

Towards an Ontology of Task Dependence in Organizations

Formal Model

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1 Agents, Tasks, and Goals

hasTask connects agents with tasks:

$$\forall a, t (hasTask(a, t) \rightarrow (Agent(a) \wedge Task(t))) \quad (1)$$

hasGoal connects agents with goals:

$$\forall a, g (hasGoal(a, g) \rightarrow (Agent(a) \wedge Goal(g))) \quad (2)$$

hasTask and *taskOf* are inverse relations:

$$\forall a, t (hasTask(a, t) \leftrightarrow taskOf(t, a)) \quad (3)$$

hasGoal and *goalOf* are inverse relations:

$$\forall a, g (hasGoal(a, g) \leftrightarrow goalOf(g, a)) \quad (4)$$

Every *Agent* has at least one *Task* and one *Goal*:


$$\forall a (Agent(a) \rightarrow (\exists t, g (Task(t) \wedge Goal(g) \wedge hasTask(a, t) \wedge hasGoal(a, g)))) \quad (5)$$


towards connects *Tasks* with *Goals*:


$$\forall t, g (towards(t, g) \rightarrow (Task(t) \wedge Goal(g))) \quad (6)$$

A *Task* (intention of an agent to work towards a goal) is defined in terms of the *Goal* it is oriented *towards*, i.e., every task has a goal it is oriented towards:

$$\forall t (Task(t) \rightarrow (\exists g (towards(t, g)))) \quad (7)$$

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hasActivity connects a *Task* with an *Activity* associated with it:

$$\forall t, a (hasActivity(t, a) \rightarrow (Task(t) \wedge Activity(a))) \quad (8)$$

hasActivity and *activityOf* are inverse relations:

$$\forall t, a (hasActivity(t, a) \leftrightarrow activityOf(a, t)) \quad (9)$$

A *Goal* is defined in terms of an *Agent* which has the goal and a desired *State*:

$$\begin{aligned} \forall g (Goal(g) \equiv (\exists a, s (Agent(a) \wedge State(s) \\ \wedge goalOf(g, a) \wedge hasDesiredState(g, s)))) \end{aligned} \quad (10)$$

hasDesiredState connects goals and (desired) states:

$$\forall g, s (hasDesiredState(g, s) \rightarrow (Goal(g) \wedge State(s))) \quad (11)$$

hasDesiredState and *desiredStateOf* are inverse relations:

$$\forall g, s (hasDesiredState(g, s) \leftrightarrow desiredStateOf(s, g)) \quad (12)$$

2 States

A *ComplexState* is a *State* that has at least one (proper) substate:

$$\begin{aligned} \forall s_1 (ComplexState(s_1) \rightarrow \exists s_2 (State(s_2) \\ \wedge hasSubState(s_1, s_2) \wedge (s_1 \neq s_2))) \end{aligned} \quad (13)$$

A *ComplexState* can be either a *ConjunctiveState* or *DisjunctiveState*, both of which are mutually exclusive:

$$\forall s (ComplexState(s) \rightarrow (ConjunctiveState(s) \vee DisjunctiveState(s))) \quad (14)$$

$$\forall s_1, s_2 ((ConjunctiveState(s_1) \wedge (DisjunctiveState(s_2)) \rightarrow (s_1 \neq s_2))) \quad (15)$$

An *AtomicState* cannot have a substate:

$$\forall s_1 (AtomicState(s_1) \rightarrow \neg(\exists s_2 (hasSubState(s_1, s_2)))) \quad (16)$$

A *State* is complex or atomic:

$$\forall s (State(s) \rightarrow (ComplexState(s) \vee AtomicState(s))) \quad (17)$$

ComplexStates and *AtomicStates* are disjoint:

$$\forall s_1, s_2 (ComplexState(s_1) \wedge AtomicState(s_2) \rightarrow (s_1 \neq s_2)) \quad (18)$$

hasSubState connects a state to another state:

$$\forall s_1, s_2 (hasSubState(s_1, s_2) \rightarrow (State(s_1) \wedge State(s_2))) \quad (19)$$

A state cannot be a substate of itself:

$$\forall s_1, s_2 (hasSubState(s_1, s_2) \rightarrow (s_1 \neq s_2)) \quad (20)$$

hasSubState and *subStateOf* are inverse relations:

$$\forall s_1, s_2 (hasSubState(s_1, s_2) \leftrightarrow subStateOf(s_2, s_1)) \quad (21)$$

A state cannot have itself as a substate:

$$\forall s_1, s_2 (subStateOf(s_1, s_2) \rightarrow (s_1 \neq s_2)) \quad (22)$$

A state cannot be a substate of its substate:

$$\forall s_1, s_2 (hasSubState(s_1, s_2) \rightarrow \neg subStateOf(s_1, s_2)) \quad (23)$$

An *AtomicState* is defined in terms of a *StateCharacteristic*, *Operator*, and *Value*:

$$\begin{aligned} \forall s (AtomicState(s) \equiv \exists c, o, v (StateCharacteristic(c) \wedge Operator(o) \\ \wedge Value(v) \wedge hasStateCharacteristic(s, c) \\ \wedge hasOperator(s, o) \wedge hasValue(s, v))) \end{aligned} \quad (24)$$

hasStateCharacteristic and *stateCharacteristicOf* are inverse relationships:

$$\forall s, c (hasStateCharacteristic(s, c) \rightarrow stateCharacteristicOf(c, s)) \quad (25)$$

hasOperator and *operatorOf* are inverse relationships:

$$\forall s, o (hasOperator(s, o) \rightarrow operatorOf(o, s)) \quad (26)$$

hasValue and *valueOf* are inverse relationships:

$$\forall s, v (hasValue(s, v) \rightarrow valueOf(v, s)) \quad (27)$$

3 Activities and Resources

An *Activity* is a function, or well-defined pattern of operation, and *causes* a *State*:

$$\forall a (Activity(a) \rightarrow \exists s (causes(a, s))) \quad (28)$$

causes connects activities and states:

$$\forall a, s (causes(a, s) \rightarrow (Activity(a) \wedge State(s))) \quad (29)$$

performedBy connects activities and agents, i.e., *Activity* is performed by an *Agent*:

$$\forall a, g (performedBy(a, g) \rightarrow (Activity(a) \wedge Agent(g))) \quad (30)$$

activityOf connects activities and tasks.

$$\forall a, t (\text{activityOf}(a, t) \rightarrow (\text{Activity}(a) \wedge \text{Task}(t))) \quad (31)$$

causes and *causedBy* are inverse relationships:

$$\forall a, s (\text{causes}(a, s) \leftrightarrow \text{causedBy}(s, a)) \quad (32)$$

performedBy and *performs* are inverse relationships:

$$\forall a, g (\text{performedBy}(a, g) \leftrightarrow \text{performs}(g, a)) \quad (33)$$

activityOf and *hasActivity* are inverse relationships:

$$\forall a, t (\text{activityOf}(a, t) \leftrightarrow \text{hasActivity}(t, a)) \quad (34)$$

An *Outcome* is a *State* that is *causedBy* an *Activity*:

$$\forall s, act (\text{causedBy}(s, act) \rightarrow \text{Outcome}(s)) \quad (35)$$

enables connects states with the activities they enable.

$$\forall a, s (\text{enables}(s, a) \rightarrow (\text{State}(s) \wedge \text{Activity}(a))) \quad (36)$$

enables and *enabledBy* are inverse relations:

$$\forall a, s (\text{enables}(s, a) \leftrightarrow \text{enabledBy}(a, s)) \quad (37)$$

3.1 Resources

A *Resource* is an entity that an *Activity* either *requires* or *produces*:

$$\forall r (\text{Resource}(r) \leftrightarrow \exists a (\text{requires}(a, r) \vee \text{produces}(a, r))) \quad (38)$$

requires connects an *Activity* with a *Resource* it needs. *produces* connects an *Activity* with a *Resource* it produces:

$$\forall a, r (\text{requires}(a, r) \rightarrow \text{Activity}(a) \wedge \text{Resource}(r)) \quad (39)$$

$$\forall a, r (\text{produces}(a, r) \rightarrow \text{Activity}(a) \wedge \text{Resource}(r)) \quad (40)$$

requires and *requiredBy* are inverse relationships. *produces* and *producedBy* are inverse relationships:

$$\forall r, a (\text{requires}(a, r) \leftrightarrow \text{requiredBy}(r, a)) \quad (41)$$

$$\forall r, a (\text{produces}(a, r) \leftrightarrow \text{producedBy}(r, a)) \quad (42)$$

A resource can either be shareable or nonshareable:

$$\begin{aligned} \forall r (\text{Resource}(r) \rightarrow & \text{ShareableResource}(r) \\ & \vee \text{NonShareableResource}(r)) \end{aligned} \quad (43)$$

NonShareableResource and *ShareableResource* are disjoint classes:

$$\begin{aligned} \forall r_1, r_2 (ShareableResource(r_1) \wedge NonShareableResource(r_2) \\ \rightarrow (r_1 \neq r_2)) \end{aligned} \quad (44)$$

A resource can either be consumable or nonconsumable, both of which are disjoint:

$$\begin{aligned} \forall r (Resource(r) \rightarrow ConsumableResource(r) \\ \vee NonConsumableResource(r)) \end{aligned} \quad (45)$$

ConsumableResource and *NonConsumableResource* are disjoint classes:

$$\begin{aligned} \forall r_1, r_2 (ConsumableResource(r_1) \wedge NonConsumableResource(r_2) \\ \rightarrow (r_1 \neq r_2)) \end{aligned} \quad (46)$$

The *uses* and *consumes* are subrelations of *requires* when the resource is non-consumable or consumable, respectively:

$$\forall a, r (uses(a, r) \rightarrow NonConsumableResource(r) \wedge requires(a, r)) \quad (47)$$

$$\forall a, r (consumes(a, r) \rightarrow ConsumableResource(r) \wedge requires(a, r)) \quad (48)$$

3.2 Activity Decomposition

An activity decomposition is a decomposition of an activity into at least two other activities (which it is a composition of):

$$\begin{aligned} \forall d (ActivityDecomposition(d) \rightarrow \exists a_1, a_2, a_3 (Activity(a_1) \wedge Activity(a_2) \\ \wedge Activity(a_3) \wedge decompositionOf(d, a_1) \wedge compositionOf(d, a_2) \\ \wedge CompositionOf(d, a_3) \wedge (a_1 \neq a_2) \wedge (a_2 \neq a_3) \wedge (a_1 \neq a_3))) \end{aligned} \quad (49)$$

decompositionOf and *compositionOf* connect activity decompositions with activities:

$$\begin{aligned} \forall d, a (decompositionOf(d, a) \rightarrow ActivityDecomposition(d) \\ \wedge Activity(a)) \end{aligned} \quad (50)$$

$$\begin{aligned} \forall d, a (compositionOf(d, a) \rightarrow ActivityDecomposition(d) \\ \wedge Activity(a)) \end{aligned} \quad (51)$$

decompositionOf and *hasDecomposition* are inverse relations. *compositionOf* and *hasComposition* are inverse relations:

$$\forall d, a (decompositionOf(d, a) \leftrightarrow hasDecomposition(a, d)) \quad (52)$$

$$\forall d, a (compositionOf(d, a) \leftrightarrow hasComposition(a, d)) \quad (53)$$

hasSubActivity connects an activity with another activity:

$$\begin{aligned} \forall a_1, a_2 (hasSubActivity(a_1, a_2) \rightarrow Activity(a_1) \wedge Activity(a_2) \\ \wedge (a_1 \neq a_2)) \end{aligned} \quad (54)$$

If an activity has a decomposition which is a composition of another activity, then the former activity has the latter as a subactivity:

$$\forall d, a_1, a_2 (Activity(a_1) \wedge Activity(a_2) \wedge hasDecomposition(a_1, d) \wedge compositionOf(d, a_2) \rightarrow hasSubActivity(a_1, a_2)) \quad (55)$$

hasSubActivity and *subActivityOf* are inverse relations:

$$\forall a_1, a_2 (hasSubActivity(a_1, a_2) \leftrightarrow subActivityOf(a_2, a_1)) \quad (56)$$

hasFirstActivity and *hasLastActivity* connects an activity decomposition with an activity:

$$\forall d, a (hasFirstActivity(d, a) \rightarrow ActivityDecomposition(d) \wedge Activity(a)) \quad (57)$$

$$\forall d, a (hasLastActivity(d, a) \rightarrow ActivityDecomposition(d) \wedge Activity(a)) \quad (58)$$

hasFirstActivity and *firstActivityOf* are inverse relations. *hasLastActivity* and *lastActivityOf* are inverse relations:

$$\forall d, a (hasFirstActivity(d, a) \leftrightarrow firstActivityOf(a, d)) \quad (59)$$

$$\forall d, a (hasLastActivity(d, a) \leftrightarrow lastActivityOf(a, d)) \quad (60)$$

hasSuccessor and *hasPredecessor* connect an activity with another activity:

$$\forall a_1, a_2 (hasSuccessor(a_1, a_2) \rightarrow Activity(a_1) \wedge Activity(a_2) \wedge (a_1 \neq a_2)) \quad (61)$$

$$\forall a_1, a_2 (hasPredecessor(a_1, a_2) \rightarrow Activity(a_1) \wedge Activity(a_2) \wedge (a_1 \neq a_2)) \quad (62)$$

First and last activities in a decomposition are not preceded or succeeded by any activity, respectively:

$$\forall d, a_1 (hasFirstActivity(d, a_1) \rightarrow \neg(\exists a_2 (hasPredecessor(a_1, a_2)))) \quad (63)$$

$$\forall d, a_1 (hasLastActivity(d, a_1) \rightarrow \neg(\exists a_2 (hasSuccessor(a_1, a_2)))) \quad (64)$$

An activity cannot be both a successor and predecessor of another activity:

$$\forall a_1, a_2 (hasSuccessor(a_1, a_2) \rightarrow \neg hasPredecessor(a_1, a_2)) \quad (65)$$

$$\forall a_1, a_2 (hasPredecessor(a_1, a_2) \rightarrow \neg hasSuccessor(a_1, a_2)) \quad (66)$$

hasSuccessor and *hasPredecessor* are inverse relations:

$$\forall a_1, a_2 (hasSuccessor(a_1, a_2) \leftrightarrow hasPredecessor(a_2, a_1)) \quad (67)$$

If an activity's subactivity requires or produces a resource, then so does the activity:

$$\forall a_1, a_2, r (subActivityOf(a_2, a_1) \wedge requires(a_2, r) \rightarrow requires(a_1, r)) \quad (68)$$

$$\forall a_1, a_2, r (subActivityOf(a_2, a_1) \wedge produces(a_2, r) \rightarrow produces(a_1, r)) \quad (69)$$

If an activity requires or produces a resource and has a decomposition, then it must have a subactivity that requires or produces the resource:

$$\begin{aligned} \forall a_1, d, r (hasDecomposition(a_1, d) \wedge requires(a_1, r) \\ \rightarrow \exists a_2 (hasSubActivity(a_1, a_2) \wedge requires(a_2, d))) \end{aligned} \quad (70)$$

$$\begin{aligned} \forall a_1, d, r (hasDecomposition(a_1, d) \wedge produces(a_1, r) \\ \rightarrow \exists a_2 (hasSubActivity(a_1, a_2) \wedge produces(a_2, d))) \end{aligned} \quad (71)$$

3.3 Activity Characteristics

hasActivityCharacteristic connects an activity with an activity characteristic associated with it:

$$\begin{aligned} \forall a, c (hasActivityCharacteristic(a, c) \rightarrow Activity(a) \\ \wedge ActivityCharacteristic(c)) \end{aligned} \quad (72)$$

hasActivityCharacteristic and *activityCharacteristicOf* are inverse relation:

$$\begin{aligned} \forall a, c (hasActivityCharacteristic(a, c) \\ \leftrightarrow activityCharacteristicOf(c, a)) \end{aligned} \quad (73)$$

Each *ActivityCharacteristic* must be tied to a specific *Activity*:

$$\forall c (ActivityCharacteristic(c) \rightarrow \exists a (activityCharacteristicOf(c, a))) \quad (74)$$

Each *ActivityCharacteristic* belongs to exactly one *Activity*:

$$\begin{aligned} \forall a_1, a_2, c (hasActivityCharacteristic(a_1, c) \\ \wedge hasActivityCharacteristic(a_2, c) \wedge Activity(a_1) \\ \wedge Activity(a_2) \rightarrow (a_1 = a_2)) \end{aligned} \quad (75)$$

SpatialCharacteristic, *SpatialCharacteristic*, *InputCharacteristic*, *ProcessCharacteristic*, and *OutputCharacteristic* are types of activity characteristics:

$$\forall c (TemporalCharacteristic(c) \rightarrow ActivityCharacteristic(c)) \quad (76)$$

$$\forall c (SpatialCharacteristic(c) \rightarrow ActivityCharacteristic(c)) \quad (77)$$

$$\forall c (InputCharacteristic(c) \rightarrow ActivityCharacteristic(c)) \quad (78)$$

$$\forall c (ProcessCharacteristic(c) \rightarrow ActivityCharacteristic(c)) \quad (79)$$

$$\forall c(OutputCharacteristic(c) \rightarrow ActivityCharacteristic(c)) \quad (80)$$

Start, *End*, and *Duration* are types of temporal characteristics:

$$\forall c(Start(c) \rightarrow TemporalCharacteristic(c)) \quad (81)$$

$$\forall c(End(c) \rightarrow TemporalCharacteristic(c)) \quad (82)$$

$$\forall c(Duration(c) \rightarrow TemporalCharacteristic(c)) \quad (83)$$

Location is a type of spatial characteristics:

$$\forall c(Location(c) \rightarrow SpatialCharacteristic(c)) \quad (84)$$

Material, *ResourceConsumption*, and *Cost* are types of input characteristics:

$$\forall c(Material(c) \rightarrow InputCharacteristic(c)) \quad (85)$$

$$\forall c(ResourceConsumption(c) \rightarrow InputCharacteristic(c)) \quad (86)$$

$$\forall c(Cost(c) \rightarrow InputCharacteristic(c)) \quad (87)$$

Implementation and *Method* are types of process characteristics:

$$\forall p(Implementation(c) \rightarrow ProcessCharacteristic(c)) \quad (88)$$

$$\forall p(Method(c) \rightarrow ProcessCharacteristic(c)) \quad (89)$$

Quantity, *Quality*, and *Design* are types of output characteristics:

$$\forall p(Quantity(c) \rightarrow OutputCharacteristic(c)) \quad (90)$$

$$\forall p(Quality(c) \rightarrow OutputCharacteristic(c)) \quad (91)$$

$$\forall p(Design(c) \rightarrow OutputCharacteristic(c)) \quad (92)$$

There can be at most a single instance of a characteristic of an activity for the following types of characteristics:

$$\begin{aligned} &\forall a, c_1, c_2 (hasActivityCharacteristic(a, c_1) \\ &\quad \wedge hasActivityCharacteristic(a, c_2) \\ &\quad \wedge ((Start(c_1) \wedge Start(c_2)) \vee (End(c_1) \wedge End(c_2)) \\ &\quad \vee (Duration(c_1) \wedge Duration(c_2))) \rightarrow (c_1 = c_2)) \end{aligned} \quad (93)$$

$$\begin{aligned} &\forall a, c_1, c_2 (hasActivityCharacteristic(a, c_1) \\ &\quad \wedge hasActivityCharacteristic(a, c_2) \\ &\quad \wedge ((Design(c_1) \wedge Design(c_2)) \vee (Quality(c_1) \wedge Quality(c_2)) \\ &\quad \vee (Quantity(c_1) \wedge Quantity(c_2))) \rightarrow (c_1 = c_2)) \end{aligned} \quad (94)$$

$$\begin{aligned}
& \forall a, c_1, c_2 (hasActivityCharacteristic(a, c_1) \\
& \quad \wedge hasActivityCharacteristic(a, c_2) \\
& \quad \wedge ((Material(c_1) \wedge Material(c_2)) \\
& \quad \vee (ResourceConsumption(c_1) \wedge ResourceConsumption(c_2)) \\
& \quad \vee (Cost(c_1) \wedge Cost(c_2))) \rightarrow (c_1 = c_2))
\end{aligned} \tag{95}$$

$$\begin{aligned}
& \forall a, c_1, c_2 (hasActivityCharacteristic(a, c_1) \\
& \quad \wedge hasActivityCharacteristic(a, c_2) \\
& \quad \wedge (Location(c_1) \wedge Location(c_2)) \rightarrow (c_1 = c_2))
\end{aligned} \tag{96}$$

$$\begin{aligned}
& \forall a, c_1, c_2 (hasActivityCharacteristic(a, c_1) \\
& \quad \wedge hasActivityCharacteristic(a, c_2) \\
& \quad \wedge ((Method(c_1) \wedge Method(c_2)) \\
& \quad \vee (Implementation(c_1) \wedge Implementation(c_2))) \\
& \quad \rightarrow (c_1 = c_2))
\end{aligned} \tag{97}$$

TemporalCharacteristic, *SpatialCharacteristic*, *InputCharacteristic*, *ProcessCharacteristic*, and *OutputCharacteristic* are disjoint classes:

$$\begin{aligned}
& \forall c (\neg((TemporalCharacteristic(c) \wedge SpatialCharacteristic(c)) \\
& \quad \vee (TemporalCharacteristic(c) \wedge InputCharacteristic(c)) \\
& \quad \vee (TemporalCharacteristic(c) \wedge ProcessCharacteristic(c)) \\
& \quad \vee (TemporalCharacteristic(c) \wedge OutputCharacteristic(c)) \\
& \quad \vee (SpatialCharacteristic(c) \wedge InputCharacteristic(c)) \\
& \quad \vee (SpatialCharacteristic(c) \wedge ProcessCharacteristic(c)) \\
& \quad \vee (SpatialCharacteristic(c) \wedge OutputCharacteristic(c)) \\
& \quad \vee (InputCharacteristic(c) \wedge ProcessCharacteristic(c)) \\
& \quad \vee (InputCharacteristic(c) \wedge OutputCharacteristic(c)) \\
& \quad \vee (ProcessCharacteristic(c) \wedge OutputCharacteristic(c))))
\end{aligned} \tag{98}$$

Start, *End*, and *Duration* are disjoint classes:

$$\begin{aligned}
& \forall c (\neg((Start(c) \wedge Duration(c)) \vee (End(c) \wedge Duration(c)) \\
& \quad \vee (Start(c) \wedge End(c)))
\end{aligned} \tag{99}$$

Design, *Quality*, and *Quantity* are disjoint classes:

$$\begin{aligned}
& \forall c (\neg((Design(c) \wedge Quality(c)) \vee (Design(c) \wedge Quantity(c)) \\
& \quad \vee (Quality(c) \wedge Quantity(c)))
\end{aligned} \tag{100}$$

ResourceConsumption, *Material*, and *Cost* are disjoint classes:

$$\begin{aligned}
& \forall c (\neg((ResourceConsumption(c) \wedge Cost(c)) \vee (Cost(c) \wedge Material(c)) \\
& \quad \vee (Material(c) \wedge ResourceConsumption(c)))
\end{aligned} \tag{101}$$

Method and *Implementation* are disjoint classes:

$$\forall c(\neg((Method(c) \wedge Implementation(c))) \quad (102)$$

4 Task Dependence

A *BasisOfDependence* is defined in terms of the dependum through which it exists:

$$\begin{aligned} \forall b(BasisOfDependence(b) \equiv \exists d(&hasDependum(b, d) \\ &\wedge (Activity(d) \vee State(d) \\ &\vee ActivityCharacteristic(d) \vee StateCharacteristic(d) \\ &\vee Resource(d)))) \end{aligned} \quad (103)$$

hasDependum and *dependumOf* are inverse relations:

$$\forall b, d(hasDependum(b, d) \leftrightarrow dependumOf(d, b)) \quad (104)$$

A basis of dependence has exactly one dependum:

$$\forall b, d_1, d_2(hasDependum(b, d_1) \wedge hasDependum(b, d_2) \rightarrow (d_1 = d_2)) \quad (105)$$

constrains and *alteredBy* connects a basis of dependence with either a task, activity, or activity characteristic:

$$\begin{aligned} \forall b, x(constrains(b, x) \rightarrow BasisOfDependence(b) \\ \wedge (Task(x) \vee Activity(x) \vee ActivityCharacteristic(x))) \end{aligned} \quad (106)$$

$$\begin{aligned} \forall b, x(alteredBy(b, x) \rightarrow BasisOfDependence(b) \\ \wedge (Task(x) \vee Activity(x) \vee ActivityCharacteristic(x))) \end{aligned} \quad (107)$$

constrains and *constrainedBy* are inverse relations. *alteredBy* and *alters* are inverse relations

$$\forall b, x(constrains(b, x) \leftrightarrow constrainedBy(x, b)) \quad (108)$$

$$\forall b, x(alteredBy(b, x) \leftrightarrow alters(x, b)) \quad (109)$$

Availability is a type of *BasisOfDependence* where the dependum must be a resource:

$$\begin{aligned} \forall b(Availability(b) \rightarrow BasisOfDependence(b) \\ \wedge \exists r(Resource(r) \wedge hasDependum(b, r))) \end{aligned} \quad (110)$$

Functionality is a type of *BasisOfDependence* where the dependum must be an activity:

$$\begin{aligned} \forall b(Functionality(b) \rightarrow BasisOfDependence(b) \\ \wedge \exists a(Activity(a) \wedge hasDependum(b, a))) \end{aligned} \quad (111)$$

Compatibility is a type of *BasisOfDependence* where the dependum must be a characteristic (either state or activity):

$$\begin{aligned} \forall b(Compatibility(b) \rightarrow BasisOfDependence(b) \\ \wedge \exists x((ActivityCharacteristic(x) \\ \vee StateCharacteristic(x)) \wedge hasDependum(b, s))) \end{aligned} \quad (112)$$

Complementarity is a type of *BasisOfDependence* where the dependum must be a characteristic (either state or activity):

$$\begin{aligned} \forall b(Complementarity(b) \rightarrow BasisOfDependence(b) \\ \wedge \exists x((ActivityCharacteristic(x) \\ \vee StateCharacteristic(x)) \wedge hasDependum(b, s))) \end{aligned} \quad (113)$$

Uncertainty is a type of *BasisOfDependence* where the dependum must be a characteristic (either state or activity):

$$\begin{aligned} \forall b(Uncertainty(b) \rightarrow BasisOfDependence(b) \\ \wedge \exists c((ActivityCharacteristic(c) \\ \vee StateCharacteristic(c)) \wedge hasDependum(b, c))) \end{aligned} \quad (114)$$

Complexity is a type of *BasisOfDependence* that does not necessarily specify the type of dependum:

$$\forall b(Complexity(b) \rightarrow BasisOfDependence(b)) \quad (115)$$

A *dependsOn* relation can only be between two tasks, activities, or activity characteristic:

$$\begin{aligned} \forall x, y(dependsOn(x, y) \rightarrow ((Task(x) \wedge Task(y)) \\ \vee (Activity(x) \wedge Activity(y)) \\ \vee (ActivityCharacteristic(x) \wedge ActivityCharacteristic(y)))) \end{aligned} \quad (116)$$

An activity characteristic *dependsOn* another activity characteristic if there exists a basis of dependence that constrains the former activity characteristic and is also altered by the latter characteristic:

$$\begin{aligned} \forall b, a_1, a_2, c_1, c_2(hasActivityCharacteristic(a_1, c_1) \\ \wedge hasActivityCharacteristic(a_2, c_2) \\ \wedge constrains(b, c_2) \wedge alteredBy(b, c_1) \\ \wedge (c_1 \neq c_2) \rightarrow dependsOn(c_2, c_1)) \end{aligned} \quad (117)$$

If an activity characteristic *dependsOn* another activity characteristic, then the activity of the former activity characteristic is dependent on the activity of the second activity characteristic:

$$\begin{aligned} \forall a_1, a_2, c_1, c_2(Activity(a_1) \wedge Activity(a_2) \wedge (a_1 \neq a_2) \\ \wedge hasActivityCharacteristic(a_1, c_1) \\ \wedge hasActivityCharacteristic(a_2, c_2) \\ \wedge dependsOn(c_2, c_1) \rightarrow dependsOn(a_2, a_1)) \end{aligned} \quad (118)$$

If an activity *dependsOn* another activity, then the task that the former activity is a part of is dependent on the task that the second activity is a part of:

$$\begin{aligned} \forall t_1, t_2, a_1, a_2 (& Task(t_1) \wedge Task(t_2) \wedge hasActivity(t_1, a_1) \\ & \wedge hasActivity(t_2, a_2) \wedge (t_1 \neq t_2) \\ & \wedge dependsOn(a_2, a_1) \rightarrow dependsOn(t_2, t_1)) \end{aligned} \quad (119)$$

An activity *dependsOn* another activity if there exists a basis of dependence that constrains the former activity and is also altered by a characteristic of the latter activity:

$$\begin{aligned} \forall a_1, a_2, b, c (& Activity(a_1) \wedge Activity(a_2) \wedge constrains(b, a_1) \\ & \wedge alteredBy(b, c) \wedge hasActivityCharacteristic(a_2, c) \\ & \wedge (a_1 \neq a_2) \rightarrow dependsOn(a_1, a_2)) \end{aligned} \quad (120)$$

An activity *dependsOn* another activity if there exists a basis of dependence that constrains a characteristic of the former activity and is also altered by the latter activity:

$$\begin{aligned} \forall a_1, a_2, b, c (& Activity(a_1) \wedge Activity(a_2) \wedge constrains(b, c) \\ & \wedge alteredBy(b, a_2) \wedge hasActivityCharacteristic(a_1, c) \\ & \wedge (a_1 \neq a_2) \rightarrow dependsOn(a_1, a_2)) \end{aligned} \quad (121)$$

An activity *dependsOn* another activity if there exists a basis of dependence that constrains the former activity and is also altered by the latter activity:

$$\begin{aligned} \forall a_1, a_2, b (& Activity(a_1) \wedge Activity(a_2) \wedge constrains(b, a_1) \\ & \wedge alteredBy(b, a_2) \wedge (a_1 \neq a_2) \rightarrow dependsOn(a_1, a_2)) \end{aligned} \quad (122)$$

A task *dependsOn* another task if there exists a basis of dependence that constrains the former task and is also altered by the task:

$$\begin{aligned} \forall t_1, t_2, b (& Task(t_1) \wedge Task(t_2) \wedge constrains(b, t_1) \wedge alteredBy(b, t_2) \\ & \wedge (t_1 \neq t_2) \rightarrow dependsOn(t_1, t_2)) \end{aligned} \quad (123)$$