
SIGNALS & SYSTEMS

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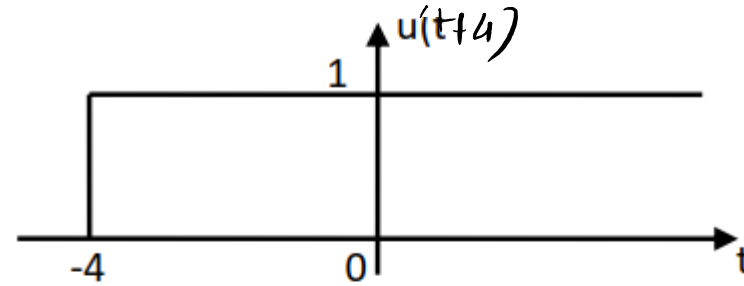
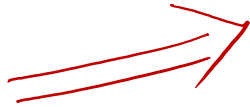
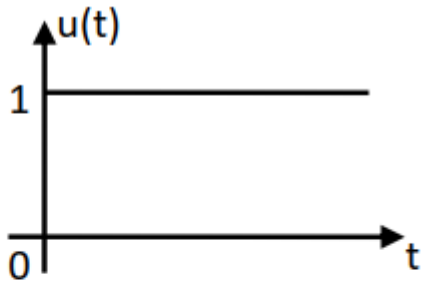
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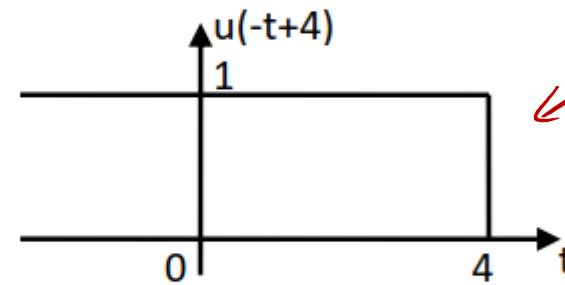
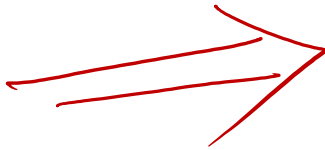
Sketch the following signals

a) $x(t) = u(t+4) u(-t+4)$

Always draw $u(t)$

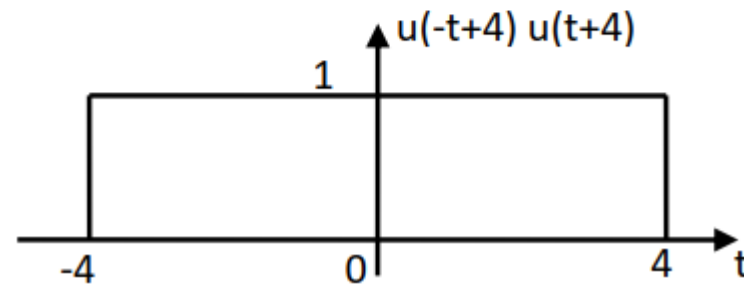
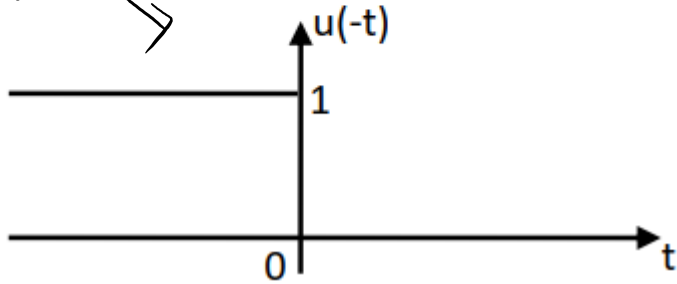


Time shifting $u(t+4)$
Advanced



Time shifting
 $u(-t+4)$
Delayed

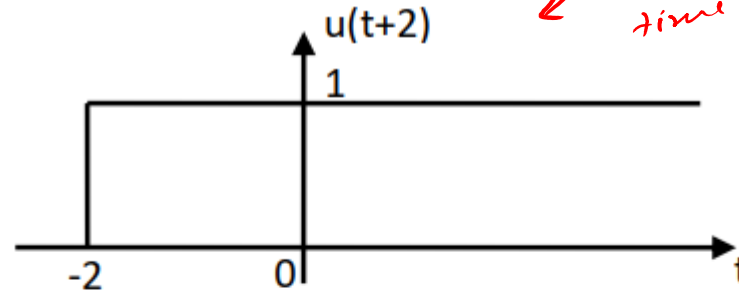
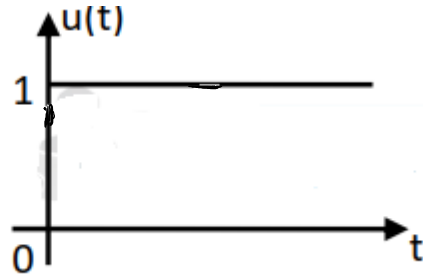
Folding of
 $u(t)$



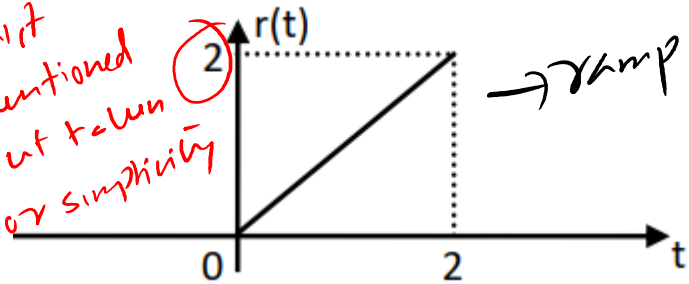
b) $x(t) = r(-t) u(t+2)$

multiplication operation

*Advanced signal
time shifting by 2 units
 $u(t+2)$*

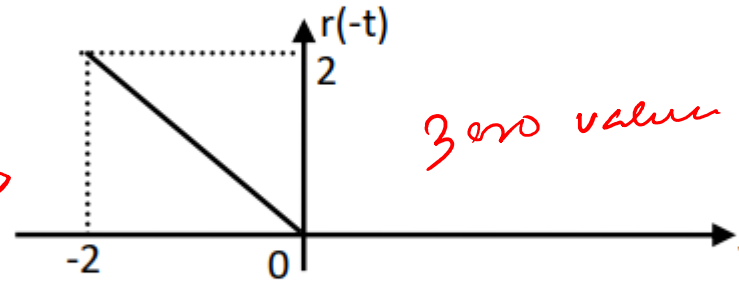


Not mentioned but taken for simplicity

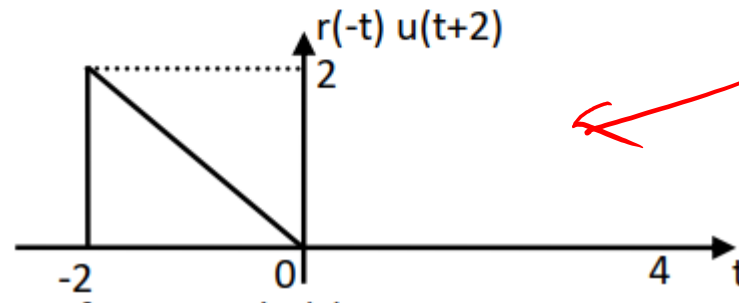


ramp signal

folding of $r(t)$



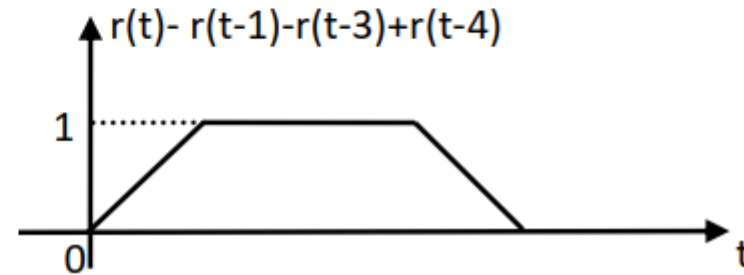
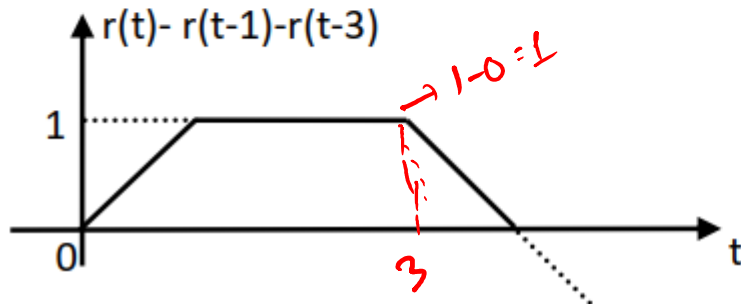
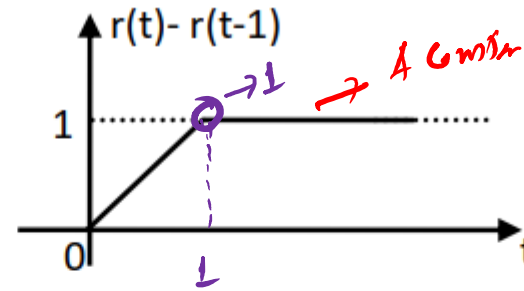
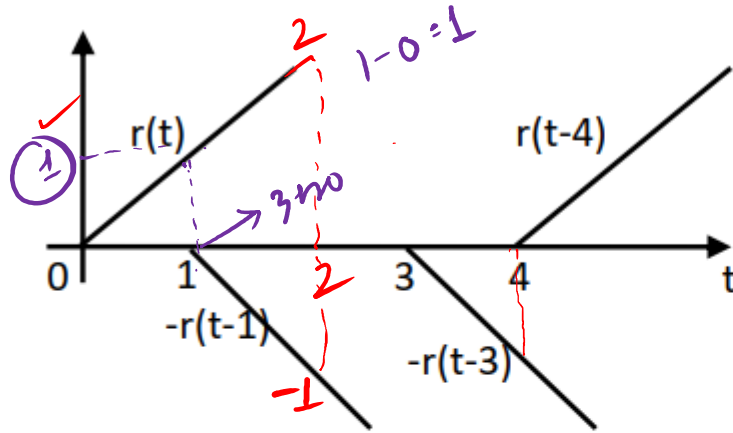
zero value



c) $x(t) = \underline{r(t)} - r(t-1) - r(t-3) + r(t-4)$

$r(t-1)$ → perform amplitude scaling to get $-2r(t-1)$

say 1



Causal and Non-causal System : A system is said to be **causal** if its output $y(t)$ at any arbitrary time t_0 depends only on the values of its input $x(t)$ for $t \leq t_0$. In the causal system the output does not begin before the input signal is applied. If the independent variable represents time, a system must be causal in order to be physically realizable. Noncausal systems can sometimes be useful in practice, however, as the independent variable need not always represent time.

Determine whether the following systems are causal or non-causal

- | | | |
|-------------------------------|-------------------------|-----------------------------|
| (i) $y(t) = 0.2x(t) - x(t-1)$ | (ii) $y(t) = 0.8x(t-1)$ | (iii) $y(n) = x(n-1)$ |
| (iv) $y(t) = x(t+1)$ | (v) $y(n-2) = x(n)$ | (vi) $y(n) = x(n) - x(n+1)$ |



Solution:

(i) Given that $y(t) = 0.2x(t) - x(t-1)$

In the above equation put $t=0$ then $y(0) = 0.2x(0) - x(-1)$

put $t=1$ then $y(1) = 0.2x(1) - x(0)$

Since the output $y(t)$ depends on the present and the past input values of $x(t)$, the system is **causal**

(ii) Given that $y(t) = 0.8x(t-1)$

In the above equation put $t=0$ then $y(0) = 0.8x(-1)$

put $t=1$ then $y(1) = 0.8x(0)$

Since the output $y(t)$ depends on only the past input values of $x(t)$, the system is **causal**

(iii) Given that $y(n) = x(n-1)$

In the above equation put $n=0$ then $y(0) = x(-1)$

put $n=1$ then $y(1) = x(0)$

Since the output $y(n)$ depends on only the past input values of $x(n)$, the system is **causal**



(iv) Given that $y(t) = x(t+1)$

In the above equation put $t=0$ then $y(0) = x(1)$

put $t=1$ then $y(1) = x(2)$

Since the output $y(t)$ depends on future input values of $x(t)$, the system is **non-causal**

(v) Given that $y(n-2) = x(n)$

In the above equation put $n=0$ then $y(-2) = x(0)$

put $n=1$ then $y(-1) = x(1)$

Since the output $y(t)$ depends on future input values of $x(t)$, the system is **non-causal**

(vi) Given that $y(n) = x(n) - x(n+1)$

In the above equation put $n=0$ then $y(0) = x(0) - x(1)$

put $n=1$ then $y(1) = x(1) - x(2)$

Since the output $y(t)$ depends on the present and the future input values of $x(t)$, the system is **non-causal**

