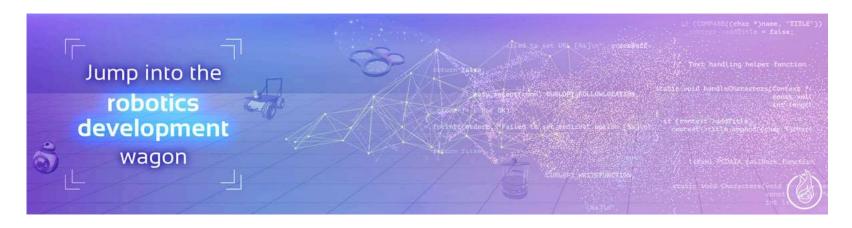
ROS Basics in 5 days

Unit 0 Introduction



Congratulations! You're on the path to becoming a ROS Developer.

The demand for robotics developers is growing, but there are not enough developers with the knowledge to program robots. This is your chance to stand out among the rest of the world's engineers. If you jump on the wagon of robotics development now, you will have a clear advantage over other developers.



(Further reading: Why programming robots has a big future (https://www.theconstructsim.com/become-robotics-developer/).)

0.1 Why should you take this course?

If you want to create the intelligent robot of the future, you need to learn the **robot programming standards**. At present, ROS is the way most service robots are programmed. **ROS** is the **standard for robotics programming**.

If you want to become a robotics developer, you need to learn ROS!

If you want to make a difference and create an intelligent robot, you need to learn ROS.

Learning ROS is NOT an easy task

We know from our own experience how difficult it is to learn ROS. It requires a lot of time and effort to learn. Also, learning from just the ROS official documentation, slides, posts, or videos is very frustrating because you don't get the chance to practice. This is not very helpful for a beginner and can even get you lost.

That is why we have created this specific program to help you learn it with more efficiency and depth, but with less trouble.

The main purpose of this platform is to help you learn ROS fast, in an easy, intuitive, and practice-based way. **Our method is called 30/70**. You are going to dedicate 30% of the time learning theory and 70% of the time practicing with simulated robots.

Let's see how this method works with your very first exercise.

0.2 Hands-on right now!

Start learning by doing right now. You are going to practice with simple ROS commands, the Linux terminal, and the robot simulation. Go ahead!

- Demo -



Execute the following command in Terminal number #1 in order to start moving the BB-8 robot around the desert!.

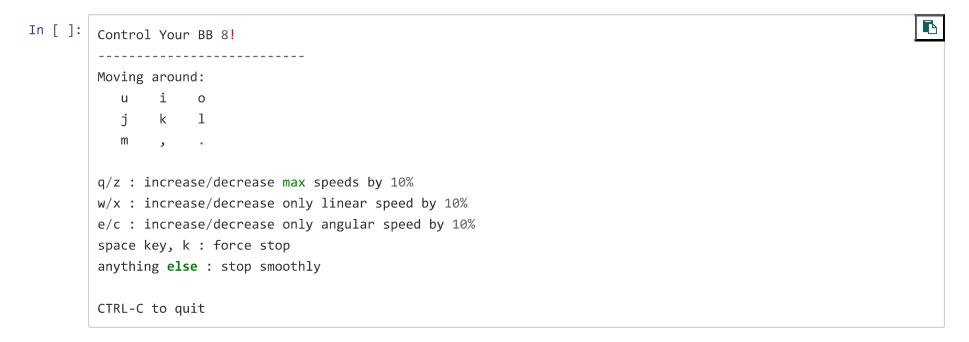
Terminals are like Linux terminals, but on the web. They are located, by default, at the bottom right section of the screen. You can type Linux commands there.

► Execute in terminal #1

In []: roslaunch bb_8_teleop keyboard_teleop.launch



With this command you are executing a simple ROS program which allows you to control the BB-8 robot with your keyboard. Quite interesting, right? Keep reading for further instructions!



Now, you can use the keys indicated in the Terminal Output in order to move the robot around. The basic keys are the following:

i	Move forward
,	Move backward
j	Turn left
	Turn right
k	Stop
q	Increase / Decrease Speed
Z	

Try it!! When you're done, you can press **Ctrl+C** to stop the execution of the program.

- End of Demo -

0.3 What you will learn

In this ROS BASICS IN 5 DAYS course, you are going to focus 100% on learning what really matters, avoiding all the unnecessary stuff. Also, you are going to practice with robots from the very beginning. No more only listening to long videos of someone talking, or watching very nice videos of a robot doing cool stuff, without learning anything. In this course, you will learn how to interact with robots, and YOU WILL actually DO IT.



Main points

- You are going to use different robots.
- You will have access to our experts to ask them questions in the Forum.
- You are going to have our full encouragement and support.
- You are going to practice... a lot!

It is going to be challenging, but with your perseverance and our guidance, you're going to succeed and **become one of the few robotics developers** in the world!

The robots of the future are waiting for you :). Welcome to the new adventure!

