detectBRISKFeatures	Determines points of noise and similarities
detectFASTFeatures	Determines only points of noise
detectHarrisFeatures	Determines intersections of similarities
detectMinEigenFeatures	Determines points of noise and intersections
detectMSERFeatures	Determines different regions
detectORBFeatures	Determine noise regions and similarities
detectSURFFeatures	Determine specific points of noise
detectKAZEFeatures	Determine points of noise
extractFeatures	Determine points of noise comparing photos
extractLBPFeatures	Determine similarities in gradients
extractHOGFeatures	Determines impact of object on image comparison
matchFeatures	Determines points of similarities between two images in RGB
showMatchedFeatures	Determines points of similarities between two images in grayscale
binaryFeatures	Determines similar features between two images
BRISKPoints	Determine points of noise and similarities in matrix form
KAZEPoints	Determine points of noise in matrix form
cornerPoints	Determines edges in photos
SURFPoints	Determine specific points of noise in matrix form
MSERRegions	Determines different regions of similar photos in matrix form
ORBPoints	Determine noise regions and similarities in matrix form