# **Shortest route** in a grid with obstacles

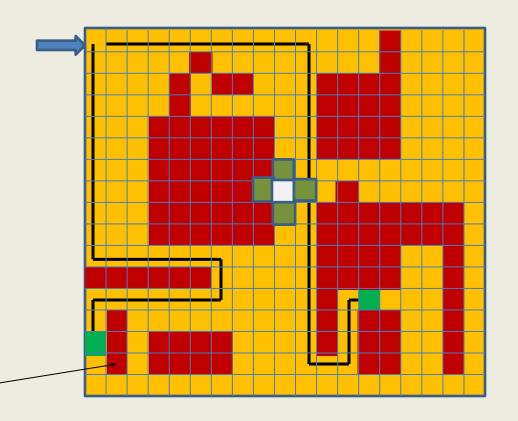
## Shortest route in a grid

From a cell in the grid, we can move to any of its <u>neighboring</u> cell in one <u>step</u>.

**Problem:** From top left corner, find shortest route to each cell avoiding obstacles.

**Input**: a Boolean matrix **G** representing the grid such that

G[i,j] = 0 if (i,j) is an obstacle, and 1 otherwise.

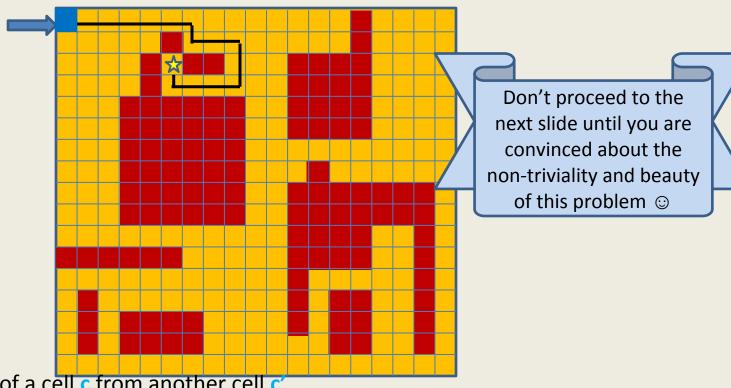


# Step 1:

Realizing the nontriviality of the problem

# Shortest route in a grid

#### nontriviality of the problem



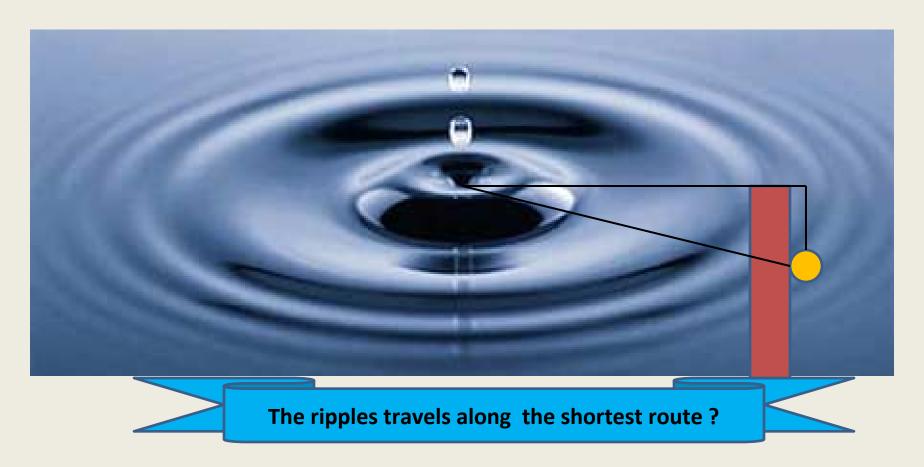
**Definition:** Distance of a cell c from another cell c'

is the length (number of steps) of the shortest route between c and c'.

We shall design algorithm for computing distance of each cell from the start-cell.

As an exercise, you should extend it to a data structure for retrieving shortest

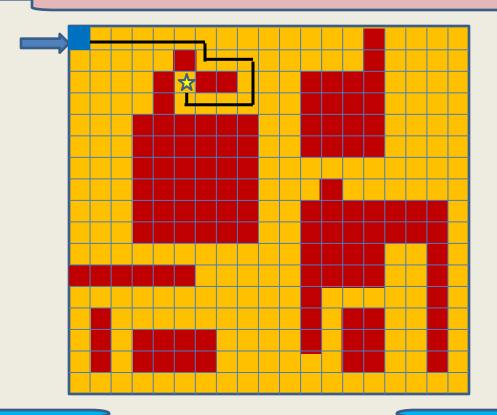
# Get inspiration from nature



# Shortest route in a grid

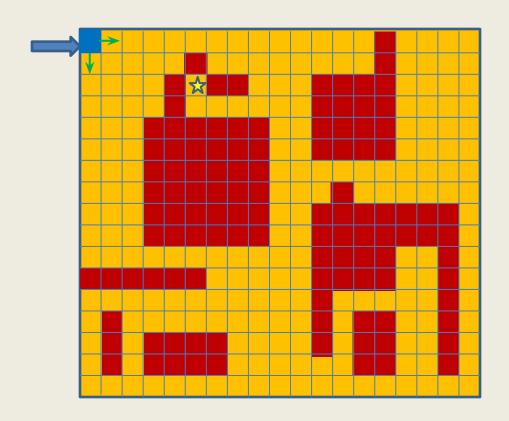
#### nontriviality of the problem

How to find the shortest route to ★ in the grid?

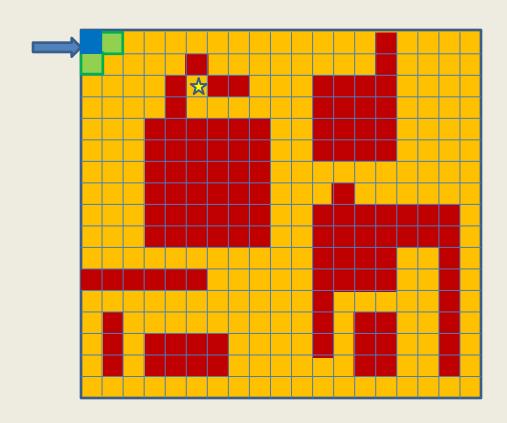


Create a ripple at the start cell and trace the path it takes to ★

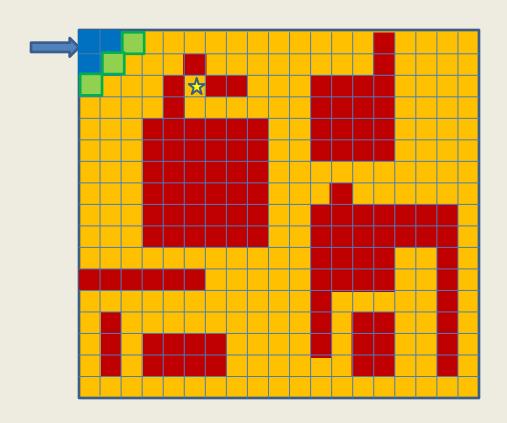
## propagation of a ripple from the start cell



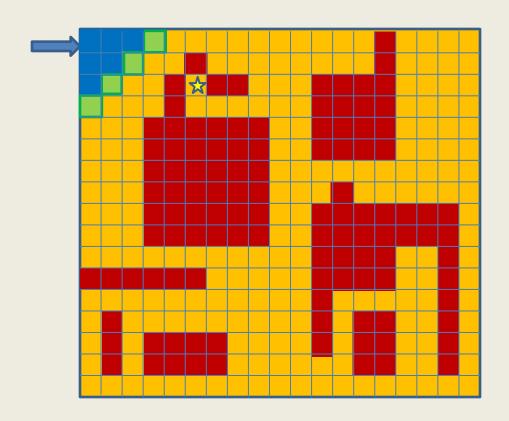
#### ripple reaches cells at distance 1 in step 1



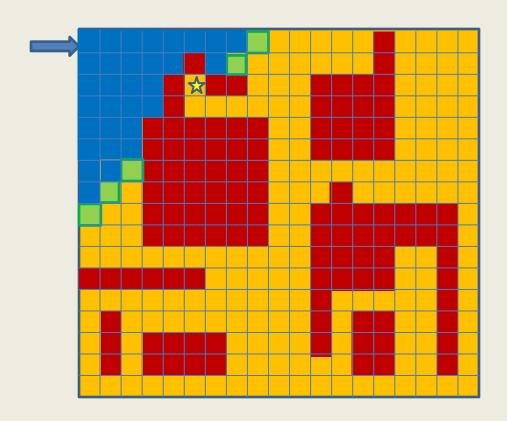
#### ripple reaches cells at distance 2 in step 2



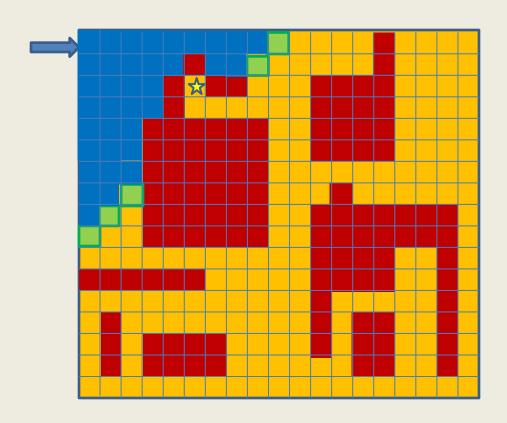
#### ripple reaches cells at distance 3 in step 3



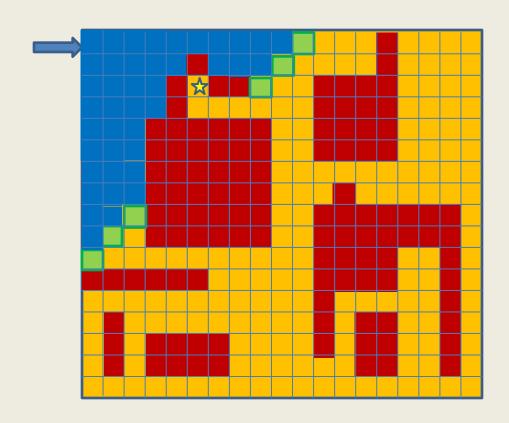
#### ripple reaches cells at distance 8 in step 8



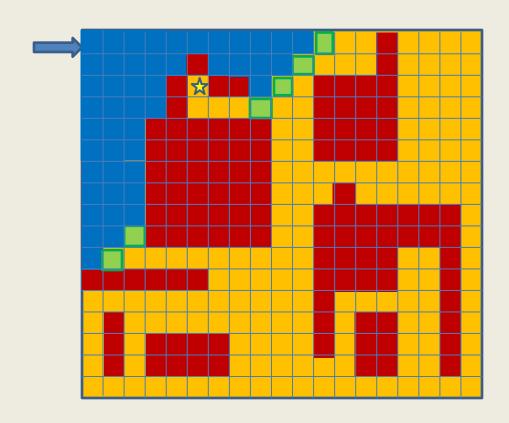
#### ripple reaches cells at distance 9 in step 9



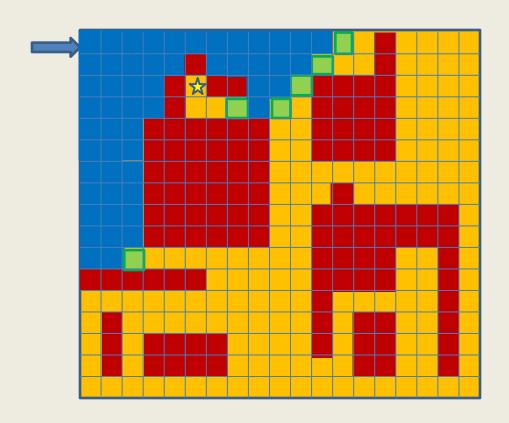
#### ripple reaches cells at distance 10 in step 10



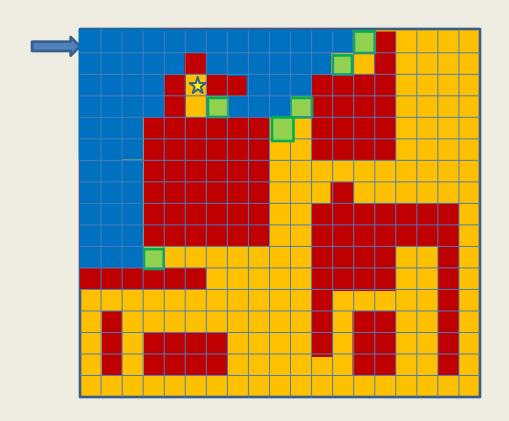
#### ripple reaches cells at distance 11 in step 11



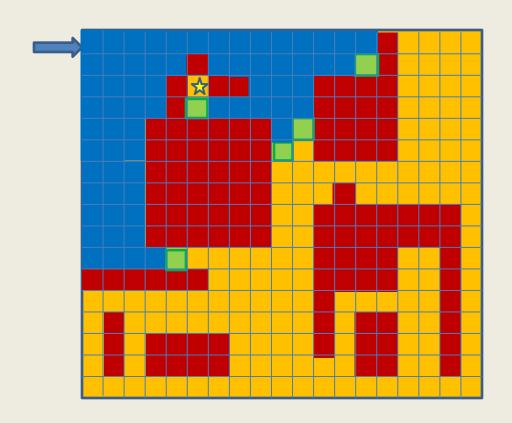
#### ripple reaches cells at distance 12 in step 12



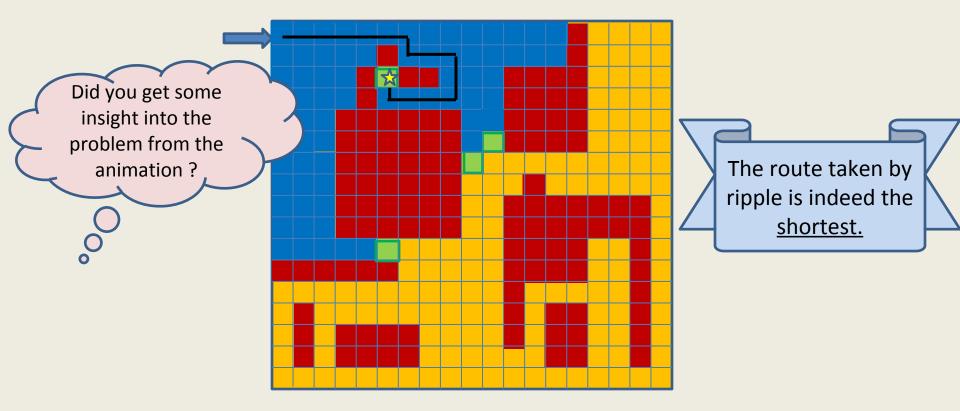
#### ripple reaches cells at distance 13 in step 13



#### ripple reaches cells at distance 14 in step 14



#### ripple reaches cells at distance 15 in step 15



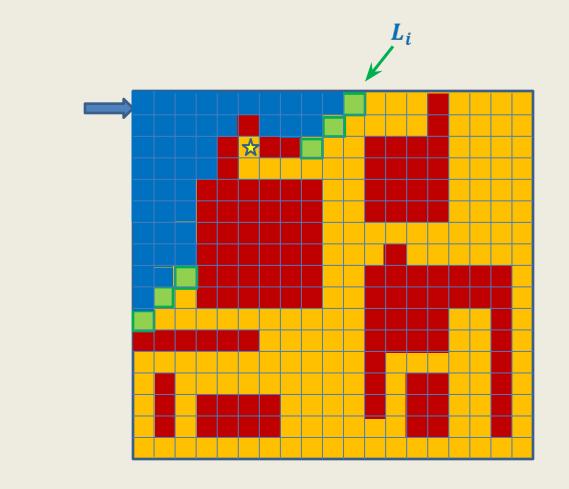
Think for a few more minutes with a free mind .

# Step 2: Designing algorithm for distances in grid

(using an insight into propagation of ripple)

## A snapshot of ripple after *i* steps

#### A snapshot of ripple after *i* steps

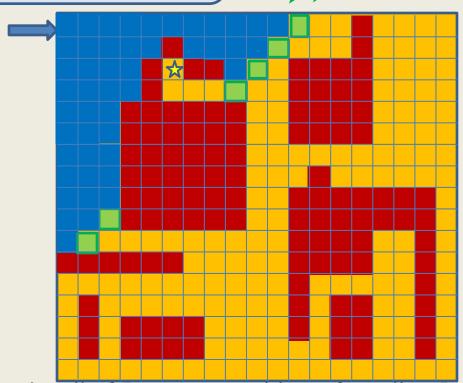


 $L_i$ : the cells of the grid at distance i from the starting cell.

#### A snapshot of the ripple after i + 1 steps

All the hardwork on the animation was done just to make you realize <u>this important</u> **Observation**. If you have got it, feel free to erase the animation from your mind ③.



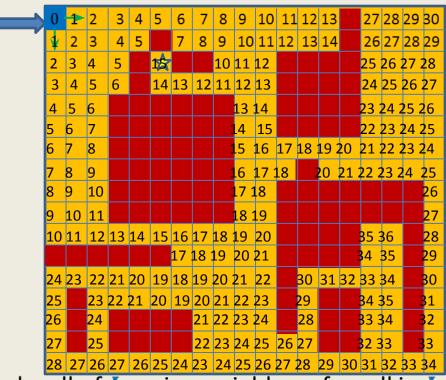


**Observation:** Each cell of  $L_{i+1}$  is a neighbor of a cell in  $L_i$ .

#### Distance from the start cell

It is worth spending some time on this matrix.

Does the matrix give some idea to answer the question?

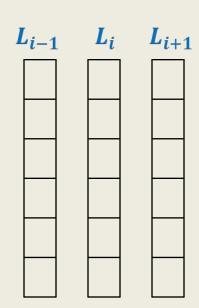


How can we generate  $L_{i+1}$  from  $L_i$ ?

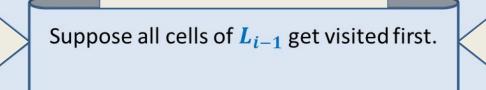
**Observation:** Each cell of  $L_{i+1}$  is a neighbor of a cell in  $L_i$ .

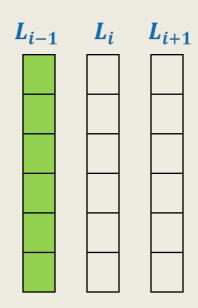






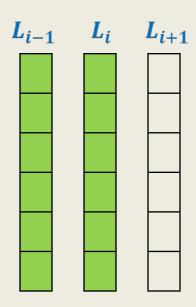






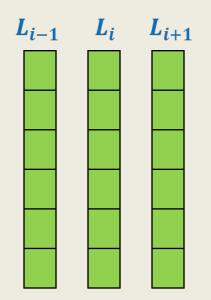


Suppose all cells of  $L_{i-1}$  get visited first. Then all cells of  $L_i$  are visited, and





Suppose all cells of  $L_{i-1}$  get visited first. Then all cells of  $L_i$  are visited, and then all cells of  $L_{i+1}$  are visited.



So by the time all cells of  $L_i$  are visited, if a cell neighboring to a cell of  $L_i$  is unvisited, it must be a cell of  $L_{i+1}$ .



#### So the algorithm should be:

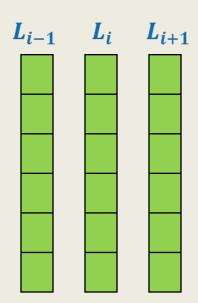
Initialize the distance of all cells except start cell as ∞

First compute  $L_1$ .

Then using  $L_1$  compute  $L_2$ 

Then using  $L_2$  compute  $L_3$ 

•••



## Algorithm to compute $L_{i+1}$ if we know $L_i$

```
Compute-next-layer(G, L_i)
  CreateEmptyList(L_{i+1});
  For each cell c in L_i
       For each neighbor b of c which is <u>not</u> an obstacle
             if (Distance[b] = \infty)
                   Insert(b, L_{i+1});
                   Distance[b] \leftarrow i + 1;
  return L_{i+1};
```

## The first (not so elegant) algorithm

(to compute distance to all cells in the grid)

```
Distance-to-all-cells(G, c_0) { L_0 \leftarrow \{c_0\}; For(i = 0 to ??) L_{i+1} \leftarrow Compute-next-layer(G, L_i); }
```

It can be as high as  $O(n^2)$ 

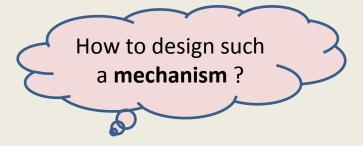
#### The algorithm is not elegant because of

So many temporary lists that get created.

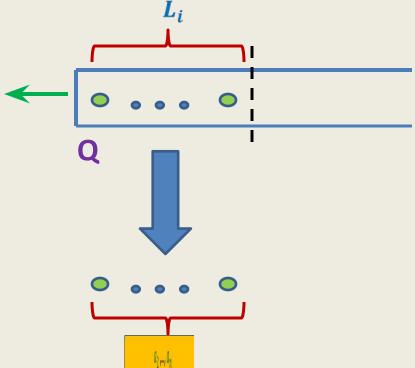
#### Towards an elegant algorithm ...

#### Key points we observed:

- We can compute cells at distance i + 1 if we know all cells up to distance i.
- Therefore, we need a mechanism
   to enumerate the cells in non-decreasing order of distances from the start cell.



# Keep a queue Q



Spend some time to see how seamlessly the queue ensured the requirement of visiting cells of the grid in non-decreasing order of distance.

## An elegant algorithm

(to compute distance to all cells in the grid)

```
Distance-to-all-cells(\mathbf{G}, \mathbf{c}_0)
  CreateEmptyQueue(Q);
  Distance(\mathbf{c}_0) \leftarrow 0;
  Enqueue(\mathbf{c}_0,Q);
  While(
              Not IsEmptyQueue(Q)
            c ← Dequeue(Q);
            For each neighbor b of c which is not an obstacle
                   if (Distance(b) = \infty)
                           Distance(b) ←
                                                   Distance(c) +1
                            Enqueue(b, Q);
```

## Proof of correctness of algorithm

Question: What is to be proved?

**Answer:** At the end of the algorithm,

**Distance**[c]= the distance of cell c from the starting cell in the grid.

Question: How to prove?

**Answer:** By the principle of mathematical induction on

the distance from the starting cell.

#### Inductive assertion:

#### P(i):

The algorithm correctly computes distance to all cells at distance *i* from the starting cell.

As an exercise, try to prove P(i) by induction on i.