

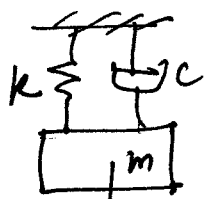
TU/HW-3 → Discussions

①

Prob. 1

This is a straightforward problem.

$$\omega_f = 2\pi \times 3 \text{ rad/s}$$



$$k = 30 \times 10^3 \text{ N/m}, m = 100 \text{ kg}$$

$$c = 1000 \text{ N-s/m}, F_0 = 80 \text{ N}$$

$$\therefore \omega_n = \sqrt{\frac{k}{m}} = \sqrt{\frac{30 \times 10^3}{100}} = 17.32 \text{ rad/s}$$

$$r = \frac{\omega_f}{\omega_n} = \frac{2\pi \times 3}{17.32} = 1.088$$

$$\zeta = \frac{c}{2m\omega_n} = \frac{1000}{2 \times 100 \times 17.32} = 0.2887$$

$$\therefore \text{Reqd amplitude} = \frac{F_0/k}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}}$$

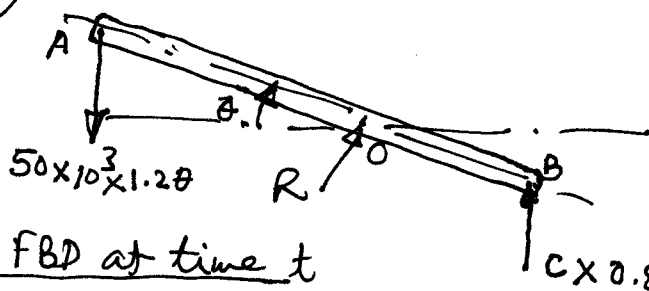
$$= \frac{80/(30 \times 10^3)}{\sqrt{(1-1.088)^2 + (2 \times 0.2887 \times 1.088)^2}}$$

$$= 4.2 \times 10^{-3} \text{ m} = \underline{\underline{4.2 \text{ mm}}}$$

$$\text{Also, } \psi = \tan^{-1}\left(\frac{2\zeta r}{1-r^2}\right) = \tan^{-1}\left(\frac{2 \times 0.2887 \times 1.088}{1-(1.088)^2}\right)$$

$$= \underline{\underline{106.3^\circ}}$$

Prob. 2



Relevant FBD at time t

Let θ be the generalized coordinate, +ive CW.
 θ is small & hence, spring deflection $\approx OA \sin \theta \approx 1.2\theta$

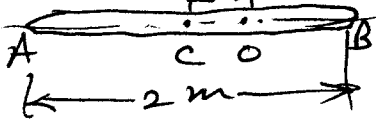
Similarly, vel. at B is $\approx 0.8\dot{\theta}$. Note that there is an unknown reaction force at O. Using the

moment balance method, we get

$$I_0 \ddot{\theta} = -50 \times 10^3 \times 1.20 \times 1.2 - c \times 0.8 \dot{\theta} \times 0.8$$

$$I_0 = \frac{1}{12} \times 80 \times 2^2 + 80 \times (0.2)^2 = 29.867 \text{ Kg m}^2$$

or, $\ddot{\theta} + 0.02143 \dot{\theta} + 2410.7 \theta = 0$ (check)
which is the reqd. DEOM for free vibrations.



Part b) Comparing ① with the standard form

$$\ddot{\theta} + 2\gamma\omega_n \dot{\theta} + \omega_n^2 \theta = 0,$$

We see that $\omega_n = \sqrt{2410.7} = 49.1 \text{ rad/s}$

$$2\gamma\omega_n = 0.02143c$$

$$\gamma = 0.5 \Rightarrow c = 2291 \text{ N-s/m (check)}$$

Note that for

$$I\ddot{\theta} + c\dot{\theta} + k_t\theta = 0$$

$$\Rightarrow \ddot{\theta} + \frac{c}{I}\dot{\theta} + \frac{k_t}{I}\theta = 0$$

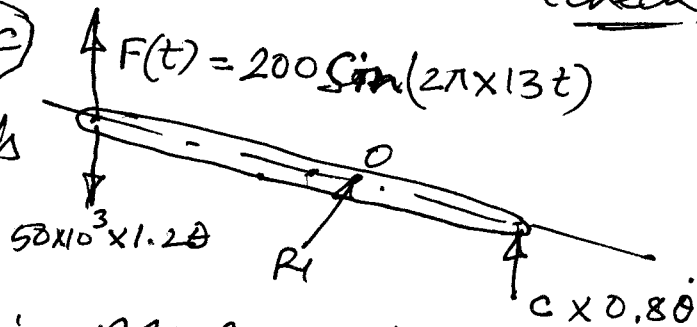
$$\Rightarrow \ddot{\theta} + 2\gamma\omega_n \dot{\theta} + \omega_n^2 \theta = 0$$

Since, $\gamma = \frac{c}{2I\omega_n}$

$$\& \omega_n = \sqrt{\frac{k_t}{I}}$$

Part c)

$$\omega_f = 2\pi f_f = 2\pi \times 13 \text{ rad/s}$$



After $F(t)$ is applied as shown, the DEOM shall be :-

$$\ddot{\theta} + 49.1 \dot{\theta} + 2410.7 \theta = 8.0356 \sin 81.68t$$

(check)

Compare with $I\ddot{\theta} + c\dot{\theta} + k_t\theta = T_0 \sin \omega_f t$.

The amplitude of forced angular oscillations is

$$\theta_0 = \frac{T_0/k_t}{\sqrt{(1-r^2)^2 + (2\gamma r)^2}} ; r = \frac{\omega_f}{\omega_n}$$

$$= 0.00137 \text{ rad}$$

$$= 0.079^\circ \text{ (check)} \rightarrow$$

3

$g=1$ (given).

The DEOM is :-
(Obtain it)

$$I_0 \ddot{\theta} + c_d \dot{\theta} + k_t \theta = K I \cos \omega_f t$$

When $\omega_f = 0$ (DC), --(1)

$$\theta_0 = \theta_{ss} = \frac{KI}{k_t} \text{ --(2)}$$

So, $\theta_0 \propto I$

$I_0 \rightarrow$ Moment of inertia.

$I \rightarrow$ ~~Direct~~ current amplitude

If you don't like this nomenclature, use

I_0 instead of I_0

when $\omega_f = 6 \times 2\pi \text{ rad/s}$, $r = \frac{\omega_f}{\omega_n} = \frac{12\pi}{4 \times 2\pi} = 1.5$

Let us denote by θ_6 , the amplitude of θ when ω_f corresponds to 6 Hz.

Then, $\theta_{ss} = \theta(t) = \theta_6 \cos(\omega_f t - \psi)$

where $\theta_6 = \frac{KI/k_t}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}} = \left(\frac{KI}{k_t} \right) \times 0.308 \text{ --(3)}$

from (2) & (3), thus, $\frac{\theta_6}{\theta_0} = 0.308$

Hence, if θ_0 corresponds to 1 amp,

θ_6 " " 0.308 amp

& the pointer would indicate(?)

a current of 0.31 amp approx.

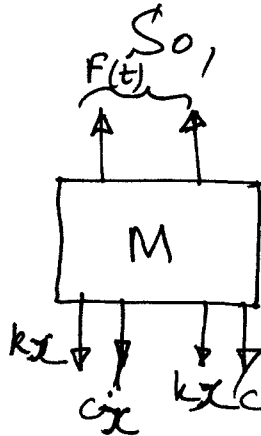
This problem may raise questions. You may leave it out for the moment

\rightarrow This example shows that a DC ammeter is very unsatisfactory for measuring alternating current.

④ (Note that we used different notations for the theory part. What is r is our 'e')

→ With the way δ is given, note that the vertical shaking force is

note $2 \times m e \omega^2 \cos \omega t$. $m = 1.15 \text{ kg}$, $e = 0.05 \text{ m}$



→ The DEOM is ($\omega_f = \frac{2000 \times 2\pi}{60} \text{ rad/s}$)

$$M \ddot{x} + 2c \dot{x} + 2kx = 5044.5 \cos 209.44t$$

→ Compare with

$$m \ddot{x} + c \dot{x} + kx = F_0 \cos \omega_f t$$

whose SS amplitude is

$$\frac{F_0/k}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}}$$

Relevant FBD

Read about the phasor method (notes sent already)

So, for this rotating unbalance problem, we didn't use the special formula developed for rotating unbalance case

Given:-

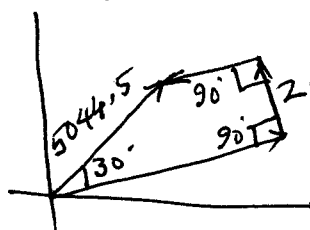
SS amplitude = $6 \times 10^{-3} \text{ m}$

$$\psi = \tan^{-1} \left(\frac{2\zeta r}{1-r^2} \right) = 30^\circ$$

→ Looks like there are 3 unknowns, viz., m , c & k & we have only two relations.

→ Try to solve the problem analytically.

→ Try the phasor method: $x_{ss} = x = 6 \times 10^{-3} \cos(209.44t - \frac{\pi}{6})$ (Given)



Hence,

$$5044.5 \cos 30^\circ = 2c \times 209.44 \times 6 \times 10^{-3}$$

$$\Rightarrow c = 1004 \text{ Ns/m Ans.}$$

$$\Rightarrow \dot{x} = \text{etc.}$$

$$\Rightarrow 2c\dot{x} = \text{etc.}$$

(cont.) →

④ 2nd part (part b) :-

$$\omega_f = 209.44 \text{ rad/s}, \text{ time period } T = \frac{2\pi}{\omega_f}$$

Instantaneous power = $F(t)x$ & ~~this~~ this varies with time. So, reqd. mean ~~power~~

$$\text{power output} = \frac{1}{T} \int_0^T F(t)x dt, \text{ where}$$

$$x(t) = 6 \times 10^{-3} \cos(209.44t - \pi/6)$$

→ Now perform the integration etc.

& get the final answer. [Ans: -1585W]
(Check)

⑤ Case 1:- $\frac{\omega_f}{\omega_n} = 2$. Assume 1 stroke is equivalent to one cycle of motion, we assume.

$$\text{So, } f_f = \frac{240}{60} \text{ cycles/s} \text{ \& } \omega_f = 2\pi f_f = 25.13 \text{ rad/s}$$

$$m = 2000 \text{ kg.}$$

$$F(t) = 12 \times 100 \times 10^{-3} \times (25.13)^2 \sin \omega_f t \text{ N}$$

$$= 757.82 \sin \omega_f t \text{ N, } \gamma = 0,$$

$$K_{eq} = 4K \text{ (let each spring has stiffness } K)$$

$$\text{Now, the DEOM is: } M\ddot{x} + K_{eq}x = 757.82 \sin \omega_f t$$

$$\text{Case (i)} \quad r = \frac{\omega_f}{\omega_n} = 2 \Rightarrow \underline{\underline{\omega_n = \frac{\omega_f}{2} = 12.565 \text{ rad/s}}}$$

$$\text{(a) Static deflection} = \frac{Mg}{K_{eq}} = \frac{g}{\sqrt{\frac{K_{eq}}{M}}} = \frac{g}{\omega_n^2} = \frac{9.81}{(12.565)^2}$$

$$= 0.0621 \text{ m} = 62.1 \text{ mm} \text{ Ans}$$

⑥ [Note that Transmission Ratio here means 'Transmissibility']

$$TR = \frac{\sqrt{1+(2pr)^2}}{\sqrt{(1-r^2)^2+(2pr)^2}} = \left| \frac{1}{1-r^2} \right| = \left| \frac{1}{1-2^2} \right| = 0.3333$$

(c) $\omega_n = \sqrt{\frac{k_{eq}}{M}} \Rightarrow k_{eq} = M\omega_n^2 = 315758.45 \text{ N/m}$
 $= 315.76 \text{ kN/m}$

Hence, $k = \frac{k_{eq}}{4} = 78939.61 \text{ N/m}$
 $= 78.9 \text{ kN/m}$

(d) Req'd amplitude = $\left| \frac{F_0/k_{eq}}{1-r^2} \right| = 0.8 \times 10^{-3} \text{ m}$
 $= 0.8 \text{ mm}$

→ Do the 2nd part. Answers: (a) 248 mm

(b) 0.067

(c) 19.7 kN/m

(d) 0.64 mm

Check

→ With the addition of 6000 kg Concrete platform, $M = 8000 \text{ kg}$. ω_f & r are unchanged. Hence $\omega_n = 12.565 \text{ rad/s}$ as before.

(a) Static deflection = $\frac{g}{\omega_n^2}$, remains same
 (62.1 mm)

(b) $Tr = \left| \frac{1}{1-r^2} \right| \rightarrow \text{same}$ (~~0.3333~~)

(c) $k_{eq} = M_{new}\omega_n^2$ & hence, k_{eq} & so, k will change.
 $k_{eq} = 8000 \times (12.565)^2$

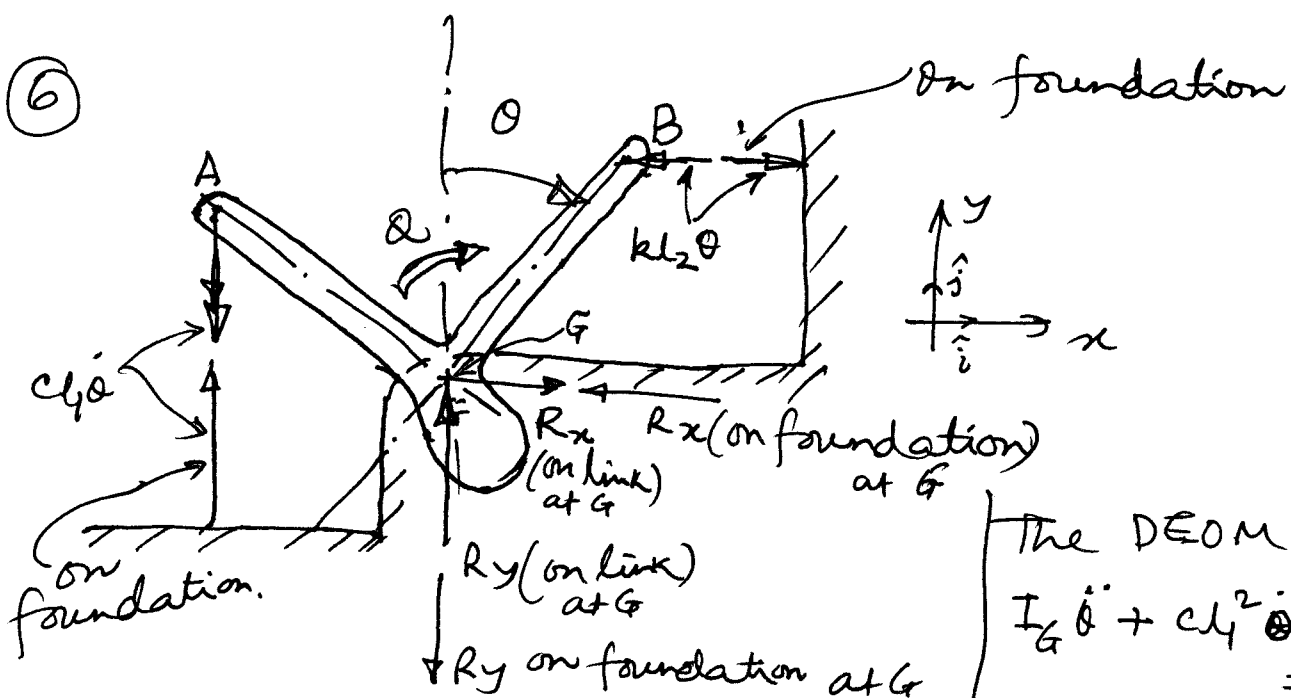
$\Rightarrow k = \frac{k_{eq}}{4} = 315758.45 \text{ N/m}$
 $= 315.8 \text{ kN/m}$

(d) Amplitude = 0.2 mm

Check

→

⑥



⑦

The DEOM is :

$$I_G \ddot{\theta} + c l_1^2 \dot{\theta} + k l_2^2 \theta = Q$$

Since $\bar{a}_G = \text{acceleration of CG 'G'} = 0$,
 net ~~force~~ force on link in x-direction = 0
 " " " " " y-direction = 0.

$$\Rightarrow R_x \hat{i} - k l_2 \theta \hat{i} = 0 \quad \text{--- (1)}$$

$$\& R_y \hat{j} - c l_1 \dot{\theta} \hat{j} = 0 \quad \text{--- (2)}$$

Now, net force on foundation due to the vibrating link = $-R_x \hat{i} + k l_2 \theta \hat{i} - R_y \hat{j} + c l_1 \dot{\theta} \hat{j} = 0$, by virtue of (1) & (2).
 (proved)

→ The net couple transmitted to the foundation = $k l_2 \theta \times l_2 + c l_1 \dot{\theta} \times l_1 = k l_2^2 \theta + c l_1^2 \dot{\theta}$

DEOM: $I_G \ddot{\theta} + c l_1^2 \dot{\theta} + k l_2^2 \theta = Q_0 \sin \omega t$ --- (3)

① $\theta_{ss} = \theta(t) = H_0 \sin(\omega t - \psi)$ --- (4)

$$\Rightarrow \dot{\theta} = H_0 \omega \cos(\omega t - \psi)$$

∴ From (3), couple transmitted = $k l_2^2 H_0 \sin(\omega t - \psi) + c l_1^2 \omega H_0 \cos(\omega t - \psi)$

$$= \sqrt{(k l_2^2)^2 + (c l_1^2 \omega)^2} H_0 \sin(\omega t - \psi + \phi) \text{ etc. (Do it)}$$

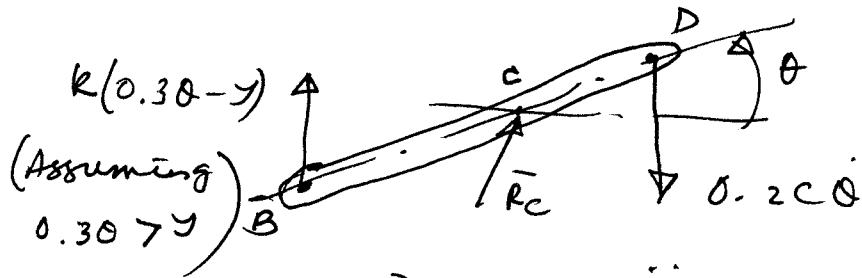
⑧

∴ Amplitude of Centre transmitted

$$= \frac{\sqrt{k^2 x_2^4 + c^2 x_1^4 \omega^2} \cdot Q_0 / (k x_2^2)}{\sqrt{(1-r^2)^2 + (2\gamma r)^2}} \quad [\because \textcircled{H}_0 = e A c]$$

= Given expression (Check)

⑦ (Base Excitation problem)



$$\Rightarrow 0.25 \ddot{\theta} + (0.2)^2 c \ddot{\theta} + (0.3)^2 k \theta = 0.3 k y - (1)$$

$$K = 700 \text{ N/m}, C = 60 \text{ N-s/m}$$

$$y = 0.01 \sin 10t \text{ m}$$

$$\Rightarrow 0.25 \ddot{\theta} + 2.4 \dot{\theta} + 63 \theta = 2.1 \sin 10t$$

$$\text{Let } \theta_{ss} = \theta(t) = \textcircled{H}_0 \sin(10t - \psi)$$

$$\text{So, } \textcircled{H}_0 = \frac{2.1/63}{\sqrt{[1 - (0.63)^2]^2 + (2 \times 0.30 \times 0.63)^2}} \text{ rad}$$

$$= 0.0467 \text{ rad}$$

$$= 2.678^\circ \text{ Ans}$$

Check

$$\omega_n = \sqrt{\frac{63}{0.25}} = 15.874 \text{ rad/s}$$

$$r = \frac{10}{15.874} = 0.63$$

$$\phi = \frac{2.4}{2 \times 0.25 \times 15.874} = 0.302$$