

Geometry::getRotationMatrix



```
graph LR; A[Geometry::getRotationMatrix] --> B[Math::cos]; A --> C[Math::sin];
```

The diagram illustrates a function call. A gray rectangular box on the left contains the text 'Geometry::getRotationMatrix'. Two blue arrows originate from the right side of this box. The top arrow points to a white rectangular box containing 'Math::cos'. The bottom arrow points to another white rectangular box containing 'Math::sin'. All boxes have a thin black border.

Math::cos

Math::sin