in setting up the environment for each job.

. To reduce—the wastage time of cpu in serial processing, bater processing way

-> A piece of s/w earled monitor plays an important sole hue due to which the programmer had to no longer interact with the m/e directly

The user submits the job to a computer of the operator butches the similar jobs togen out inbut I have a places the entire batch on an input device, for the use by monitor.

The monitor is a program that resides in the (mainmemony)
from the 2/4 device, execute it 2 print out its result on the printer. Then it immediately reads the next job & repeat these steps until all jobs of the batch are over.

The monister handles the execution with Jel, (Jos control language) which is a special type of programming language used to provide instructions la monitor.

Advantages

17 Reduces the Idle time of epu, becoz transition from one job to another didn't require operator

interference

2) Environment set up time by reduced due to batching of similar jobs. En-If all-line FORTRAN jobs are batched together, the system needs to load the FORTRAN compiler once for processing all their iobs.

interaction is possible with the userduring program execution.

3) Multiprogramming: -(Ea-windows, unix, dinux)

There are two types of jobs 1) epu-bound jobs 2/1/0 bound jobs CPU-boundjobs - These jobs heavily utilize coo by performing numerical calculations a performy very little 2/0 operations.

e ombutations & most of the time they perform 1/0 operations. Hence their epu utilization is very 7 Multiprogramming refers to the interleaved ealeution of two or more different programs by - lue compaler. nemory 2 can use the epu. How operation takes place Juhen an user program that was eurrently executing, stards performing I/o operations, the epu is allocated to another user program in the main memory, that is ready to esse epu, instead of allowing epu-le be idle. Writing OS JobA JobA (Seenario of jobs in a multiprogramming JOBB J03C for cout system) While 305 A is not utilizing epul busy in 2/0 operation, epuls allocated to 308 B New Job Leady to epu Running) Advantages

Advantages

Blocked

Job must

2/0 completion 1) epunerer becomes idle, so heavy epuutiliz-Disady proper Memory Mgt. is needed

2) proper Memory Mgt. is needed to select

2) proper scheduling algh is needed to select

one job out of many jobs to sun

on chu.

Denteractive/ Time charing/ Multitasking punia Ding Systems. - It is a mechanism in which several users can use computer system simultaneously for performing their tast, given an impression that he/sh TEach user 1s own computer. Merminal 1 1 Tora - - - Tor N -7 A time shaving eystem has many user terminals simultaneously connected to the server. -7 Here each user process is allocated a very short period of time called time slice solot. which is 10 to 100 ms. 7 The cru provides service to each user process one by one in a circular fashion. 27 > Each user process gets service until the time elice expires. After the time slice expired the epo is forcefully taken away from the running process 2 allocated to the next one. New Ready Tob is allowated
Running

Time slice expires D/O Job must wait for D/O operation

The is also known as multitasking system because the oc because the os supports concurrent execution of multiple tasks in a multiprogramming environment Reduces cru idle time provides quick response to all users offers good computing Jack Hy to small cusers

Muldiprocessing systems: -The systems - I had ean have mobre-than one processor which sharps the computer bus, clock, Bometimes memory a asses peripheral devices ? other resources is known as multiprocessing systems. The term multiprocessing describes the interconnected compulers with more than one epo having the ability to simultaneously execute several programs 7. Différent Q independent programs can be processed Simultaneously by different epus or the epu may esimultaneously execute différent parts of the same program. Muttiprocessing systems are of a types. (1) Tighty coupled systems 1. -Here a single system wide primary memory is shared by all processous called shared memory. Memory [cpv] [cpv] (2) doosely coupled Systems: -Here each processor has its own memory. ocal M/13 MICZ M/C1 40 epu CPU Memory Memory Memory haved dada

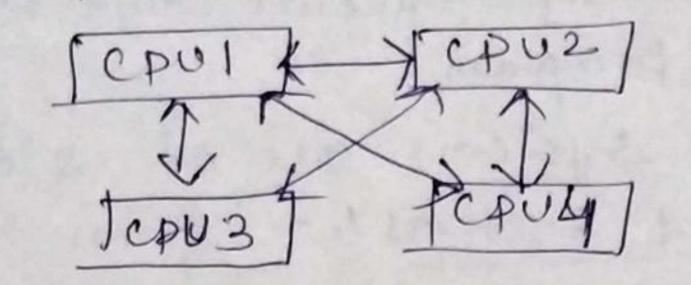
7 The os which is used by these types multiprocessor operating of systems Is known as systems.

can be either symmetric -7 The multiprocessor os or asymmetric.

- Symmessie model

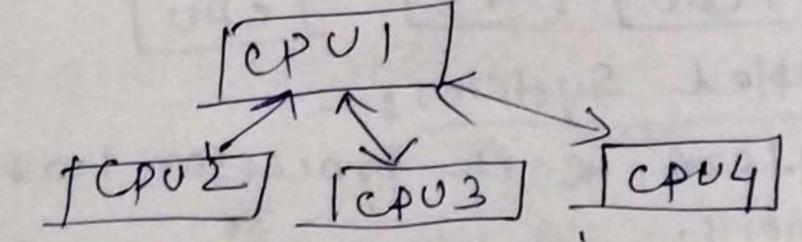
In this model each processor runs an identical copy of os a these copies communieade with one another as needed.

En - Encore's version of UNIX for Multiman romputers, sun os version-s



Asymmetric model

In this model each processor is assigned a specifie task. A master processor controls the entire system & other slave processors work as per the instruction of the master En sun os. version-4, cyber 170



Advantages of Multiprocessing

17 Bester performance - No. of processors, do the work in a shorter period of 27 Better Reliability - It one processor fails, then other processor ean take its workload.

initiations of Multiprocessing Requires a sophisticated os to support multiprocessors 2) Design of OS is more complex q enfensive 37 Maintainance is castly

Multipragramming

1724 is the interleaved execution of two or more jobs by a single epu computer system 2) Program segments are encented one after another

3) Implementation is less eastly 4) Encention is slower than multiprocessing

27 Less reliable than multipraes 57 More reliable, becoz it eng, be 102 failure of one epu', fails the entire system.

6) Main tamaneres is less costly 7) Destyn of this os is less complicated

(6) Real: time systems! -

Multiprocessing 1724 is the simultaneous execution of two os more Jobs by a momputer having more than one etc.

2) D+ makes possible for the system-20 simultaneously more or segments of one or different Program

3) eastly 4) Here at a particular instance, one can get more no. of out buts. So fastes execution is performed here

one epu fails, its work can be handled by other

Dy Maintainance is costlier 7) Requires more sophisticales os, whose design is complex.

Another form of spectal purpose of is the

7A real time system is used when there are styld time requirements on the operation of a processor.

os has a well defined -> De chasea so a real time fixed time constraints.

-7 Processing must be done within the well defined tized time limit, otherwise the system will fail.

7 200 Air Defence system receiving infort about aircraft movements from radars, Process controllin inglus

seientégle experiments, roboties, air traffie &.

-> Such os requires a priority based preemptive scheduling

. 7 Real time song of a types

a) Hard Real Ame os - Here all existeal faskshame to be completed strictly within the specified time limits, otherwise undesirable damage can occur b) soft Real time os - Here meeting of deadline by desirable but not mandatory. If the deadline could not be met, then any damage will not occur, but the result will lose its value. In Harmony, Marut ete

Personal computer operating system

the computer system dedicated for a

single user is known as per the os used in the
is called Plos.

design exiteria for this os.

7 some pc os emphasizes on user convenience where as some emphasizes on maximizing epu & peripheral utilization.

en windows as, as, xp, 2000, dinancett.

B) Distributed OS

Distributed OS are the oberating

Systems for a network of autonomous computers

connected by a communication network.

A distributed OS controls & manages the h/w

& s/w resources of a distributed system such

that its users view the entire system as a

powerful monolithic computer system.

when a program is enecuted in a dietalbated of user early know where the program system, the is enecated a from where the resources are accessed. Reasons for building a distributed systemates-17 Resource sharing - II a no. of different sites are connected to each other, then user at one at other the 2) Computation speed up - If a particular computation at other stee ean be divided into a no. of subcomputation, that ean sun simultaneously, then sesult can be 3) Reliability - Hailure of one system doesn't affect the rest. If one stlefails, then other stee can to exchange data with another system. 5) Flexibility - one of the most important feature of dist. 02. Dist. 02 is more flexible due to Rease of modification 2 117 ease of enhancement. 6) Scalability - It refers to the capability of expression are handle increased nearly new workload exactly.

To handle increased handle the new workload exactly.

added, then of ear handle the new workload exactly. 7) System wide sharing of resources 8) crobal naming of resources & remote processes.

a) pecessing remote resources & remote processes. anoeba, chorous Ste 2 Ste 3 CPU CPO Memor Memor

Multitasking us Multiprogramming

1) Multitasking referes to the eatability of an os to support concurrent execution of multiple-tasks in a muttiprogramming environment.

whereas multiprogramming refers to the capabili of an os to simultaneously maintain the code & data of several programs in the main memory.

P it requires solphisticaled memory management a protection features.

2) Multitasking is a subset of multiprogramming

37 In both eases epu & 2/0 devices are multipleared among artive trograms, but in multiplearing epu executes multiple tasks by switching beth them very frequently which gives the

multitasking eonsiders 2/0 interrupt whereas interrupt. 4) Mustiprogramming eonstders 2/0

e de la constant de l