

# Operating Systems - Winter 2018

## Assignment 1

Date of Submission : February 17, 2018

### A Simple System Call

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#### Description

It is required of us to print all the fields of task\_struct associated with a particular PID.

#### Functions Used

1. for\_each\_process : To iterate over all processes
2. The functions to get the various fields of task\_struct:

```
proc->comm
(long)task_pid_nr(proc)
(long)proc->state
(long)proc->prio
(long)proc->rt_priority
(long)proc->static_prio
(long)proc->normal_prio
(long)proc->on_cpu
(unsigned int)proc->se.on_rq
proc->blocked
proc->real_blocked
proc->thread.sp
```

3. Sprintf: To output to a text file.

#### Logic/Process:

The code iterates for the Process ids of all process and compares that to the pid input by the user.

The details for the same get printed as the output using the functions described above. `printf` has been used to output the same set of info to a file. `fd>=0` implies the user input is correct by all means and the output gets printed to the file passed as an argument in the test file. (test.c acc to our code) `fd<0` is where the error handling comes in.

## Implementation Details

### Changes to the Source Code

1. First, we created a new directory in the linux source code called `sh_task_info`. (name as was required)
2. In this directory we created two files, a `sh_task_info.h` header file and another `sh_task_info.c` file which is the file that contains the system call.
3. Then we created the Makefile through which the binary for the `.c` file would be created.
4. Next, we change the Makefile of the source code. Here, we give the link to the new directory.
5. Next, in the `arch` directory we go to `x86` folder and inside this there is the `syscalls` folder. In this folder we have the `syscall_64.tbl` file and here we add our system call.
6. Next we go to the `include` folder and inside that we go to the `linux` folder and to the `syscalls.h` header file. Here we give the link to our system call function that we wrote in `sh_task_info.c`
7. Finally we compile the kernel and update the grub.
8. To test the code we create a test file through which we see if we can conclude if the file was correctly executed or not as it returns 0 or -1, correct and incorrect implementation respectively.
9. The output is printed to a text file as well.

### Input by User

In the test file

(318,pid\_no.,filename) arguments are passed and the file compiled and run to get output.

### Error Handling

Error handling is done by `errno` which is an inbuilt variable in c.

## Expected Output and Interpretation

**The process name :** `proc->comm`

**The process ID :** `(long)task_pid_nr(proc)`

**Process State:** `(long)proc->state`

**Process priority:** `(long)proc->prio`

**Rt\_priority:** `(long)proc->rt_priority`

**Process Static Priority:** `(long)proc->static_prio`

**Process Normal Priority:** `(long)proc->normal_prio`

**CPU / on-cpu:** `(long)proc->on_cpu`

**Ready Queue:** (unsigned int)proc->se.on\_rq  
**Sigset\_blocked:** proc->blocked  
**Sigset\_real blocked:** proc->real\_blocked  
**Thread:** proc->thread.sp

A terminal display of the output is as below:

```
[ 136.029678] Process : init
[ 136.029678] pid_number : 1
[ 136.029678] process state : 1
[ 136.029678] priority : 120
[ 136.029678] rt_priority : 0
[ 136.029678] static priority : 120
[ 136.029678] normal priority : 120
[ 136.029678] , on_cpu : 0
[ 136.029678] , sched_entity : 0
[ 136.029678] , sigset blocked : 0
[ 136.029678] , sigset real_blocked : 0
[ 136.029678] , thread sp : 18446612133349013696
```

Sources:

medium.com  
LKD by Robert Love  
Elixir  
Source Pages  
Documents on errno



