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# SIGNALS & SYSTEMS

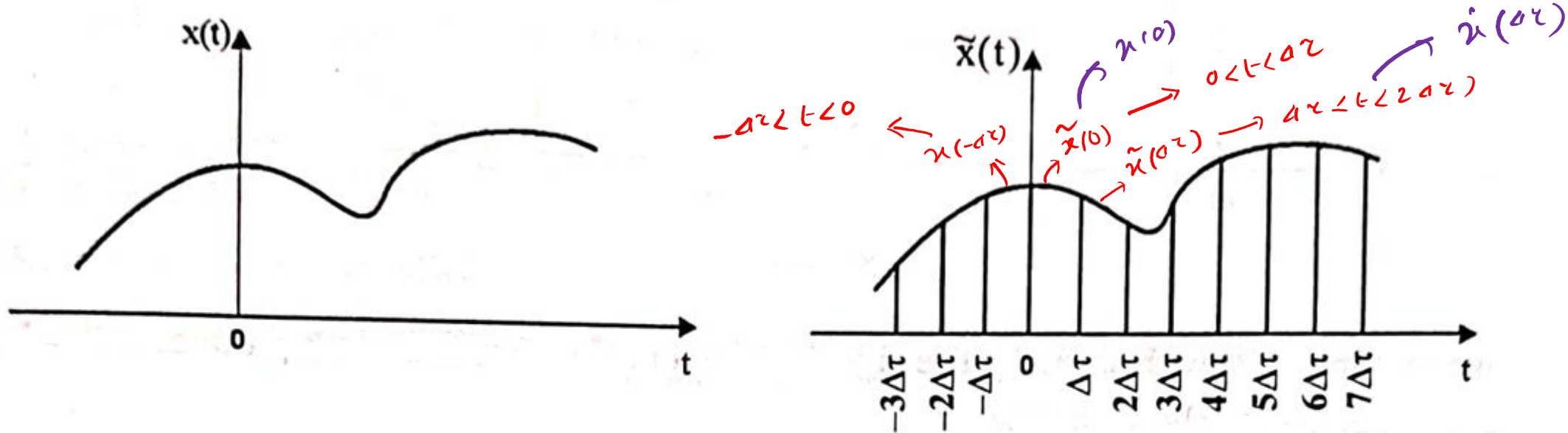
MR. ANKUR JYOTI SARMAH

ASSISTANT PROF., DEPT. OF ELECTRONICS & TELECOM. ENGG.

ASSAM ENGINEERING COLLEGE



## Representation of continuous time signal as an integral of impulse



Let us divide  $x(t)$  as narrow pulses of width  $\Delta\tau$  as shown in fig

Now the signal  $x(t)$  can be expressed as,

$$x(t) = \lim_{\Delta\tau \rightarrow 0} \int_{-\infty}^{\infty} \tilde{x}(t) dt \quad \longrightarrow \quad \text{Eqn 1}$$

$$\begin{aligned}
 & \vdots \\
 x(-2\Delta\tau) &= \tilde{x}(t) \quad ; \quad \text{for } -2\Delta\tau < t < -\Delta\tau \\
 x(-\Delta\tau) &= \tilde{x}(t) \quad ; \quad \text{for } -\Delta\tau < t < 0 \\
 x(0) &= \tilde{x}(t) \quad ; \quad \text{for } 0 < t < \Delta\tau \\
 x(\Delta\tau) &= \tilde{x}(t) \quad ; \quad \text{for } \Delta\tau < t < 2\Delta\tau \\
 x(2\Delta\tau) &= \tilde{x}(t) \quad ; \quad \text{for } 2\Delta\tau < t < 3\Delta\tau \\
 & \vdots
 \end{aligned}$$

$$\tilde{x}(t) = x(-2\Delta\tau) ,$$

$$\tilde{x}(t) = x(-\Delta\tau)$$

$$\therefore x(t) = \lim_{\Delta\tau \rightarrow 0} \sum \tilde{x}(t)$$

$$= \lim_{\Delta\tau \rightarrow 0} \sum [ \dots x(-2\Delta\tau) + x(-\Delta\tau) + x(0) + x(\Delta\tau) + x(2\Delta\tau) + \dots ]$$

Eqn 2



Consider the pulse signal of width  $\Delta\tau$  and height  $1/\Delta\tau$  as shown in fig  
be expressed as,

$$P_{\Delta}(t) = \frac{1}{\Delta\tau} \quad ; \quad 0 \leq t \leq \Delta\tau$$

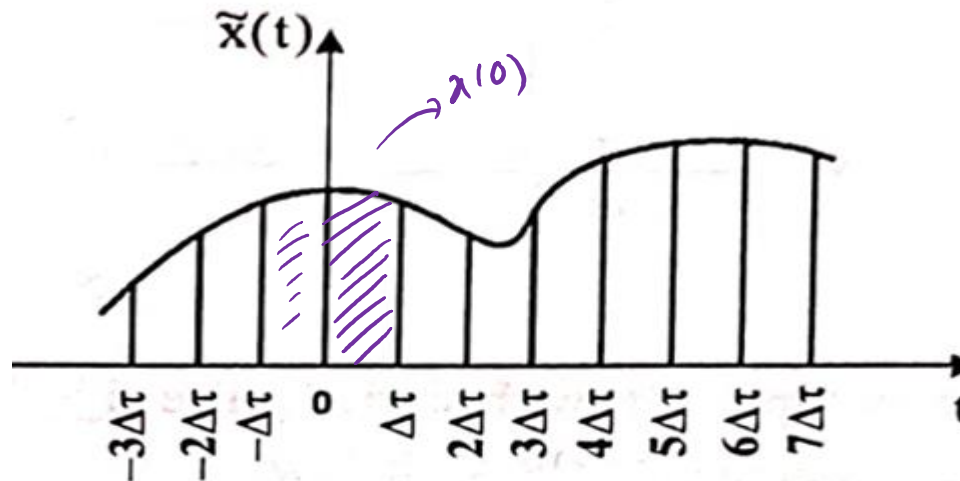
$$= 0 \quad ; \quad \text{otherwise}$$

$$\frac{1}{\Delta\tau} \times \Delta\tau = 1$$

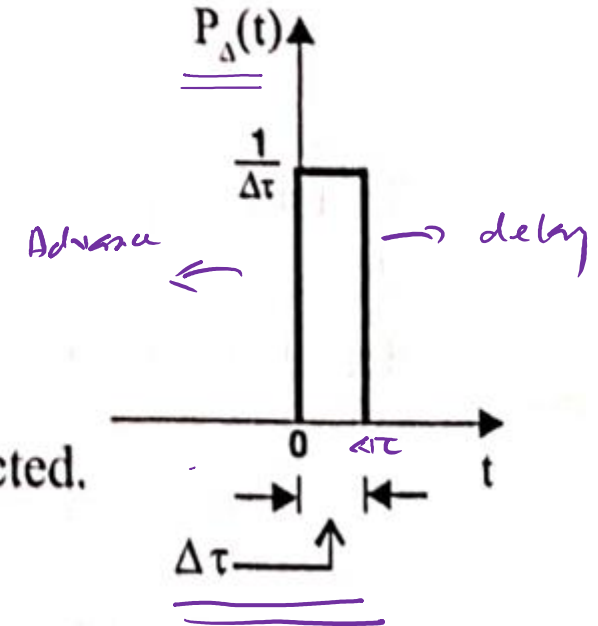
Now,  $P_{\Delta}(t) \times \Delta\tau =$  A pulse of unit amplitude.

$\therefore$  On multiplying  $P_{\Delta}(t) \times \Delta\tau$  with the signal  $\tilde{x}(t)$ , the signal  $x(0)$  is selected.

$$\therefore x(0) = \tilde{x}(t) P_{\Delta}(t) \Delta\tau$$

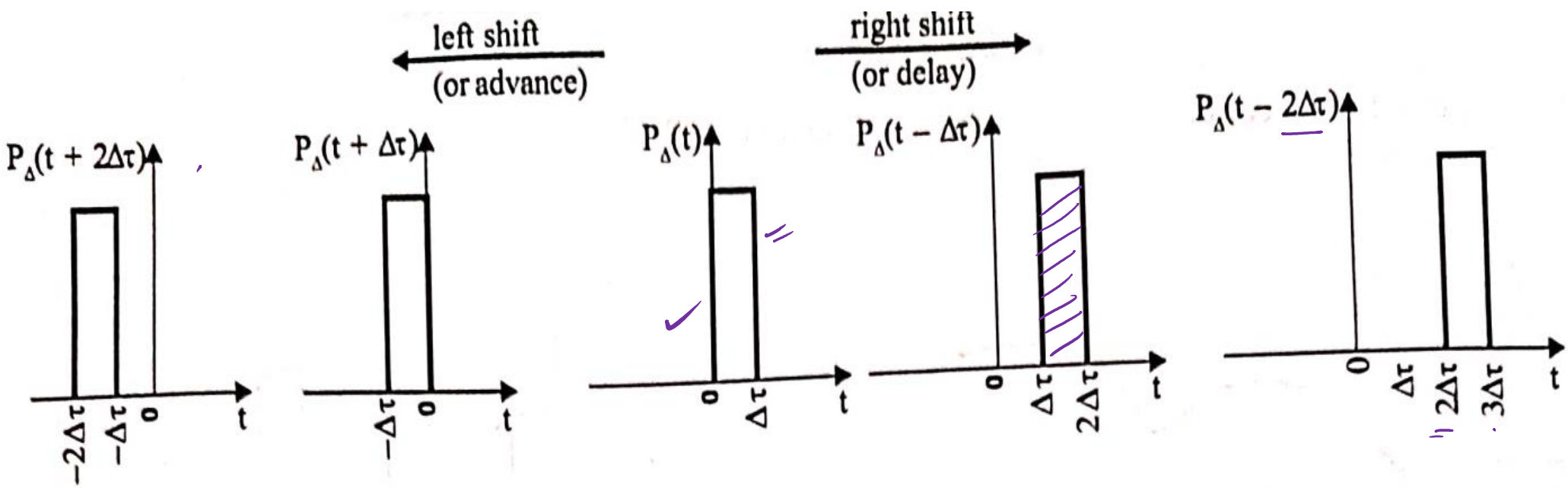
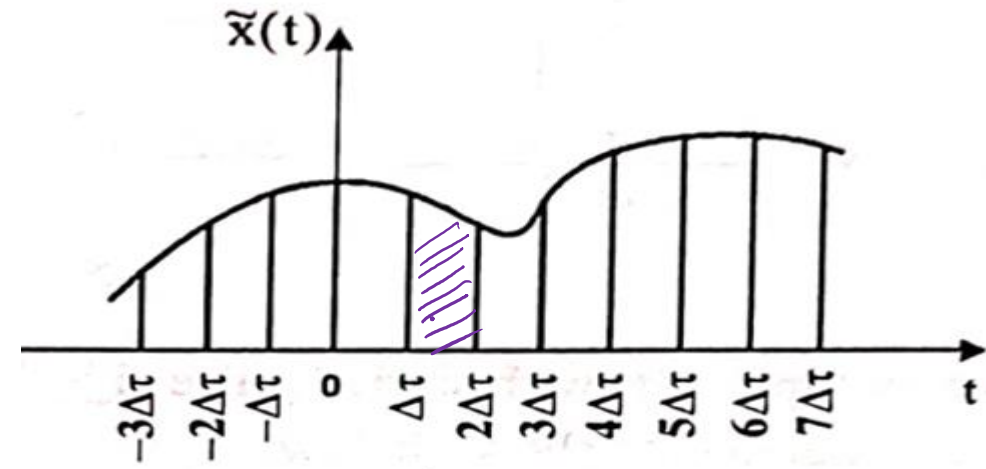


This pulse signal can



$$p_{\Delta}(t) \times \Delta\tau \times \tilde{x}(t) = x(t)$$

$$x(t) = p_{\Delta}(t - \Delta\tau) \times \Delta\tau \times \tilde{x}(t)$$





If we multiply  $\tilde{x}(t)$  with shifted pulse signals shown in fig , then each product will select one pulse of the signal  $\tilde{x}(t)$  as shown below.

$$\vdots$$

$$x(-2\Delta\tau) = \tilde{x}(t) P_{\Delta}(t+2\Delta\tau) \Delta\tau$$

$$x(-\Delta\tau) = \tilde{x}(t) P_{\Delta}(t+\Delta\tau) \Delta\tau$$

$$\underline{x(0) = \tilde{x}(t) P_{\Delta}(t) \Delta\tau}$$

$$x(\Delta\tau) = \tilde{x}(t) P_{\Delta}(t-\Delta\tau) \Delta\tau$$

$$x(2\Delta\tau) = \tilde{x}(t) P_{\Delta}(t-2\Delta\tau) \Delta\tau$$

$$\vdots$$


In the above equation  $\tilde{x}(t)$  can be replaced by respective selected pulses itself as shown below,

$$\begin{aligned} & \vdots \\ \therefore x(-2\Delta\tau) &= \tilde{x}(-2\Delta\tau) P_{\Delta}(t+2\Delta\tau) \Delta\tau \\ x(-\Delta\tau) &= \tilde{x}(-\Delta\tau) P_{\Delta}(t+\Delta\tau) \Delta\tau \\ x(0) &= \tilde{x}(0) P_{\Delta}(t) \Delta\tau \\ x(\Delta\tau) &= \tilde{x}(\Delta\tau) P_{\Delta}(t-\Delta\tau) \Delta\tau \\ x(2\Delta\tau) &= \tilde{x}(2\Delta\tau) P_{\Delta}(t-2\Delta\tau) \Delta\tau \\ & \vdots \end{aligned}$$



On substituting the above equations in equation 2 we get,

$$\begin{aligned}\tilde{x}(t) &= \lim_{\Delta\tau \rightarrow 0} \left[ \dots \tilde{x}(-2\Delta\tau) P_{\Delta}(t+2\Delta\tau) \Delta\tau + \tilde{x}(-\Delta\tau) P_{\Delta}(t+\Delta\tau) \Delta\tau + \tilde{x}(0) P_{\Delta}(t) \Delta\tau \right. \\ &\quad \left. + \tilde{x}(\Delta\tau) P_{\Delta}(t-\Delta\tau) \Delta\tau + \tilde{x}(2\Delta\tau) P_{\Delta}(t-2\Delta\tau) \Delta\tau + \dots \right] \\ &= \lim_{\Delta\tau \rightarrow 0} \sum_{n=-\infty}^{+\infty} \tilde{x}(n\Delta\tau) P_{\Delta}(t-n\Delta\tau) \Delta\tau\end{aligned}$$

On applying limit  $\Delta\tau \rightarrow 0$  the signal  $\tilde{x}(n\Delta\tau)$  becomes continuous, the signal  $P_{\Delta}(t-n\Delta\tau)$  becomes an impulse and so the summation becomes integration.

Hence the above equation can be expressed as,

$$x(t) = \int_{-\infty}^{+\infty} x(\tau) \delta(t-\tau) d\tau$$

$$x(t) \longrightarrow \boxed{x(t)} \longrightarrow y(t)$$

$$x(t) = \lim_{\Delta\tau \rightarrow 0} \tilde{x}(t)$$

$$x(t) = \int_{-\infty}^{+\infty} x(\tau) \delta(t-\tau) d\tau$$

