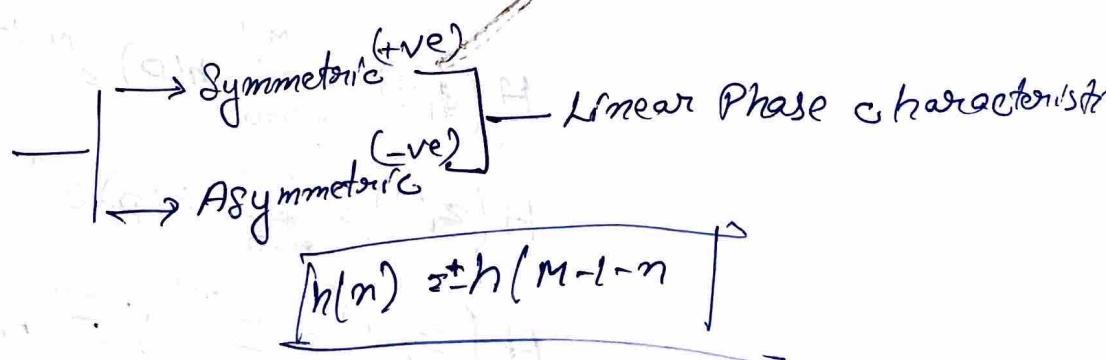
$$Y(z) = \sum_{k=0}^{M-1} b_k z^{-k} X(z)$$

$$\Rightarrow H(z) = \frac{Y(z)}{X(z)} = \sum_{k=0}^{M-1} b_k z^{-k}$$

Inverse Z-T

$$h(n) = \begin{cases} b_0, & 0 \leq n \leq M-1 \\ 0, & \text{otherwise} \end{cases}$$

* Inherently stable



FIR filter phase.

$$\angle H(\omega) = \begin{cases} -\omega \left(\frac{m-1}{2} \right) & |H(\omega)| > 0 \\ -\omega \left(\frac{m-1}{2} \right) + \pi & |H(\omega)| < 0 \end{cases}$$

Q. Show that if z_1 is zero of linear phase filter \rightarrow FIR
then $\frac{1}{z_1}$ is also the zero of filter?

$$\rightarrow H(z) = \sum_{n=0}^{M-1} h(n) z^{-n}$$

$$z = z_1, \quad H(z) \Rightarrow H(z_1) = 0$$

$$H(z_1) = \sum_{n=0}^{M-1} h(n) z_1^{-n} = 0 \quad \text{Given} \quad (1)$$

$$z = \frac{1}{z_1} \rightarrow z^{-1} H(z_1^{-1}) = 0 \quad \text{If this is true } \underline{\text{Prove}}$$

$$H(z_1^{-1}) = \sum_{n=0}^{M-1} h(n) (z_1^{-1})^n = \sum_{n=0}^{M-1} h(n) z_1^n \quad (2)$$

Linear phase filter

$$\rightarrow h(n) = h(M-1-n)$$

$$H(z_1^{-1}) = \sum_{n=0}^{M-1} h(M-1-n) z_1^n$$

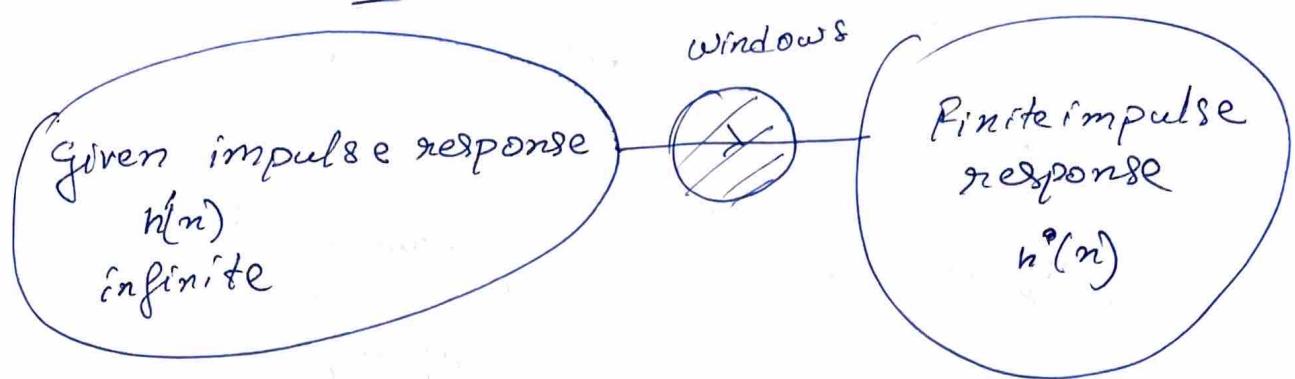
$$H(z_1^{-1}) = \sum_{n=0}^{M-1} h(P) z^{M-1-P}$$

$$H(z_1^{-1}) = \sum_{n=0}^{M-1} h(P) z^{M-1-P}$$

$$H(z_1^{-1}) = z^{M-1} \left\{ \sum_{n=0}^{M-1} h(P) z^{-P} \right\}$$

$$H(z_1^{-1}) = 0$$

Windowing Techniques



Causal windows \rightarrow positive

Anti-causal windows \rightarrow both \mathbb{R}^+ & \mathbb{R}^-

① Rectangular Window

Length of window is M

$$w_R(n) = \begin{cases} 1 & , n=0, 1, 2, \dots, M-1 \\ 0, & \text{otherwise} \end{cases}$$

} causal

$$h^*(n) = h'(n) w_R(n)$$

Let the power transform of rectangular window is

$$W_R(n) = \sum_{m=0}^{M-1} w_R(m) e^{-j\omega m}$$

$$W_R(n) = \sum_{m=0}^{M-1} (e^{-j\omega})^m$$

$$W_R(n) = \frac{1 - e^{-j\omega M}}{1 - e^{-j\omega}}$$

$$W_R(n) = \frac{e^{-j\omega M/2} \cdot e^{j\omega n/2} - e^{-j\omega M/2} \cdot e^{-j\omega n/2}}{e^{-j\omega/2} \cdot e^{j\omega/2} - e^{-j\omega/2} \cdot e^{j\omega/2}}$$

$$\sum_{k=N_1}^{N_2} a^k = \frac{a^{N_1} - a^{N_2+1}}{1-a}$$

$$= \frac{e^{-j\omega m/2} \left(e^{j\omega m/2} - e^{-j\omega m/2} \right)}{e^{-j\omega/2} \cdot \left(e^{j\omega/2} - e^{-j\omega/2} \right)}$$

$w_p(n) = e^{-j\omega(m-1)/2}$

$\frac{\sin(\omega m/2)}{\sin(\omega/2)}$

2) Bartlett Window (Triangular)

$$w_T(n) = \begin{cases} 1 - \frac{2|n - \frac{m-1}{2}|}{m-1} & n=0, 1, \dots, m-1 \\ 0, \text{ otherwise} & \end{cases}$$

↑
Causal.

3) Blackmann Window

$$w_B(n) = 0.42 + 0.5 \cos \frac{2\pi n}{m-1} + 0.08 \cos \frac{4\pi n}{m-1}$$

4) Hamming Window

$$w_H(n) = 0.54 + 0.46 \cos \frac{2\pi n}{m-1}$$

5) Hanning Window

$$w_{Hn}(n) = 0.5 + 0.5 \cos \frac{2\pi n}{m-1}$$

Windowing Techniques - Numerical Approach.

Step-1 Frequency Response of filter to be designed is given.

Step-2 we find the unit sample response $h_d(n)$ from $H_d(\omega)$ by taking inverse fourier transform.

$$h_d(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_d(\omega) e^{j\omega n} d\omega$$

Step-3 The response obtained in step-2 has infinite duration so we need to convert it into a finite duration response (in length). This is done by using appropriate window

$$h(n) = h_d(n) w(n)$$

Step-4 If required find the frequency response of FIR filter.

$$H(e^{j\omega}) = \sum_{n=0}^{M-1} h(n) e^{-j\omega n}$$

Q. Design a digital FIR filter

$$H(e^{j\omega}) = \begin{cases} e^{-j2\omega}, & -\pi/4 \leq |\omega| < \pi/4 \\ 0, & \pi/4 \leq |\omega| < \pi \end{cases}$$

length = 5

$$\rightarrow H(e^{j\omega}) = \begin{cases} e^{-j2\omega}, & -\pi/4 \leq |\omega| < \pi/4 \\ 0, & \pi/4 \leq |\omega| < \pi \end{cases}$$

Find the filter coefficients in magnitude and phase

For n = 0, 1, 2, 3, 4

$$h_d(n) = \frac{1}{2\pi} \int_{-\pi/4}^{\pi/4} H(e^{j\omega}) e^{jnw} d\omega$$

$$= \frac{1}{2\pi} \int_{-\pi/4}^{\pi/4} e^{-j2\omega} e^{jnw} d\omega$$

$$= \frac{1}{2\pi} \int_{-\pi/4}^{\pi/4} e^{\frac{j(n-2)}{2}\omega} d\omega$$

$$= \frac{1}{2\pi} \left[\frac{e^{j(n-2)\pi/4}}{j(n-2)} \right]_{-\pi/4}^{\pi/4}$$

$$= \frac{1}{\pi(n-2)} \left[\frac{e^{j(n-2)\pi/4} - e^{-j(n-2)\pi/4}}{2j} \right]$$

$$= \frac{1}{\pi(n-2)}$$

$$h_d(n) = \frac{8 \sin(n-2)\pi}{\pi(n-2)}$$

$$\frac{e^{j\theta} - e^{-j\theta}}{2j} = 8 \sin(\theta)$$

$$h_d(0) \quad h_d(1) \quad h_d(2) \quad h_d(3) \quad h_d(4)$$

$$h_d(2) = \int_{-\pi/4}^{\pi/4} \frac{1}{2\pi} e^{j(n-2)\omega} d\omega \Big|_{n=2}$$

$$= \frac{1}{2\pi} \int_{-\pi/4}^{\pi/4} d\omega = \frac{1}{4}$$

$$h(n) = h_d(n) \omega(n)$$

For rectangular window

$$\omega(n) = 1$$

$$h(n) = h_d(n)$$

- Q. Design a symmetric desired response, i.e.

FIR filter whose

$$H_d(\omega) = \begin{cases} e^{-j\omega C} & \text{if } |\omega| \leq \omega_c \\ 0, & \text{otherwise} \end{cases}$$

length of filter = 5 & $\omega_c = 1 \text{ rad/sec}$. Use rectangular window.

$$\rightarrow h_d(n) = \frac{1}{2\pi} \int H_d(\omega) e^{j\omega n} d\omega$$

$$\begin{aligned}
 &= \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{j(m-\epsilon)\omega} d\omega \\
 &= \frac{1}{2\pi} \left[\frac{e^{j(m-\epsilon)\omega}}{(m-\epsilon)j} \right]_{-\pi}^{\pi} \\
 h_d(n) &= \begin{cases} \frac{8\sin(n-\epsilon)}{\pi(n-\epsilon)}, & \text{when } n \neq \epsilon \\ \frac{1}{\pi}, & \text{when } n = \epsilon \end{cases}
 \end{aligned}$$

$$h_d(n) = h_d(m-1-n) \quad \boxed{\text{V.V.I}}$$

$$\begin{aligned}
 \frac{8\sin(n-\epsilon)}{\pi(n-\epsilon)} &= \frac{8\sin(m-1-n-\epsilon)}{\pi(m-1-n-\epsilon)} \\
 m-\epsilon &= -(m-1-n-\epsilon) \\
 \therefore \epsilon &= \frac{m-1}{2} \quad | m=5
 \end{aligned}$$

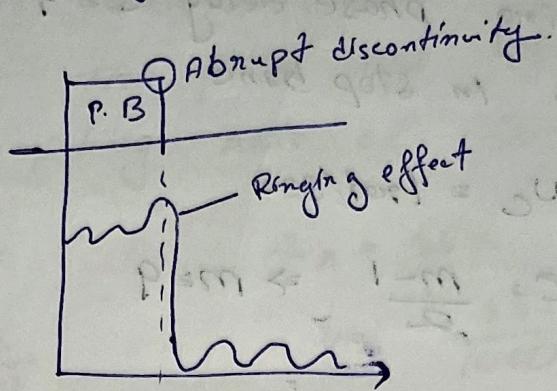
$$h_d(n) = \begin{cases} \frac{8\sin(n - \frac{m-1}{2})}{\pi(n - \frac{m-1}{2})}, & n \neq \epsilon \\ \frac{m-1}{2}, & n = \epsilon \end{cases}$$

$$h(n) = h_d(n) \cdot w(n) \quad | \text{For rectangular window.}$$

$$\frac{1}{\pi\epsilon} = (w)_bd$$

Problem with Rectangular window

- Gibbs' phenomenon



* Type-II

Order of FIR filter

$$m = k \left(\frac{2\pi}{\omega_2 - \omega_1} \right)$$

k is calculated from width of main lobe

$$\text{width of main lobe} = k \left(\frac{2\pi}{m} \right).$$

$$\omega_1 = \frac{\pi}{F_s} \quad \omega_2 = \frac{\pi}{F_s}$$

~~Window~~

Transition width of main lobe

Min stopband attenuation

Rectangular

$$4\pi/m+1$$

-21 dB

Bartlett

$$8\pi/m$$

-25 dB

Hanning

$$8\pi/m$$

-44 dB

Hamming

$$8\pi/m$$

-53 dB

Blackmann

$$12\pi/m$$

-74 dB

Q. Design a normalized linear phase FIR filter having phase delay $\tau = 4$ & at least 40dB attenuation in stop band.

$$\rightarrow \omega_c = 1 \text{ rad/sec}$$

$$\tau = \frac{m-1}{2} \Rightarrow m=9$$

\therefore Hanning window

$$\omega(n) = 0.5 - 0.5 \cos \frac{2\pi n}{m-1}$$

$$\omega(n) = 0.5 - 0.5 \cos \left(\frac{\pi n}{4} \right)$$

$$h_d(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_d(\omega) e^{j\omega n} d\omega$$

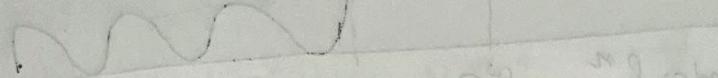
$$H_d(\omega) = \begin{cases} e^{-j\omega c} & |\omega| \leq \omega_c \\ 0 & \text{otherwise} \end{cases}$$

$$h(n) = h_d(n) \omega_n$$

Q. Design a low LPF that will have -3dB cutoff at 30π rad/sec and an attenuation of $\frac{50}{\sqrt{t}}$ dB at 45π rad/sec. The filter has linear phase & uses a sampling rate of 1000 samples/sec.

$$\rightarrow \omega_1 = 30\pi \quad \omega_2 = 45\pi \quad F_s = 1000$$

$$\omega_1 = \frac{30\pi}{1000} \quad \omega_2 = \frac{45\pi}{1000}$$



K

$$\text{width of lobe} = K \left(\frac{2\pi}{m} \right)$$

$$\frac{8\pi}{m} = K \left(\frac{2\pi}{m} \right) \Rightarrow K = 4.$$

$$4W \geq \omega_2 - \omega_1 \quad 8 + 1 \geq |(\omega_2 - \omega_1)| \geq 8 - 1$$

K

$$m \geq K \left(\frac{2\pi}{\omega_2 - \omega_1} \right)$$

Kaiser Window

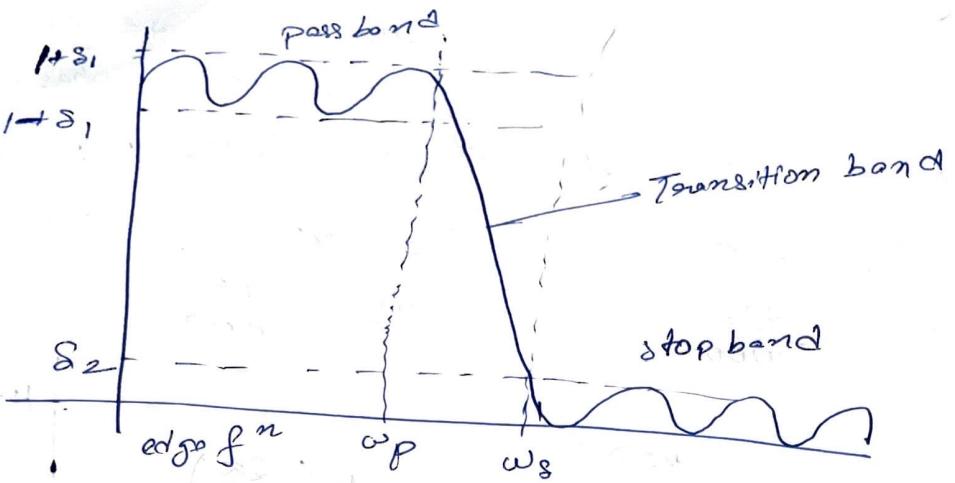
$$\omega_k(n) = \begin{cases} \frac{I_0\left\{\beta \left[1 - \left(\frac{n-\alpha}{\alpha}\right)^2\right]\right\}^{1/2}}{I_0(\beta)}, & \text{if } 0 \leq n \leq M \\ 0, & \text{otherwise} \end{cases}$$

$$\alpha = \frac{m}{2}$$

$$(P8-A) \approx 0.11^{\circ}$$

$$I_0(x) = 1 + \frac{0.25x^2}{(1)^2} + \frac{(0.25x^2)^2}{(2)^2} + \frac{(0.25x^2)^3}{(3)^2} + \dots$$

$I_0()$ → zero order modified Bessel's function



Standard MR

$$|1 - \delta_1| \leq |H(\omega)| \leq 1 + \delta_1, \quad \forall 0 \leq \omega \leq \omega_p$$

$$0 \leq |H(\omega)| \leq \delta_2, \quad \forall \omega_s \leq \omega \leq \pi$$

$\delta \rightarrow$ minimum of δ_1 & δ_2 .

transition b/w

$$\Delta\omega = \omega_s - \omega_p$$

Attenuation

$$A = -20 \log \delta$$

$$m = \frac{A - 8}{2.285 \Delta\omega}$$

$$B = \begin{cases} 0.1102(A-87) & \text{if } A \geq 50 \\ 0.5842(A-21)^{0.7} + 0.07886(A-21) & \text{if } 21 \leq A \leq 50 \\ 0 & \text{if } A < 21 \end{cases}$$

Q. Design a FIR filter phase filter using Kaiser window

$$0.99 \leq |H(e^{j\omega})| \leq 1.01 \quad \forall 0 \leq |\omega| \leq 0.19\pi$$

$$|H(e^{j\omega})| \leq 0.01 \quad \forall 0.21\pi \leq |\omega| \leq \pi$$

$$\rightarrow -1 - 0.01 \leq |H(e^{j\omega})| \leq 1 + 0.01 \quad \forall 0 \leq |\omega| \leq 0.19\pi$$

$$|H(e^{j\omega})| \leq 0.01 \quad \forall 0.21\pi \leq |\omega| \leq \pi$$

$$S_1 = 0.01 \quad S_2 = 0.01 \quad \omega_p = 0.19\pi \\ \omega_s = 0.21\pi$$

$$H_d(\omega) = \delta$$

$$\delta = \min(S_1, S_2) = 0.01$$

$$\Delta\omega = \omega_s - \omega_p = 0.02\pi$$

$$A = -20 \log_{10} \delta =$$

$$\beta_2 = 0.5892(A-21)^{0.4} + 0.07886(A-21)$$

$$= 3.395$$

$$\omega_c = \frac{\omega_s + \omega_p}{2}$$

$$\approx 0.2\pi$$

$$m = \frac{A-8}{2.285 \Delta\omega}$$

$$\approx 23$$

$$\omega(n) \rightarrow h_d(n) = \begin{cases} \frac{\sin[\omega_c(n-\frac{m}{2})]}{\pi(n-\frac{m}{2})}, & n \neq \frac{m}{2} \\ \frac{\omega_c}{\pi}, & n = \frac{m}{2} \end{cases}$$