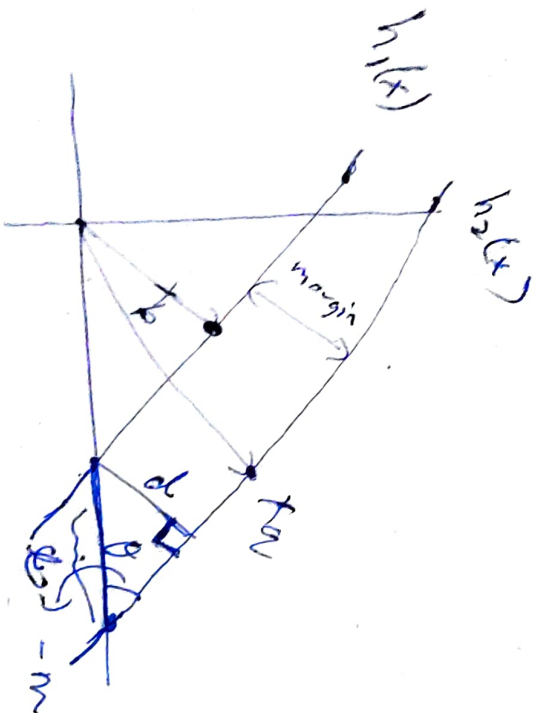


Case I (a). Support vectors  $x_p$  &  $x_a$ .

$x_p(x_{p1}, x_{p2}) \in \text{Class 1}$ ;  $x_a(x_{a1}, x_{a2}) \in \text{Class 2}$

$$h(x) : w_0 + w_1 x_1 + w_2 x_2 = 0$$

Expression of margin b/w parallel lines passing through  $x_p$



$$h_1(x_p) = (w_0)_p + w_1 x_{p1} + w_2 x_{p2} = 0$$

$$\Rightarrow (w_0)_p = -w_1 x_{p1} - w_2 x_{p2}$$

$$h_2(x_a) = (w_0)_a + w_1 x_{a1} + w_2 x_{a2} = 0$$

$$\Rightarrow (w_0)_a = -w_1 x_{a1} - w_2 x_{a2}$$

Then  $h_1(x) = w_1(x_1 - x_{p1}) + w_2(x_2 - x_{p2})$

$$h_2(x) = w_1(x_1 - x_{a1}) + w_2(x_2 - x_{a2})$$

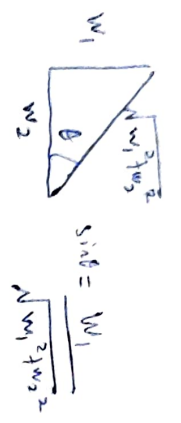
Then intercepts of  $h_1(x)$  &  $h_2(x)$  are

$$\text{margin}(h_1(x)) = \frac{w_1 x_{a1} + w_2 x_{a2}}{w_2} \quad \& \quad \text{margin}(h_2(x)) = \frac{w_1 x_{a1} + w_2 x_{a2}}{w_2}$$

$$\therefore d = \left| \frac{w_1 x_{a1} + w_2 x_{a2} - w_1 x_{b1} - w_2 x_{b2}}{w_2} \right|$$

~~also~~  $\tan \theta = -m = \frac{w_1}{w_2}$

$$d = d \sin \theta = \left| \frac{w_1}{w_2} (x_{a1} - x_{b1}) + (x_{a2} - x_{b2}) \right| \sin \theta$$



$$\sin \theta = \frac{w_1}{\sqrt{w_1^2 + w_2^2}}$$

$$\therefore d = \left| \frac{w_1}{w_2} (x_{a1} - x_{b1}) + (x_{a2} - x_{b2}) \right| \frac{w_1}{\sqrt{w_1^2 + w_2^2}}$$

b) Best margin slope. ( $\therefore$  Hard margin classification) given in previous question.

Feeder is  $\max_{w_1, w_2} d = \max_{w_1, w_2} \left| \frac{w_1}{w_2} (x_{a1} - x_{b1}) + (x_{a2} - x_{b2}) \right| \frac{w_1}{\sqrt{w_1^2 + w_2^2}}$

parameters are  $w_1$  &  $w_2$  &  $x_{a1}, x_{a2}$  support vectors.  $x_{a1}$  &  $x_{a2}$  are fixed.

Also constraint.

$$y_i (w_0 + w_1 x_{i1} + w_2 x_{i2}) \geq 1 \quad \forall i \in \{1, 2, \dots, n\}$$

Using Lagrange Multiplier.  $\lambda$  is some multiplier

~~also~~  $\lambda = \frac{1}{2d^2}$  ~~is some multiplier~~

Using Lagrange Multiplier.

$$\lambda = d - \sum_{i=1}^n \lambda_i (y_i (w_0 + w_1 x_{i1} + w_2 x_{i2}))$$

$$\mathcal{L} = \text{cost}$$

$$\left| \frac{w_1}{w_2} (x_{a1} - x_{b1}) + (x_{a2} - x_{b2}) \right| \frac{w_1}{\sqrt{w_1^2 + w_2^2}} - \sum_{i=1}^m \lambda_i (y_i (w_0 + w_1 x_{1i} + w_2 x_{2i}))$$

$$\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial}{\partial w_1} \left( \frac{w_1}{\sqrt{w_1^2 + w_2^2}} (x_{a1} - x_{b1}) + (x_{a2} - x_{b2}) \right)$$

Assume  $\frac{w_2}{w_1}$  distance of  $h_2(x)$  from origin  $>$  distance of  $h_1(x)$  from origin

This removes mod |

$$\mathcal{L} = \frac{w_1^2}{w_2 \sqrt{w_1^2 + w_2^2}} (x_{a1} - x_{b1}) + w_1 \frac{(x_{a2} - x_{b2})}{\sqrt{w_1^2 + w_2^2}} - \sum_{i=1}^m \lambda_i (y_i (w_0 + w_1 x_{1i} + w_2 x_{2i}))$$

to differentiate substitute first part.

with  $\tan \theta = \frac{w_1}{w_2}$  and apply chain rule

$$\mathcal{L} = \tan \theta (x_{a1} - x_{b1}) + (x_{a2} - x_{b2}) \sin \theta - \sum_{i=1}^m \lambda_i (y_i (w_0 + w_1 x_{1i} + w_2 x_{2i}))$$

$$\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial \mathcal{L}}{\partial \theta} \frac{\partial \theta}{\partial w_1} = \frac{\sec^2 \theta}{\sec^2 \theta} (x_{a1} - x_{b1}) \sin \theta \frac{\partial \theta}{\partial w_1} + (\tan \theta (x_{a1} - x_{b1}) + (x_{a2} - x_{b2})) \cos \theta \frac{\partial \theta}{\partial w_1} - \sum_{i=1}^m \lambda_i (y_i (x_{1i})) = 0 \quad \text{--- (1)}$$

$$\text{Now } \frac{\partial \theta}{\partial w_1} = \frac{\partial}{\partial w_1} \left( \tan^{-1} \left( \frac{w_1}{w_2} \right) \right) = \frac{1}{1 + \left( \frac{w_1}{w_2} \right)^2} = \frac{w_2^2}{w_1^2 + w_2^2}$$

$$\frac{\partial \theta}{\partial w_2} = \frac{\partial}{\partial w_2} \cot^{-1} \left( \frac{w_1}{w_2} \right) = \frac{-1}{1 + \left( \frac{w_1}{w_2} \right)^2} = \frac{-w_1^2}{w_1^2 + w_2^2}$$

Now substituting in (1)

$$\frac{\partial \mathcal{L}}{\partial w_1} = \tan \theta \sec \theta (x_{a1} - x_{b1}) \frac{w_2^2}{w_1^2 + w_2^2} + \left[ \sin \theta (x_{a1} - x_{b1}) + \cos \theta (x_{a2} - x_{b2}) \right] \frac{w_2^2}{w_1^2 + w_2^2} - \sum_{i=1}^m \lambda_i (y_i (x_{1i})) = 0$$

$$\frac{\partial}{\partial w_1} \frac{\partial l}{\partial w_1} = \frac{w_1}{w_2} \frac{\sqrt{w_1^2 + w_2^2}}{w_2} (x_{q1} - x_{p1}) \frac{w_2^2}{w_1^2 + w_2^2} +$$

$$\left[ \frac{w_1}{\sqrt{w_1^2 + w_2^2}} (x_{q1} - x_{p1}) + \frac{w_2}{\sqrt{w_1^2 + w_2^2}} (x_{q2} - x_{p2}) \right] \frac{w_2^2}{w_1^2 + w_2^2}$$

$$- \sum_{i=1}^n \lambda_i (y_i) (x_{p,i}) = 0$$

$$\Rightarrow \frac{w_1}{\sqrt{w_1^2 + w_2^2}} (x_{q1} - x_{p1}) + \frac{w_1 w_2^2}{\sqrt{w_1^2 + w_2^2}} (x_{q1} - x_{p1}) + \frac{w_2^3}{(w_1^2 + w_2^2)^{3/2}} (x_{q2} - x_{p2})$$

$$- \sum_{i=1}^n \lambda_i (y_i) (x_{p,i}) = 0 \quad \text{--- (a)}$$

$$\text{Now } \frac{\partial l}{\partial w_2} = \frac{\partial}{\partial w_2} \left( \frac{1}{2} \theta (x_{q1} - x_{p1}) \sin \theta \right) \frac{\partial \theta}{\partial w_2} + \left( \tan \theta (x_{q1} - x_{p1}) + (x_{q2} - x_{p2}) \cot \theta \right)$$

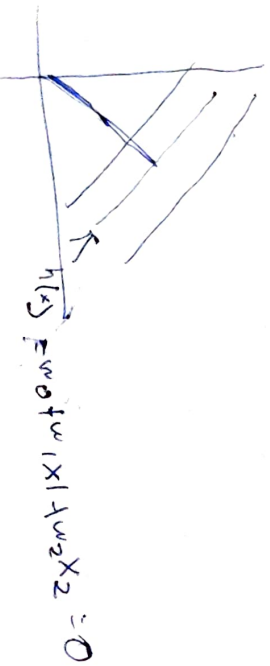
$$- \sum_{i=1}^n \lambda_i y_i w_2 x_{p,i} = 0$$

$$\Rightarrow \frac{w_1}{w_2}$$

$$\frac{\partial l}{\partial \lambda} = 0$$

$$\text{Solve } \frac{\partial l}{\partial w_1}, \frac{\partial l}{\partial w_2} \text{ \& } \frac{\partial l}{\partial \lambda} \text{ to get answers}$$

Case 2:



$$w = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$w \cdot x + b = 0$$

Perp distance of optima hyp plane from origin is

$$M = \frac{-b}{\|w\|} = \frac{-b}{\sqrt{w_1^2 + w_2^2}} = \frac{2}{\sqrt{w_1^2 + w_2^2}}$$

$$M = \frac{-b}{\|w\|} = \frac{-b}{\sqrt{w_1^2 + w_2^2}} = \frac{2}{\sqrt{w_1^2 + w_2^2}}$$