A simple pendulum consisting of a mass "m" is hanging from a string of length "L". Write the equation of motion of the pendulum. Modify the equation motion of the pendulum, if it is damped by –  $mk\omega$  and forced by  $mAcos(\Omega t)$  forces. The detail of the notations is as follows.

 $\omega$ : Angular velocity of the mass

*k* : Positive constant

 $\Omega$  : Driving angular frequency

A : Amplitude of the driving force

## <u>Step -1</u>

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Formulate the algorithm to solve the equation of motion using (i) Euler predictor-corrector method (ii) Taylor series method, and (iii) second and fourth-order Runge-Kutta methods. Estimate the order of accuracy of each algorithm.

Step-2 Tabulate and also plot  $\theta$  (in radians) as a function of *time* using the following parameters.

	m(kg)	$L\left( m\right)$	$g(m/s^2)$	$\theta(0)$ (rad)	$\theta'(0) (rad/s)$	k	Α	Ω
1	1	1	1	0.2	0	0	0	
2	1	1	1	0.2	0	1,5,10	0	
3	1	1	1	0.2	0	1/2	0.5,1.2	2/3

$\Delta t$	n: no of steps	$sin\theta \approx \theta$
0.5, 1, 2	30	

Write the inference from the five plots.