

~~20~~ $\frac{\partial T}{\partial \theta} = 0$; $\frac{\partial V}{\partial \theta} = mg(R-r) \sin \theta \approx mg(R-r) \theta$
for small θ . Substitution of these

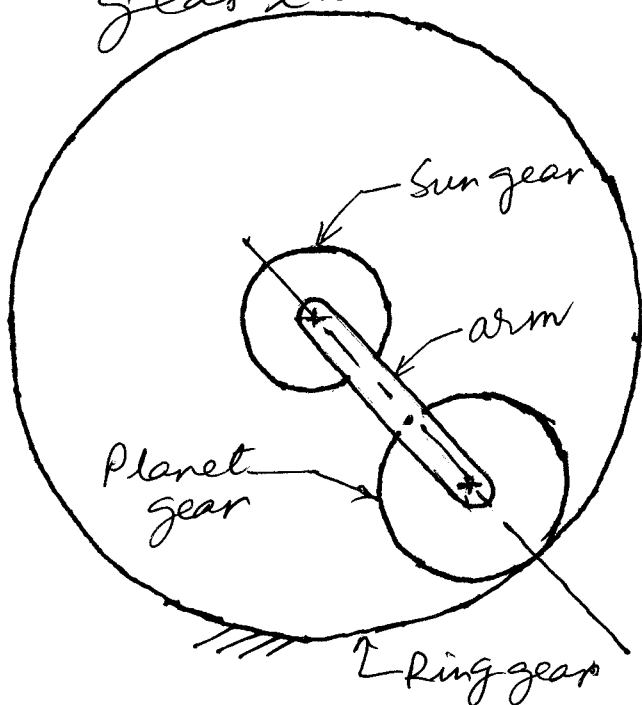
in ① gives the req^d DEOM as:

$$\frac{3}{2} m(R-r)^2 \ddot{\theta} + mg(R-r) \theta = 0 \quad \text{--- ④}$$

A comparison with $I_d \ddot{\theta} + K\theta = 0$ gives

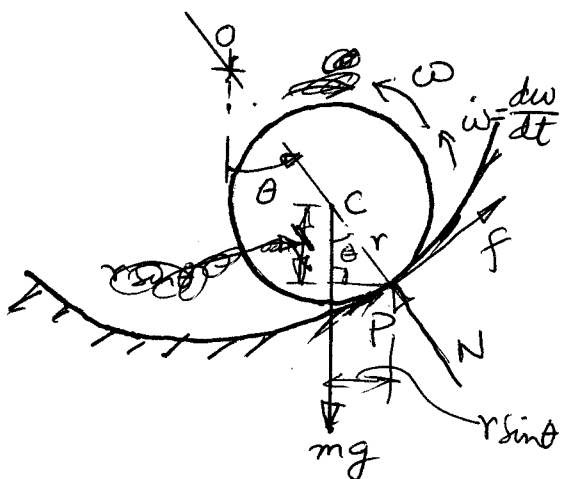
$$\omega_n = \sqrt{\frac{mg(R-r)}{\frac{3}{2} m(R-r)^2}} = \sqrt{\frac{2g}{3(R-r)}}, \text{ the req^d natural frequency.}$$

→ The question now is - where do we find a set-up such as the one discussed above? You must have studied ^(or, planetary) epicyclic gear trains. So, if we put an arm and a sun-gear and ~~replace~~ each gear and replace each gear by its pitch cylinder, then the above set-up becomes part of an epicyclic gear train as shown below.



Thus, the above system can be considered to be a subsystem of the gear train shown here and ~~as~~ a study of its vibrational characteristics could lead to a study of the same for the whole system shown here!

~~Epicyclic~~



(Angles exaggerated)
for clarity

You could also use the energy method (or, the power balance method) $\frac{d(T+V)}{dt} = 0$ to get the same DEOM.

How could you get it using ~~the~~ Newton's method (the force balance method)?

For that, you must draw the FBD as

shown in the figure here.

~~where~~ where f is the friction force & N the normal reaction. In order to eliminate the unknown forces f & N , we apply the moment balance method about point P which qualifies ~~for the~~ as the point about which the simple equation $I_P \ddot{\omega} = \text{Sum of moments of external forces applied}$, thus, ~~taking~~ since the whole body (cylinder) instantaneously rotate about P .

Thus, taking moments about P , we get

$$I_P \ddot{\omega} = -mgr \sin \theta \quad \left(\omega = \left(\frac{R-r}{r} \right) \dot{\theta} \Rightarrow \ddot{\omega} = \left(\frac{R-r}{r} \right) \ddot{\theta} \right)$$

$$\text{or, } \frac{3}{2} m r^2 \left(\frac{R-r}{r} \right) \ddot{\theta} + mgr \sin \theta = 0 \quad (\text{Assuming } \sin \theta \approx \theta)$$

~~which~~ which is basically the same as DEOM (4) derived earlier.