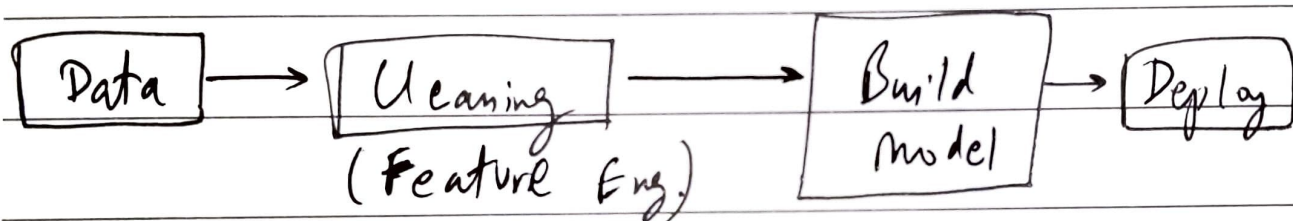
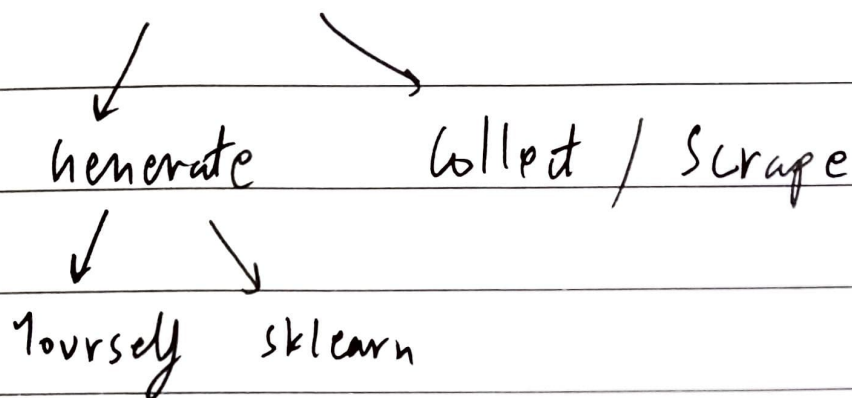


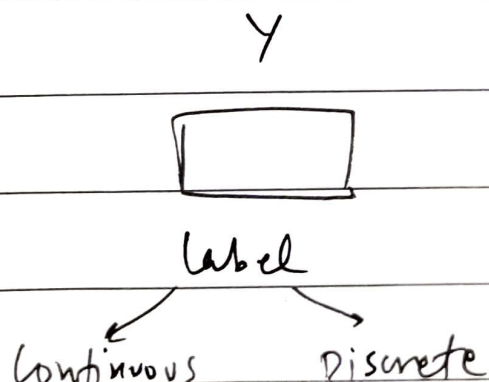
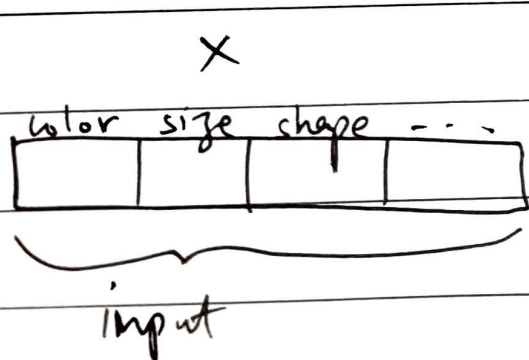
## Machine Learning Pipeline

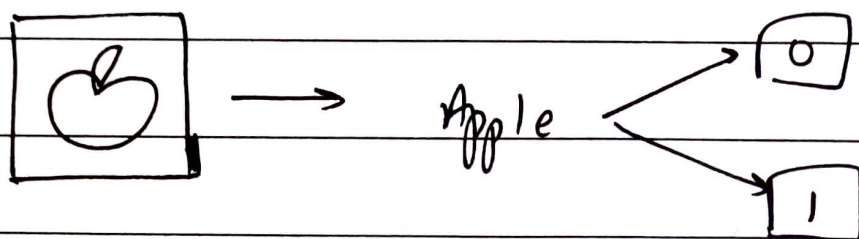
Data ?



### \* Supervised learning :

- Learn from data in past (labelled data)
- Generalise predictions on future data and avoid overfitting (This is training)





Representation :

$$X = \begin{bmatrix} x^{(1)} \\ x^{(2)} \\ \vdots \\ x^{(m)} \end{bmatrix} = \begin{bmatrix} x_1^{(1)} & x_2^{(1)} & x_3^{(1)} & \dots & x_n^{(1)} \\ \hline & & x_j^{(i)} & & \\ \hline \end{bmatrix}_{m \times n}$$

$j^{\text{th}}$  feature of  $i^{\text{th}}$  example

$$x^{(i)} = \langle x_1^{(i)} \dots x_n^{(i)} \rangle$$

$m$  examples &  
 $n$  features

$$y = \begin{bmatrix} 1 \\ y^{(i)} \\ 1 \end{bmatrix}_{m \times 1}$$

## Output (Supervised)

### Regression

Output is continuous

Ex: Housing, Stock price,  
GPA

Role of model is to

map a function from

$$x \rightarrow y \text{ i.e., } f(x) \rightarrow y$$

$$x \in \mathbb{R}^n$$

$$y \in \mathbb{R}$$

Goal: Minimize

Loss (Error)

Avoid overfitting

(High Accuracy in training, low in testing)

### Classification

Discrete Value

Ex: Disease or not,  
Apple or mango or

banana, Object

Classification

$$f(x) \rightarrow y$$

$$x \in \mathbb{R}^n$$

$$y \in [1 \dots k]$$

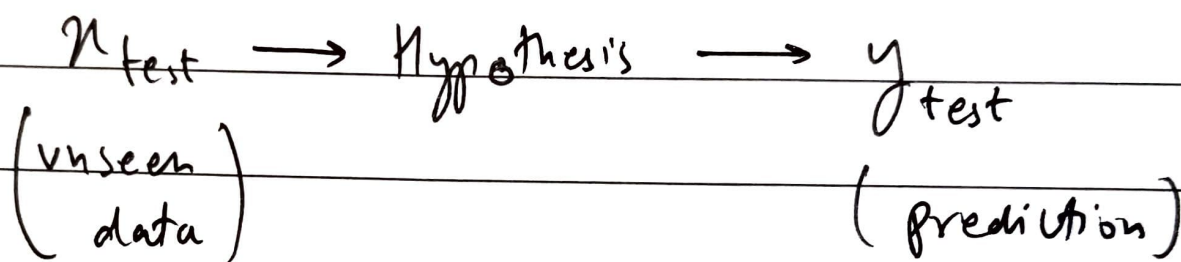
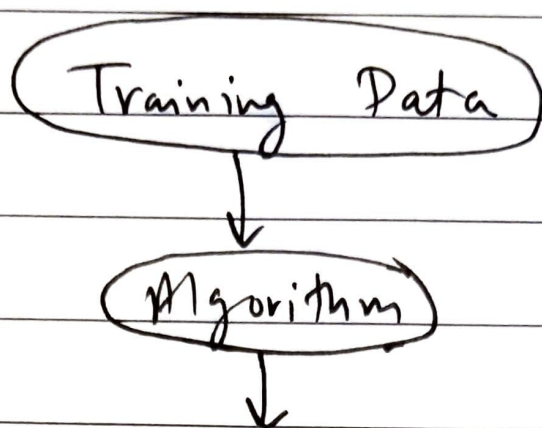


Output is one of the classes

$x^{(i)} \rightarrow n$  features

Goal: Minimise no. of  
misclassifications

Avoid overfitting



Hypothesis: Function having some parameters which will map input to desired output.

Multi label Classification:

Say you are given a text about Mars Rover, it can have labels such as Science, Tech, etc. i.e. more than one labels. You get multiple outputs for same class. i.e. multiple outputs.



## Examples of Supervised Learning:

- Spam Detection
- Document Classification (multilabel)
- NLP
- Image Classification
- Sequence (music / Text / Speech)
- Predictive.

## \* Unsupervised Learning:

- No supervision
- Algorithm finds pattern, ex: Clustering (grouping similar data)
- No labelled data (only  $x$ , no  $y$ )

Semi-supervised: we manually label few data points.

ex:

Say you 10 mil tweets, labeling is difficult. But if you label some data yourself, it can label others now.

## Applications of Unsupervised Learning:

- object segmentation
- Similarity detection
- Cluster Automatic Labeling

## \* Reinforcement Learning:

[Computer Games]

- Learns how humans learn (like riding a bicycle)
- Hit & trial method is used for learning
- Person who rides the bike is called Agent

In program, it is an object which interacts with the environment

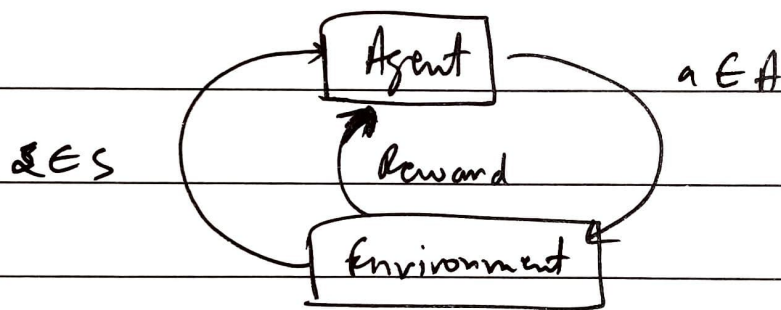
- Environment: Agent interacts with it, a simulation, can be a game, etc.
- Goal: You will have agent and environment, environment has a state  
ex of state: speed, x, y position, etc.

Goal of agent is to interact with environment by taking some action  $a$ .

$a \in A$  [ $A$ : set of actions]

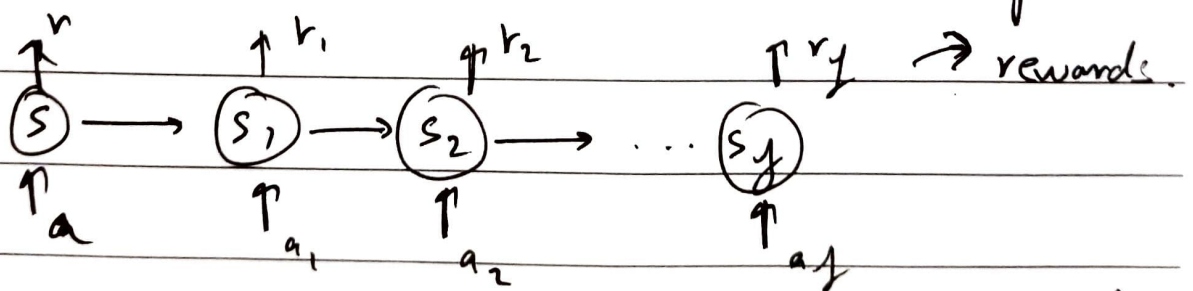
Like ex: You can move, jump, etc.

Now, environment reaches state  $s$ ,  $s \in S$   
Each state gives you reward.



So, the agent is going to take some action, on the environment and environment will reach state  $s$ , repeat till final state (Game over).

Game over: Killed or Game Complete



(Goal of agent is to maximise total reward)



∴ we need to design a policy / algorithm that helps in getting maximum reward.

Name Policy:

Ex: for racing game, car can go left(1) or right(0)

Find Probability of <sup>correct</sup> ~~right~~ action A:

$P(A|s)$  = Posterior Probability

↓  
★★ Best action to take in given state S.

★ Method / Algorithm to get best possible action, one example for this is, Deep Q-learning.



