

## Stepper motor (clockwise)

```
#include <stdio.h>
#include <reg51.h>
char xdata point at 0xe803;
char xdata porta at 0xe800;
char xdata acc at 0x30;
delay();
{ int j;
  for(j=0; j<800; j++) {}
}
void main() {
  point = 0x80;
  while(1) {
    acc = 0x88;
    porta = acc;
    delay();
    acc = 0x44;
    porta = acc;
    delay();
    acc = 0x22;
    porta = acc;
    delay();
```

```
acc = 0x11;
pouta = acc;
delay(); }
```