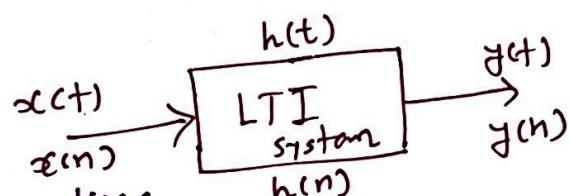


## Convolution

- It is a mathematical operation which express input-output relation of an LTI system.
- Convolution is widely used in many fields like probability & statistics.
- Convolution of two signals produces a third signal.
- By using convolution, we can find the zero state response.



- For continuous time

$$\begin{aligned} y(t) &= x(t) * h(t) \\ &= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \\ &= \int_{-\infty}^t x(t-\tau) h(\tau) d\tau \end{aligned}$$

$$\rightarrow y(\omega) = x(\omega) h(\omega)$$

- For discrete signal

$$\begin{aligned} y(n) &= x(n) * h(n) \\ &= \sum_{k=-\infty}^{\infty} x(n) h(n-k) \\ &= \sum_{k=0}^{\infty} x(n-k) h(n) \end{aligned}$$

# Properties of Convolution

## ① Commutative property

$$x_1(t) * x_2(t) = x_2(t) * x_1(t)$$

## ② Distributive property

$$x_1(t) * [x_2(t) + x_3(t)] = x_1(t) * x_2(t) + x_1(t) * x_3(t)$$

## ③ Associative property

$$x_1(t) * [x_2(t) * x_3(t)] = [x_1(t) * x_2(t)] * x_3(t)$$

## ④ Shifting property

$$- x_1(t) * x_2(t) = z(t)$$

$$- x_1(t) * x_2(t-t_1) = z(t-t_1)$$

$$- x_1(t-t_1) * x_2(t) = z(t-t_1)$$

$$- x_1(t-t_1) * x_2(t-t_2) = z(t-t_1-t_2)$$

$$\text{if } x(t) * j(t) = z(t)$$

$$\underline{\underline{=}} \quad x(t-3) * j(t+1)$$

$$= z(t-3+1)$$

$$= z(t-2)$$

## ⑤ Convolution with impulse

$$- x(t) * \delta(t) = x(t)$$

$$- x(t) * \delta(t-t_1) = x(t-t_1)$$

$$\underline{\underline{*}} \quad \boxed{\delta(at) = \frac{1}{|a|} \delta(t)}$$

$$\underline{\underline{e.g.}} \quad x(t) * \delta(t-2)$$

$$= x(t-2)$$

$$\underline{\underline{e.g.}} \quad x(t-2) * \delta(t+1)$$

$$= x(t-2+1)$$

$$= x(t-1)$$

$$\underline{\underline{e.g.}} \quad x(t) * \delta(2t-6)$$

$$= x(t) * \delta(2(t-3))$$

$$= x(t) * \frac{1}{2} \delta(t-3)$$

$$= \frac{1}{2} [x(t) * \delta(t-3)]$$

$$= \frac{1}{2} x(t-3)$$

## Additional properties of Convolution

$$\rightarrow x(t) * h(t) = y(t)$$

$$\rightarrow \frac{d y(t)}{dt} = \frac{d x(t)}{dt} * h(t) = x(t) * \frac{d h(t)}{dt}$$

$$\rightarrow u(t) * u(t) = x(t)$$

$$\rightarrow u(t-t_1) * u(t-t_2) = x(t-(t_1+t_2))$$

$$\rightarrow y(-t) = x(-t) * h(-t)$$

$$\rightarrow \frac{d^n x(t)}{dt^n} * \frac{d^m h(t)}{dt^m} = \frac{d^{n+m} y(t)}{dt^{n+m}}$$

## Scaling of Convolution

- When Input & Impulse signals are scaled by  $\alpha$  then Output will be

$$\Rightarrow x(t) * h(t) = y(t)$$

$$\Rightarrow x(\alpha t) * h(\alpha t) = \frac{1}{|\alpha|} y(\alpha t)$$

- $y(t) = \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau$

- $x(\alpha t) * h(\alpha t) = \int_{-\infty}^{\infty} x(\alpha \tau) h(\alpha t - \alpha \tau) d\tau$   
 $= \int_{-\infty}^{\infty} x(\alpha \tau) h(\alpha t - \alpha \tau) d\tau$

- If  $\alpha \tau = \lambda \Rightarrow \alpha d\tau = d\lambda$

$$\Rightarrow d\tau = \frac{d\lambda}{\alpha}$$

$$= \int_{-\infty}^{\infty} x(\alpha \tau) \frac{h(\alpha t - \lambda)}{\alpha} d\lambda$$

$$= \frac{1}{\alpha} \int_{-\infty}^{\infty} x(\lambda) h(\alpha t - \lambda) d\lambda$$

$$= \boxed{\frac{1}{\alpha} y(\alpha t)}$$

$$\Rightarrow x(\alpha t) * h(\alpha t)$$

## Area of Convolved Signal

- If Input signal  $x(t)$  is having area  $A_i$
- If System  $h(t)$  is having area  $A_h$
- then area of convoluted signal

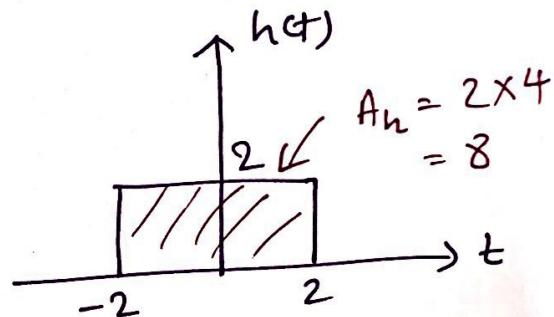
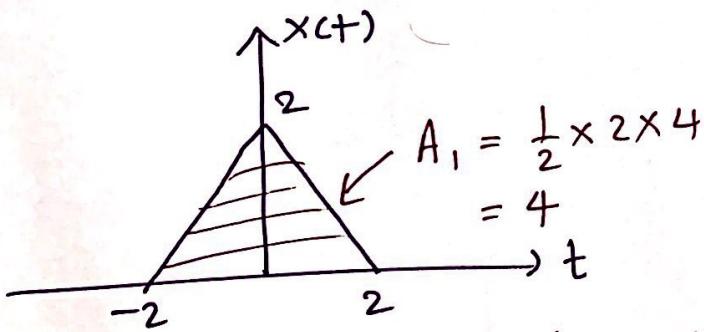
$$A = A_i A_h$$

$$\begin{aligned} \rightarrow y(t) &= x(t) * h(t) \\ &= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \end{aligned}$$

→ to get area (integrate yet)

$$\begin{aligned} \int y(t) dt &= \iint x(\tau) h(t-\tau) d\tau \\ &= \int x(\tau) d\tau \int h(t-\tau) d\tau \end{aligned}$$

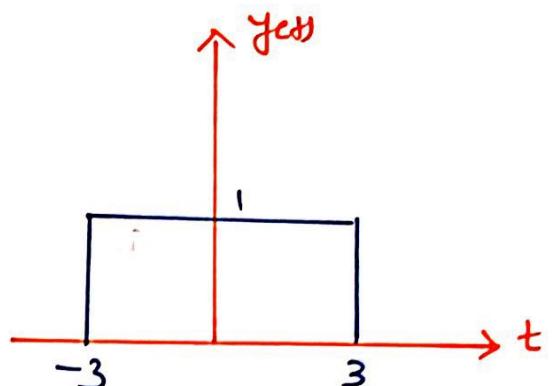
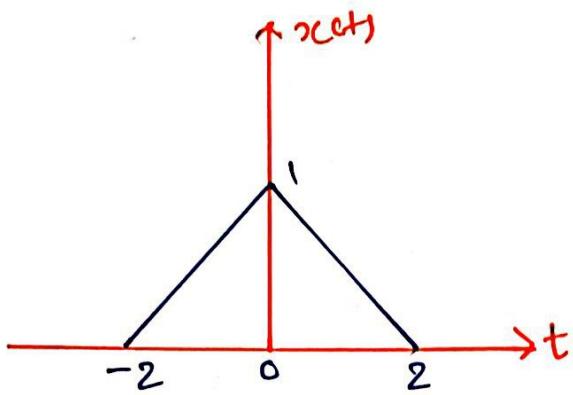
$$A = A_i A_h$$



→ Convolved signal  $y(t) = x(t) * h(t)$ .

$$\rightarrow \text{Area of } y(t) = A_i A_h = 4 \times 8 = 32$$

## Limits of Convolved Signal

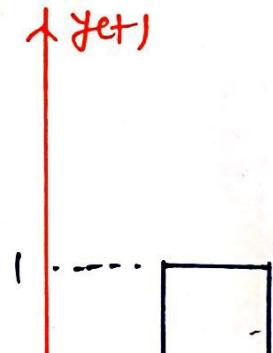
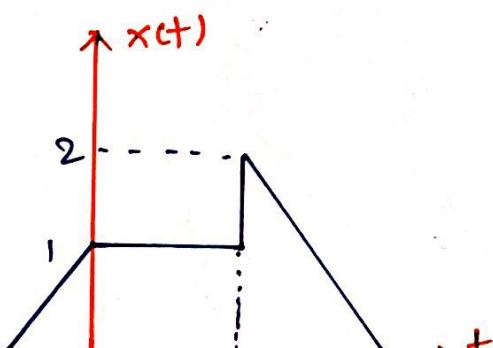


$$\rightarrow z(t) = x(t) * y(t)$$

$$\rightarrow \text{Lower limit of } z(t) = -2 - 3 = -5$$

$$\rightarrow \text{Upper limit of } z(t) = 2 + 3 = 5$$

$$\text{Limits of } z(t) \rightarrow \boxed{-5 < t < 5}$$



## Convolution using Slide & Shift method

$$\rightarrow x(t) = t^2 + 2t + 1$$

$$y(t) = t^2 + 3t + 4$$

Find  $z(t) = x(t) * y(t)$  using slide & shift method

$$\rightarrow z(t) = x(t) * y(t)$$

$$= \int_{-\infty}^{\infty} x(\tau) y(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} x(t-\tau) y(\tau) d\tau$$

	$t^2$	$2t$	1	
$4$	$3t$	$t^2$		$= t^4$
$4$	$3t$	$t^2$		$= 3t^3 + 2t^3 = 5t^3$
$4$	$3t$	$t^2$		$= 4t^2 + 6t^2 + t^2 = 11t^2$
$4$	$3t$	$t^2$		$= 8t + 3t = 11t$
$4$	$3t$	$t^2$		$= 4$

$$\rightarrow z(t) = x(t) * y(t)$$

$$= t^4 + 5t^3 + 11t^2 + 11t + 4$$

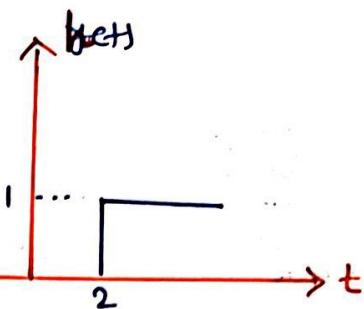
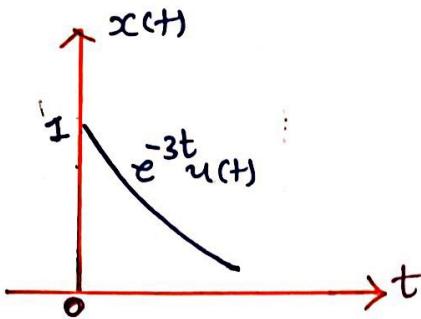
$$\rightarrow x(t) = 3t^3 + t + 1$$

$$y(t) = t^2 + t + 2$$

	$3t^3$	$0$	$t$	1	
$2$	$t$	$t^2$			$= 3t^5$
$2$	$t$	$t^2$			$= 3t^4$
$2$	$t$	$t^2$			$= 6t^3 + t^3 = 6t^3$
$2$	$t$	$t^2$			$= t^2 + t^2 = 2t^2$
$2$	$t$	$t^2$			$= 2t + t = 3t$
$2$					$= 2$

$$z(t) = \frac{x(t) * y(t)}{3t^5 + 3t^4 + 6t^3 + 2t^2 + 3t + 2}$$

## Convolution by Image method



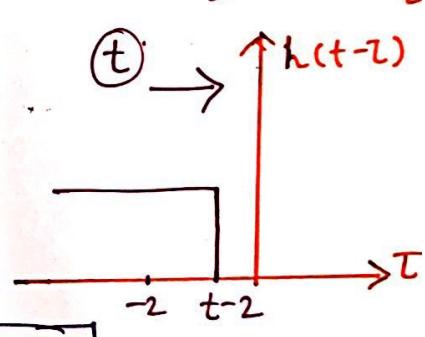
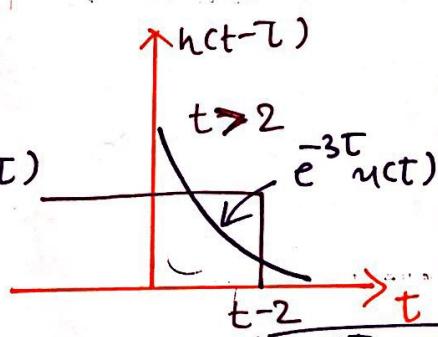
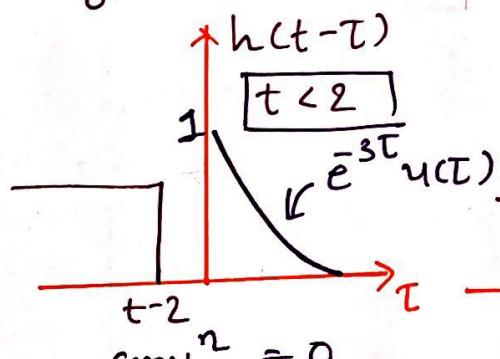
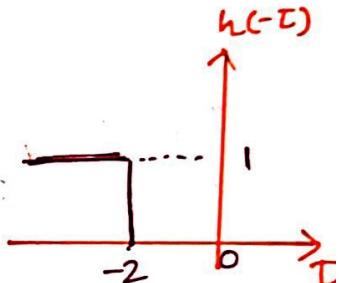
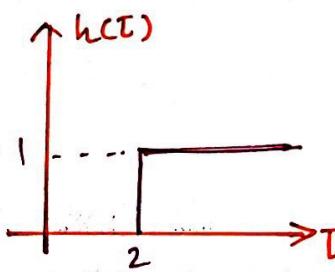
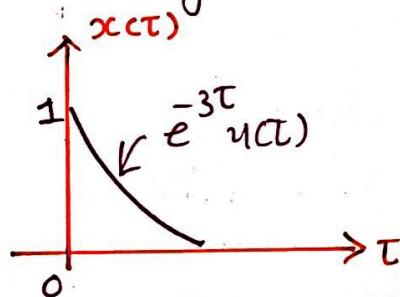
Find Convolution using Image method

$$\rightarrow z(t) = x(t) * h(t)$$

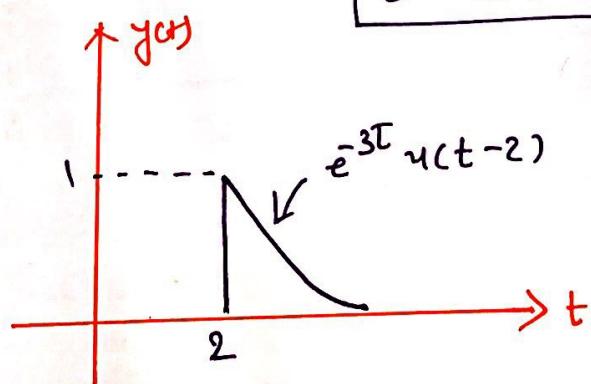
$\rightarrow$  limits of  $z(t)$

$$\begin{aligned} &= \text{sum of lower limit } < t < \text{sum of upper limit} \\ &= 0 + 2 < t < \infty + \infty \\ &= [2 < t < \infty] \end{aligned}$$

Represent signal in terms of  $\tau$

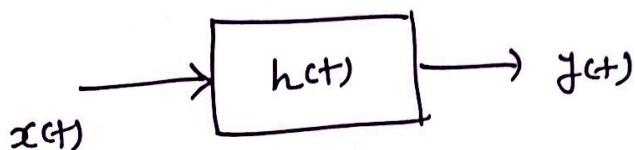


$$\text{Conv.}^n = 0$$



Example of convolution based on distributive property.

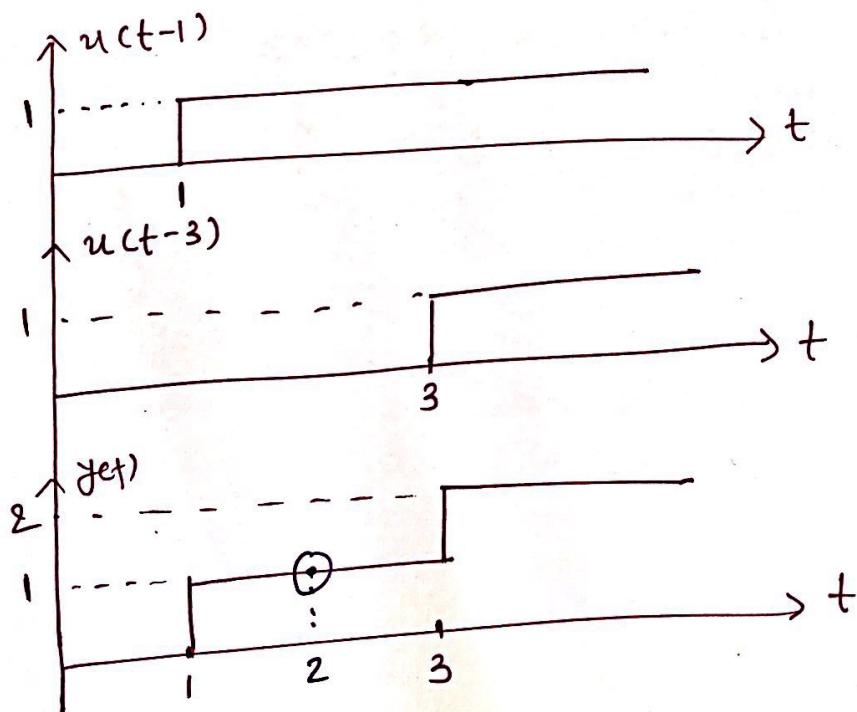
The impulse response of continuous system is given by  
 $h(t) = \delta(t-1) + \delta(t-3)$ . The value of step response at  
t = 2 sec is ①



$$\rightarrow u(t) = u(t)$$

$$h(t) = \delta(t-1) + \delta(t-3)$$

$$\begin{aligned}\rightarrow y(t) &= u(t) * h(t) \\ &= u(t) * [\delta(t-1) + \delta(t-3)] \\ &= u(t) * \delta(t-1) + u(t) * \delta(t-3) \\ &= u(t-1) + u(t-3)\end{aligned}$$



## Convolution example

Given  $z(t) = \int_{-\infty}^{\infty} x(t-\tau+b) h(\tau) d\tau$ .

express  $z(t)$  in terms of  $y(t) = x(t) * h(t)$

$$\rightarrow y(t) = x(t) * h(t)$$

$$= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$y(t) = \int_{-\infty}^{\infty} x(t-\tau) h(\tau) d\tau \quad \checkmark \quad -①$$

$$\rightarrow z(t) = \int_{-\infty}^{\infty} x(t-\tau+b) h(\tau) d\tau$$

$$\begin{aligned} t-\tau &= \lambda \quad \rightarrow \tau = t-\lambda \\ d\tau &= d\lambda \end{aligned}$$

$$= \int_{-\infty}^{\infty} x(-(t-\lambda)+b) h(\lambda) d\lambda$$

$$= \int_{-\infty}^{\infty} x((t+b)-\lambda) h(\lambda) d\lambda \quad -②$$

$$\rightarrow \text{Compare eqn } ① \text{ & } ② \Rightarrow \boxed{z(t) = y(t+b)}$$

Example of Convolution based on properties of Convolution

$$\text{IF } x(t) = u(t-3) - u(t-5)$$

$$h(t) = e^{-3t} u(t)$$

Find  $\frac{d x(t)}{dt} * h(t)$ .

$$\rightarrow \frac{d x(t)}{dt} = \frac{d [u(t-3) - u(t-5)]}{dt}$$
$$= \delta(t-3) - \delta(t-5)$$

$$\rightarrow h(t) = e^{-3t} u(t)$$

$$\rightarrow \frac{d(x(t))}{dt} * h(t) = [\delta(t-3) - \delta(t-5)] * e^{-3t} u(t)$$
$$= \delta(t-3) * e^{-3t} u(t) - \delta(t-5) * e^{-3t} u(t)$$
$$= \frac{\delta(t-3)}{e^{-3(t-3)}} u(t-3) - \frac{\delta(t-5)}{e^{-3(t-5)}} u(t-5)$$

Example based on Area of Convolution and Reversing Convolution

Find area of given convoluted signal

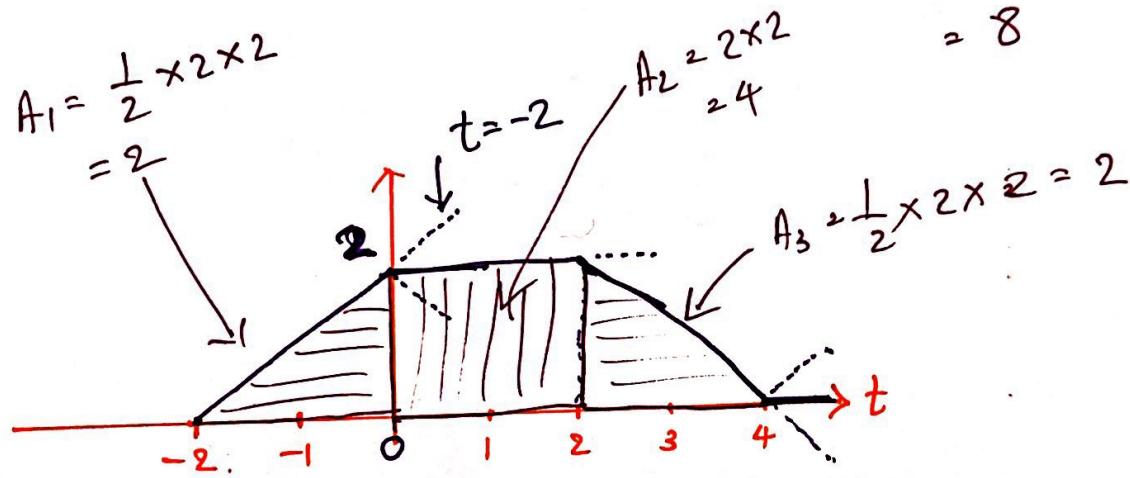
$$[u(t+1) - u(t-3)] * [u(t+1) - u(t-1)]$$

$$= u(t+1) * u(t+1) - u(t+1) * u(t-1) - u(t-3) * u(t+1) + u(t-3) * u(t-1)$$

$$= \boxed{[x(t+2) - x(t) - x(t-2) + x(t-4)]}$$

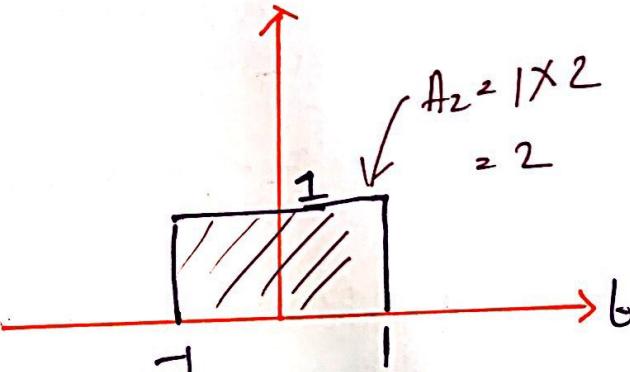
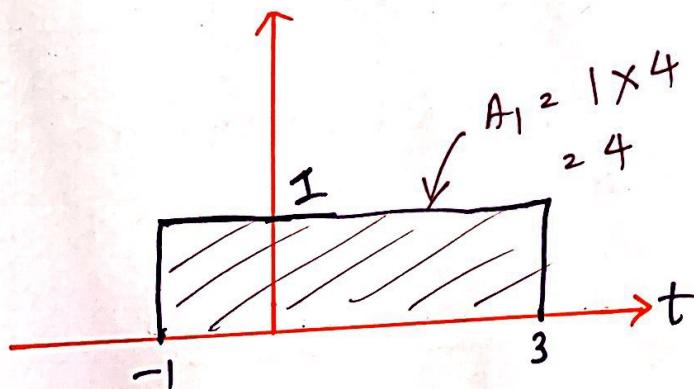
$$\text{total Area} = A_1 + A_2 + A_3 \\ = 2 + 4 + 2$$

$$= 8$$



$$u(t+1) - u(t-3)$$

$$u(t+1) - u(t-1)$$



→ Area of convoluted signal

$$A = A_1 A_2$$

$$= 4 \times 2 = 8$$

- linear convolution for discrete signal

$$x(n) = \{1, 2, 3, 4\} \text{ and } h(n) = \{1, 1, -1, 1\}$$

Find linear convolution of above signal

$$- y(n) = x(n) * h(n)$$

$$- \text{total samples} = m+n-1 = 4+4-1 = 7$$

$$\begin{array}{c|cccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 1 & 2 & 3 & 4 \\ 1 & 1 & 2 & 3 & 4 \\ -1 & -1 & -2 & -3 & -4 \\ 1 & 1 & 2 & 3 & 4 \end{array} \quad y(n) = x(n) * h(n)$$
$$y = \{1, 3, 4, 6, 3, -1, 4\}$$

Find linear convolution of given signals

$$x(n) = \{1, 3, 2, 1\}$$

$$y(n) = \{1, 2\}$$

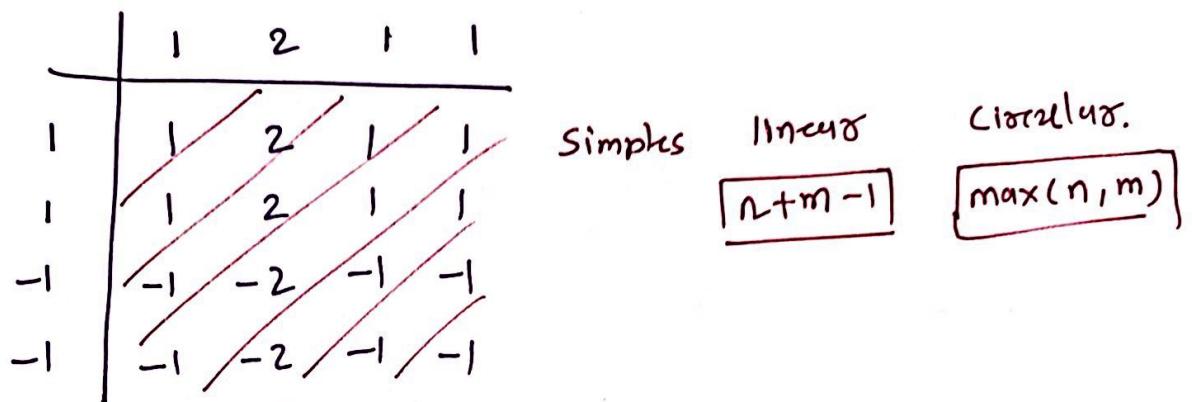
$$- z(n) = x(n) * y(n)$$

$$- \text{total samples} = m+n-1 = 4+2-1 = 5$$

$$\begin{array}{c|cccc} & 1 & 3 & 2 & 1 \\ \hline 1 & 1 & 3 & 2 & 1 \\ 2 & 2 & 6 & 4 & 2 \end{array} \quad z(n) = x(n) * y(n)$$
$$= \{1, 5, 8, 5, 2\}$$

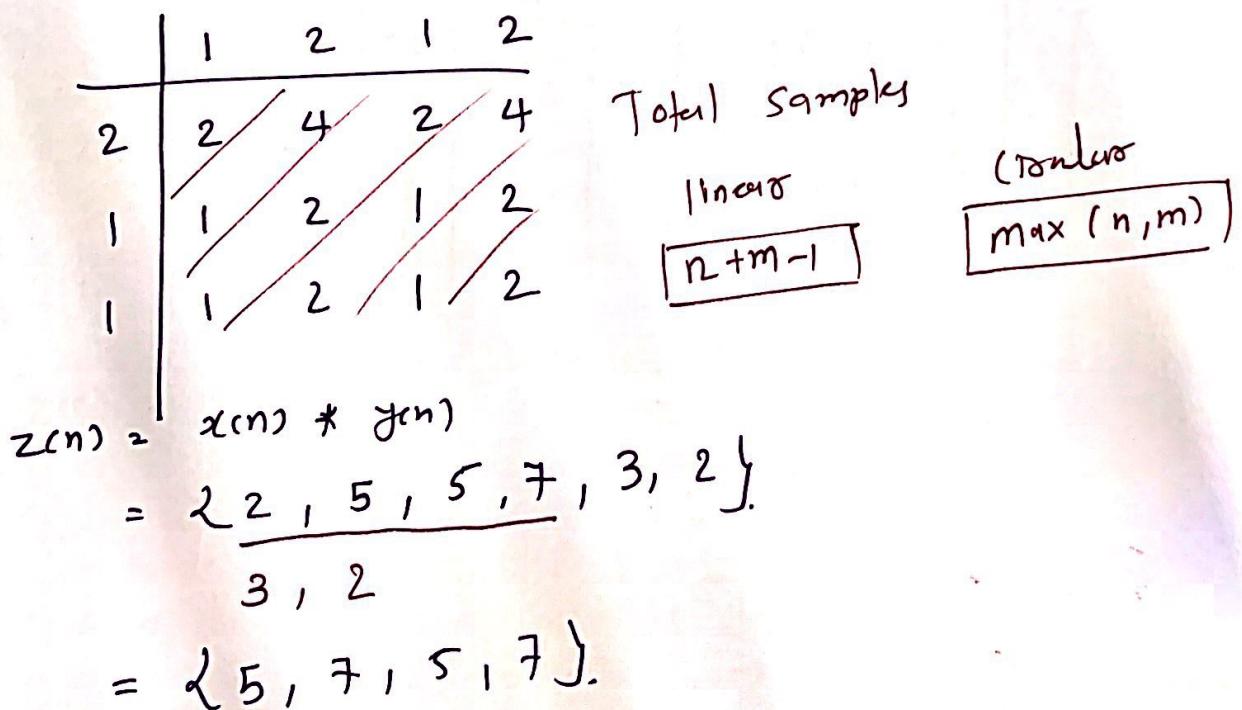
## \* Circular Convolution or Periodic Convolution

- $x(n) = \{1, 2, 1, 1\}$  &  $y(m) = \{1, 1, -1, -1\}$   
Find Periodic Convolution of above signal



$$\begin{aligned}
 - z(n) &= x(n) * y(n) \\
 &= \underbrace{\{1, 3, 2, -1, -2, -2, -1\}}_{-2, -2, -1} \\
 &= \{-1, 1, 1, -1\}
 \end{aligned}$$

- $x(n) = \{1, 2, 1, 2\}$  &  $y(m) = \{2, 1, 1\}$   
Find Circular Convolution of above signal.



## Circular Convolution by matrix method

- Find Circular Convolution of given signals

$$x(n) = \{1, 1, -1, 2\}$$

$$h(n) = \{1, 2, 3, 4\}$$

$$= \begin{bmatrix} 1 & 2 & -1 & 1 \\ 1 & 1 & 2 & -1 \\ -1 & 1 & 1 & 2 \\ 2 & -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 1+4-3+4 \\ 1+2+6-4 \\ -1+2+3+8 \\ 2-2+3+4 \end{bmatrix} = \begin{bmatrix} 6 \\ 5 \\ 12 \\ 7 \end{bmatrix}$$

$$\rightarrow z(n) = x(n) * h(n)$$
$$= \{6, 5, 12, 7\}.$$

- Find Circular convolution by matrix method for given signals

$$x(n) = \{1, 2, 1, 1\}$$

$$y(n) = \{2, 2, 1, 3\}$$

$$= \begin{bmatrix} 1 & 1 & 1 & 2 \\ 2 & 1 & 1 & 1 \\ 1 & 2 & 1 & 1 \\ 1 & 1 & 2 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 2+2+1+6 \\ 4+2+1+3 \\ 2+4+1+3 \\ 2+2+2+3 \end{bmatrix} = \begin{bmatrix} 11 \\ 10 \\ 10 \\ 9 \end{bmatrix}$$

$$\Rightarrow z(n) = x(n) * y(n) = \{11, 10, 10, 9\}.$$

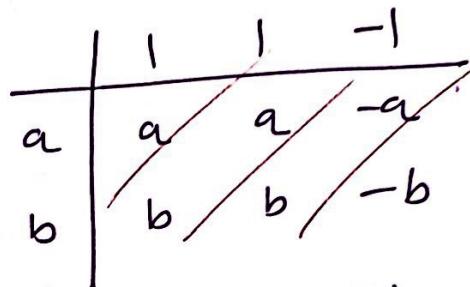
## Deconvolution

If a signal  $x(n) = \{1, 1, -1\}$  is convoluted with an unknown signal & the convolution result is noted as  $\{1, 3, 1, -2\}$ . Find  $h(n)$ .

$$\rightarrow y(n) = x(n) * h(n)$$

$\rightarrow$  In linear convolution total samples

$$\begin{aligned} &= m+n-1 \\ \Rightarrow 4 &= 3+n-1 \\ \Rightarrow n &= 2 \end{aligned}$$



$$\rightarrow h(n) = \{a, b\}$$

$$\rightarrow y(n) = x(n) * h(n) = \{a, b+a, b-a, -b\} \\ = \{1, 3, 1, -2\}$$

$$\rightarrow a = 1, b = 2$$

$$\rightarrow h(n) = \{1, 2\}$$

- Now  $y(n) = x(n) * h(n)$ .

$$\text{IF } y(n) = \{2, 1, 3, 1, 1\}$$

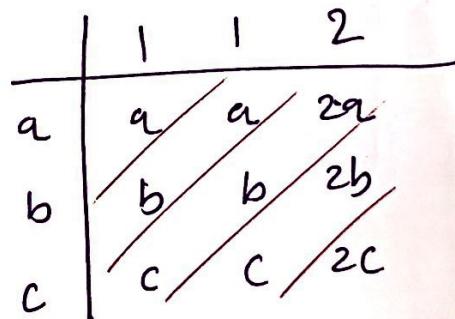
$x(n) = \{1, 1, 2\}$ , then find  $h(n)$

$$\rightarrow \text{total samples} = m+n-1$$

$$\Rightarrow 5 = 3+n-1$$

$$\Rightarrow n = 3$$

$$\rightarrow h(n) = \{a, b, c\}.$$



$$\rightarrow \text{If } y(n) = x(n) * h(n)$$

$$= \{a, b+a, c+b+2a, (+2b, 2c)\}.$$

$$= \{2, 1, 3, \underline{\underline{4, 1}}\}$$

$$\rightarrow a = 2, b = -1, c + b + 2a = 3$$

$$\Rightarrow c = 3 - b - 2a \\ = 3 + 1 - 4 = 0$$

$\rightarrow h(n)$  can not be calculated as ITS in worst.

## Division method for deconvolution

- If  $y(n) = x(n) * h(n)$

where  $x(n) = \{1, 1, -1\}$

$y(n) = \{1, 3, 1, -2\}$

Find  $h(n)$ .

$$\begin{array}{r} 1 + 2x \\ \hline 1 + x - x^2 \Big| 1 + 3x + x^2 - 2x^3 \\ - 1 - x + x^2 \\ \hline 0 + 2x + 2x^2 - 2x^3 \\ - 2x + 2x^2 - 2x^3 \\ \hline 0 \end{array}$$

→ As remainder is 0

→  $h(n) = \{1, 2\}$ .