

Design factor:

$$n_d = \frac{\text{loss of function parameter}}{\text{max. allowable parameter}}$$

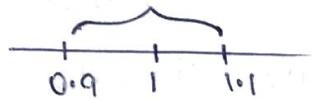
$$\text{Max. allowable parameter} = \frac{\text{loss of fun parameter}}{n_d}$$

Example: uncertainty in failure load = $\pm 10\%$.

max. load acting = $\pm 5\%$
on structure

Nominal failure load = 10 kN

@ assume uncertainty in failure load only

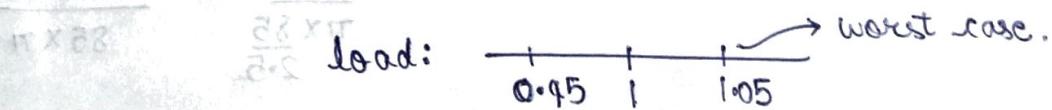


$$\text{Max. allowable parameter} = \frac{\text{failure load}}{n_d}$$

$$= 0.9 \times \text{Nominal failure load}$$

$$\Rightarrow n_d = \frac{1}{0.9}$$

① Assume uncertainty in max. load on structure only.



\Rightarrow Design based on: Max load = $1.05 \times$ Nominal value.

$$\text{Nominal } \overset{\text{max.}}{\text{value}} = \frac{1}{1.05} \times \text{abs. Max. value}$$

$$n_d = \frac{1}{\frac{1}{1.05}} = 1.05$$

Finally when both uncertainties are present,
(assumed to be independent)

$$n_d = n_{d1} \times n_{d2} = \frac{1.05}{0.9} = \frac{7}{6}$$

Max. allowable load = $\frac{\text{failure load}}{n_d} = \frac{60}{7} \text{ kN}$.

Factor of safety

$$n_f = n_d \text{ (after all dimensions are final)}$$

Eg: A solid circular rod under torsion $T = 100 \text{ Nm}$
Data available: Material shear strength = 85 MPa

$$\text{Design factor } n_d = 2.5$$

Design the rod. (diameter)

Unknown: Diameter of the rod.

Max. shear stress acting on the rod

$$\tau_{\max} = \frac{2T}{\pi r^3} \quad \text{or} \quad \frac{T r}{J} \quad J = \frac{\pi d^4}{32}$$

(on top surface) $= \frac{\pi r^4}{2}$

$$\leq \frac{\text{shear strength}}{n_d} = \frac{85}{2.5} \text{ MPa}$$

$$\Rightarrow r^3 \geq \frac{2T}{\pi \times 85 / 2.5} = \frac{2 \times 100 \times 2.5}{85 \times \pi}$$

$$\Rightarrow r \geq 12.3 \text{ mm.}$$

$$\text{Diameter} = d = 24.6 \text{ mm}$$

Standard size: $d = 25 \text{ mm}$ (Table A-17 of Shigley's book)

$$\text{Allowable shear stress (actual)} = \tau_{\text{allow}} = \frac{2T}{\pi r^3} = 32.59 \text{ MPa}$$

$$\text{factor of safety} = n_f = \frac{85 \text{ MPa}}{32.59 \text{ MPa}} = 2.6$$

Modes of material failure

1. static yielding → plastic deformation in ductile materials
2. Brinelling — localized yielding in regions of contact b/w curved surfaces.
3. Brittle fracture / rupture
4. Ductile rupture
5. Fatigue
6. Corrosion
7. Wear
8. Spalling — small pieces get spontaneously removed from a part.
9. Buckling

Engineering materials

1. steel — predominantly used
— alloy of iron and carbon
— Cr, Mn, Ni, V, Mo
Ni — increases strength without decreasing ductility
Cr — increases wear resistance, hardness
Mn — Acts as deoxidising and desulphurising agent (corrosion resistance)

2. Cast Iron

3. Non-ferrous metals

- aluminium

- Copper based alloys

4. Non-metals

- Glass

- Plastic

- Wood

- Polycarbonate

- Composites

Material Selection

- Need to pay attention to →
 - operational / functional aspects
 - potential failure modes
 - market related factors

Functional aspects

1. High strength / volume ratio → yield/ ultimate strength
 2. High strength to weight → yield/ ultimate strength per unit mass.
 3. Long term dimensional → Elastic modulus
stability
thermal expⁿ coefficient
corrosion resistance,
creep resistance
- :

Performance metric of a structure / part

functional requirement

geometry

material properties

$$P = f(F, G, M)$$

functional

Geometry

When the aspects are independent

$$P = f_1(F) f_2(G) f_3(M)$$

for optimum design, maximise or minimise

- Eg. Want to design light, stiff, axially loaded end-of constant cross section.

Performance matrix $P = "m"$ is to be
↳ mass minimized.

Stiffness of the rod $K = \frac{F}{\delta} = \frac{EA}{l}$

$$\Rightarrow A = \frac{Kl}{E}$$

Mass of the rod $m = \rho A \cdot l = \rho \cdot \frac{Kl}{E} \cdot l$

$$= K \cdot l^2 \cdot \left(\frac{\rho}{E}\right)$$

functional ↴ ↓ material
geometry

minimise m :

Define

Performance matrix $P = \frac{m}{K}$

∴ for optimum choice, minimise P

$$\frac{m}{K} = l^2 \left(\frac{\rho}{E}\right)$$

$$= f_3(m)$$

↓
material efficiency coefficient

. for choosing material: maximize $\boxed{E/\rho}$

from Ashby chart, (2-1)

(candidate materials - Al_2O_3)

Technical ceramic

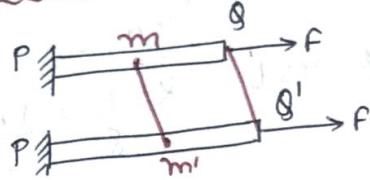
Si_3N_4

B_4C

→ Refer slides.

strain and deformation

1D:



(original)

(after deformation)

$$q \rightarrow q', m \rightarrow m'$$

$$\text{strain} \rightarrow e = \frac{L_f - L_0}{L_0} = \frac{\Delta u}{L_0} \quad (\text{engineering strain})$$

$$2. \epsilon = \frac{L_f - L_0}{L_f} = \frac{\Delta u}{L_f} \quad (\text{true strain})$$

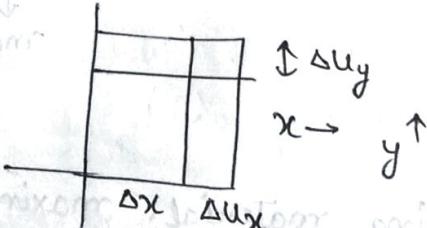
$$3. \epsilon = \ln\left(\frac{L_f}{L_0}\right) = \ln(\lambda) \quad \xrightarrow{\text{stretch}}$$

$\epsilon = \ln(\lambda)$ (logarithmic strain)

2 similar cases. Consider first one.

$$\epsilon = \int_0^L \frac{\delta L}{L} \quad (\text{true})$$

2D:

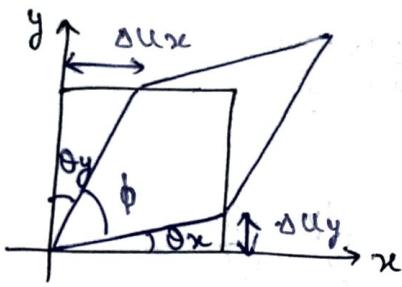


$$\epsilon_x = \frac{\Delta u_x}{\Delta x} = \frac{\partial u_x}{\partial x} \quad (\text{as } \Delta x \rightarrow 0)$$

(strain along x-direction)

$$\epsilon_y = \frac{\Delta u_y}{\Delta y} = \frac{\partial u_y}{\partial y} \quad (\text{as } \Delta y \rightarrow 0)$$

(along y-direction)



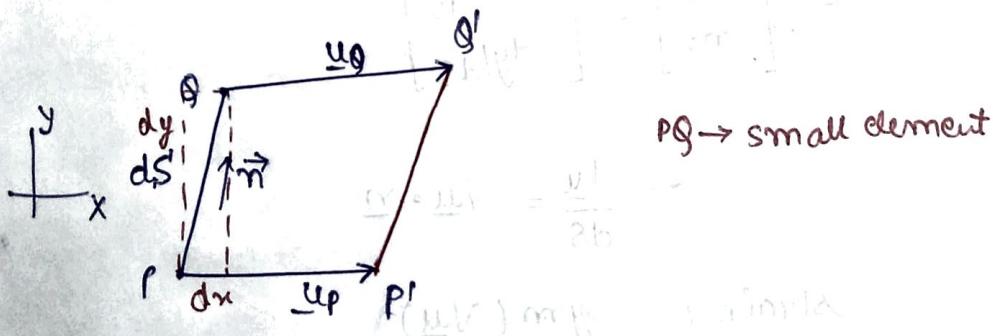
$$\gamma_{xy} = \frac{\pi}{2} - \phi = \theta_x + \theta_y$$

$$\cong \frac{\Delta u_x}{\Delta y} + \frac{\Delta u_y}{\Delta x} = \frac{\partial u_y}{\partial x} + \frac{\partial u_x}{\partial y}$$

$$\Rightarrow \epsilon_{xy} = \frac{1}{2} \gamma_{xy}.$$

Materials resist any relative displacement any two points.

Strain is a measure of quantifying such relative displacement.



\underline{u}_p : displacement of point P

\underline{u}_Q : _____ " _____ Q

\vec{n} : unit vector along PQ

Relative displacement bet^n Q and P:

$$du = \underline{u}_Q - \underline{u}_P = \begin{bmatrix} du_x \\ du_y \end{bmatrix} \quad \text{functions of } x \text{ and } y.$$

unit relative displacement:

$$\frac{du}{ds} = \begin{bmatrix} \frac{du_x}{ds} \\ \frac{du_y}{ds} \end{bmatrix}$$

$$\frac{d\mathbf{u}_x}{ds} = \frac{\partial u_x}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial u_x}{\partial y} \frac{\partial y}{\partial s}$$

$$\frac{d\mathbf{u}_y}{ds} = \frac{\partial u_y}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial u_y}{\partial y} \frac{\partial y}{\partial s}$$

$$\Rightarrow \begin{bmatrix} \frac{\partial u_x}{\partial s} \\ \frac{\partial u_y}{\partial s} \end{bmatrix} = \begin{bmatrix} \frac{\partial u_x}{\partial x} & \frac{\partial u_x}{\partial y} \\ \frac{\partial u_y}{\partial x} & \frac{\partial u_y}{\partial y} \end{bmatrix} \begin{bmatrix} \frac{\partial x}{\partial s} \\ \frac{\partial y}{\partial s} \end{bmatrix}$$

\underline{du} $\nabla \underline{u}$ \underline{n}

$$ds = \underline{PQ} = dx \hat{i} + dy \hat{j}$$

$$\boxed{\underline{n} = \frac{dx}{ds} \hat{i} + \frac{dy}{ds} \hat{j}}$$

Another form giving \underline{n} : unit vector along \underline{PQ}

$$\underline{n} = \begin{bmatrix} n_1 \\ n_2 \end{bmatrix} = \begin{bmatrix} dx/ds \\ dy/ds \end{bmatrix}$$

Normal stress σ_{xx}

$$\Rightarrow \frac{d\underline{u}}{ds} = \nabla \underline{u} \cdot \underline{n}$$

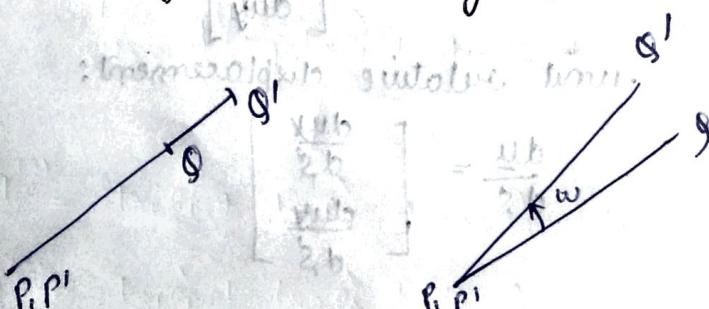
Strain: $\text{sym}(\nabla \underline{u})$

$$(E) = [\nabla \underline{u} + (\nabla \underline{u})^T]/2$$

$$\text{Rotation } \underline{\Omega} = [\nabla \underline{u} - (\nabla \underline{u})^T]/2$$

$E \cdot \underline{n}$ gives change in length of PQ

$\underline{\Omega} \cdot \underline{n}$ gives rotation of PQ .



1. Only stretch, no rotation

2. Only rotation

Verify that: $\underline{\underline{E}} \cdot \underline{n} \neq 0$, $\underline{\underline{\tau}} \cdot \underline{n} = 0$ in 1

$\underline{\underline{E}} \cdot \underline{n} = 0$, $\underline{\underline{\tau}} \cdot \underline{n} \neq 0$ in 2

* In 3D the same relations hold.

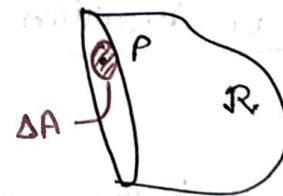
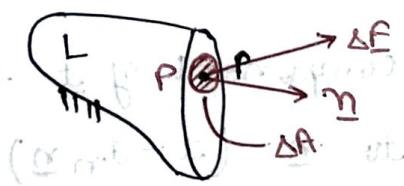
Stresses:

- Body force - acts on entire volume, ignoring effect of boundary on body, imagine cut



- Contact force (applied on surface or boundary)

Cauchy hypothesis: We can define a surface traction on any point inside the body.



\underline{n} : unit outward normal to ΔA at P

- Effect of material (in ΔA on R) on the ΔA in left half in a distributed force in ΔA around $P \rightarrow$ Has a resultant $\underline{\underline{F}}$

can think of an internal response at P .
Contact force on ΔA at P is $\underline{\underline{F}}$

traction vector at P :

$$\underline{\underline{t}} = \lim_{\Delta A \rightarrow 0} \frac{\underline{\underline{F}}}{\Delta A}$$

(P is always inside ΔA)
during limit process

• We always assume that limit exists

contact force per unit area

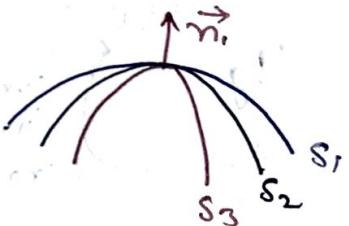
$$= \frac{\underline{\underline{F}}}{\Delta A}$$

- Traction vector \underline{t} at P depends on the orientation of the imaginary cut plane.

$$\underline{t} = t(x, \eta)$$

Hypothesis:

- If different surfaces are chosen at P with same normal, then \underline{t} remains the same.

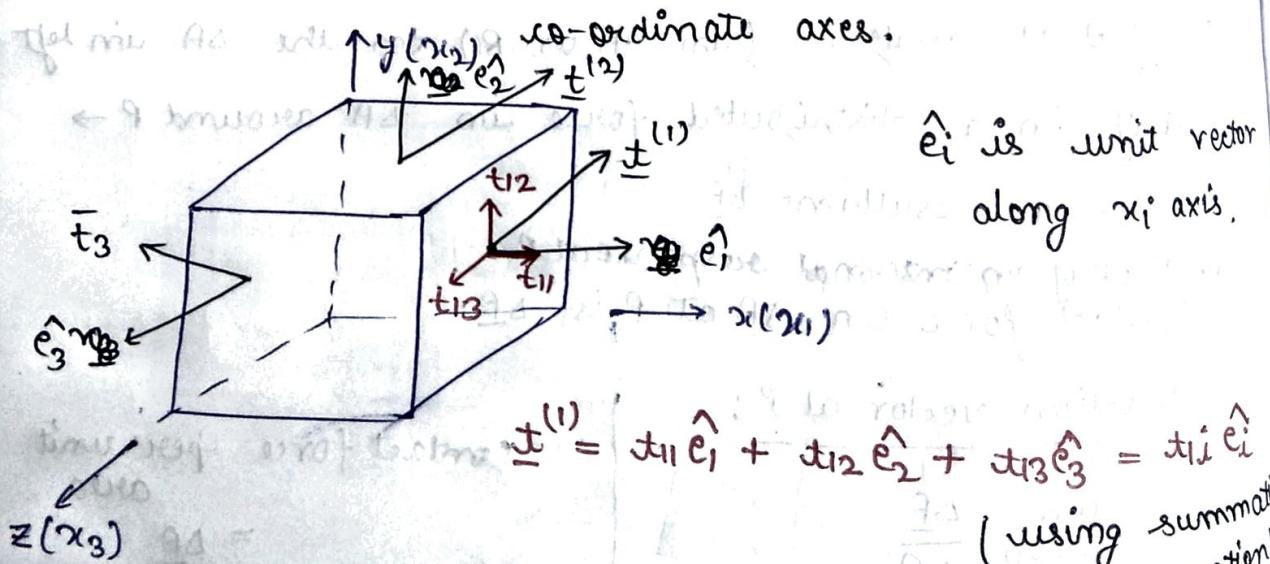


- If two surfaces at P have different normal, then \underline{t} is different.

⇒ There are infinitely many surfaces with different normals passing through P!!

- $t_n = \underline{t} \cdot \underline{n}$ is normal traction (-stress)
- shear traction: component of \underline{t} perpendicular to $\underline{n} = (\underline{t} - t_n \underline{n})$

In a 3D body: Define traction on 3 planes passing through P. Planes are perpendicular to co-ordinate axes.



$$\underline{t}^{(1)} = t_{11} \hat{e}_1 + t_{12} \hat{e}_2 + t_{13} \hat{e}_3 = t_{1i} \hat{e}_i$$

(using summation convention)

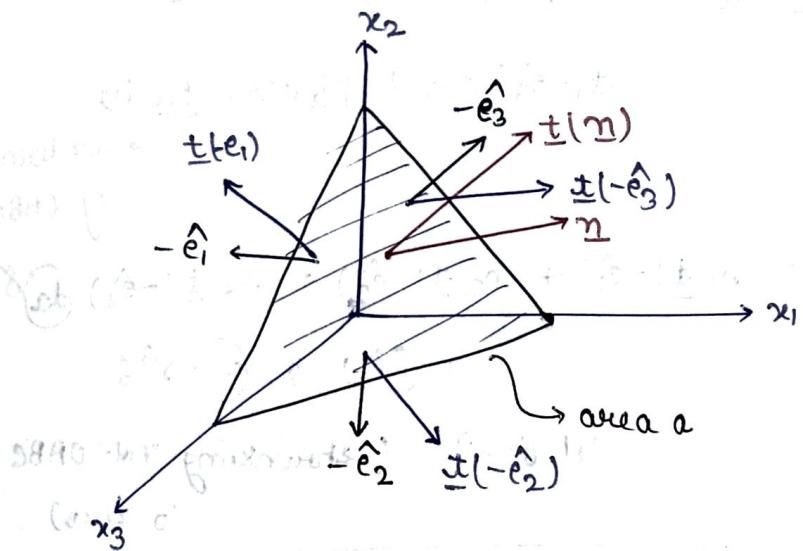
$$\underline{t}^{(2)} = t_{21} \hat{e}_1 + t_{22} \hat{e}_2 + t_{23} \hat{e}_3 = t_{2i} \hat{e}_i$$

$$\underline{t}^{(3)} = t_{31} \hat{e}_1 + t_{32} \hat{e}_2 + t_{33} \hat{e}_3 = t_{3i} \hat{e}_i$$

Normal stress components at P: $\sigma_{11}, \sigma_{22}, \sigma_{33}$

shear — " — : $\tau_{12}, \tau_{31}, \tau_{21}, \tau_{23}, \tau_{32}, \tau_{13}$.

Traction vector on an arbitrary plane



Inclined surface

$$\text{unit normal} = \hat{n} = \hat{e}_1 + \hat{e}_2 + \hat{e}_3$$

$$\text{traction vector} = \hat{t}(\hat{n})$$

$$\text{area} = a.$$

on other surfaces:

OAC: normal: $-\hat{e}_1$, traction $\pm(-\hat{e}_1)$

$$\text{area} = a_1$$

OAB: normal: $-\hat{e}_2$, traction: $\pm(-\hat{e}_2)$, a_2

OAC: normal: $-\hat{e}_3$, traction: $\pm(-\hat{e}_3)$, a_3

$$\hat{n} = n_1 \hat{e}_1 + n_2 \hat{e}_2 + n_3 \hat{e}_3$$

$$da_1 = \text{area of OAC} = da \cdot n_1 \sim s^2$$

$$da_2 = \text{area of OAB} = da \cdot n_2 \sim s^2$$

$$da_3 = \text{area of OBC} = da \cdot n_3 \sim s^2$$

$$\text{Volume of OABC} = dv$$

$s = \text{distance of inclined plane ABC from origin O.}$

$$da \sim \delta^2$$

$$dv \sim \delta^3$$

linear momentum balance of OABC:

$$\underline{t}(m) da + \underline{t}(-\hat{e}_1) da_1 + \underline{t}(-\hat{e}_2) da_2 +$$

$$\underline{t}(-\hat{e}_3) da_3 + p_b dv = f_a dv$$

acceleration
of OABC

$$\left\{ \begin{array}{l} \underline{t}(m) + m_1 \underline{t}(-\hat{e}_1) + m_2 \underline{t}(-\hat{e}_2) + m_3 \underline{t}(-\hat{e}_3) (\underline{da})^{\delta^2} \\ = p(\underline{a} - \underline{b}) \odot dv \end{array} \right.$$

let $\delta \rightarrow 0$ (shrinking vol. OABC
to zero)

\Rightarrow

$$\underline{t}(m) + m_1 \underline{t}(-\hat{e}_1) + m_2 \underline{t}(-\hat{e}_2) + m_3 \underline{t}(-\hat{e}_3)$$

Let $\underline{n} = \hat{e}_1$, $\underline{m} = \begin{bmatrix} m_1 \\ m_2 \\ m_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

$$\Rightarrow m_1 = 1, m_2 = m_3 = 0$$

\Rightarrow

$$\underline{t}(m) = m_1 \underline{t}(\hat{e}_1) + m_2 \underline{t}(\hat{e}_2) + m_3 \underline{t}(\hat{e}_3)$$

$$\underline{t}_1 = \underline{t}(\hat{e}_1) = \sigma_{11} \hat{e}_1 + \sigma_{12} \hat{e}_2 + \sigma_{13} \hat{e}_3$$

$$= \sigma_{ij} \hat{e}_j$$

$$\underline{t}(m) = \begin{bmatrix} t_1 \\ t_2 \\ t_3 \end{bmatrix}, \quad \underline{t}_1 = \underline{t}(\hat{e}_1) = \begin{bmatrix} \sigma_{11} \\ \sigma_{12} \\ \sigma_{13} \end{bmatrix}$$

$$\underline{t}_2 = \underline{t}(\hat{e}_2) = \begin{bmatrix} \sigma_{21} \\ \sigma_{22} \\ \sigma_{23} \end{bmatrix}$$

$$\underline{t}_3 = \underline{t}(\hat{e}_3) = \begin{bmatrix} \sigma_{31} \\ \sigma_{32} \\ \sigma_{33} \end{bmatrix}$$

$$\Rightarrow \underline{\underline{\sigma}}(\underline{n}) = n_1 \underline{\underline{\sigma}}(\hat{e}_1) + n_2 \underline{\underline{\sigma}}(\hat{e}_2) + n_3 \underline{\underline{\sigma}}(\hat{e}_3)$$

$$\begin{bmatrix} \sigma_1(n) \\ \sigma_2(n) \\ \sigma_3(n) \end{bmatrix} = \begin{bmatrix} \sigma_{11} & \sigma_{21} & \sigma_{31} \\ \sigma_{12} & \sigma_{22} & \sigma_{32} \\ \sigma_{13} & \sigma_{23} & \sigma_{33} \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix}$$

$$\underline{\underline{\sigma}}(\underline{n}) = \underline{\underline{\sigma}} \cdot \underline{n} = \begin{bmatrix} \sigma_{11} & \sigma_{21} & \sigma_{31} \\ \sigma_{12} & \sigma_{22} & \sigma_{32} \\ \sigma_{13} & \sigma_{23} & \sigma_{33} \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix}$$

$$\boxed{\underline{\underline{\sigma}}(\underline{n}) = \underline{\underline{\sigma}} \cdot \underline{n}}$$

Angular momentum balance:

$$\underline{\underline{\sigma}} = \underline{\underline{\sigma}}^T$$

$\Rightarrow \underline{\underline{\sigma}}$ is a symmetric tensor

$$\Rightarrow \sigma_{12} = \sigma_{21}$$

$$\sigma_{13} = \sigma_{31}$$

$$\sigma_{23} = \sigma_{32}$$

$\bullet \underline{\underline{\sigma}}$ has six independent elements

Plane-stress



\bullet Thin disk subject to lateral traction

\bullet Traction on lateral surfaces

\bullet The body is thin

Can assume:

\bullet Qualities of $\underline{\underline{\sigma}}$ independent of z

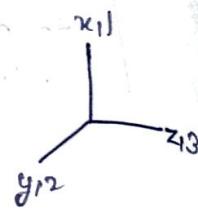
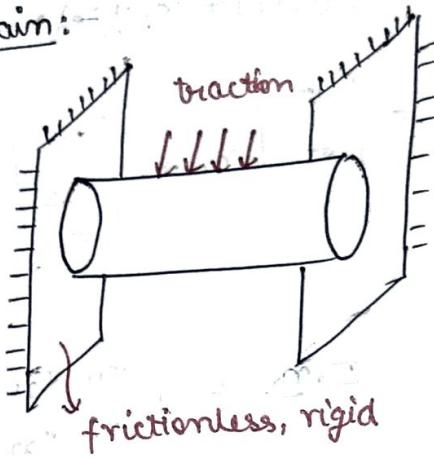
$$\bullet \sigma_{zz} = \tau_{zx} = \tau_{zy} = 0.$$

$$\text{or } \sigma_{11} = \sigma_{33} = \sigma_{23} = 0.$$

Unknown stresses: $\sigma_{11}, \sigma_{22}, \sigma_{12}$ (Ans)

$$\text{or } \sigma_x, \sigma_y, \tau_{xz}$$

Plane strain:



$$(\sum M_D)_x$$

$$\sum f_z = 0$$

$$\sum F_x =$$

⑥

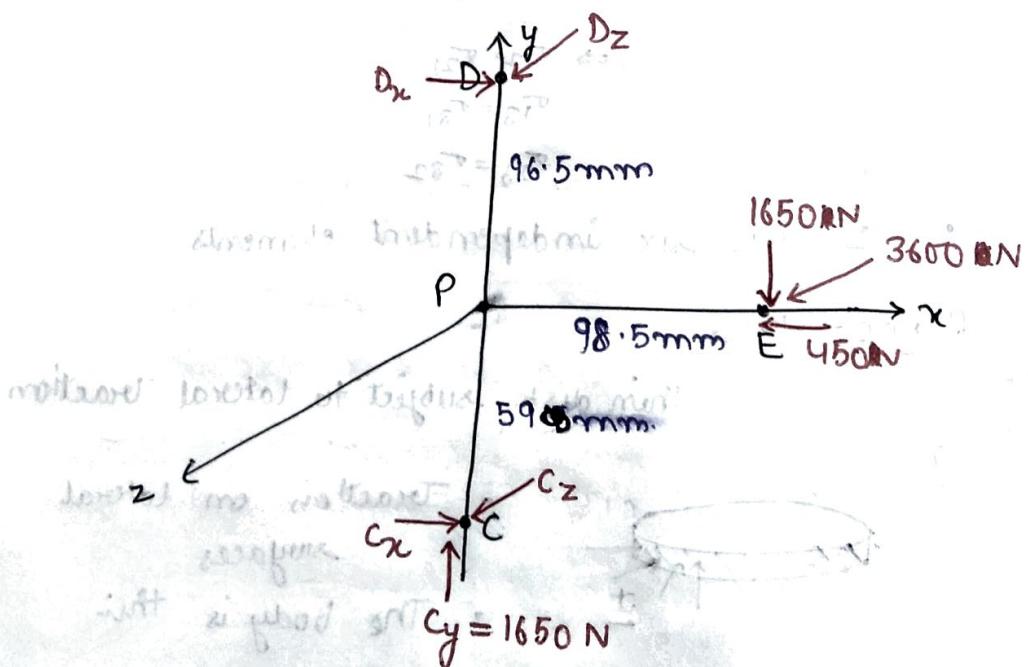
$$\epsilon_{zz} = \epsilon_{xz} = \epsilon_{yz} = 0.$$

Non zero strain

ϵ_x, ϵ_y and ϵ_{xy}

function of x and y only.

Tutorial-3 - Problem 1



$C_y = 1650 \text{ N}$ as all the thrust is taken by bearing at C

$$\Rightarrow D_y = 0 \text{ N.}$$

$$(\sum M_D)_z : -1650 \times 98.5 - 450 \times 96.5 + C_x \times (155.5) =$$

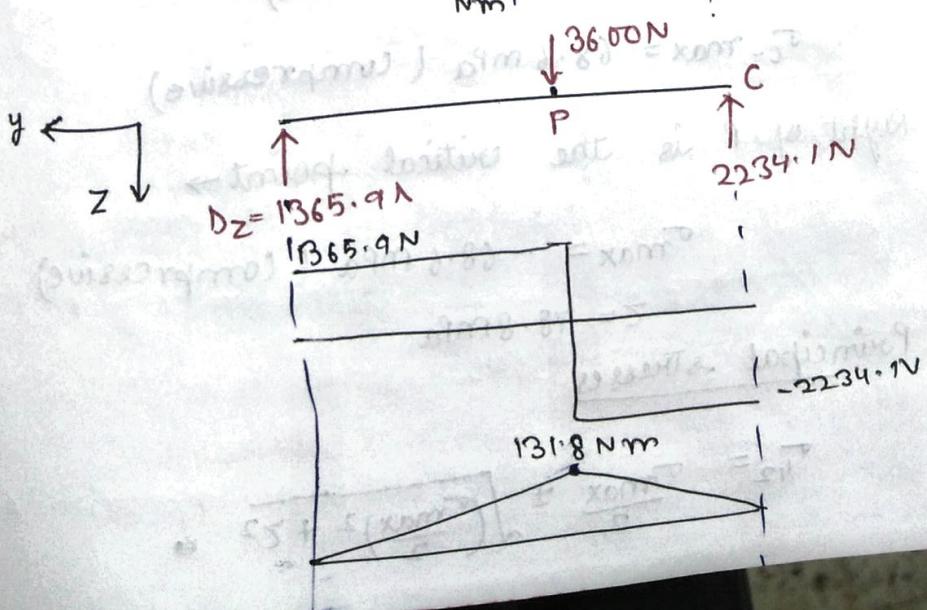
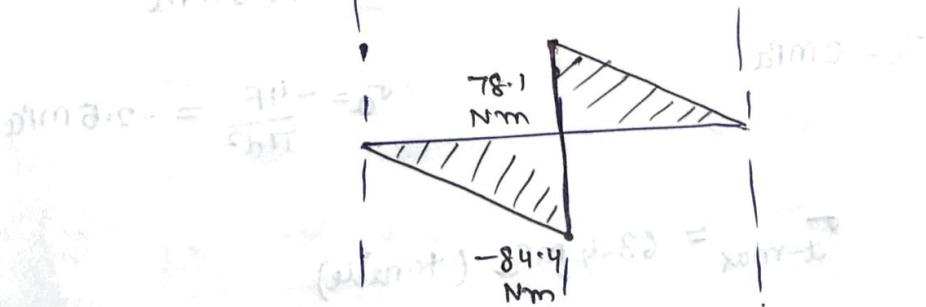
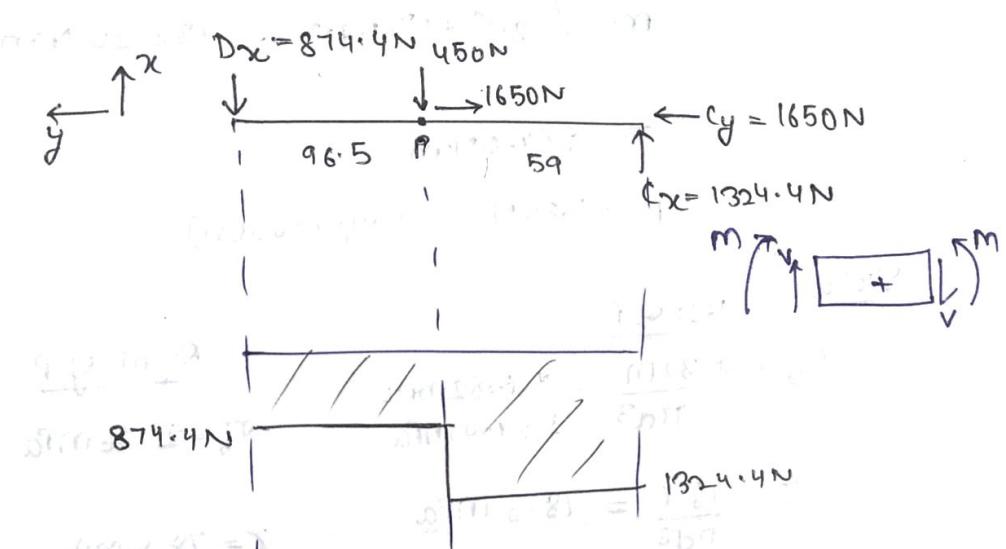
$$\Rightarrow C_x = 1324.437 \text{ N}$$

$$\underline{(\sum M)_x = 0} \Rightarrow -C_z \times 155.5 - 3600 \times 96.5 = 0 \\ \Rightarrow C_z = -2234.084 \text{ N.}$$

$$\underline{\sum f_z = 0} \Rightarrow D_z + C_z = -3600 \text{ N} \\ \Rightarrow D_z = -1365.92 \text{ N}$$

$$\underline{\sum F_x = 0} \quad C_x + D_x = 450 \text{ N} \\ \Rightarrow D_x = -874.437 \text{ N}$$

⑥ SFD and BMD



② Critical pt.

Left of P:

Bending moment $M = \sqrt{(84.4)^2 + (131.8)^2} = 156.51 \text{ Nm}$

Torque: $T = 3650 \times 0.0985 \text{ N}\cdot\text{m} = 354.6 \text{ Nm}$

Axial force $\Rightarrow F_a = 0 \text{ N}$

Right of P:

$$M = \sqrt{78.1^2 + (131.8)^2} = 153.20 \text{ Nm}$$

$T = 354.6 \text{ Nm}$

$F_a = -1650 \text{ N}$ (compression)

Stresses

Left of P

$$\sigma_b = \pm \frac{32M}{\pi d^3} = \pm \frac{32 \times 156.51}{\pi \times 10^3} = \pm 67.4 \text{ MPa}$$

$$\tau = \frac{16T}{\pi d^3} = 78.8 \text{ MPa}$$

$$\sigma_a = 0 \text{ MPa}$$

Right of P

$$\sigma_b = \pm 66 \text{ MPa}$$

$$\tau = 78.8 \text{ MPa}$$

$$\sigma_a = -\frac{4F}{\pi d^2} = -2.5 \text{ MPa}$$

$$\sigma_{t-\max} = 63.4 \text{ MPa}$$
 (tensile)

$$\sigma_{c-\max} = 68.6 \text{ MPa}$$
 (compressive)

Right of P is the critical point \rightarrow

$$\sigma_{\max} = -68.6 \text{ MPa}$$
 (compressive)

$$\tau = 78.8 \text{ MPa}$$

③ Principal stresses

$$\sigma_{1,2} = \frac{\sigma_{\max}}{2} \pm \sqrt{\left(\frac{\sigma_{\max}}{2}\right)^2 + \tau^2} =$$

$$= -\frac{68.6}{2} \pm \sqrt{\left(\frac{68.6}{2}\right)^2 + (78.8)^2} = -120.2 \text{ MPa},$$

51.6 MPa

Maximum shear stress:

$$\tau_{\max} = \sqrt{\left(\frac{\sigma_{\max}}{2}\right)^2 + \tau^2} = 85.94 \text{ MPa.}$$

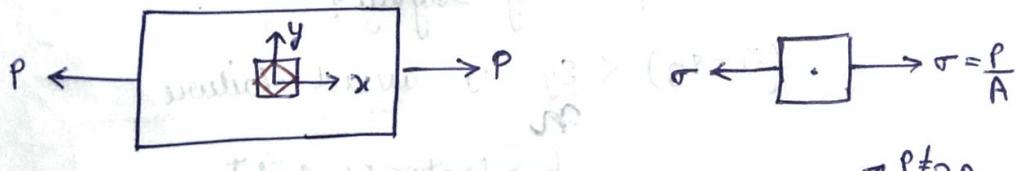
Failure → A part is broken / functionality is ~~not~~ lost / not reliable.

We will discuss - stress / strength based failure

Under static Loading

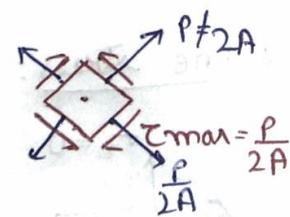
- Maximum shear stress theory (Tresca)
 - Ductile material yielding
 - Failure or yielding happens when at a critical point, maximum shear stress exceeds

- a limit.
- yield strength (in shear)
 - depends on material
 - experimentally obtained.



- Shear stress is max. on a plane at 45° with x-axis.

$$\therefore \tau_{\max} = \frac{P}{2A} = \frac{\sigma}{2}.$$



Notes/15 p. 2 in 2019

(maximum shear stress)

for failure : $\sigma_{max} > s_{sy} \rightarrow$ yield strength in shear

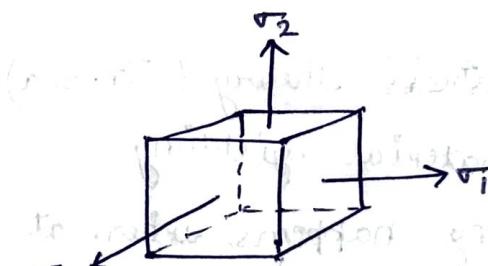
$$\Rightarrow \frac{\sigma}{2} \geq s_{sy} = \frac{s_y}{2}$$

$$\Rightarrow \sigma \geq s_y$$

$$s_y = 2s_{sy} = \text{yield strength}$$

3D state of stress

In principal C.S.



Assume

$$\sigma_1 \geq \sigma_2 \geq \sigma_3$$

Maximum shear stress

for failure, $\sigma_{max} = \frac{\sigma_1 - \sigma_3}{2} \geq s_y$

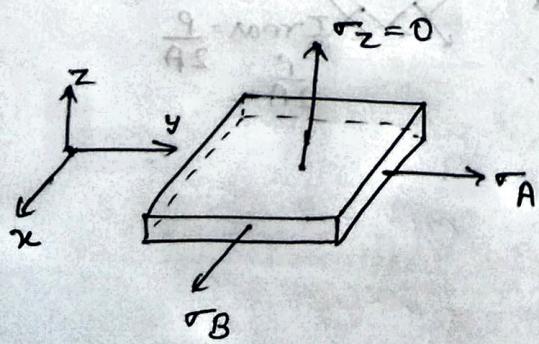
$$\Rightarrow (\sigma_1 - \sigma_3) \geq 2s_y$$

To include a factor of safety:

$$(\sigma_1 - \sigma_3) < \frac{s_y}{n} \text{ to avoid failure}$$

n → factor of safety

Plane stress:



- σ_A and σ_B are principal stresses in x-y plane.
- Plane stress is a 3D state of stress. (although approximate)

Principal stresses are $\sigma_A, \sigma_B, 0$.

Case-1 \rightarrow

$$\sigma_A > \sigma_B \geq 0 \Rightarrow z_{\max} = \frac{\sigma_A}{2}$$

For failure: $\frac{\sigma_A}{2} = \frac{S_y}{2}$ or $\boxed{\sigma_A = S_y}$

Case 2 \rightarrow

$$\sigma_B > \sigma_A \geq 0 \Rightarrow z_{\max} = \frac{\sigma_B}{2}$$

For failure $\boxed{\sigma_B = S_y}$

Case 3 \rightarrow

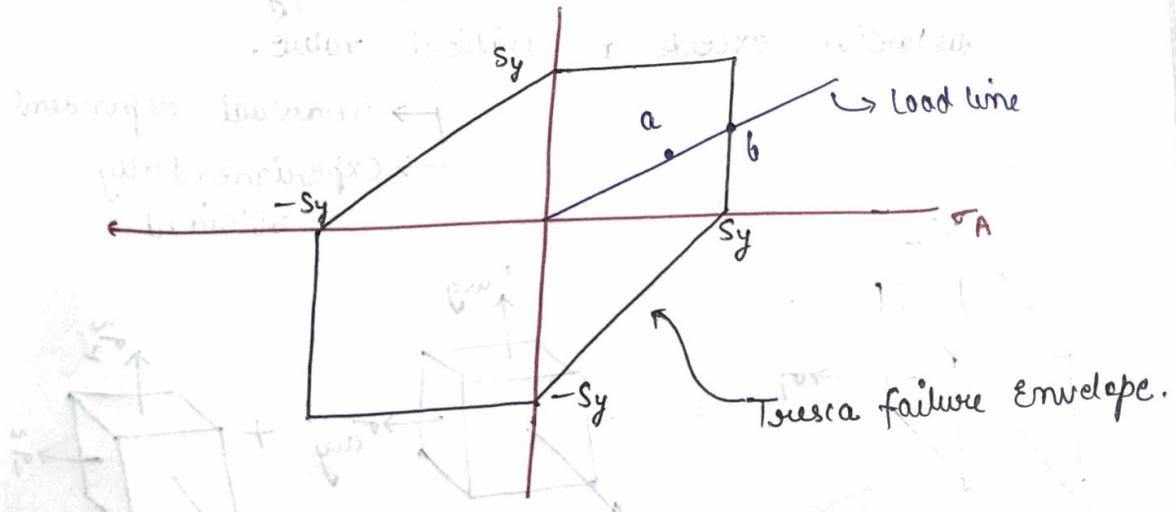
$$0 > \sigma_B > \sigma_A \Rightarrow z_{\max} = -\frac{\sigma_A}{2}$$

$\Rightarrow \boxed{\sigma_A = -S_y}$

Case 4 \rightarrow

$$0 > \sigma_A > \sigma_B \Rightarrow z_{\max} = -\frac{\sigma_B}{2}$$

$\Rightarrow \boxed{\sigma_B = -S_y}$



Case 5 \rightarrow

$$\sigma_A > 0 > \sigma_B \Rightarrow z_{\max} = \frac{\sigma_A - \sigma_B}{2}$$

$\Rightarrow \boxed{\sigma_A - \sigma_B = S_y}$

Case 6 \rightarrow

$$\sigma_B > 0 > \sigma_A \Rightarrow z_{\max} = \frac{\sigma_B - \sigma_A}{2}$$

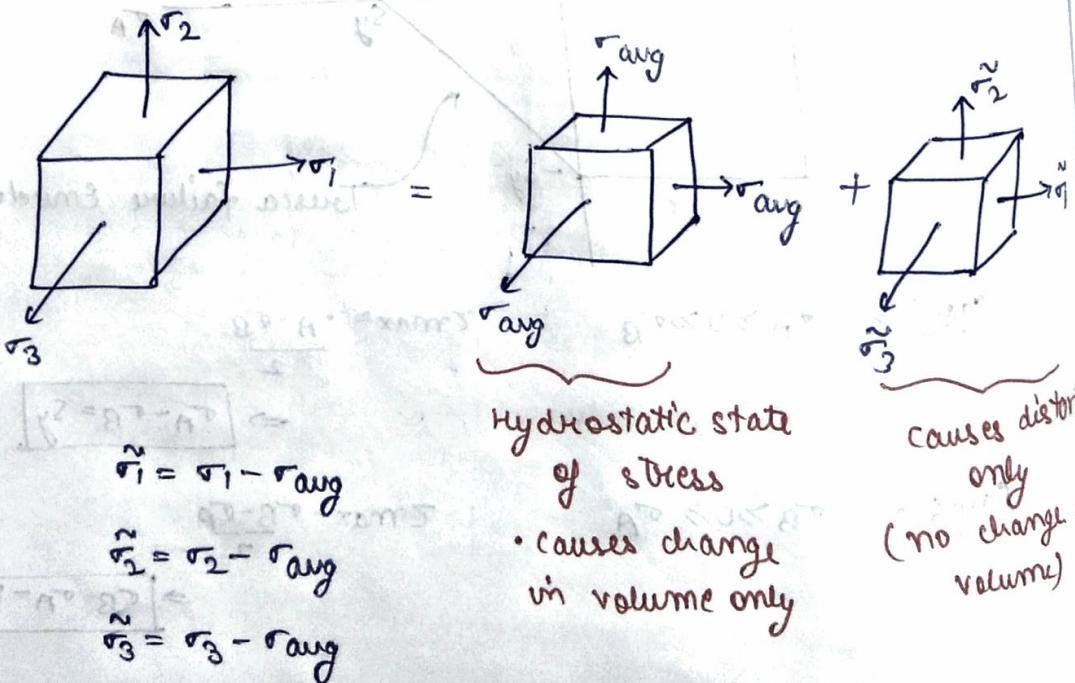
$\Rightarrow \boxed{\sigma_B - \sigma_A = S_y}$

- To avoid failure stress state (σ_A, σ_B) must be inside this envelope.
- Let 'a' denote state of stress under some load.
- Upon increase of load (1 parameter) - σ_A and σ_B will increase proportionally with load
 \Rightarrow stress state will follow the load line
- Failure occurs when load line intersects with failure envelope.
- Factor of safety \Rightarrow

$$n = \frac{\sigma_b}{\sigma_a}$$

Maximum distortion Energy Theory (von Mises)

- Failure occurs when strain energy due to distortion exceeds a critical value.
 - Material dependent
 - Experimentally obtained



Total strain energy

$$w = \frac{1}{2} \sigma \cdot \epsilon = \frac{1}{2} (\sigma_x \epsilon_x + \sigma_y \epsilon_y + \sigma_z \epsilon_z + 2\tau_{xy} \epsilon_{xy} + 2\tau_{xz} \epsilon_{xz} + 2\tau_{yz} \epsilon_{yz}) \\ = \frac{1}{2} (\sigma_1 \epsilon_1 + \sigma_2 \epsilon_2 + \sigma_3 \epsilon_3)$$

$$\epsilon_1 = \frac{1}{E} \{ \sigma_1 - \nu(\sigma_2 + \sigma_3) \}$$

$$\epsilon_2 = \frac{1}{E} \{ \sigma_2 - \nu(\sigma_1 + \sigma_3) \}$$

$$\epsilon_3 = \frac{1}{E} \{ \sigma_3 - \nu(\sigma_1 + \sigma_2) \}$$

$$w = \frac{1}{2E} \{ \sigma_1^2 + \sigma_2^2 + \sigma_3^2 - 2\nu(\sigma_1 \sigma_2 + \sigma_2 \sigma_3 + \sigma_3 \sigma_1) \}$$

strain energy due to volume change

$$(\epsilon_1 + \epsilon_2 + \epsilon_3) = \frac{1-2\nu}{E} (\sigma_1 + \sigma_2 + \sigma_3)$$

- Average strain: $\epsilon_{avg} = \frac{\epsilon_1 + \epsilon_2 + \epsilon_3}{3} = \frac{1-2\nu}{E} \left(\frac{\sigma_1 + \sigma_2 + \sigma_3}{3} \right)$

- $w_{vol} = \frac{1}{2} \sigma_{avg} \cdot \epsilon_{avg} = \frac{1}{2} \left(\frac{1-2\nu}{E} \right) \left(\frac{\sigma_1 + \sigma_2 + \sigma_3}{3} \right)^2$

Take

$$\sigma_1 = \sigma_2 = \sigma_3 = \sigma_{avg}$$

$$\Rightarrow w_v = \frac{1}{2} (\sigma_1 \epsilon_1 + \sigma_2 \epsilon_2 + \sigma_3 \epsilon_3)$$

$$= \frac{1}{2} \sigma_{avg} (\epsilon_1 + \epsilon_2 + \epsilon_3) \\ = \frac{3}{2E} (1-2\nu) \sigma_{avg}^2$$

strain energy due to distortion

$$w_d = w - w_v = \frac{1}{2E} \{ (\sigma_1^2 + \sigma_2^2 + \sigma_3^2 - 2\nu(\sigma_1 \sigma_2 + \sigma_2 \sigma_3 + \sigma_3 \sigma_1)) \\ - \frac{(1-2\nu)}{2} (\sigma_1 + \sigma_2 + \sigma_3)^2 \}$$

$$= \left(\frac{1+\nu}{3E} \right) \left[((\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + \frac{6E}{(\sigma_3 - \sigma_1)^2}) / 2 \right]$$

Uniaxial Elongation

$$\sigma_1 \neq 0$$

$$\sigma_2 = \sigma_3 = 0$$

$$\Rightarrow W_{vol} = \left(\frac{1+\nu}{3E} \right) \sigma_1^2 \geq W_{ext} = \left(\frac{1+\nu}{3E} \right) s_y^2$$

$$\boxed{\sigma_1 \geq s_y}$$

In general

$$\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{2} \geq s_y^2$$

$$(\sigma')^2$$

$$\text{or } \sigma' = \sqrt{\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{2}} \geq s_y$$

von mises stress

for failure

Von Mises Failure Theory

Von Mises Stress:

$$\sigma' = \sqrt{\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{2}} \geq s_y$$

for failure

for general stress state:

$$\sigma = \begin{bmatrix} \sigma_x & \tau_{xy} & \tau_{xz} \\ \tau_{xy} & \sigma_y & \tau_{yz} \\ \tau_{xz} & \tau_{yz} & \sigma_z \end{bmatrix}$$

$$\sigma' = \sqrt{\frac{(\sigma_x - \sigma_y)^2 + (\sigma_y - \sigma_z)^2 + (\sigma_z - \sigma_x)^2 + 6(\tau_{xy}^2 + \tau_{yz}^2 + \tau_{xz}^2)}{2}}$$

For Plane stress:

$$\tau_z = \tau_{xz} = \tau_{yz} = 0.$$

$$\sigma' = \sqrt{\sigma_x^2 + \sigma_y^2 + 3\tau_{xy}^2 - \sigma_x \sigma_y}$$

or when principal stresses in the plane are known

$$\sigma_1 = \sigma_A, \quad \sigma_2 = \sigma_B, \quad \sigma_3 = 0.$$

$$\Rightarrow \sigma' = \sqrt{\sigma_A^2 + \sigma_B^2 - \sigma_A \sigma_B}$$

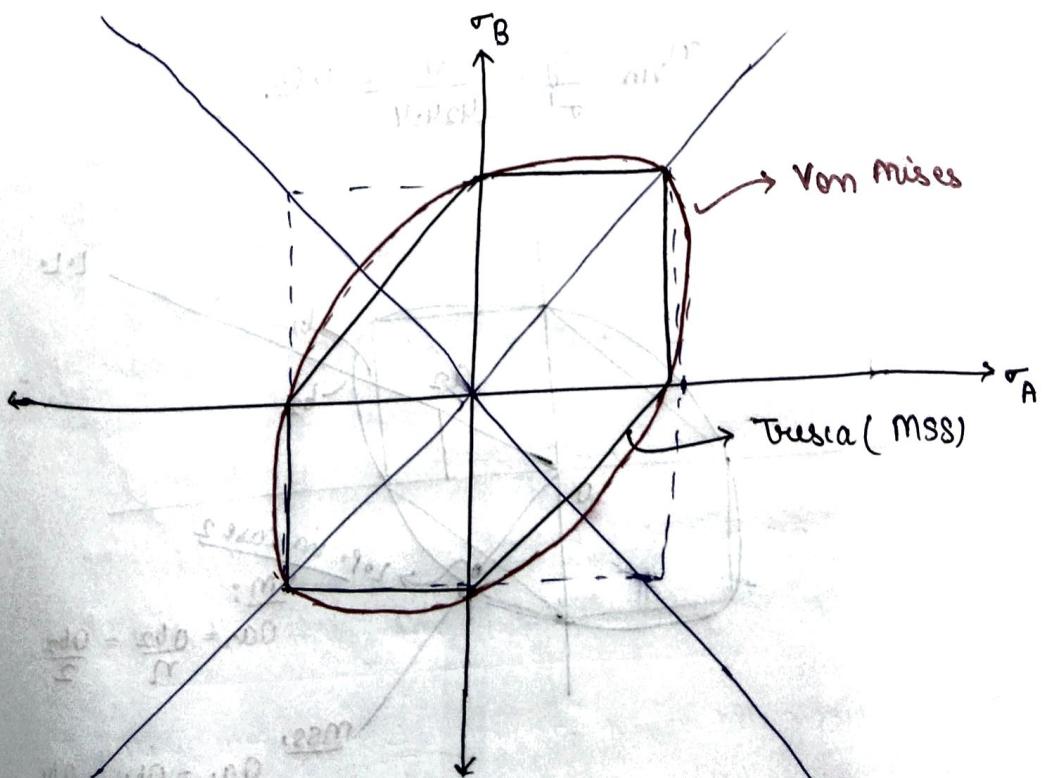
For failure,

$$\sigma' = \sqrt{\sigma_A^2 + \sigma_B^2 - \sigma_A \sigma_B} \geq s_y \text{ or } \frac{s_y}{n}$$

Equation for failure envelope:

$$\sigma_A^2 + \sigma_B^2 - \sigma_A \sigma_B = s_y^2$$

$$\frac{1}{4}(\sigma_A + \sigma_B)^2 + \frac{3}{4}(\sigma_A - \sigma_B)^2 = s_y^2$$



* Tresca failure theory is more conservative.

Eg. Yield strength: $s_y = 700 \text{ MPa}$
 (both in tension and compression)

Stresses due to loading:

$$\sigma_1 = 490 \text{ MPa}$$

$$\sigma_2 = 250 \text{ MPa}$$

$$\sigma_3 = 0.$$

Estimate the factor of safety using von Mises and Tresca criteria (Max. shear stress)

$$\text{Sol.} \rightarrow \tau_{\max} = \frac{490}{2} = 245 \text{ MPa.}$$

$$\sigma' = \sqrt{\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{2}}$$

$$\Rightarrow \sigma' = 424.4 \text{ MPa.}$$

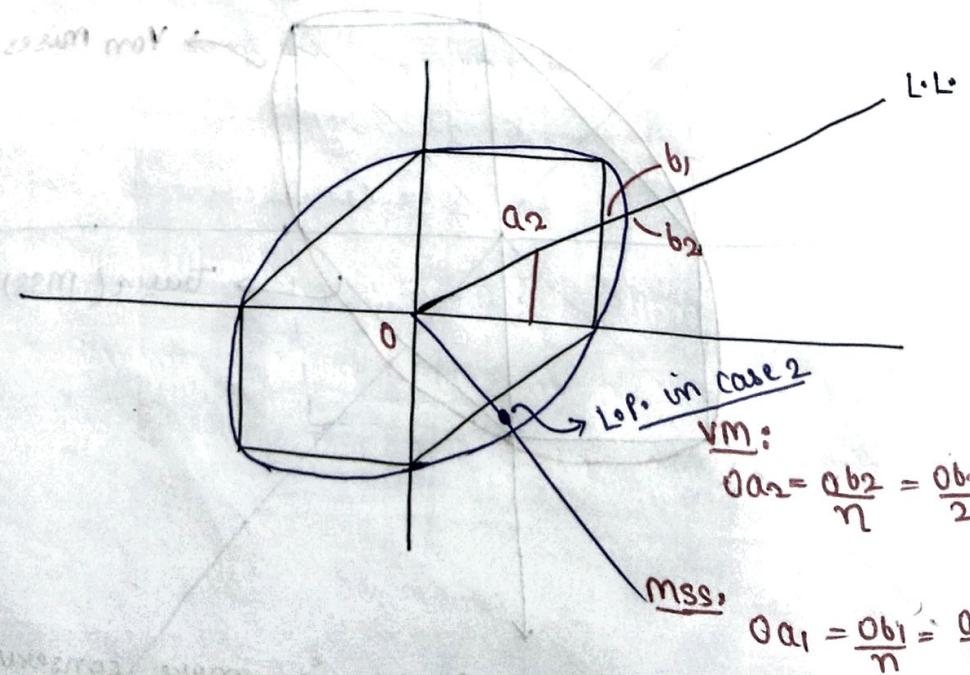
Factor of safety:

$$n_{MSS} = \frac{700}{2\tau_{\max}} \quad \left(\tau_{\max} > \frac{s_y}{2n} \right)$$

for failure

$$n_{MSS} = 1.43$$

$$n_{VM} = \frac{s_y}{\sigma'} = \frac{700}{424.4} = 1.65.$$



\Rightarrow For given n and s_y , v.m. permits larger load.

Case 2 \rightarrow

$$\sigma_1 = 490 \text{ MPa}$$

$$\sigma_2 = -250 \text{ MPa}$$

$$\sigma_3 = 0 \text{ MPa.}$$

$$\tau_{\max} = 370 \text{ MPa}$$

$$\sigma' = 652 \text{ MPa.}$$

$$n_{MSS} = \frac{700}{2\tau_{\max}} = 0.95$$

$$n_{VM} = \frac{s_y}{\sigma'} = 1.07$$

Case 3 \rightarrow

$$\sigma_x = 300 \text{ MPa}$$

$$\sigma_y = 210 \text{ MPa}$$

$$\tau_{xy} = 100 \text{ MPa.}$$

$$\tau_{\max} = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} = 109.66 \text{ MPa.} \\ \approx 110 \text{ MPa.}$$

XX

$$n_{MSS} = \frac{700}{2 \times 110} = 3.18$$

$$n_{VM} = \frac{700}{318} = 2.20$$

$$\underline{\underline{mss}}: \sigma_A > \sigma_B > 0 \Rightarrow \tau_{\max} = \frac{\sigma_A}{2} = 365 \text{ MPa.}$$

$$\Rightarrow n_{MSS} = \frac{700}{365} =$$

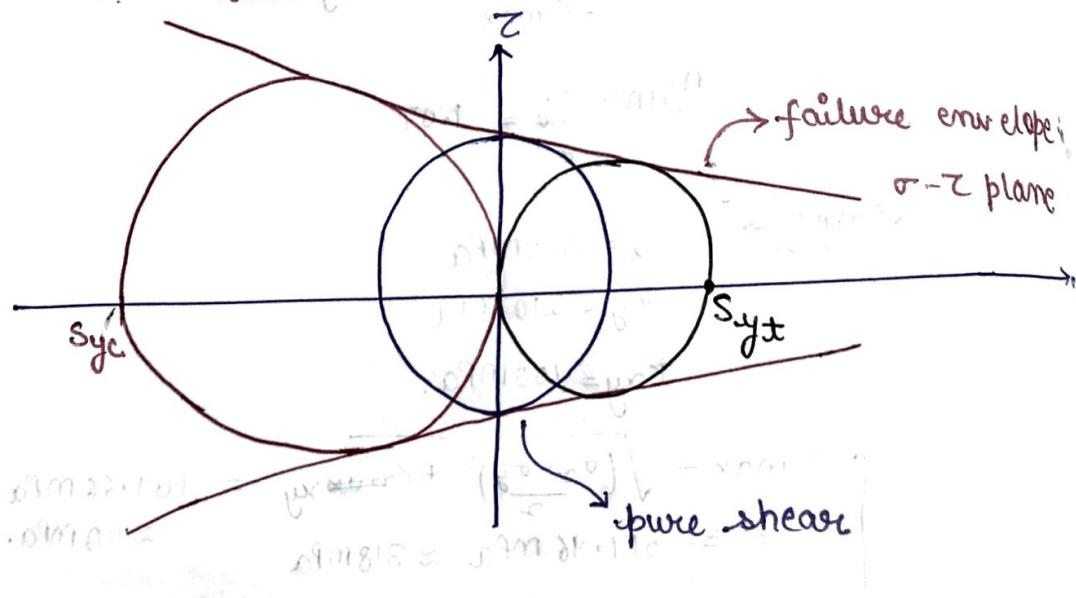
$$n_{VM} = \frac{300}{318} =$$

when yield strength in tension and compression are different

- $s_{yt} \rightarrow$ yield strength in tension
- $s_{yc} \rightarrow$ ——— compression

Mohr's criteria for ductile materials:

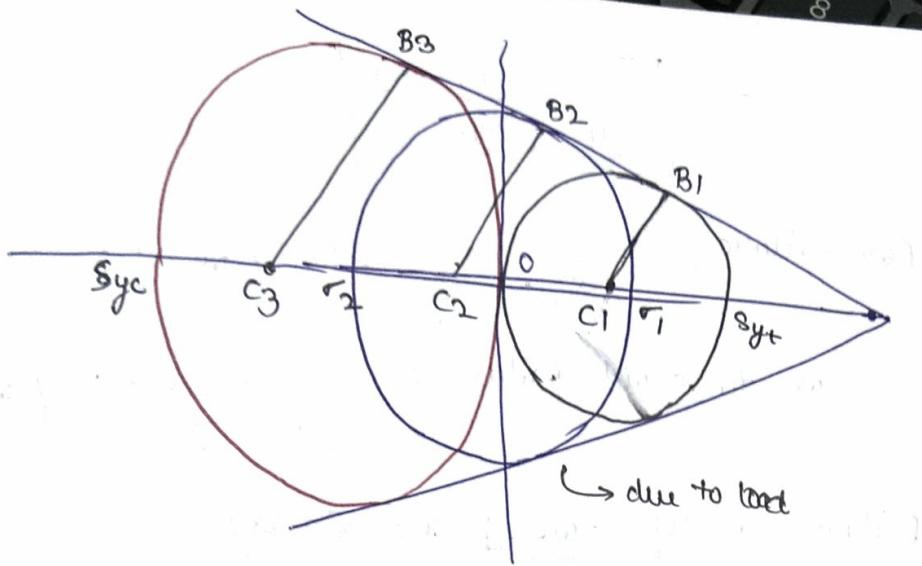
uses test results for pure tension, pure compression and pure shear \rightarrow uniaxial



$$\begin{aligned} \text{pressure } p &\Rightarrow \sigma_A = 2p; \sigma_B = -p \Rightarrow \tau_{avg} = \frac{p}{2}, \\ &\rightarrow 2p \Rightarrow \sigma_A = 4p; \sigma_B = -2p \quad \tau_{max} = \frac{3p}{2} \\ &\qquad\qquad\qquad \Rightarrow \sigma_{avg} = p \quad \tau_{max} = \frac{3p}{2} \end{aligned}$$

Mohr-Coulomb: (Internal friction theory)

- Assumes failure curve is a straight line
 \Rightarrow only two test data are sufficient.



$$B_1 C_1 = \frac{Syt}{2}$$

$$B_2 C_2 = \frac{(\sigma_1 - \sigma_3)}{2}$$

$$B_3 C_3 = \frac{Syc}{2}$$

$$\left. \begin{array}{l} C_3 \rightarrow \left(-\frac{Syc}{2}, 0 \right) \\ C_2 \rightarrow \left(\frac{\sigma_1 + \sigma_3}{2}, 0 \right) \\ C_1 \rightarrow \left(\frac{Syt}{2}, 0 \right) \end{array} \right\} \text{co-ordinates}$$

$\Delta O B_1 C_1$, $\Delta O B_2 C_2$, $\Delta O B_3 C_3$ are similar

$$\Rightarrow \frac{B_3 C_3}{O C_3} = \frac{B_2 C_2}{O C_2} = \frac{B_1 C_1}{O C_1} \Rightarrow \frac{B_3 C_3 - B_1 C_1}{O C_3 - O C_1} = \frac{B_2 C_2 - B_1 C_1}{O C_2 - O C_1}$$

$$\Rightarrow \frac{B_3 C_3 - B_1 C_1}{C_1 C_3} = \frac{B_2 C_2 - B_1 C_1}{C_1 C_2}$$

$$\Rightarrow \frac{(Syc - Syt)/2}{(Syc + Syt)/2} = \frac{\{(\sigma_1 - \sigma_3) - Syt\}/2}{\{Syt - (\sigma_1 + \sigma_3)\}/2}$$

$$\Rightarrow \frac{Syc - Syt}{Syc + Syt} = \frac{(\sigma_1 - \sigma_3) - Syt}{Syt - (\sigma_1 + \sigma_3)}$$

$$\Rightarrow \boxed{\frac{\sigma_1}{Syt} - \frac{\sigma_3}{Syc} = 1}$$

For failure, $\frac{\sigma_1}{Syt} - \frac{\sigma_3}{Syc} \geq 1$ (or ≥ 1)

or to avoid failure: $\frac{\sigma_1}{Syt} - \frac{\sigma_3}{Syc} < 1$ (or < 1)

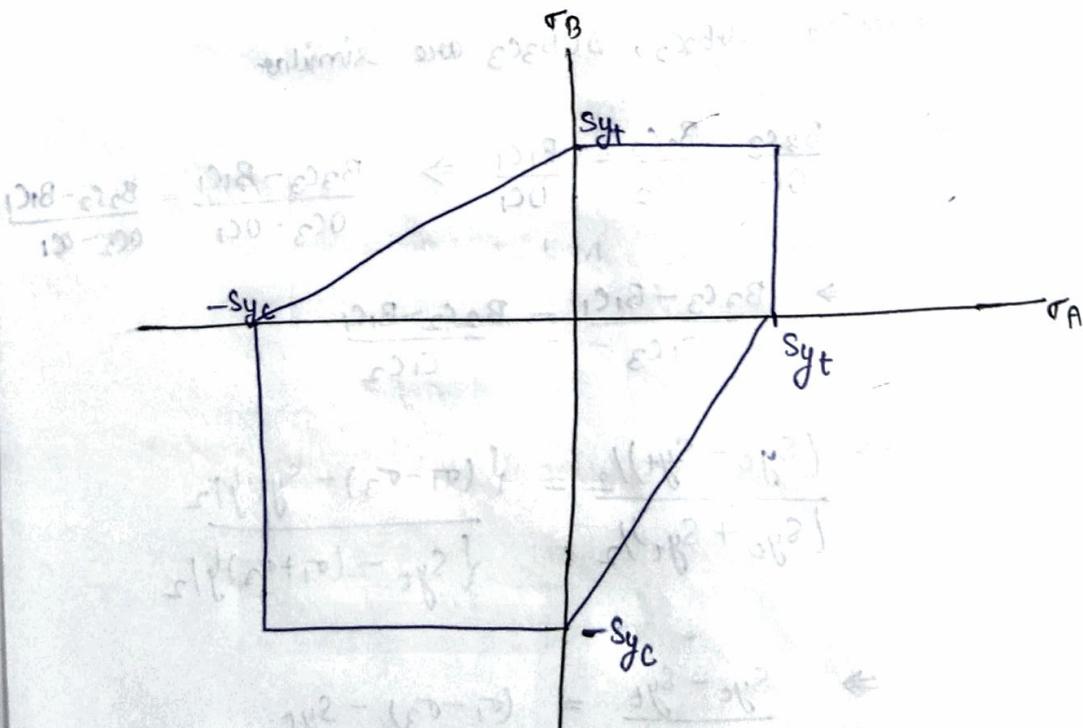
Failure envelope for plane stress:

Principal stresses are: $\sigma_A, \sigma_B, 0$

1. $\sigma_A \geq \sigma_B > 0 : \sigma_1 = \sigma_A, \sigma_3 = 0$

$$\Rightarrow \frac{\sigma_A}{Syt} \geq 1 \text{ for failure}$$

2. $0 > \sigma_B \geq \sigma_A \Rightarrow \sigma_1 = 0, \sigma_3 = \sigma_A \Rightarrow -\frac{\sigma_A}{Syc} \geq 1$
for failure



3. $\sigma_A > 0 \geq \sigma_B \Rightarrow \sigma_1 = \sigma_A, \sigma_3 = \sigma_B \Rightarrow \frac{\sigma_A}{Syt} - \frac{\sigma_B}{Syc} \geq 1$

4. $\sigma_B > 0 \geq \sigma_A \Rightarrow \sigma_1 = \sigma_B, \sigma_3 = \sigma_A \Rightarrow \frac{\sigma_B}{Syt} - \frac{\sigma_A}{Syc} \geq 1$

Load in pure shear:

$\Rightarrow \tau > S_{sy}$ for failure

or limit: $\tau = S_{sy} \rightarrow$ yield strength in shear

$$\sigma_A = S_{sy} \quad \sigma_B = -S_{sy}$$

\Rightarrow Envelope, $\frac{\sigma_A}{S_{yt}} - \frac{\sigma_B}{S_{yc}} = 1$

$$\Rightarrow \frac{S_{sy}}{S_{yt}} + \frac{S_{sy}}{S_{yc}} = 1 \Rightarrow S_{sy} = \frac{S_{yt} S_{yc}}{(S_{yt} + S_{yc})}$$

Von Mises

find σ for pure shear

$$\sigma' < s_y$$

for pure shear

$$\sigma_A = S_{sy}, \quad \sigma_B = -S_{sy} \quad \sigma' = \sqrt{3} S_{sy}$$

$$\Rightarrow \sqrt{3} S_{sy} = s_y$$

$$\text{or } S_{sy} = \frac{s_y}{\sqrt{3}} \text{ or } 0.572 s_y$$

Failure of ductile materials

1. If $S_{yt} = S_{yc}$, use Tresca or Von Mises

2. If $S_{yt} \neq S_{yc}$ use Mohr-Coulomb.

Failure of brittle materials:

- very less deformation before failure
- failure due to fracture

maximum Normal stress Theory:

- material fails when normal stress exceeds a value experimentally obtained
- $\sigma_1 > \sigma_2 > \sigma_3$ are the principal stresses.

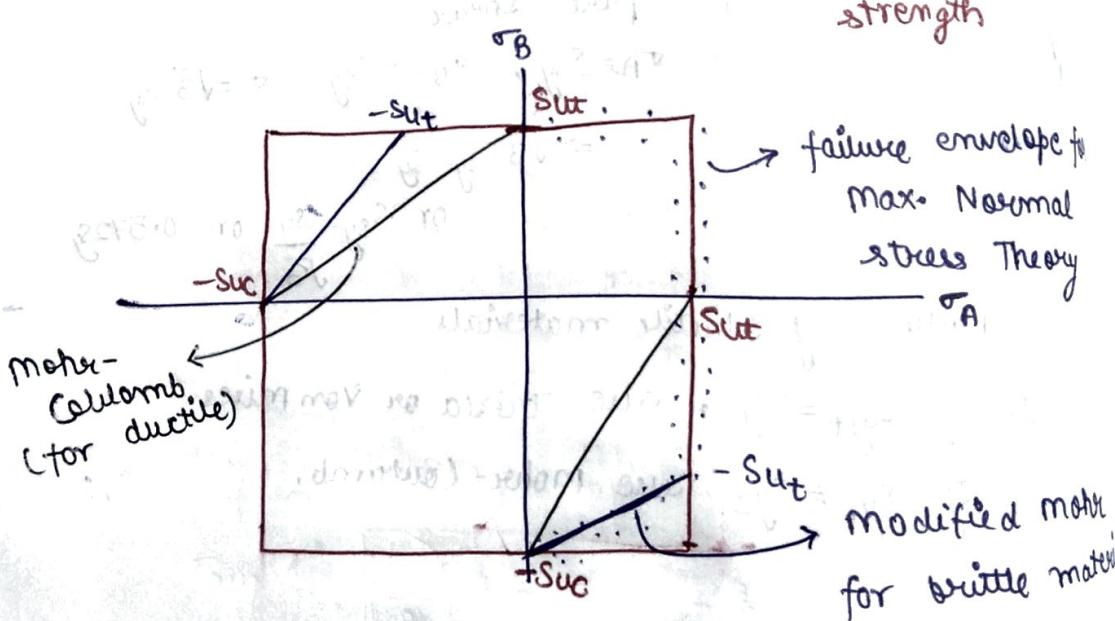
⇒ failure condition:

$$\sigma_1 > S_{ut} \text{ or } \left(\frac{S_{ut}}{n} \right)$$

↳ ultimate tensile strength

$$\text{or } \sigma_3 \leq -S_{uc} \left(\frac{S_{uc}}{n} \right)$$

↳ ultimate compressive strength



$$2. \quad \frac{S_{uc}}{S_{ut}}$$

$$3. \quad \sigma_B$$

Failure



Modified Mohr (Plane stress condition)

$$1. \quad \sigma_1 = S_{ut} \text{ or } \frac{S_{ut}}{n} \quad \text{if } \sigma_A > \sigma_B \geq 0$$

$$\sigma_A > 0 > \sigma_B$$

$$\text{and } \left| \frac{\sigma_B}{\sigma_A} \right| \leq 1$$

$$2. \quad \frac{S_{uc}}{S_{ut}}$$

$$3. \quad \sigma_B$$

2. $\frac{S_{uc} - S_{ut}}{S_{uc} S_{ut}} \cdot \sigma_A - \frac{\sigma_B}{S_{uc}} = 1 \quad (\text{or } \frac{1}{n}) \quad \text{if}$

$\sigma_A > 0 > \sigma_B$
and $|\frac{\sigma_B}{\sigma_A}| > 1$

3. $\sigma_B = -S_{uc} \left(\text{or } -\frac{S_{uc}}{n} \right) \quad \text{if } 0 > \sigma_A \geq \sigma_B$

Failure by instability: (Column buckling)



- Column (member under compression) failure does not happen due to yielding or fracture. Rather deflection becomes large
- Critical buckling load depends on
 1. length
 2. Young's modulus
 3. gross section.

1. For simply supported ends:

$$P_{cr} = \frac{n^2 \pi^2 EI}{l^2}$$

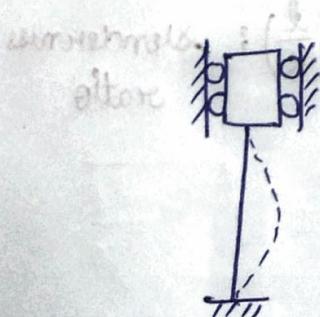
for subse
militants

Lowest value is for $n=1$.

\Rightarrow Critical buckling load:

$$P_{cr} = \frac{\pi^2 EI}{l^2}$$

2. fixed-fixed ends:



$$P_{cr} = \frac{4\pi^2 EI}{l^2}$$

$$\lambda = 4$$

3. fixed-free



$$P_{cr} = \frac{1}{4} \frac{\pi^2 EI}{l^2}$$

4. Pinned-fixed:



$$P_{cr} = 2 \frac{\pi^2 EI}{l^2}$$

$$c=2$$

In summary:

$$P_{cr} = c \cdot \frac{\pi^2 EI}{l^2}$$

end condition
constant

$$\rightarrow P_{cr} = c \cdot \frac{\pi^2 EI}{l^2}$$

$$I = A \cdot k^2$$

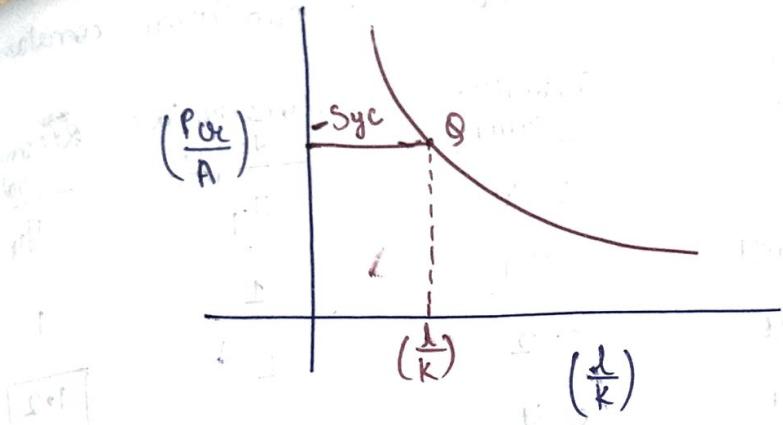
↓
radius of
gyration

$$= c \cdot \frac{A \pi^2 E}{(lk)^2}$$

τ_{avg}
(Average
stress)

$$\boxed{\frac{P_{cr}}{A} = c \cdot \frac{\pi^2 E}{\left(\frac{l}{k}\right)^2}}$$

$\left(\frac{l}{k}\right)$: slenderness
ratio



- Critical buckling load depends more on $(\frac{l}{k})$ than material
- Mild steel, High strength steel have same E, but significant diff. yield strength.
- If $\frac{P_{ax}}{A} \leq -S_{yc}$ or $-S_{uc}$ failure is due to yielding or fracture

when

$$\left(\frac{l}{k}\right) = \left(\frac{l}{k}\right)_Q : \quad \left|\frac{P_{ax}}{A}\right| = S_{yc} \Rightarrow S_{yc} = c \frac{\pi^2 E}{(l/k)^2}$$

$$\Rightarrow \left(\frac{l}{k}\right)_Q = \sqrt{\frac{c \pi^2 E}{S_{yc}}}$$

Euler-buckling:

$$\frac{P_{ax}}{A} = c \frac{\pi^2 E}{(l/k)^2} \quad \text{when } \left(\frac{l}{k}\right) > \left(\frac{l}{k}\right)_Q$$

$$= S_{yc} \quad \text{when } \left(\frac{l}{k}\right) \leq \left(\frac{l}{k}\right)_Q$$

- Recommended values for end-condition constant

End cond'n

fixed-free

Theoretical value

$$c = 1/4$$

Conservative design

$$1/4$$

Recommended
 $1/10$

pinned-pinned

$$c = 1$$

$$1$$

fixed-pinned

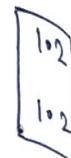
$$c = 2$$

$$1$$

fixed-fixed

$$c = 4$$

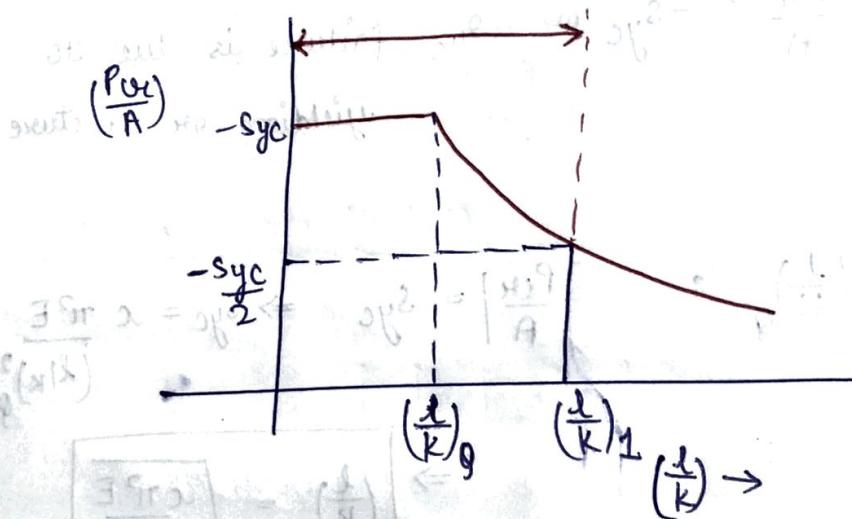
$$1$$



→ Euler-column theory works well for large $(\frac{l}{k})$.

Near $(\frac{l}{k}) = (\frac{l}{k})_0$ not very accurate.

intermediate length column



- Rule of Thumb: Apply Euler-column formula

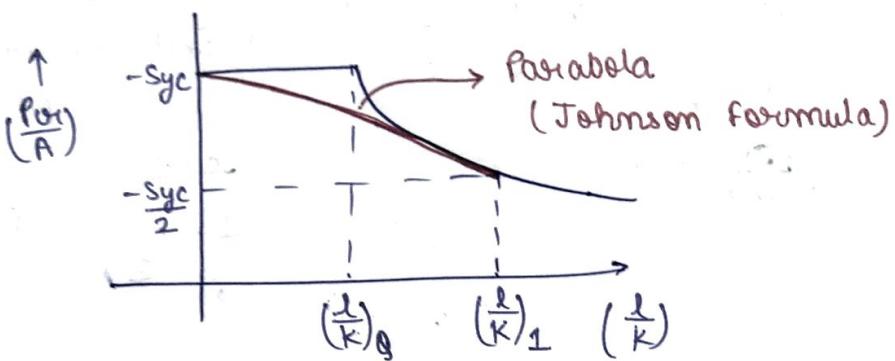
$$\text{if } (\frac{l}{k}) > (\frac{l}{k})_1$$

Typically $(\frac{l}{k})_1$ is chosen such that

$$\frac{P_{cr}}{A} = \frac{S_{yc}}{2} \quad \text{or} \quad (\frac{l}{k})_1 = \sqrt{2C \frac{\pi^2 E}{S_{yc}}}$$

Intermediate length columns

$$0 \leq \left(\frac{l}{k}\right) \leq \left(\frac{l}{k}\right)_1$$



→ Johnson proposed a parabola for $0 \leq \frac{l}{k} \leq (\frac{l}{k})_1$

$$\frac{P_{cr}}{A} = a - b \left(\frac{l}{k} \right)^2 \quad \text{for } 0 \leq \frac{l}{k} \leq (\frac{l}{k})_1$$

- $\frac{P_{cr}}{A} = syc$ for $\frac{l}{k} = 0$.

- $\frac{P_{cr}}{A} = \frac{syc}{2}$ for $\frac{l}{k} = (\frac{l}{k})_1 = \sqrt{\frac{2c\pi^2 E}{syc}}$

$$\Rightarrow a = syc, \quad b = \left(\frac{syc}{2\pi} \right)^2 \cdot \frac{1}{CE}$$

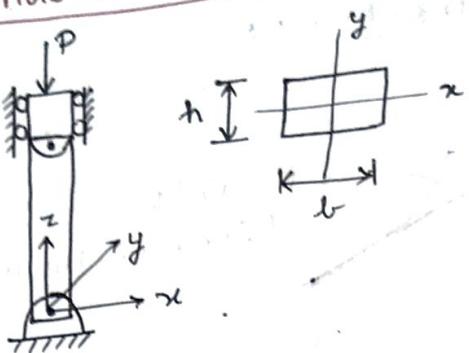
Johnson Column formula:

$$\frac{P_{cr}}{A} = syc - \left(\frac{syc}{2\pi} \frac{l}{k} \right)^2 \cdot \frac{1}{CE} \quad \text{for } 0 \leq \frac{l}{k} \leq (\frac{l}{k})_1$$

$$= c \frac{\pi^2 E}{(lk)^2} \quad \text{for } (\frac{l}{k}) > (\frac{l}{k})_1$$

$$(\frac{l}{k})_1 = \sqrt{\frac{2c\pi^2 E}{syc}} \quad \left(\text{at } \frac{l}{k} = (\frac{l}{k})_1 : \frac{P_{cr}}{A} = \frac{syc}{2} \right)$$

A note on end condition:



Buckling in $x-z$ plane

- End condition - pinned-pinned

$$c = 1$$

$$I = \frac{b h^3}{12} \quad P_{cr} = \frac{\pi^2 E I}{L^2}$$

- Buckling in $y-z$ plane (out of plane)

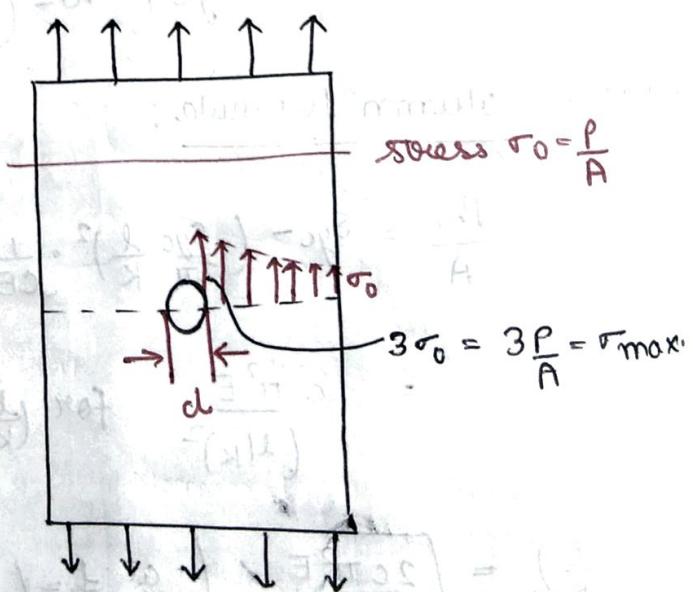
→ End condition - fixed-fixed

$$c = 4 \quad (\text{theoretical})$$

$$= 1.2 \quad (\text{recommended})$$

$$I = \frac{b h^3}{12}$$

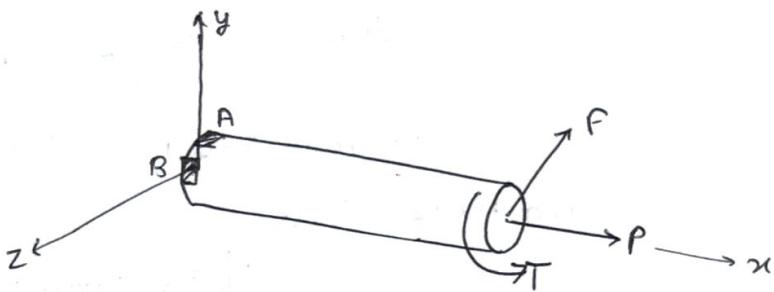
Stress concentration



$$\text{Stress concentration factor} \quad K_t = \frac{\sigma_{\max}}{\sigma_0}$$

$$\Rightarrow \sigma_{\max} = K_t \cdot \sigma_0$$

Problem → Length = 150 mm
 Dia = 15 mm
 Material = AISI 1006 CD.



$$F = 0.55 \text{ kN}$$

$$P = 4 \text{ kN}$$

$$T = 25 \text{ N}\cdot\text{m}$$

Compute stress at A & B.

$$\text{At A: Axial } \sigma_{\text{axial}} = \frac{4P}{\pi d^2} = 22.6 \text{ MPa}$$

$$\text{Shear stress: } \tau = \frac{16T}{\pi d^3} = 37.7 \text{ MPa.}$$

$$\text{Bending moment at } x=0 \quad M = Fl = 55 \text{ Nm}$$

$$\text{Bending stress: } \sigma_{\text{bending}} = 0 \text{ MPa.}$$

Shear stress due to transverse force F

$$\text{maximum at A: } \tau_F = \frac{4F}{3A} = \frac{16F}{3\pi d^2} \\ = 4.14 \text{ MPa.}$$

Total shear stress at A:

$$\tau = \frac{16T}{\pi d^3} - \frac{4F}{3A} = 33.56 \text{ MPa.}$$

Von Mises stress:

$$\sigma' = \sqrt{(\sigma_{\text{bending}} + \sigma_{\text{axial}})^2 + 3\tau^2}$$

$$= \sqrt{22.6^2 + 33.56^2} = 48.46 \text{ MPa}$$

$$= 62.4 \text{ MPa}$$

At B: Axial stress $\sigma_{\text{axial}} = 22.6 \text{ MPa}$
 Bending stress $\tau_b = \frac{32M}{\pi d^3} = 166 \text{ MPa}$

Torsion $\tau = \frac{16T}{\pi d^3} = 37.7 \text{ MPa}$

Transverse force F: $\tau = 0 \text{ MPa}$

Von Mises stress

$$\sigma'_B = \sqrt{(\sigma_{\text{axial}} + \tau_b)^2 + 3\tau^2}$$

$$= \sqrt{(166+22.6)^2 + 3 \times 37.7^2}$$

$$= 199.6 \text{ MPa.}$$

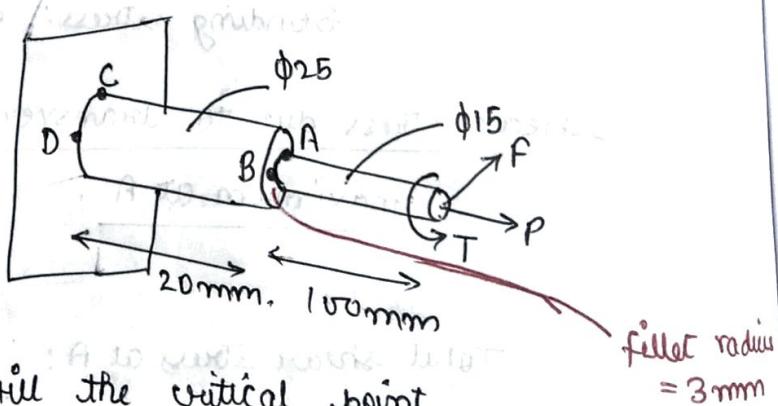
Find material prop of AISI 1006 CD.

From table A20, $S_y = 280 \text{ MPa}$

$$\text{factor of safety} \Rightarrow n_A = \frac{280}{62.4} = 4.48$$

$$n_B = \frac{280}{199.6} = 1.4$$

→ Added a step →



⇒ B is still the critical point.

Stresses at B:

	Nominal	Stress con. factor	Actual stress
Axial	$\sigma_{a0} = 22.6 \text{ MPa}$	1.65 (fig A15-7)	37.3 MPa
Bending	$\tau_{b0} = 166 \text{ MPa}$	1.42 (A-15-9)	235.7 MPa
Torsion	$\tau_0 = 37.7 \text{ MPa}$	1.23 (A-15-8)	46.4 MPa
Transverse force	$\tau_0 = 0 \text{ MPa}$	-	-

$$\frac{D}{d} = \frac{25}{15} = 1.67$$

$$\frac{\sigma_c}{d} = \frac{3}{15} = 0.2$$

$$\sigma_B' = \sqrt{137.3 + 235.71^2 + 3 \times 46.4^2} = 286.6 \text{ MPa.}$$

$$m = \frac{280}{286.6} = 0.97$$

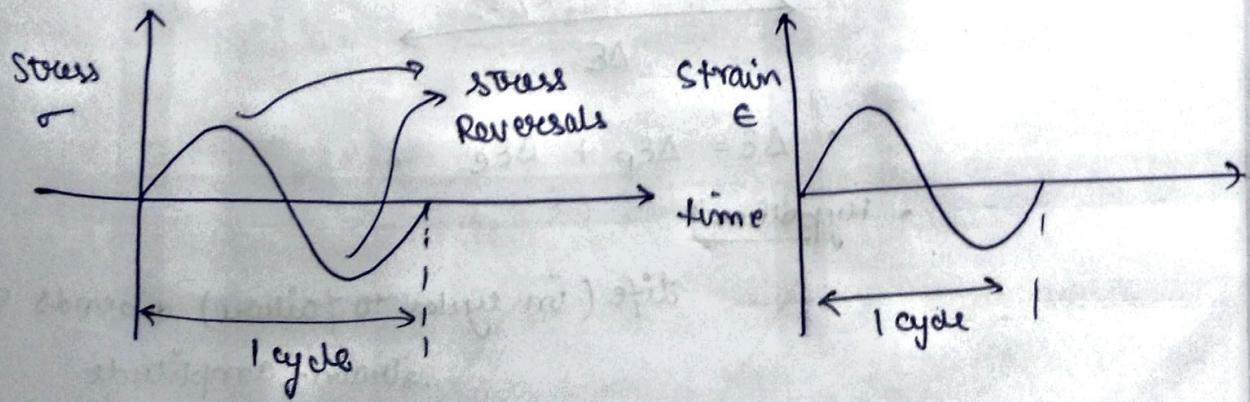
Fatigue failure

- Load varies with time
- Most of the time failure happens much before yield strength or ultimate strength is reached.
- fails mainly due to crack formation and propagation
(comes without warning)

Failure location →

- Rapid change in cross section or geometry.
- Surfaces under high contact pressure or relative motion.
- microscopic defects due to processing.

Fatigue failure



Estimating fatigue life:

- strength at which a part fails depends on No. of cycles of operation

$$N = \text{No. of cycles}$$

$$\Rightarrow 2N = \text{No. of Reversals}$$

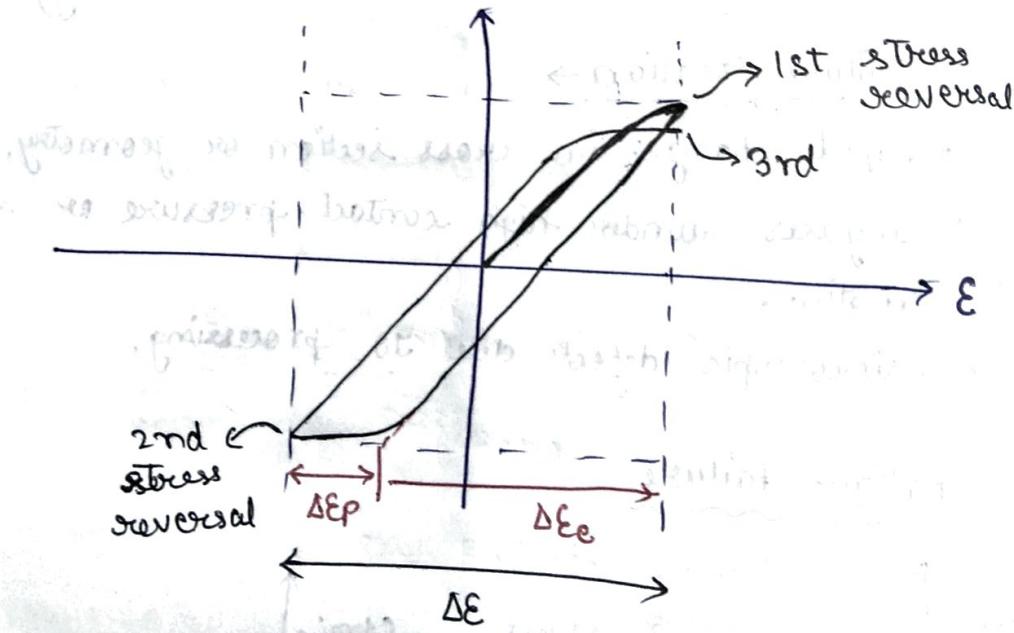
Methods of estimating life

1. strain-life method } will discuss
2. stress-life method
3. linear elastic fracture mechanics

strain-life

For fatigue failure to occur there must be plastic strain accumulation.

(envelope method)



$$\Delta \epsilon = \Delta \epsilon_p + \Delta \epsilon_e$$

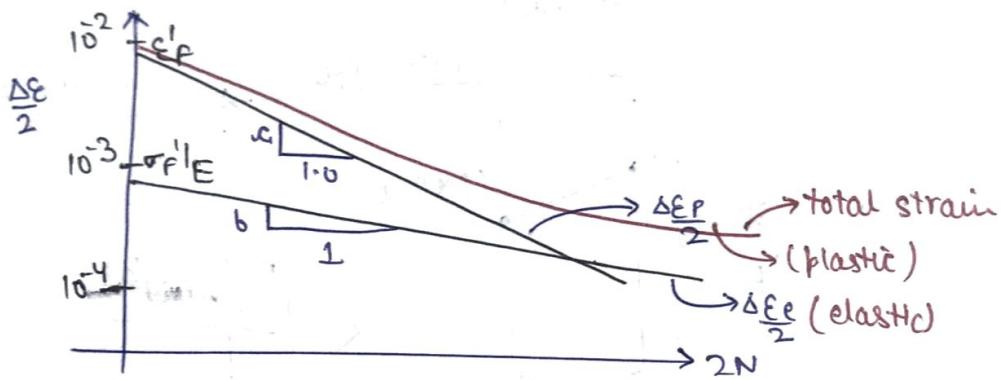
Hypothesis

life (in cycles to failure) depends on
strain-amplitude

Manson-Coffin relation

$$\frac{\Delta \epsilon}{2} = \frac{\sigma_f'(2N)^b}{E} + \epsilon_f'(2N)^c$$

$\underbrace{\frac{\Delta \epsilon_e}{2}}_{\Delta \epsilon_e}$ $\underbrace{\frac{\Delta \epsilon_p}{2}}_{\Delta \epsilon_p}$

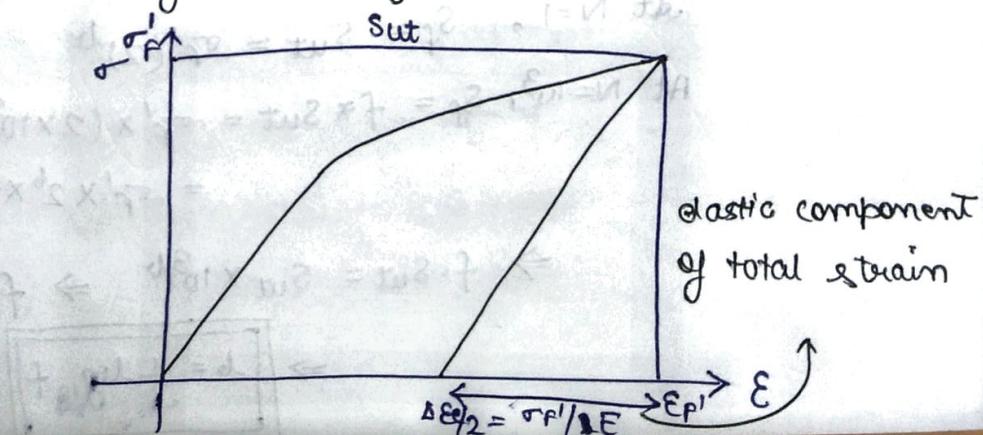


$$S_{ut} = \frac{\Delta \epsilon_e}{E} = \frac{\sigma_f'}{E}$$

$$\frac{\Delta \epsilon}{2} = \frac{\sigma_f'}{E} (2N)^b + \epsilon_f' (2N)^c$$

- ϵ_f' = True strain at failure after one reversal
(Fatigue ductility coefficient)
- σ_f' = True stress $\frac{\Delta \epsilon_e}{E}$
(Fatigue strength coefficient)

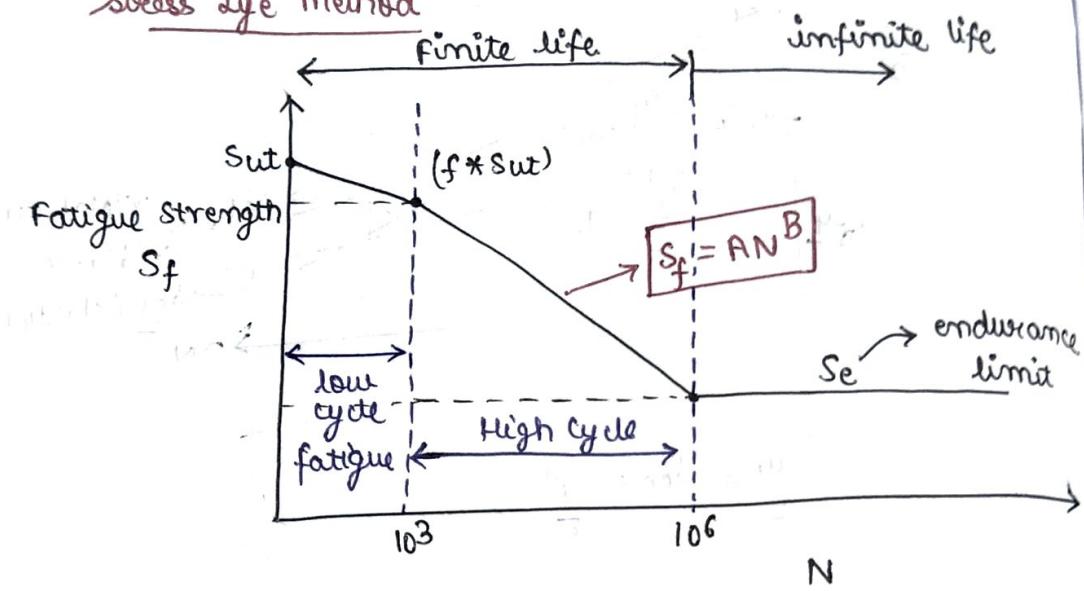
- b = fatigue strength exponent
- c = fatigue ductility exponent



Limitations of strain-life method

1. Determination of local strain at notch, (around stress-concentration location)
2. Accurate for low cycle fatigue ($1-10^3$ cycles)

Stress life Method



- Accurate for high cycle ($10^3 - 10^6$)
- Easy to implement in design

For $1 < N < 10^3$

(from strain-life method)

$$\frac{\Delta \epsilon}{2} = \frac{\sigma_f'(2N)^b}{E} + \epsilon_f'(2N)^c$$

(After N -cycles) $(\Delta \epsilon_c / 2)$

$$S_f = E \cdot \frac{(\Delta \epsilon_c)}{2} = \sigma_f'(2N)^b$$

$$\text{At } N=1, S_f = S_{ut} = \sigma_f'(2)^b$$

$$\begin{aligned} \text{At } N=10^3, S_f &= f \cdot S_{ut} = \sigma_f' \times (2 \times 10^3)^b \\ &= \sigma_f' \times 2^b \times 10^{3b} \end{aligned}$$

$$\Rightarrow f \cdot S_{ut} = S_{ut} \times 10^{3b} \Rightarrow f = 10^{3b}$$

$$\Rightarrow b = \frac{1}{3} \log_{10} f$$

Also,

$$f = \frac{\sigma_f' \times 2^b \times 10^{3b}}{S_{ut}}$$

(from table)
★ A-23 ★

At $N = 10^6$: $S_f = S_c \rightarrow$ endurance limit

★ Fig 6-18, figure of relation b/w f and S_{ut} .

→ S_f is linear with N in log-log plot

$$\Rightarrow S_f = AN^B \rightarrow \text{eqn of line}$$

$$\Rightarrow f \cdot S_{ut} = A(10^3)^B = A \times 10^{3B}$$

$$S_c = A \times 10^{6B}$$

$$\Rightarrow \frac{f \cdot S_{ut}}{S_c} = \frac{1}{10^{3B}}$$

$$B = -\frac{1}{3} \log \left(\frac{f S_{ut}}{S_c} \right)$$

$$or$$

$$\Rightarrow A = \frac{(f \cdot S_{ut})^2}{S_c}$$

summary: 1. $S_f = S_{ut} N^{(\log f / 3)}$

for $N < 10^3$.

2. $S_f = \frac{(f \cdot S_{ut})^2}{S_c} \times N^{-\frac{1}{3} \log \left(\frac{f S_{ut}}{S_c} \right)}$
for $10^3 < N < 10^6$,

Two parameters :-

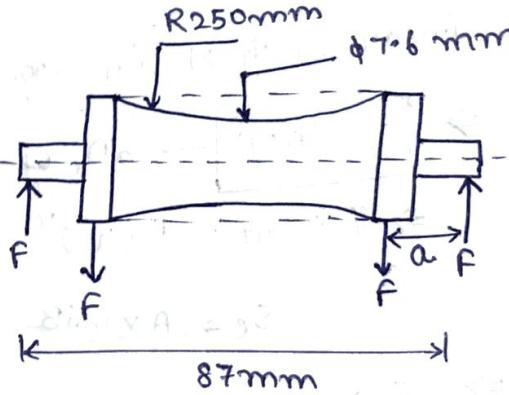
$f \rightarrow$ obtain from fig 6-18 (or from values of σ_f' and b in A-23)

2. S_c the endurance limit

Endurance limit:

From R.R. Moore specimen:

$$S_e' = \begin{cases} 0.5 S_{ut} & \text{for } S_{ut} \leq 1400 \text{ MPa} \\ 700 \text{ MPa} & \text{for } S_{ut} > 1400 \text{ MPa.} \end{cases}$$



Bending moment

$$M = F \cdot a$$

Note:

1. Al alloys do not have endurance limit
2. Actual endurance limit $S_e \neq S_e'$
R.R. Moore
Typically, $S_e \leq S_e'$
3. Modifications is due to - shape, size, loading scenario, manufacturing processes.

For actual Scenario:

$$S_e \leq S_e'$$

Marin Equation:

$$S_e = k_a k_b k_c k_d k_e k_f S_e'$$

1. $k_a = a S_{ut}^b$: surface modification factor (ground, cold rolled, ...)

Table 6.2 for a and b.

2. K_b = size factor (if the size is different from R.R. Moore specimen)

Bending and torsion

$$K_b = \begin{cases} 1.24 d^{-0.107} & \text{for } 2.79 \leq d \leq 51 \text{ mm} \\ 1.51 d^{-0.157} & \text{for } 51 \leq d \leq 254 \text{ mm} \end{cases}$$

For axial loading $K_b = 1$.

For non-rotating and non-circular cross-section
use an equivalent diameter (d_e) in place of d

(Table 6.3) ←

3. K_c = load factor

$$= \begin{cases} 1 & \text{for pure bending} \\ 0.59 & \text{for pure torsion} \\ 0.85 & \text{for pure axial loading} \end{cases}$$

For combined loading : take $K_c = 1$.

4. K_d = temperature factor

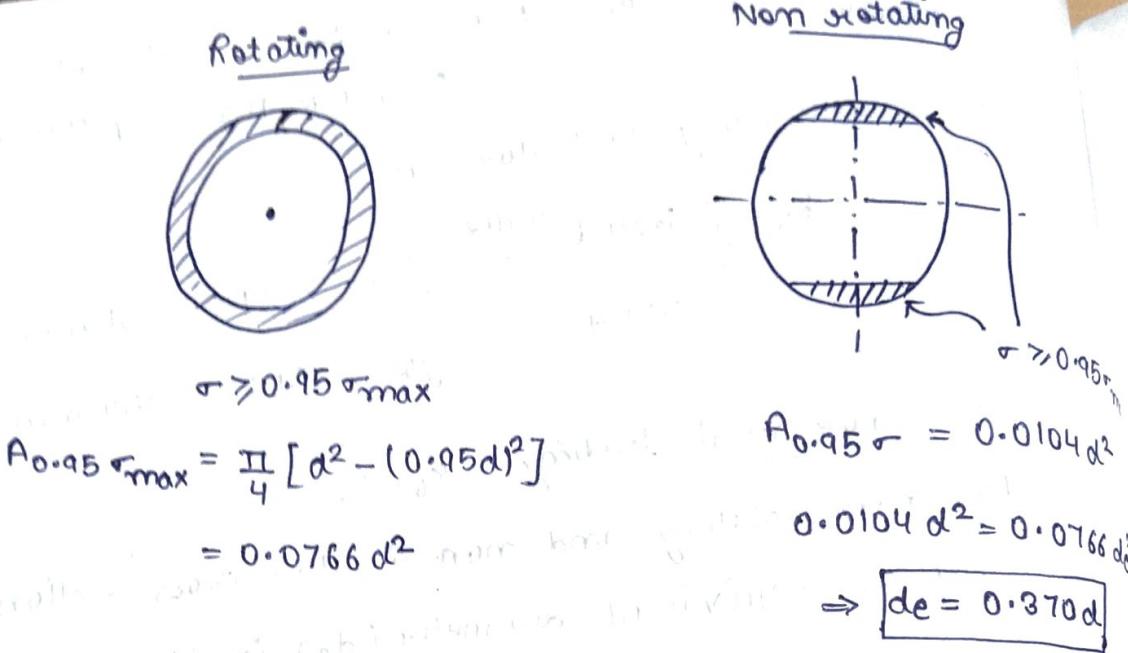
$K_d = 1$ always (for the course)

5. K_e = Reliability factor (due to scatter in data)

(Table 6.5)

6. K_f = miscellaneous effect factor

$K_f = 1$ (for the course)



AISI 1020CD:

$$S_e' = 235 \text{ MPa} \quad (S_{ut} = 470 \text{ MPa}) \\ < 1400 \text{ MPa}$$

AISI 4340, heated, to get $S_{ut} = 1760 \text{ MPa}$
Treated

$$S_e' = 700 \text{ MPa}$$

2024 T3 Al: (Al-alloy) - no endurance limit

Stress concentration and Notch sensitivity:

- For fluctuating load effect of stress concentration gets reduced
- A reduced value of stress concentration factor is used.
- For fatigue: K_f , K_{fs} (in shear)

Define notch sensitivity

$$\alpha_r = \frac{K_f - 1}{K_t - 1} \rightarrow \text{fatigue scf}$$

↳ static scf

~~Revised~~

$$\alpha_{\text{shear}} = \frac{\frac{K_{fs} - 1}{K_{ts} - 1}}{\longrightarrow \text{fatigue SCF}}$$

$\longrightarrow \text{static SCF in shear}$

$$\Rightarrow K_f = 1 + \alpha_r (K_t - 1)$$

$$K_{fs} = 1 + \alpha_{\text{shear}} (K_{ts} - 1)$$

$$0 \leq \alpha_r \leq 1 \quad \text{and} \quad 0 \leq \alpha_{\text{shear}} \leq 1$$

- $\alpha_r = 1$ or $\alpha_{\text{shear}} = 1 \Rightarrow K_f = K_t, K_{fs} = K_{ts}$

↓
fully sensitive
notch

- $\alpha_r = 0$ or $\alpha_{\text{shear}} = 0 \Rightarrow K_f = 1, K_{fs} = 1$

↓
not sensitive

fig 6-20 for α_r

fig 6-21 for α_{shear}

} wrt notch radius

Eg → steel rotating beam

$$S_{ut} = 840 \text{ MPa (122 ksi)}$$

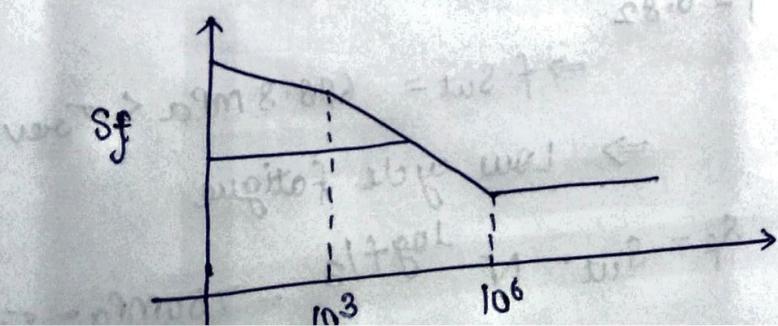
Stress amplitude: $\sigma_{\text{gen}} = 490 \text{ MPa}$

(completely reversible)

Estimate life

$$S_e' = S_e = 420 \text{ MPa.} < 490 \text{ MPa}$$

⇒ finite life



find f: (from 6-18)

$$f = 0.82$$

$$\Rightarrow f \cdot S_{ut} = 0.82 \times 840 = 688.8 \text{ MPa.} > \sigma_{rev}$$

\Rightarrow high cycle fatigue

$$S_f = A N^B, \quad B = \frac{1}{3} \log \left(\frac{f \cdot S_{ut}}{\sigma_e} \right)$$

$$A = \frac{(f \cdot S_{ut})^2}{\sigma_e}$$

$$\Rightarrow A = 968.28 \text{ MPa} \quad B = -0.0716$$
$$A = 1129.632 \text{ MPa}$$

for σ_e $S_f = \sigma_{rev} = 490 \text{ MPa}$

$$\Rightarrow 490 = A \cdot N^B \Rightarrow N = \left(\frac{490}{A} \right)^{\frac{1}{B}}$$

$$\Rightarrow N = 1.16 \times 10^5 \text{ cycles.}$$

Same question but $S_{ut} = 1610 \text{ MPa}$

$$\Rightarrow \sigma_e' = 700 \text{ MPa.} > \sigma_{rev}$$

\Rightarrow infinite life

Now, $S_{ut} = 840 \text{ MPa}$

$$\sigma_{rev} = 750 \text{ MPa.}$$

$$\sigma_e' = 420 \text{ MPa.} < \sigma_{rev}$$

\Rightarrow finite life

$$f = 0.82$$

$$\Rightarrow f \cdot S_{ut} = 688.8 \text{ MPa.} < \sigma_{rev}$$

\Rightarrow Low cycle fatigue

$$S_f = S_{ut} \cdot N^{\frac{\log f}{3}} = 750 \text{ MPa.} = \sigma_{rev}$$

$$\Rightarrow N = \left(\frac{S_{ut}}{750} \right)^{-3/\log f}$$

$$N = 51 \text{ cycles.}$$

Eg → 32 mm dia rod

- Material: AISI 1040 HR Steel
- Machined finish
- $S_{ut} = 710 \text{ MPa}$ (after heat treatment)

(a) Estimate endurance strength

$$S_e' = 0.5 S_{ut} = 355 \text{ MPa}$$

$$S_e = K_a K_b K_c K_d K_e K_f S_e'$$

1. surface finish factor

$$K_a = a S_{ut}^b \quad (a=4.51, b=-0.265 \text{ from Table 6.2}) \\ = 0.792$$

2. size factor

$$K_b = 1.24 d^{-0.107} \\ = 0.86$$

3. Load factor $K_c = 1$

4. $K_d = K_e = K_f = 1$.

$$S_e = 0.792 \times 0.86 \times 1 \times 1 \times 1 \times 1 \times 355 \\ = 241.8 \text{ MPa}$$

(b) Assume $\sigma_{rev} = 500 \text{ MPa}$ Estimate life

$\sigma_{rev} > S_e \Rightarrow$ finite life

$$\text{Find } f \quad S_{ut} = 710 \text{ MPa} = 103.11 \text{ ksi}$$

$$f = 0.842 \text{ (fig 6-18)}$$

$$\Rightarrow f \cdot S_{ut} = 597.82 \text{ MPa} > \sigma_{rev}$$

→ high cycle fatigue.

$$\Rightarrow S_f = A N^B$$

$$A = \frac{(f \cdot S_{ut})^2}{S_e} \quad B = -\frac{1}{3} \log \left(\frac{f \cdot S_{ut}}{S_e} \right)$$

$$\Rightarrow N = 4501 \text{ cycles}$$

$$= 1474.97 \text{ MPa} \quad = -0.131$$

Combined Loading:

Take load factor $K_c = 1$.

$$\text{Bending} \rightarrow \sigma_b \rightarrow K_f \cdot \sigma_b \quad \xrightarrow{\text{fatigue scf}}$$

$$\text{Axial} \rightarrow \sigma_{\text{axial}} \rightarrow K_f \cdot \sigma_{\text{axial}}$$

$$\text{Tension/shear: } \tau \rightarrow K_{fs} \cdot \tau$$

$\xrightarrow{\text{fatigue scf}}$

in shear

Calculate von Mises stress

$$\sigma' = \sqrt{(K_f \cdot \sigma_{\text{bending}} \pm K_f \cdot \sigma_{\text{axial}})^2 + 3(K_{fs} \cdot \tau)^2}$$

takes into account
 $K_c = 0.59$ implicitly

$$\left(\begin{array}{l} \text{v. m.} \\ \text{c. a.} \end{array} \right) \left\{ \begin{array}{l} 100 \cdot 0 = 0 \\ 225 \cdot 0 = 0 \end{array} \right. \quad \left. \begin{array}{l} \text{v. m.} = 0 \\ \text{SPT} = 0 \end{array} \right.$$

$$\text{SPT} = 0$$

$$F01 \cdot 0 = 0 \quad \text{SPT} = 1 = K_f$$

$$28 \cdot 0 =$$

$$+ = 34 \quad \text{v. m. head.} = 0$$

$$+ = 34 = 34 = K_f = 1$$

$$225 \times 1 \times 1 \times 1 \times 1 \times 28 \cdot 0 \times \text{SPT} = 0 = 0$$

$$0 \text{ m} 8 - 1 \text{ m} =$$

$$1 \text{ m} 0 \text{ m} 8 - 0 \text{ m} 8 = 0 \text{ m} 8 \quad \text{immed.} \quad \textcircled{1}$$

$$0 \text{ m} 8 < 32 < 0 \text{ m} 8$$

$$0 \text{ m} 8 = 0 \text{ m} 0 \text{ m} 8 = 0 \text{ m} 8 \quad 4 \text{ min.}$$

$$(31 - 3) \cdot 14 = 428 \cdot 0 = 4$$