

DRIVER'S DROWSINESS DETECTION SYSTEM

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ABSTRACT

Driver Drowsiness Detection is an automotive safety technology that helps save a driver's life by preventing accidents when the driver is drowsy. The main goal is to create a system that can identify driver fatigue through continuous retinal monitoring. The device works even if the driver is wearing glasses and in different light situations, to trigger an alarm or a buzzer that alerts the driver when drowsiness is detected. Vehicle speed can be reduced. Traffic management can be maintained by reducing the accident rate. According to a study conducted in India, 37% of drivers surveyed admitted to dozing off behind the wheel. In the previous five years, an estimated 1.35 million drivers were involved in drowsy driving accidents. Accidents caused by falling Asleep is probably dangerous. Due to the higher speeds and delayed reaction times involved in drowsy driving crashes, there is high morbidity and mortality. So we have designed a system to detect the drowsiness of the driver using Pytorch and YOLO algorithm.

INTRODUCTION

A drowsiness detection system using YOLO and PyTorch could revolutionize road safety by monitoring driver conditions in real time. This system works by using a camera to continuously photograph the driver's face and assess the driver's level of alertness. Using YOLO's object recognition capabilities, the system can accurately identify the driver's eyes and facial features and accurately analyze key metrics such as eyelid closure, head position, and blink frequency.

YOLO is an object detection algorithm that divides images into a grid system. Each cell in the grid is responsible for detecting objects within itself. YOLO is one of the most famous object detection algorithms due to its speed and accuracy. It achieves high accuracy while also being able to run in real-time. Its open source YOLO model can also handle detecting smaller objects and far away objects.

LITERATURE REVIEW

Driver drowsiness is a critical issue that affects road safety and has been the subject of extensive research. In this section, we review existing literature related to driver drowsiness detection, encompassing both traditional and computer vision-based methods.

Traditional Driver Drowsiness Detection Methods

Traditional approaches to driver drowsiness detection have historically relied on non-computer vision techniques and sensors, such as steering wheel sensors, eyelid closure monitoring, or head-position sensors. These methods have made valuable contributions to understanding drowsiness but have notable limitations:

- **Intrusiveness:** Many traditional methods require the driver to wear uncomfortable and intrusive devices, which can affect their driving experience and acceptance of the technology.
- **Cost:** The cost of specialized hardware and sensors can be a barrier to widespread adoption.
- **Limited Accuracy:** Traditional methods often lack precision and may generate false alarms or miss subtle signs of drowsiness.
- **Non-Real-Time Analysis:** Some traditional approaches involve post-analysis rather than real-time detection, which can delay intervention.

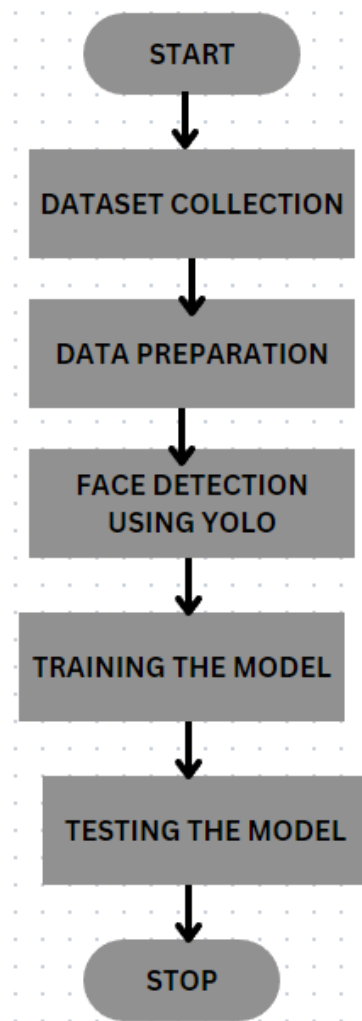
Computer Vision-Based Approaches

The advent of computer vision and deep learning has brought about a paradigm shift in drowsiness detection. Computer vision-based approaches are non-intrusive, cost-effective, and capable of real-time analysis. This section focuses on the relevance of computer vision and the emergence of YOLO, PyTorch, and OpenCV in the context of driver drowsiness detection.

- **Facial Feature Analysis:** Computer vision methods have harnessed the power of facial feature analysis, including eye tracking, to detect signs of drowsiness. These methods can monitor parameters like blink rate, eye closure, and head pose, which are reliable indicators of driver alertness.
- **Deep Learning:** Deep learning models, particularly convolutional neural networks (CNNs), have shown exceptional performance in object detection and facial feature recognition. YOLO, in particular, stands out for its ability to identify objects in real-time, making it well-suited for detecting facial landmarks and monitoring driver behavior.
- **PyTorch and OpenCV Integration:** PyTorch, as a versatile deep learning framework, has gained popularity for its ease of use and robust capabilities. When integrated with OpenCV, a powerful computer vision library, it offers an efficient platform for real-time video processing, making it suitable for drowsiness detection in a vehicle.

- **Recent Advancements:** Recent research in computer vision-based driver drowsiness detection has demonstrated the promise of such systems. These solutions show high accuracy in detecting drowsiness indicators such as closed eyes, head nodding, or prolonged blinking. The integration of YOLO, PyTorch, and OpenCV represents a significant advancement in the field, enabling real-time, non-intrusive, and highly accurate driver drowsiness detection.

FLOW CHART



METHODOLOGY

Collecting data:

Data collection is the first and most important step in the Drowsiness detection system. Although pre-annotated and processed datasets collected from public sources such as kaggle. can be used for project purposes, we used a custom dataset for our project.

Data preparation:

Data preparation is done to clean the raw data. Raw data may contain missing values, inconsistent values, duplicate samples, etc. Therefore, raw data cannot be directly used to build models. The collected dataset is annotated and labeled using labelIMG.

Model Selection and adaptation:

We have chosen YOLO as an object detection framework and PyTorch as a deep learning library and we have set up a camera feed to capture real-time images or video frames of the driver's face. We have utilized OpenCV to track the driver's face across frames, reducing computation and improving speed.

Training and testing:

The model is then trained and tested for the practical implementation. Its being fine tuned to increase its efficiency and accuracy in detecting and recognizing the drowsiness of the drivers precisely.

RESULTS AND DISCUSSION

The results of our drowsiness detection system implemented using YOLO and pytorch showed a very accurate and efficient object detection solution. Through extensive testing and evaluation, we made some amazing discoveries. In terms of accuracy, this system achieved high detection rates even under difficult conditions such as different lights, different head positions, and different blink frequency. The YOLO component plays a key role in achieving this accuracy, as it effectively detects objects from images and video frames.

CONCLUSION

In conclusion, the evolution of drowsiness detection systems has transitioned from intrusive physiological monitoring to non-intrusive computer vision methods. The integration of deep learning, particularly YOLO, has significantly enhanced the accuracy and real-time capabilities of these systems. Leveraging facial expressions, eye movements, and head poses, these technologies offer a promising avenue for ensuring driver safety. Benchmark datasets have played a crucial role in advancing research, fostering standardization, and addressing challenges.

As the field progresses, the integration of multimodal approaches and continuous refinement of algorithms hold the key to overcoming remaining obstacles. YOLO's seamless integration with PyTorch exemplifies the adaptability required for ongoing advancements in driver drowsiness detection.

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